

# CS502-Fundamental Of Algorithm FINAL TERM MCQS

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ALL answers are verified if found any mistake then Correct ACCORDINGLY

1. Which method is preferable for dealing with chain matrix multiplication?

- Divide and conquer strategy
- **Dynamic programming formulation**

- Graph theory
- Greedy Approach

2. Huffman algorithm produces the.....prefix code tree.

- Better
- **Optimal**

- Worst
- Best

3. A....w is adjacent to vertex v if there is an edge from v to w.

- Acyclic

- **Vertex**

- Loop
- Cycle

4. Using ASCII standard the string "greedy" will be encoded with

- 44 bits
- 120 bits
- 40 bits

- 48 bits**

5. Find the maximum value of the items which can carry using knapsack weight capacity =50

Item weight	Value
-------------	-------

10	70
----	----

20	20
----	----

30	80
----	----

70	200
----	-----

- 90

- 280

- 200

- 100**

6. In activity scheduling algorithm, each activity is represented by a

- Rectangle**

- Square

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- iii. Circle
- iv. Triangle

7. Those problems in which greedy finds good, but not always best is called a greedy.....

**i. Heuristic**

- ii. Solution
- iii. Result
- iv. Algorithm

8. The knapsack problem belongs to the domain of.....Problems

- i. Searching
- ii. Sorting
- iii. Linear solution

**iv. Optimization**

9. The general coin change problem can be solved using

- i. Recursion
- ii. Greedy algorithm

**iii. Dynamic programming**

- iv. Divide and conquer

10. Huffman algorithm produces the.....prefix code tree

**i. Optimal**

- ii. Better
- iii. Best
- iv. Worst

11. Huffman algorithm generates an optimum .....code

- i. Postfix
- ii. Infix
- iii. None of the given options

**iv. Prefix**

12. ....ways of representing graphics

- i. 1
- ii. 2
- iii. 3
- iv. 4

13. Knapsack word originates from .....language

**i. German**

- ii. English
- iii. French
- iv. Norwegian

14. Graphs are important.....model for many application problems

**i. Mathematical**

- ii. Unpredictable
- iii. Haphazard
- iv. Unsystematic

15. Which type of algorithm is harder to prove the correctness?

- i. Dynamic

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ii. Greedy

- iii. Divide and conquer
- iv. Brute force

16. ....Items are not allowed in 0/1 knapsack problem

i. Fractional

- ii. 0
- iii. 1
- iv. 0/1

17. Matrix multiplication is a(n).....operation

- i. Nether commutative nor associative
- ii. Transitive
- iii. Commutative

iv. Associative

18. For a Diagraph  $G=(V,E)$ , Sum of in-degree (v) -----.

- Not equal to sum of out-degree(v)
- = sum of out-degree(v) pg#115
- < sum of out-degree(v)
- > sum of out-degree(v)

19. DFS or BFS yields a-----of the graph.

- Traversed tree
- Spanning tree pg#125
- Simple tree
- Free tree

20. Using ASCII code, each character is represented by a fixed-length code of-----bits per character.

- 4
- 6
- 10

• 8 pg#100

21. In Knapsack Problem, the goal is to put items in the Knapsack such that the value of the items is-----

-----subject to weight limit of the Knapsack.

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- Minimized
  - Decreased
  - Maximized pg#109
  - None of the above given
22. Consider the string "abcdaacac", if the string is coded with ASCII codes, the message length would be---
- 70 bits
  - 60 bits
  - 90 bits
  - 72 bits
23. A graph is said to be acyclic if it contains-----.
- At least one cycle
  - Exactly one cycle
  - Always more than one cycle
  - No cycles pg#116
24. The number of edges that come out of a vertex is called the-----of that vertex in the digraph.
- Post-degree
  - in-degree
  - out-degree pg#114
  - pre-degree
25. If Matrix-A has dimensions "3x2" and Matrix-B has dimensions "2x3", then multiplication of Matrix-A and Matrix-B will result a new Matrix-C having dimensions.
- 3x2
  - 2x3
  - 2x2
  - 3x3pg#87
26. A/an-----is one in which you want to find, not just a solution, but the best solution.

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- Optimization problem

- Divide and Conquer
- NP complete problem
- Best problem

27. Fractional Knapsack is founded on-----method.

- Greedy page no109

- Recursive
- Divide and Conquer
- Dynamic programming

28. If the graph is represented using an adjacency matrix, then Breadth-first search takes-----  
-time.

- $O(E+1)$

- $O(V^2)$

- $O(V)$
- $O(E)$

29. In inductive approach of Knapsack problem, we consider 2 cases, -----or-----.

- Median, Mode
- Recursive, Iterative

- Leave object, Take object pg#93

- Sequentially, Parallel

30. A Greedy algorithm can NOT be used to solve all the-----problems.

- Dynamic programming (Google)

- Memorization programming
- Edit-distance programming
- Storing value programming

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31. In Huffman encoding, the-----is the number of occurrences of a character divided by the total characters in the message.

- Counting
- Parsing
- Relative Probability pg#100
- Weight

32. The Binary Tree constructed by a Huffman Encoding is a:

- Full Binary Tree pg#102
- Partial Binary Tree
- Incomplete Binary Tree
- None of the given option

33. Following is not the application of Edit Distance Problem.

- Speech recognition pg#76
- Spelling correction
- Ascending order
- Computational Molecular Biology

34. Consider three Matrices X, Y, Z of dimensions  $1 \times 2$ ,  $2 \times 3$ ,  $3 \times 4$  respectively. The number of multiplication of(XYZ) is:

- 18
- 32
- 24
- 30

35. In ----- Knapsack Problem, limitation is that an item can either be put in the bag or not. Fractional items are not allowed.

- a. 0
- b. 1
- c. 0/1 pg#91
- d. Fractional

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36. An in-place sorting algorithm is one that-----uses additional array for storage.

- Always
- Permanently
- Does not pg#54
- Sometime

37. If Matrix-A has dimensions “pxq” and Matrix-B has dimensions “qxr”, then multiplication of Matrix-A and Matrix-B will result a new Matrix-C having dimensions.

- P x q
- P x r page#84
- q x r
- q x p

38. Counting sort is suitable to sort the elements in range 1 to K.

- K is large
- K is small pg#71
- K may be large or small
- None

39. When matrix A of 5x 3 is multiply with matrix B of 3x 4 then the multiplication required is:

- 15
- 12
- 36
- 60

40. -----is a linear time sorting algorithm.

- Merge sort
- Quick sort

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- Bubble sort

- Radix sort

41. In Dynamic Programming approach, we do not store the solution to each sub problem in case if it reappears.

- True

- False page#75

42. Dynamic Programming approach is usually useful in solving optimization problem.

- True page#97

- False

43. Which of the following algorithm provides an optimal solution for the activity selection problem?

- Divide and Conquer

- Brute force

- Greedy pg#105

- Recursive

44. A graph is----- if every vertex can reach every other vertex.

- Connected pg#116

- Cycle

- Acyclic

- Loop

45. In a Huffman encoding when a new node is created by combining two nodes, the new node is placed in the \_\_\_\_\_.

- Priority queue pg#100

- Linked list

- Min heap tree

- Graph traversal

46. Huffman algorithm produces the \_\_\_\_\_ prefix code

- Optimal pg#105

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- Best
- Worst
- Better

47. In \_\_\_\_\_ algorithm, you hope that by choosing a local optimum at each step, you will end up a global

optimum.

- Simple
- Divide and conquer

• Greedy pg#97

- Brute Force

48. The string "Imncde" is coded with ASCII code, the message length would be \_\_\_\_\_ bits.

- 24
- 36
- 48
- 60

49. For graph traversal, breadth-first search strategy \_\_\_\_\_

- Is always recursive
- Cannot be recursive
- Cannot be non-recursive
- Can be both recursive and non-recursive page 119

50. In activity scheduling algorithm , the width of a rectangle \_\_\_\_\_

- Is always ignored
- Directs towards recursion
- Should be maximized
- Indicates the duration of an activity pg#106

51. If the graph is represented using an adjacency list, then Breadth-first search takes----- time

- $O(V^2)$

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- $O(V)$

•  $O(V+E)$  pg#138

- $O(E+1)$

52. Suppose you are given infinite coins of 1,2 ,3, and 4.Select the ways of the minimum number of coins that required to achieve a sum of 6:

- 1

• 2 Conceptual

- 3

- 4

53. sing ASCII standard the string “greedy” will be encoded with

• 48 bits Conceptual

- 120 bits

- 44 bits

- 40 bits

54. The Huffman codes provide a method of -----data efficiency.

- Reading/Writing

• Encoding/Decoding pg#99

- Divide/Conquer

- Inserting/Deleting

55. In the context of activity selection algorithm, time s dominated by sorting of the activities by-----

- Start Times

• Finish Times pg#106

- Average Times

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- CPU Burst Times

56. Time complexity of the “0-1” knapsack algorithm depends on----

- Number of items
- Capacity of the knapsack
- Size of the Table
- Number of items and capacity of knapsack (confirm)

57. The greedy approach gives us an optimal solution when the coins are all powers of a ----- denomination

- Fixed pg#98
- Variable
- Constant
- Static

58. In Activity Selection, we say that two activities are non-interfering if their start-finish interval-----overlap

- Do
- Do not pg#105
- Sometimes
- Once

59. How many steps are involved to design the dynamic programming strategy?

- 2
- 3
- 1

- 4 pg#92

60. Bag is a-----

- type of algorithm pg#119
- data structure

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- program
  - compiler
61. If a problem is in NP-complete, it must also be in NP.
- ▶ True page#170
  - ▶ False
62. The Huffman algorithm finds a optimal solution.
- ▶ True pg#105
  - ▶ False
63. The Huffman algorithm finds an exponential solution
- ▶ True
  - ▶ False pg#105
64. The Huffman algorithm finds a polynomial solution
- ▶ True google
  - ▶ False
65. The greedy part of the Huffman encoding algorithm is to first find two nodes with **smallest** frequency.
- ▶ True pg#100
  - ▶ False
66. The code word assigned to characters by the Huffman algorithm have the property that no code word is the prefix of any other.
- ▶ True pg#101
  - ▶ False
67. Huffman algorithm uses a greedy approach to generate a postfix code T that minimizes the expected length B (T) of the encoded string.
- ▶ True
  - ▶ False pg#102
68. Dijkstra's single source shortest path algorithm works if all edges weights are non-negative and there are negative cost cycles.
- ▶ True
  - ▶ False pg#154

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69. The term “coloring” came from the original application which was in architectural design.

▶ True

▶ **False pg#176**

70. In the clique cover problem, for two vertices to be in the same group, they must be adjacent to each other.

▶ True pg#176

▶ False

71. Dijkstra’s algorithm is operated by maintaining a subset of vertices

▶ True pg#155

▶ False

72. We do sorting to,

- ▶ keep elements in random positions
- ▶ keep the algorithm run in linear order
- ▶ keep the algorithm run in  $(\log n)$  order

▶ **keep elements in increasing or decreasing order pg#40**

73. After partitioning array in Quick sort, pivot is placed in a position such that

▶ **Values smaller than pivot are on left and larger than pivot are on right pg#48**

▶ Values larger than pivot are on left and smaller than pivot are on right

➤ Pivot is the first element of array

▶ Pivot is the last element of array

74. Merge sort is stable sort, but not an in-place algorithm

▶ True pg#54

▶ False

75. A  $p \times q$  matrix A can be multiplied with a  $q \times r$  matrix B. The result will be a  $p \times r$  matrix C. There are  $(p \cdot r)$  total entries in C and each takes \_\_\_\_\_ to compute.

▶  **$O(q)$  pg#84**

▶  $O(1)$

▶  $O(n^2)$

▶  $O(n^3)$

76. One of the clever aspects of heaps is that they can be stored in arrays without using any

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- Pointers pg#40

- constants
  - variables
  - functions
77. Merge sort requires extra array storage,

- True pg#54

- False
78. The Huffman codes provide a method of encoding data **inefficiently** when coded using

ASCII standard.

- True
- False pg#99

79. Using ASCII standard the string abacdaacac will be encoded with \_\_\_\_\_ bits.

- 80 pg#99

- 160
- 320
- 100

80. Using ASCII standard the string abacdaacac will be encoded with 160 bits.

- True
- False pg#99

81. Using ASCII standard the string abacdaacac will be encoded with 10 bytes.

- ❖ True
- ❖ False pg#99

82. The greedy part of the Huffman encoding algorithm is to first find two nodes with

**character** frequency

- ❖ True
- ❖ False

83. Huffman algorithm uses a greedy approach to generate an prefix code T that minimizes the expected length  $B(T)$  of the encoded string.

- ❖ True pg#100
- ❖ False

84. An optimization problem is one in which you want to find,

- ▶ Not a solution
- ▶ An algorithm
- ▶ Good solution
- ▶ The best solution pg#97

85. Although it requires more complicated data structures, Prim's algorithm for a minimum spanning tree is better than Kruskal's when the graph has a large number of vert

- ▶ True pg#149
- ▶ False

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86. If a problem is in NP, it must also be in P.

- ▶ True
- ▶ False

▶ **unknown** pg#173

87. What is generally true of Adjacency List and Adjacency Matrix representations of graphs?

▶ **Lists require less space than matrices but take longer to find the weight of an edge (v1,v2)** pg#116

- ▶ Lists require less space than *matrices* and they are faster to find the weight of an edge (v1,v2)
- ▶ Lists require more space than *matrices* and they take longer to find the weight of an edge (v1,v2)
- ▶ Lists require more space than *matrices* but are faster to find the weight of an edge (v1,

88. If a graph has  $v$  vertices and  $e$  edges then to obtain a spanning tree we have to delete

- ▶  $v$  edges.
- ▶  $v - e + 5$  edges
- ▶  $v + e$  edges.

▶ **None of these**

89. Maximum number of vertices in a Directed Graph may be  $|V|^2$

- ▶ True

▶ **False** pg#115

90. The Huffman algorithm finds a (n) \_\_\_\_\_ solution.

▶ **Optimal** pg#105

- ▶ Non-optimal
- ▶ Exponential
- ▶ Polynomial

91. The Huffman algorithm finds an exponential solution

- ▶ True

▶ **False** pg#115

92. Edge (u, v) is a forward edge if

- ▶ u is a proper descendant of v in the tree
- ▶ **v is a proper descendant of u in the tree** pg#129
- ▶ None of these

93. After partitioning array in Quick sort, pivot is placed in a position such that

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▶ Values smaller than pivot are on left and larger than pivot are on right (Page 48)

- ▶ Values larger than pivot are on left and smaller than pivot are on right
- ▶ Pivot is the first element of array
- ▶ Pivot is the last element of array

94. Merge sort is stable sort, but not an in-place algorithm

▶ True Page #54

- ▶ False

95. In counting sort, once we know the ranks, we simply \_\_\_\_\_ numbers to their final positions in an output array.

- ▶ Delete

▶ copy Page# 57

- ▶ Mark
- ▶ arrange

96. . Dynamic programming algorithms need to store the results of intermediate sub-problems.

▶ True pg#75

- ▶ False

97. . A  $p \times q$  matrix A can be multiplied with a  $q \times r$  matrix B. The result will be a  $p \times r$  matrix C. There are  $(p \cdot r)$  total entries in C and each takes \_\_\_\_\_ to compute.

▶  $O(q)$  pg#48

- ▶  $O(1)$
- ▶  $O(n^2)$
- ▶  $O(n^3)$

98. . \_\_\_\_\_ is a graphical representation of an algorithm

- ▶  $\Sigma$  notation
- ▶  $\Theta$  notation

▶ Flowchart

- ▶ Asymptotic notation

99. .Which of the following is calculated with **big o notation**?

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- ▶ Lower bounds
  - ▶ **Upper bounds pg#25**
  - ▶ Both upper and lower bound
  - ▶ Medium bounds
100. Merge sort makes two recursive calls. Which statement is true after these recursive calls finish, but before the merge step?

- ▶ The array elements form a heap
  - ▶ **Elements in each half of the array are sorted amongst themselves**
  - ▶ Elements in the first half of the array are less than or equal to elements in the second half of the array
  - ▶ None of the above
101. What is the solution to the recurrence  $T(n) = T(n/2) + n$ ,  $T(1) = 1$

- ▶  $O(\log n)$
- ▶  **$O(n)$  pg#37**

- ▶  $O(n \log n)$
  - ▶  $O(2n)$
102. Consider the following Huffman Tree

The binary code for the string TEA is

- ▶ **10 00 010**
- ▶ 011 00 010
- ▶ 10 00 110
- ▶ 11 10 110

103. .A greedy algorithm does not work in phases.

▶ True

▶ **False pg#97**

104. Can an adjacency matrix for a directed graph ever not be square in shape?

▶ Yes

▶ **No pg#116**

105. 44. One of the clever aspects of heaps is that they can be stored in arrays without using any\_\_\_\_\_.

▶ **Pointers pg#40**

- ▶ constants
- ▶ variables
- ▶ functions

106. .Merge sort requires extra array storage,

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▶ True Page 54

▶ False

107. .Non-optimal or greedy algorithm for money change takes \_\_\_\_\_

• ▶ O(k) Pg #99

• ▶ O(kN)

• ▶ O(2k)

• ▶ O(N)

108. The Huffman codes provide a method of encoding data **inefficiently** when coded using ASCII standard.

• ▶ True

❖ ▶ False Pg# 99

109. Using ASCII standard the string abacdaacac will be encoded with \_\_\_\_\_ bits.

• ▶ 80 pg# 99

• ▶ 160

• ▶ 320

• ▶ 100

110. Using ASCII standard the string abacdaacac will be encoded with 160 bits.

• ▶ True

❖ ▶ False (Pg# 99)

111. Using ASCII standard the string abacdaacac will be encoded with 320 bits.

❖ ▶ True

❖ ▶ False (Pg# 99)

112. .Using ASCII standard the string abacdaacac will be encoded with 100 bits.

❖ ▶ True

❖ ▶ False (Pg# 99)

113. Using ASCII standard the string abacdaacac will be encoded with 32 bytes

❖ ▶ True

❖ ▶ False (Pg# 99)

8bytes

114. The greedy part of the Huffman encoding algorithm is to first find two nodes with **smallest** frequency.

❖ ▶ True (Pg# 100)

❖ ▶ False

115. The greedy part of the Huffman encoding algorithm is to first find two nodes with **character** frequency

❖ ▶ True

❖ ▶ False (Pg# 100)

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116. Huffman algorithm uses a greedy approach to generate an **antefix** code T that minimizes the expected length B (T) of the encoded string.

❖ ▶ True

❖ ▶ **False (Pg# 102)**

117. Depth first search is shortest path algorithm that works on un-weighted graphs.

▶ True

▶ **False (Pg# 159)**

118. Floyd-Warshall algorithm is a dynamic programming algorithm; the genius of the algorithm is in the clever recursive formulation of the shortest path problem.

▶ **True (Pg# 162)**

▶ Flase

119. Floyd-Warshall algorithm, as in the case with DP algorithms, we avoid recursive evaluation by generating a table for

❖ ▶ k

❖ ▶  **$d_{ij}^k$  (Pg# 164)**

❖ ▶ True

❖ ▶ Flase

120. The term coloring came from the original application which was in map drawing.

❖ ▶ **True (Pg# 176)**

❖ ▶ False

121. In the clique cover problem, for two vertices to be in the same group, they must be \_\_\_\_\_ each other.

❖ ▶ Apart from

❖ ▶ Far from

❖ ▶ Near to

❖ ▶ **Adjacent to (Pg# 176)**

122. Fixed-length codes may not be efficient from the perspective of \_\_\_\_\_ the total quantity of data.

Select correct option:

▶ **Minimizing Pg# 99**

▶ Averaging

▶ Maximizing

▶ Summing

123. In greedy algorithm, at each phase, you take the \_\_\_\_\_ you can get right now, without regard for future consequences.

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▶ Worst

▶ Minimum

▶ Good

▶ **Best** **Page #97**

124. The difference between Prim's algorithm and Dijkstra's algorithm is that Dijkstra's algorithm uses a same key.

▶ True

▶ **False** **Page# 156**

125. If a problem is in NP-complete, it must also be in NP.

▶ **True** **Page# 178**

▶ False

126. If there are  $n$  items, there are \_\_\_\_\_ possible combinations of the items.

▶ 2

▶  $n$

▶  **$2^n$**  **Page# 92**

▶  $3^n$

127. .Using ASCII code, each character is represented by a fixed-length code word of \_\_\_\_\_ bits per character.

▶ 4

▶ 6

▶ **8** **pg # 99**

▶ 10

128. .In Knapsack Problem, the thief's goal is to put items in the bag such that the \_\_\_\_\_ of the items does not exceed the limit of the bag.

▶ **Value** **Page #91**

▶ Weight

▶ Length

▶ Balance

129. The knapsack problem does not belong to the domain of optimization problems.

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▶ True

▶ **False** Page# 91

130. In Huffman encoding, for a given message string, the frequency of occurrence (relative probability) of each character in the message is determined last.

▶ True

▶ **False** Page 100

131. Fixed-length codes are known for easy break up of a string into its individual characters.

▶ **True** Page# 99

▶ False

132. In \_\_\_\_\_ Knapsack Problem, limitation is that an item can either be put in the bag or not-fractional items are not allowed.

▶ 0

▶ 1

▶ **0/1** Page# 91

▶ Fractional

133. In Knapsack Problem, value and weight both are to be under consideration.

▶ **True** page #91

▶ False

134. Time complexity of DP based algorithm for computing the minimum cost of chain matrix Multiplication is \_\_\_\_\_.

▶ log n

▶ n

▶ n<sup>2</sup>

▶ **n<sup>3</sup>** Page #90

135. In DP based solution of knapsack problem, to compute entries of V we will imply a/an \_\_\_\_\_ approach.

▶ Subjective

▶ **Inductive** Page #93

▶ Brute force

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## ► Combination

136. A greedy algorithm sometimes works well for optimization problems.

► **True Page# 97**

## ► False

137. In Huffman encoding, frequency of each character can be determined by parsing the message and \_\_\_\_\_ how many times each character (or symbol) appears.

## ► Printing

## ► Incrementing

► **Counting (Page 100)**

## ► Deleting

138. Greedy algorithm can do very poorly for some problems.

► **True Page# 97**

## ► False

139. The Huffman codes provide a method of \_\_\_\_\_ data efficiently.

## ► Reading

► **Encoding Page# 99**

## ► Decoding

## ► Printing

140. In \_\_\_\_\_ based solution of knapsack problem, we consider 2 cases, Leave object Or Take object.

## ► Brute force

► **Dynamic programming Page #93**

141. Those problems in which Greedy finds good, but not always best is called a greedy\_\_\_\_\_.

## ► Algorithm

## ► Solution

► **Heuristic Page# 97**

## ► Result

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142. In brute force based solution of knapsack problem, we consider 2 cases, Leave object Or Take object.

▶ TRUE

▶ **FALSE** Page# 97

143. \_\_\_\_\_ problem, we want to find the best solution.

▶ Minimization

▶ Averaging

▶ **Optimization** Page# 97

▶ Maximization

144. Using ASCII standard the string abacdaacac will be encoded with 10 bytes.

▶ **True** Page #101

▶ False

145. In \_\_\_\_\_ algorithm, you hope that by choosing a local optimum at each step, you will end up at a global optimum.

▶ Simple

▶ Non Greedy

▶ **Greedy** Page# 97

▶ Brute force

146. Huffman algorithm uses a greedy approach to generate an prefix code T that minimizes the expected length B (T) of the encoded string.

▶ **True** Page# 102

▶ False

147. Counting Money problem is an example which cannot be optimally solved by greedy algorithm.

▶ **True** Page# 97

▶ False

148. Huffman algorithm generates an optimum prefix code.

▶ **True** Page# 102

▶ False

149. If the string "lmncde" is coded with ASCII code, the message length would be \_\_\_\_\_ bits.

▶ 24

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▶ 36

▶ **48**                      **6\*8=48**    page #99

▶ 60

150.        There are \_\_\_\_\_ nested loops in DP based algorithm for computing the minimum cost of chain matrix multiplication.

▶ 2

▶ **3**                                      **Page# 90**

▶ 4

151.        .A number of lectures are to be given in a single lecture hall. Optimum scheduling for this is an example of Activity selection.

▶ **True**                                      **Page# 105**

▶ False

152.        The activity scheduling is a simple scheduling problem for which the greedy algorithm approach provides a/an \_\_\_\_\_ solution.

▶ Simple

▶ Sub optimal

▶ **Optimal**    **Page# 105**

▶ Non optimal

153.        The string |xyz|, if coded with ASCII code, the message length would be 24 bits.

▶ **True**    **(3\*8=24)**                      **page#99**

▶ False

154.        An application problem is one in which you want to find, not just a solution, but the \_\_\_\_\_ solution.

▶ Simple

▶ **Good**                                      **Page #113**

▶ Best

155.        Suppose that a graph  $G = (V,E)$  is implemented using adjacency lists. What is the complexity of a breadth-first traversal of  $G$ ?

▶  $O(|V|^2)$

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▶  $O(V + |E|)$

▶  $O(V^2|E|)$

▶  **$O(V + |E|)$  pg #116**

156. Which is true statement?

▶ **Breadth first search is shortest path algorithm that works on un-weighted graphs Page #153**

▶ Depth first search is shortest path algorithm that works on un-weighted graphs.

▶ Both of above are true.

▶ None of above are true.

157. Forward edge is:

▶  $(u, v)$  where  $u$  is a proper descendent of  $v$  in the tree.

▶  **$(u, v)$  where  $v$  is a proper descendent of  $u$  in the tree. Page #129**

▶  $(u, v)$  where  $v$  is a proper ancestor of  $u$  in the tree.

▶  $(u, v)$  where  $u$  is a proper ancestor of  $v$  in the tree.

158. If you find yourself in maze the better traversal approach will be :

▶ **BFS google**

▶ BFS and DFS both are valid

▶ Level order

▶ DFS

159. In digraph  $G=(V,E)$  ;  $G$  has cycle if and only if

▶ The DFS forest has forward edge.

▶ **The DFS forest has back edge Page#131**

▶ The DFS forest has both back and forward edge

▶ BFS forest has forward edge

160. Back edge is:

▶  **$(u, v)$  where  $v$  is an ancestor of  $u$  in the tree. Page# 128**

▶  $(u,v)$  where  $u$  is an ancestor of  $v$  in the tree.

▶  $(u, v)$  where  $v$  is an predecessor of  $u$  in the tree.

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▶ None of above

161. Cross edge is :

▶ (u, v) where u and v are not ancestor of one another

▶ (u, v) where u is ancestor of v and v is not descendent of u.

▶ **(u, v) where u and v are not ancestor or descendent of one another** Page# 129

▶ (u, v) where u and v are either ancestor or descendent of one another.

162. Kruskal's algorithm (choose best non-cycle edge) is better than Prim's (choose best tree edge) when the graph has relatively few edges.

▶ **True** google

▶ False

163. What algorithm technique is used in the implementation of Kruskal solution for the MST?

▶ **Greedy Technique** Page# 142

▶ Divide-and-Conquer Technique

▶ Dynamic Programming Technique

▶ The algorithm combines more than one of the above techniques

164. What is the time complexity to extract a vertex from the priority queue in Prim's algorithm?

▶  $O(\log E)$

▶  $(V)$

▶  $(V+E)$

▶  **$O(\log V)$**  Page #152

165. The relationship between number of back edges and number of cycles in DFS is,

▶ Both are equal

▶ Back edges are half of cycles

▶ Back edges are one quarter of cycles

▶ **There is no relationship between no. of edges and cycles** Page# 131

166. You have an adjacency list for G, what is the time complexity to compute Graph transpose  $G^T$ ?

▶  **$(V + E)$**  Page# 138

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- ▶ (V E)
- ▶ (V)
- ▶ (V<sup>2</sup>)

167. There is relationship between number of back edges and number of cycles in DFS

- ▶ Both are equal.
- ▶ Cycles are half of back edges.
- ▶ Cycles are one fourth of back edges.

▶ **There is no relationship between back edges and number of cycles.** Page# 131

168. A digraph is strongly connected under what condition?

- ▶ A digraph is strongly connected if for every pair of vertices  $u, v \in V$ ,  $u$  can reach  $v$ .

▶ **A digraph is strongly connected if for every pair of vertices  $u, v \in V$ ,  $u$  can reach  $v$  and vice versa.** Page# 135

- ▶ A digraph is strongly connected if for at least one pair of vertex  $u, v \in V$ ,  $u$  can reach  $v$  and vice versa.

- ▶ A digraph is strongly connected if at least one third pair of vertices  $u, v \in V$ ,  $u$  can reach  $v$  and vice versa.

169. In in-place sorting algorithm is one that uses arrays for storage :

- ▶ An additional array

▶ **No additional array** Page#54

- ▶ Both of above may be true according to algorithm

- ▶ More than 3 arrays of one dimension.

170. In stable sorting algorithm

- ▶ One array is used
- ▶ In which duplicating elements are not handled.
- ▶ More than one arrays are required.

▶ **Duplicating elements remain in same relative position after sorting.** Page# 54

171. Which sorting algorithm is faster :

- ▶  $O(n^2)$

▶  **$O(n \log n)$**  Page# 46

- ▶  $O(n+k)$

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▶  $O(n^3)$

172. In Quick sort algorithm, constants hidden in  $T(n \lg n)$  are

▶ Large

▶ Medium

▶ Not known

▶ **Small**

173. Quick sort is based on divide and conquer paradigm; we divide the problem on base of pivot element and:

▶ There is explicit combine process as well to conquer the solution.

▶ No work is needed to combine the sub-arrays, the array is already sorted

▶ Merging the sub arrays

▶ **None of above. Page# 51**

174. . Dijkstra's algorithm :

▶ Has greedy approach to find all shortest paths

▶ Has both greedy and Dynamic approach to find all shortest paths

▶ **Has greedy approach to compute single source shortest paths to all other vertices Page#**

**154**

▶ Has both greedy and dynamic approach to compute single source shortest paths to all other vertices.

175. Which may be stable sort:

▶ Bubble sort

▶ Insertion sort

▶ **Both of above page# 54**

▶ Selection sort

176. In the analysis of Selection algorithm, we eliminate a constant fraction of the array with each phase; we get the convergent \_\_\_\_\_ series in the analysis,

▶ linear

▶ arithmetic

▶ **geometric page #37**

▶ exponent

177. How much time merge sort takes for an array of numbers?

▶  $T(n^2)$

▶  **$T(n)$  Page# 40**

▶  $T(\log n)$

▶  $T(n \log n)$

178. Dijkstra's algorithm is operates by maintaining a subset of vertices

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❖ True

Page# 155

❖ False

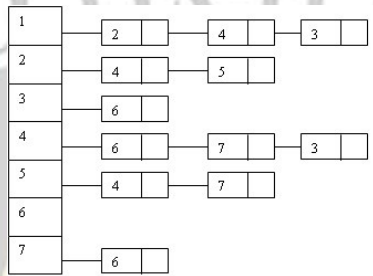
179. The difference between Prim's algorithm and Dijkstra's algorithm is that Dijkstra's algorithm uses a different key.

▶ True

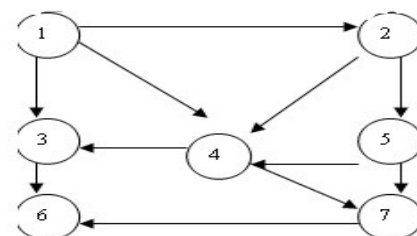
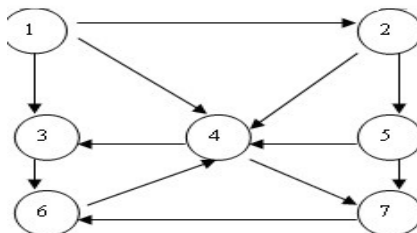
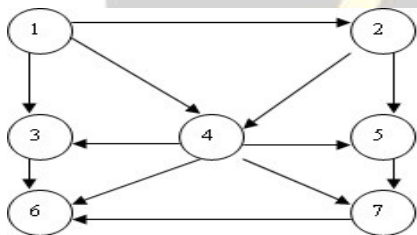
Page# 156

▶ False

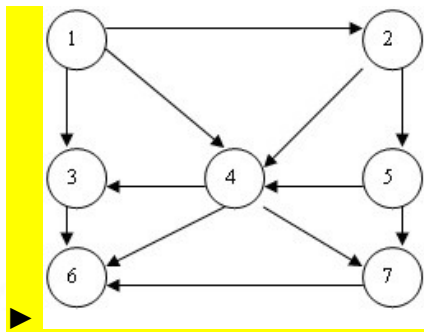
180. Consider the following adjacency list:



Which of the following graph(s) describe(s) the above adjacency list?



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Correct Option

pg#116

181. We do sorting to,

- ▶ keep elements in random positions
- ▶ keep the algorithm run in linear order
- ❖ ▶ keep the algorithm run in  $(\log n)$  order

❖ ▶ **keep elements in increasing or decreasing order**

Page# 40

182. . After partitioning array in Quick sort, pivot is placed in a position such that

❖ ▶ **Values smaller than pivot are on left and larger than pivot are on right**

Page# 48

- ❖ ▶ Values larger than pivot are on left and smaller than pivot are on right
- ❖ ▶ Pivot is the first element of array
- ❖ ▶ Pivot is the last element of array

183. . Merge sort is stable sort, but not an in-place algorithm

❖ ▶ **True** (Page# 54)

❖ ▶ False

184. In counting sort, once we know the ranks, we simply \_\_\_\_\_ numbers to their final positions in an output array.

- ❖ ▶ Delete
- ❖ ▶ **copy**
- ❖ ▶ Mark
- ❖ ▶ arrange

(Page# 57)

185. Dynamic programming algorithms need to store the results of intermediate sub-problems.

❖ ▶ **True** (Page# 75)

❖ ▶ False

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186. A  $p \times q$  matrix A can be multiplied with a  $q \times r$  matrix B. The result will be a  $p \times r$  matrix C. There are  $(p \cdot r)$  total entries in C and each takes \_\_\_\_\_ to compute.

❖ ▶ **O (q)** (Page# 84)

❖ ▶ O (1)

❖ ▶ O ( $n^2$ )

❖ ▶ O ( $n^3$ )

187. \_\_\_\_\_ is a graphical representation of an algorithm

❖ ▶  $\Sigma$  notation

❖ ▶  $\Theta$  notation

❖ ▶ **Flowchart**

❖ ▶ Asymptotic notation

188. Which of the following is calculated with **big o notation**?

❖ ▶ Lower bounds

❖ ▶ **Upper bounds** (Page# 25)

❖ ▶ Both upper and lower bound

❖ ▶ Medium bounds

189. Merge sort makes two recursive calls. Which statement is true after these recursive calls finish, but before the merge step?

❖ ▶ The array elements form a heap

❖ ▶ **Elements in each half of the array are sorted amongst themselves**

❖ ▶ Elements in the first half of the array are less than or equal to elements in the second half of the array

❖ ▶ None of the above

190. Non-optimal or greedy algorithm for money change takes \_\_\_\_\_

❖ ▶ **O(k)** (Page #99)

❖ ▶ O(kN)

❖ ▶ O(2k)

❖ ▶ O(N)

191. The Huffman codes provide a method of encoding data **inefficiently** when coded using ASCII standard.

❖ ▶ True

❖ ▶ **False** (Page# 99)

192. Using ASCII standard the string abacdaacac will be encoded with \_\_\_\_\_ bits.

❖ ▶ **80** (Page #99)

❖ ▶ 160

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- ❖ ▶ 320
- ❖ ▶ 100

193. Using ASCII standard the string abacdaacac will be encoded with 160 bits.

- ❖ ▶ True

❖ ▶ **False** (Page #99)

194. using ASCII standard the string abacdaacac will be encoded with 32 bytes

- ▶ True

▶ **False** (Page #99)

195. The greedy part of the Huffman encoding algorithm is to first find two nodes with **smallest** frequency.

▶ **True** (Page #100)

- ▶ False

196. The greedy part of the Huffman encoding algorithm is to first find two nodes with **character** frequency

- ▶ True

▶ **False** (Page# 100)

197. Huffman algorithm uses a greedy approach to generate an **antefix** code T that minimizes the expected length B (T) of the encoded string.

- ▶ True

▶ **False** (Page #102)

198. Depth first search is shortest path algorithm that works on un-weighted graphs.

- ▶ True

▶ **False** (Page# 153)

199. Dijkstra's single source shortest path algorithm works if all edges weights are non negative and there are no negative cost cycles.

▶ **True** (Page#159)

- ▶ False

200. Dijkstra's single source shortest path algorithm works if all edges weights are negative and there are no negative cost cycles.

- ▶ True

▶ **False** (Page #159)

201. Floyd-Warshall algorithm is a dynamic programming algorithm; the genius of the algorithm is in the clever recursive formulation of the shortest path problem.

▶ **True** (Page #162)

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▶ False

202. Floyd-Warshall algorithm, as in the case with DP algorithms, we avoid recursive evaluation by generating a table for

▶ k

▶  $d_{ij}^k$  (Page# 164)

▶ True

▶ False

203. the term coloring came from the original application which was in map drawing.

▶ True (Page #176)

▶ False

204. In the clique cover problem, for two vertices to be in the same group, they must be \_\_\_\_\_ each other.

▶ Apart from

▶ Far from

▶ Near to

▶ Adjacent to (Page# 176)

205. Fixed-length codes may not be efficient from the perspective of \_\_\_\_\_ the total quantity of data.

Select correct option:

▶ Minimizing (Page #99)

▶ Averaging

▶ Maximizing

▶ Summing

206. In greedy algorithm, at each phase, you take the \_\_\_\_\_ you can get right now, without regard for future consequences.

▶ Worst

▶ Minimum

▶ Good

▶ Best (Page #97)

207. The difference between Prim's algorithm and Dijkstra's algorithm is that Dijkstra's algorithm uses a same key.

▶ True

▶ False (Page# 156)

208. If a problem is in NP-complete, it must also be in NP.

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▶ True (Page #178)

▶ False

209. If there are  $n$  items, there are \_\_\_\_\_ possible combinations of the items.

❖ ▶ 2

❖ ▶  $n$

❖ ▶  $2^n$  (Page# 92)

❖ ▶  $3^n$

210. Using ASCII code, each character is represented by a fixed-length code word of \_\_\_\_\_ bits per character.

❖ ▶ 4

❖ ▶ 6

❖ ▶ 8 (Page #99)

❖ ▶ 10

211. In Knapsack Problem, the thief's goal is to put items in the bag such that the \_\_\_\_\_ of the items does not exceed the limit of the bag.

❖ ▶ Value (Page# 91)

❖ ▶ Weight

❖ ▶ Length

❖ ▶ Balance

212. The knapsack problem does not belong to the domain of optimization problems.

❖ ▶ True

❖ ▶ False (Page# 91)

213. In Huffman encoding, for a given message string, the frequency of occurrence (relative probability) of each character in the message is determined last.

❖ ▶ True

❖ ▶ False (Page #100)

214. Fixed-length codes are known for easy break up of a string into its individual characters.

▶ True (Page# 99)

▶ False

215. In \_\_\_\_\_ Knapsack Problem, limitation is that an item can either be put in the bag or not-fractional items are not allowed.

❖ ▶ 0

❖ ▶ 1

❖ ▶ 0/1 (Page# 91)

❖ ▶ Fractional

216. The term "coloring" came from the original application which was in architectural design.

❖ ▶ True

❖ ▶ False (Page# 173)

217. In Knapsack Problem, value and weight both are to be under consideration.

❖ ▶ True (page# 91)

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- ❖ ▶ False
  - 218. Time complexity of DP based algorithm for computing the minimum cost of chain matrix Multiplication is \_\_\_\_\_ .
- ❖ ▶ log n
- ❖ ▶ n
- ❖ ▶ n<sup>2</sup>
- ❖ ▶ **n<sup>3</sup>** (Page# 90)
- 219. In DP based solution of knapsack problem, to compute entries of V we will imply a/an \_\_\_\_\_ approach.
- ❖ ▶ Subjective
- ❖ ▶ **Inductive** (Page# 93)
- ❖ ▶ Brute force
- ❖ ▶ Combination
- 220. A greedy algorithm sometimes works well for optimization problems.
  - ▶ **True** (Page# 97)
  - ▶ False
- 221. In Huffman encoding, frequency of each character can be determined by parsing the message and \_\_\_\_\_ how many times each character (or symbol) appears.
- ❖ ▶ Printing
- ❖ ▶ Incrementing
- ❖ ▶ **Counting** (Page# 100)
- ❖ ▶ Deleting
- 222. Greedy algorithm can do very poorly for some problems.
  - ▶ **True** (Page# 97)
  - ▶ False
- 223. The Huffman codes provide a method of \_\_\_\_\_ data efficiently.
- ❖ ▶ Reading
- ❖ ▶ **Encoding** (Page# 99)
- ❖ ▶ Decoding
- ❖ ▶ Printing
- 224. In \_\_\_\_\_ based solution of knapsack problem, we consider 2 cases, Leave object Or Take object.
- ❖ ▶ Brute force
- ❖ ▶ **Dynamic programming** (Page #93)
- 225. Those problems in which Greedy finds good, but not always best is called a greedy \_\_\_\_\_ .
- ❖ ▶ Algorithm
- ❖ ▶ Solution
- ❖ ▶ **Heuristic** (Page# 97)
- ❖ ▶ Result

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226. In brute force based solution of knapsack problem, we consider 2 cases, Leave object Or Take object.

❖ ▶ TRUE

❖ ▶ FALSE (Page# 97)

227. \_\_\_\_\_ problem, we want to find the best solution.

❖ ▶ Minimization

❖ ▶ Averaging

❖ ▶ Optimization (Page#97)

❖ ▶ Maximization

228. Using ASCII standard the string abacdaacac will be encoded with 10 bytes.

❖ ▶ True (Page# 101)

❖ ▶ False

229. In \_\_\_\_\_ algorithm, you hope that by choosing a local optimum at each step, you will end up at a global optimum.

❖ ▶ Simple

❖ ▶ Non Greedy

❖ ▶ Greedy (Page# 97)

❖ ▶ Brute force

230. Huffman algorithm uses a greedy approach to generate an prefix code T that minimizes the expected length B (T) of the encoded string.

❖ ▶ True (Page #102)

❖ ▶ False

231. How many elements do we eliminate in each time for the Analysis of Selection algorithm?

▶ n / 2 elements (Page #37)

▶ (n / 2) + n elements

▶ n / 4 elements

▶ 2 n elements

232. Slow sorting algorithms run in,

▶  $T(n^2)$  (Page #39)

▶  $T(n)$

▶  $T(\log n)$

▶  $T(n \log n)$

233. Counting sort is suitable to sort the elements in range 1 to k:

▶ K is large

▶ K is small (Page# 57)

▶ K may be large or small

▶ None

234. Heaps can be stored in arrays without using any pointers; this is due to the \_\_\_\_\_ nature of the binary tree,

▶ left-complete (Page# 40)

▶ right-complete

▶ tree nodes

▶ tree leaves

235. Sieve Technique can be applied to selection problem?

▶ True (Page#35)

▶ False

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236. A heap is a left-complete binary tree that conforms to the \_\_\_\_\_

- ▶ increasing order only
- ▶ decreasing order only

▶ **heap order** (Page# 40)

▶ (log n) order

237. Divide-and-conquer as breaking the problem into a small number of

- ▶ pivot
- ▶ Sieve

▶ **smaller sub problems** (Page #34)

▶ Selection

238. In Sieve Technique we do not know which item is of interest

▶ **True** (Page# 34)

▶ False

239. The recurrence relation of Tower of Hanoi is given below  $T(n) = \begin{cases} 1 & \text{if } n=1 \\ 2T(n-1) & \text{if } n > 1 \end{cases}$  In order to move a tower of 5 rings from one peg to another, how many ring moves are required?

- ▶ 16
- ▶ 10
- ▶ 32

▶ **31**

240. For the heap sort, access to nodes involves simple \_\_\_\_\_ operations.

▶ **arithmetic** (Page# 41)

- ▶ binary
- ▶ algebraic
- ▶ logarithmic

241. For the sieve technique we solve the problem,

▶ **recursively** (Page# 34)

- ▶ mathematically
- ▶ precisely
- ▶ accurately

❖ 242. The sieve technique works in \_\_\_\_\_ as follows

▶ **phases** (Page #34)

- ▶ numbers
- ▶ integers
- ▶ routines

243. A (an) \_\_\_\_\_ is a left-complete binary tree that conforms to the heap order

▶ **heap** (Page# 40)

- ▶ binary tree
- ▶ binary search tree
- ▶ array

244. The sieve technique is a special case, where the number of sub problems is just

- ▶ 5
- ▶ many

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▶ 1 (Page #34)

▶ few

245. Analysis of Selection algorithm ends up with,

▶  $T(n)$

▶  $T(1 / 1 + n)$

▶  $T(n / 2)$

▶  $T((n / 2) + n)$  (Page #37)

246. For the heap sort we store the tree nodes in

▶ level-order traversal (Page #40)

▶ in-order traversal

▶ pre-order traversal

▶ post-order traversal

247. The reason for introducing Sieve Technique algorithm is that it illustrates a very important special case of,

▶ divide-and-conquer (Page# 34)

▶ decrease and conquer

▶ greedy nature

▶ 2-dimension Maxima

248. Theta asymptotic notation for  $T(n)$  :

▶ Set of functions described by:  $c \lg(n)$  Set of functions described by  $c \lg(n) \geq f(n)$  for  $c \geq 1$

▶ Theta for  $T(n)$  is actually upper and worst case comp

▶ Set of functions described by:

▶  $c \lg(n)$

249. Sieve Technique applies to problems where we are interested in finding a single item from a larger set of \_\_\_\_\_

▶ n items (Page# 34)

▶ phases

▶ pointers

▶ constant

250. Memorization is?

▶ To store previous results for future use

▶ To avoid this unnecessary repetitions by writing down the results of recursive calls and looking them up again if we need them later (Page# 47)

▶ To make the process accurate

▶ None of the above

251. Quick sort is

▶ Stable & in place

▶ Not stable but in place (Page#57)

▶ Stable but not in place

▶ Some time stable & some times in place

252. One example of in place but not stable algorithm is

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▶ Merger Sort

▶ **Quick Sort** (Page# 54)

▶ Continuation Sort

▶ Bubble Sort

253. . Continuation sort is suitable to sort the elements in range 1 to k

▶ K is Large

▶ K is not known

▶ K may be small or large

▶ **K is small** (Page# 57)

254. Which may be a stable sort?

▶ Merger

▶ Insertion

▶ **Both above** (Page #54)

▶ None of the above

255. . An in place sorting algorithm is one that uses \_\_\_ arrays for storage

▶ Two dimensional arrays

▶ More than one array

▶ **No Additional Array** (Page #54)

▶ None of the above

256. Continuing sort has time complexity of ?

▶ **O(n)**

▶ O(n+k)

▶ O(nlogn)

▶ O(k)

257. single item from a larger set of \_\_\_\_\_

▶ **n items** (Page# 34)

▶ phases

▶ pointers

▶ v constant

258. For the Sieve Technique we take time

▶ **T(nk)** ( Page# 34)

▶ T(n / 3)

▶ n<sup>2</sup>

▶ n/3

259. One Example of in place but not stable sort is

▶ **Quick** (Page# 54)

▶ Heap

▶ Merge

▶ Bubble

260. Consider the following Algorithm:

Factorial (n){

if (n=1)

return 1

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else

return (n \* Factorial(n-1))

Recurrence for the following algorithm is:

❖ ▶  $T(n) = T(n-1) + 1$

❖ ▶  $T(n) = nT(n-1) + 1$

❖ ▶  $T(n) = T(n-1) + n$

❖ ▶  **$T(n) = T(n-1) + 1$**

**261.** Due to left complete nature of binary tree, the heap can be stored in

❖ ▶ **Arrays (Page #40)**

❖ ▶ Structures

❖ ▶ Link List

❖ ▶ Stack

262. What type of instructions Random Access Machine (RAM) can execute?

❖ ▶ Algebraic and logic

❖ ▶ Geometric and arithmetic

❖ ▶ **Arithmetic and logic (Page# 10)**

❖ ▶ Parallel and recursive

263. What is the total time to heapify?

❖ ▶  **$O(\log n)$  (Page 43)**

❖ ▶  $O(n \log n)$

❖ ▶  $O(n^2 \log n)$

❖ ▶  $O(\log^2 n)$

264. word Algorithm comes from the name of the muslim author \_\_\_\_\_

❖ ▶ **Abu Ja'far Mohammad ibn Musa al-Khowarizmi.**

**265.** Al-Khwarizmi's work was written in a book titled \_\_\_\_\_

❖ ▶ **al Kitab al-mukhatasar fi hisab al-jabr wa'l-muqabalah**

**266.** Random access machine or RAM is a/an

❖ ▶ Machine build by Al-Khwarizmi

❖ ▶ Mechanical machine

❖ ▶ Electronics machine

❖ ▶ **Mathematical model (Page# 10)**

267. A RAM is an idealized machine with \_\_\_\_\_ random-access memory.

❖ ▶ 256MB

❖ ▶ 512MB

❖ ▶ **an infinitely large (Page #10)**

❖ ▶ 100GB

268. What will be the total number of max comparisons if we run brute-force maxima algorithm with n elements?

❖ ▶  $n^2$

❖ ▶  $\frac{n}{n^2}$

❖ ▶  **$n$  (Page# 14)**

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❖ ▶  $n^8$

269. Consider the following code:

```
For(j=1; j<n;j++)
```

```
    For(k=1; k<15;k++)
```

```
        For(l=5; l<n; l++)
```

```
            {
```

```
                Do_something_constant();
```

```
            }
```

What is the order of execution for this code.

❖ ▶  **$O(n)$**

❖ ▶  $O(n^3)$

❖ ▶  $O(n^2 \log n)$

❖ ▶  $O(n^2)$

270. Is it possible to sort without making comparisons?

❖ ▶ **Yes (Page# 57)**

❖ ▶ No

271. When we call heapify then at each level the comparison performed takes time

❖ ▶ **It will take  $\Theta(1)$  (Page# 43)**

❖ ▶ Time will vary according to the nature of input data

❖ ▶ It can not be predicted

❖ ▶ It will take  $\Theta(\log n)$

272. In Quick sort, we don't have the control over the sizes of recursive calls

❖ ▶ **True (Page# 40)**

❖ ▶ False

❖ ▶ Less information to decide

❖ ▶ Either true or false

273. For Chain Matrix Multiplication we cannot use divide and conquer approach because,

❖ ▶ **We do not know the optimum k (Page# 86)**

❖ ▶ We use divide and conquer for sorting only

❖ ▶ We can easily perform it in linear time

❖ ▶ Size of data is not given

274. The Knapsack problem belongs to the domain of \_\_\_\_\_ problems.

❖ ▶ **Optimization (Page# 91)**

❖ ▶ NP Complete

❖ ▶ Linear Solution

❖ ▶ Sorting

275. Suppose we have three items as shown in the following table, and suppose the capacity of the knapsack is 50 i.e.  $W = 50$ .

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Item	Value	Weight
1	60	10
2	100	20
3	120	30

The optimal solution is to pick

- ❖ ▶ Items 1 and 2
  - ❖ ▶ Items 1 and 3
  - ❖ ▶ **Items 2 and 3**
  - ❖ ▶ None of these
276.      who invented the quick sort
- ❖ ▶ **C.A.R. Hoare**
277.      main elements to a divide-and-conquer
- ❖ ▶ **Divide, conquer, combine** (Page# 27)
278.      Mergesort is a stable algorithm but not an in-place algorithm.
- 
- ❖ ▶ **True (Page# 54)**
- ❖ ▶ false
279.      Counting sort the numbers to be sorted are in the range 1 to k where k is small.
- ❖ ▶ **True** (Page# 57)
- ❖ ▶ **False**
280.      In selection algorithm, because we eliminate a constant fraction of the array with each phase, we get the
- ❖ ▶ **Convergent geometric series (Page 37)**
  - ❖ ▶ Divergent geometric series
  - ❖ ▶ None of these
281.      .In RAM model instructions are executed
- ❖ ▶ **One after another** (Page# 10)
  - ❖ ▶ Parallel

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- ❖ ▶ Concurrent
- ❖ ▶ Random
- 282. Due to left-complete nature of binary tree, heaps can be stored in
  - ❖ ▶ Link list
  - ❖ ▶ Structure
  - ❖ ▶ **Array** (Page# 40)
  - ❖ ▶ None of above
- 283. The time assumed for each basic operation to execute on RAM model of computation is-----
  - ❖ ▶ Infinite
  - ❖ ▶ Continuous
  - ❖ ▶ **Constant** (Page# 10)
  - ❖ ▶ Variable
- 284. If the indices passed to merge sort algorithm are not equal, the algorithm may return immediately.
  - ❖ ▶ True
  - ❖ ▶ **False** (Page# 28)
- 285. Brute-force algorithm uses no intelligence in pruning out decisions.
  - ❖ ▶ **True** (Page #18)
  - ❖ ▶ False
- 286. In analysis, the Upper Bound means the function grows asymptotically no faster than its largest term.
  - ❖ ▶ **True** (Page #24)
  - ❖ ▶ False
- 287. For small values of n, any algorithm is fast enough. Running time does become an issue when n gets large.
  - ❖ ▶ **True** (Page #14)
  - ❖ ▶ False
- 288. In simple brute-force algorithm, we give no thought to efficiency.
  - ❖ ▶ **True** (Page# 11)
  - ❖ ▶ False
- 289. The ancient Roman politicians understood an important principle of good algorithm design that is plan-sweep algorithm.
  - ❖ ▶ True
  - ❖ ▶ **False** (Page# 27)
- 290. In 2d-space a point is said to be \_\_\_\_\_ if it is not dominated by any other point in that space.
  - ❖ ▶ Member
  - ❖ ▶ Minimal
  - ❖ ▶ **Maximal** (Page# 11)
  - ❖ ▶ Joint
- 291. An algorithm is a mathematical entity that is dependent on a specific programming language.
  - ❖ ▶ True
  - ❖ ▶ **False** (Page# 7)

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292. The running time of an algorithm would not depend upon the optimization by the compiler but that of an implementation of the algorithm would depend on it.

❖ ▶ True (Page# 13)

❖ ▶ False

293.  $F(n)$  and  $g(n)$  are asymptotically equivalent. This means that they have essentially the same \_\_\_\_\_ for large  $n$ .

❖ ▶ Results

❖ ▶ Variables

❖ ▶ Size

❖ ▶ Growth rates (Page#23)

294.  $8n^2 + 2n - 3$  will eventually exceed  $c_2 \cdot n$  no matter how large we make  $c_2$ .

❖ ▶ True (Page# 25)

❖ ▶ False

295. If we associate  $(x, y)$  integers pair to cars where  $x$  is the speed of the car and  $y$  is the negation of the price. High  $y$  value for a car means a \_\_\_\_\_ car.

❖ ▶ Fast

❖ ▶ Slow

❖ ▶ Expensive

❖ ▶ Cheap (Page# 11)

296. The function  $f(n) = n(\log n + 1)/2$  is asymptotically equivalent to  $n \log n$ . Here Upper Bound means the function  $f(n)$  grows asymptotically \_\_\_\_\_ faster than  $n \log n$ .

▶ More

▶ Quiet

▶ Not (Page# 24)

▶ At least

297. Counting Money problem is an example which cannot be optimally solved by greedy algorithm.

❖ ▶ True (Page# 97)

❖ ▶ False

298. Huffman algorithm generates an optimum prefix code.

❖ ▶ True (Page #102)

❖ ▶ False

299. If the string "lmncde" is coded with ASCII code, the message length would be \_\_\_\_\_ bits.

❖ ▶ 24

❖ ▶ 36

❖ ▶ 48 (6\*8=48)

❖ ▶ 60

300. There are \_\_\_\_\_ nested loops in DP based algorithm for computing the minimum cost of chain matrix multiplication.

❖ ▶ 2

❖ ▶ 3 (Page# 90)

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- ❖ ▶4
- ❖ ▶5

301. Inductive approach to compute entries of V is implied in \_\_\_\_ based solution of knapsack problem.

- ❖ ▶Brute force

❖ ▶ **Dynamic programming** (Page #93)

302. A number of lectures are to be given in a single lecture hall. Optimum scheduling for this is an example of Activity selection.

❖ ▶ **True** (Page# 105)

- ❖ ▶False

303. The activity scheduling is a simple scheduling problem for which the greedy algorithm approach provides a/an \_\_\_\_ solution.

- ❖ ▶ Simple

- ❖ ▶ Sub optimal

❖ ▶ **Optimal** (Page# 105)

- ❖ ▶ Non optimal

304. The string |xyz|, if coded with ASCII code, the message length would be 24 bits.

❖ ▶ **True** ( $3*8=24$ )

- ❖ ▶False

305. An application problem is one in which you want to find, not just a solution, but the \_\_\_\_ solution.

- ❖ ▶ Simple

❖ ▶ **Good** (Page# 113)

- ❖ ▶ Best

- ❖ ▶ Worst

306. A free tree with n vertices has exactly \_\_\_\_ edges.

a. n

b. n+1

**c. n-1** page 142

307. Kruskal's algorithm works by adding \_\_\_\_ in increasing order of weight (lightest edge first)

a. Verticals

**b. Edges** page 147

- Trees
- Weights

308. Computing the strongly connected components of a digraphs is a/an \_\_\_\_ of the problem to determine whether a diagraph is strongly connected or not

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a. Size

## **b. Generalization** page 135

- Optimization
- Connection

309. The process of updating estimates in Dijkstra's algorithm is called \_\_\_\_\_

- a. Updating
- b. Amendment

## **c. Relaxation** page 154

- Insertion

310. An un-weighted graph can be considered as a graph in which every edge has weight \_\_\_\_\_ Unit.

- a. 7
- b. 5
- c. 3

## **d. 1** page 153

311. The breadth-first-search algorithm is a shortest-path algorithm that works on \_\_\_\_\_ graphs.

- a. Weighted
- b. Directed

## **c. Un-weighted** page 153

d. Un-directed



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312. Which activity creates a unique cycle in a free tree:
- adding any vertex
  - adding any sub tree
  - adding root

**d. adding any edge** **page 142**

313. The relationship between number of back edges and Number of cycles in DFS is,
- Both are equal
  - Back edges are half of cycles
  - Back edges are one quarter of cycles

**d. There is no relationship between no. of edges and cycles** **google**

314. From given algorithms which one considered as best for finding the shortest-path:

- DFS
- Bellman-Ford algorithm

**• Dijkstra's algorithm** **page 154 / google**

- BFS

315. Overall time for Kruskal algorithm is

a.  $\Theta(\log E)$

**b.  $\Theta(E \log V)$**  **page 149 / google**

c.  $\Theta(E \log E)$

d.  $\Theta(V \log E)$

316. Dijkstra's Algorithm is used to solve \_\_\_\_\_ problems.

a. All-pair shortest path

**b. Single-source shortest path** **page 154**

- Multi-source shortest path
- Sorting & searching

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317. A digraph is strongly connected under what condition?

- A digraph is strongly connected if for every pair of vertices  $u, v \in V$ ,  $u$  can reach  $v$ .

• **A digraph is strongly connected if for every pair of vertices  $u, v \in V$ ,  $u$  can**

**reach  $v$  and vice versa.**

**Page 135**

- A digraph is strongly connected if for at least one pair of vertex  $u, v \in V$ ,  $u$  can reach  $v$  and vice versa.
- A digraph is strongly connected if at least one third pair of vertices  $u, v \in V$ ,  $u$  can reach  $v$  and vice versa.



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318. Floyd-Warshall Algorithm is based on \_\_\_\_\_

**a. Dynamic Programming** **page 161**

- Greedy Approach
- Divide and Conquer
- Complexity theory

319. . In strong components algorithm, vertices are sorted in \_\_\_\_\_ order of finish times.

- a. Any
- b. Increasing

**c. Decreasing** **page 141 / google**

- d. Strong

320. . \_\_\_\_\_ is commonly the running time of Dijkstra's Algorithm using the binary heap method.

**a.  $\Theta (E \log V)$**  **page 156**

- $\Theta (V \log )$
- $\Theta (\log E)$
- $\Theta (B \log V)$

321. Which technique is used in the implementation of Kruskal solution for the MST?

**a. Greedy Technique** **page 142 / google**

- b. Divide-and-Conquer Technique
- c. Dynamic Programming Technique
- d. The algorithm combines more than one of the above techniques i.e. Divide-and-Conquer and Dynamic Programming

322. A fully connected undirected graph of 5 nodes will have \_\_\_\_\_ edges.

- 4

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- 5

10

$n(n-1)/2$

d. 15

323. Prim's algorithm is based on \_\_\_\_\_ strategy.

**a. Greedy** page 150 / google

b. Dynamic programming

c. Divide and Conquer

d. Exponential

324. We say that two vertices  $u$  and  $v$  are mutually \_\_\_\_\_ if  $u$  can reach  $v$  and vice versa.

a. Crossed

b. Forward

**c. Reachable** page 135

d. Not Reachable



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325. In Dijkstra's algorithm, initially the estimated value from source vertex to any vertex  $v$  is:

- a. Zero (0)
- b. One (1)
- c. Minus one (-1)

**d. Infinity ( $\infty$ )** **page 154**

326. A strongly connected component only apply to:

**a. Directed Graph** **page 135 / google**

- Undirected Graph
- Minimum Spanning Tree
- Breadth First Search

327. A graph may contain \_\_\_\_\_

- Exactly one MST
- No MST
- One or zero MST

• **More than one MST** **google**

328. In \_\_\_\_\_ algorithm(s), at any time, the subset of edges  $A$  forms a single tree.

- a. Kruskals

**b. Prim's** **page 149**

- c. kruskal's and Prim's
- d. BFS

329. The \_\_\_\_\_ given by DFS allow us to determine a number of things about a graph or

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Digraph

a. color stamps

**b. time stamps** **page 130**

c. line stamps

d. node stamps

330. . In Kruskal's algorithm, the vertices will be stored in\_\_\_\_\_.

a. Links

**b. Sets** **page 147**

- nodes
- Loops

331. Keeping in mind the shortest path, if given scenarios occur in computer networks like the internet where data packets have to be routed. The vertices are \_\_\_\_\_. Edges are

\_\_\_\_\_ which may be wired or wireless.

**a. Routers, communication links** **page 153**

- Internet, routers
- Communication links, routers
- Routers, internet

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332. In computing the strongly connected components of a digraph, vertices of the digraph

are \_\_\_\_\_ into subsets

a. Joined

**b. Partitioned** page 135

c. Deleted

d. Created

333. In undirected graph, by convention all the edges are called \_\_\_\_\_ edges.

a. Forward

**b. Back** page 130

c. Cross

d. Both forward and back

334. In Timestamped DFS, No back edges means \_\_\_\_\_

a. 1 cycle

**b. no cycles** page 131

c. DFS

d. BFS

335. . In Prim's algorithm, we start with the \_\_\_\_\_ vertex r, it can be any vertex.

• Pivot

• Leaf

• negative

**d. Root** page 149

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336. . The ancestor and descendent relation can be nicely inferred by the \_\_\_\_\_ lemma.

- a. addition
- b. division

**c. parenthesis page 129**

d. Node

337. Which of the following statement is true?

- Kruskal algorithm is multiple source technique for finding MST.
- Kruskal's algorithm is used to find minimum spanning tree of a graph, time complexity of this algorithm is  $O(EV)$
- Both I and II
- **Kruskal's algorithm (choose best non-cycle edge) is better than Prim's (choose best Tree edge) when the graph has relatively few edges.**

**See option B of Sr 46**

338. . The time complexity to compute Graph transposes  $G^T$  is  $(V+E)$ , if you have \_\_\_ for G.

**a. an adjacency list page 138**

- Array list
- complete list
- stack

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339. . In Prim's algorithm, If there is no edge from u to a vertex in S. we set the key value to \_\_\_\_\_

- 0
- 1
- -1

**d.  $\infty$  page 151**

340. . What is the time complexity to extract a vertex from the priority queue in Prim's algorithm?

- $O(\log E)$
- $O(V)$
- $O(V+E)$

**d.  $O(\log V)$  page 152**

341. . Edge weights can be interpreted as distance \_\_\_\_\_

- in breadth-First Search
- in Queue's

**c. in the shortest-paths page 153**

d. in depth-First Search

342. The \_\_\_\_\_ given by DFS allow us to determine whether the graph contains any

cycles.

a. Order

**b. Time stamps page 130**

- c. BFS traversing
- d. Topological sort

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343. \_\_\_\_\_. Dijkstra's algorithm works on a weighted directed graph  $G(V, E)$  in which all weights

\_\_\_\_\_ are non-negative.

a. Vertices

**b. Edges** **page 154**

- nodes
- links

344. \_\_\_\_\_. By breaking any edge on a cycle created in free tree, the free \_\_\_\_\_ is restored.

a. Edge

**b. Tree** **page 142**

- c. Cycle
- d. Vertex

345. \_\_\_\_\_. Bellman-Ford algorithm is used to solve \_\_\_\_\_ problems.

a. All pair shortest path

**b. Single source shortest path** **google**

- c. Flow of networking
- d. Double source shortest path

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346. . From the given options which one is correct regarding the time complexity of Dijkstra's algorithm

- $O(N)$
- $O(N^3)$
- $O(N^2)$

**d.  $O(\log N)$  google**

347. . In which algorithm, information of shortest path is propagated sequentially along each shortest path in the graph.

**a. Bellman-Ford page 16**

52) Brute-force technique

53) Dijkstra's

54) Prim's

348. In Timestamped DFS-cycles lemma, if edge  $(u, v)$  is a tree, forward or cross edge, then a.  $f[u] < f[v]$

**b.  $f[u] > f[v]$  page 130**

52)  $f[u] \leq f[v]$

53)  $f[u] \geq f[v]$

349. Bellman-Ford Algorithm does not allow  $G(\text{graph})$  to have \_\_\_\_\_

a. positive cost cycles

**b. negative cost cycles page 159**

c. negative weights edges

d. positive weights edges

350. Kruskal algorithm (choose best non cycle edge) is better than Prim's (choose best tree edge) when the \_\_\_\_\_ has relatively few \_\_\_\_\_

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a. tree, edges

**b. graph edges** see option D of Sr 23

- tree, branches
- graph, branches

351. Finding the faster result of the shortest path from u to v for every pair of vertices and we use \_\_\_\_\_

- Single-pair shortest-paths problem
- Two pair shortest the problem

**c. All pair shortest paths problem** page 153

d. both I and II

352. There are no \_\_\_\_\_ edges in undirected graph.

- Forward
- Back

**c. Cross** page 130

d. Both forward and back

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353. Networks are \_\_\_\_\_ in the sense that it is possible from any location in the network to

reach any other location in the digraph

**a. Complete page 135**

- b. Incomplete
- c. Not graphs
- d. Transportation

354. . Dijkstra's algorithm:

- a. Has greedy approach to find all shortest paths
- b. Has both greedy and Dynamic approach to find all shortest paths

**c. Has greedy approach to compute single source shortest paths to all other vertices page 154**

- e. Has both greedy and dynamic approach to compute single source shortest paths to all other vertices

355. Bellman-Ford algorithm is slower than

- a. Brute-force technique

**b. Dijkstra's page 159**

58) Prim's

59) Graph Algorithm

356. Dijkstra's Algorithm cannot be applied on

- a. directed and weighted graphs

**b. graphs having negative weight function google**

- unweighted graphs

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- undirected and unweighted graphs

357. . Which of the following is used in the data structure for implementing Dijkstra's Algorithm?

- a. Max heap
- b. Stack's
- c. Circular queue

**d. Priority queue** **Google**

358. . In Generic approach determining of Greedy MST, we maintain a subset A of

**a. Edges** **page 143**

- Vertices
- Cycles
- Paths

359. . In Dijkstra's algorithm the estimated value of source vertex  $d[s]$  is

**a. Equal to 0** **page 154**

- Equal to 1
- Greater than 0
- Greater than 1

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360. Dijkstra's algorithm is a simple \_\_\_\_\_ algorithm for computing the single-source

shortest-paths to all other vertices.

**a. Greedy** page 154

- c. Bellman-Ford
- d. Divide and conquer
- e. Brute-Force

361. In Timestamped DFS. If there is a back edge  $(u, v)$  then  $v$  is an ancestor of  $u$  and by following tree edge from  $v$  to  $u$ , we get \_\_\_\_\_.

a. Nothing

**b. a cycle** page 131

- c. a line
- d. a graph

362. There exists a unique path between any \_\_\_\_\_ vertices of a free tree.

a. One

**b. Two** page 142

- Three
- Four

363. \_\_\_\_\_ technique is look like propagating wave-front outward.

a. Generic traversal

**b. Breadth first traversal** page 117

c. Depth first traversal

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d. Time stamp traversal

364. You have an adjacency list for  $G$ , what is the time complexity to compute Graph transpose  $G^T$ ?

**a.  $(V+E)$  page 138**

- $V \cdot E$
- $V$
- $E$

365. In the shortest-paths problem, we are given a weighted of \_\_\_\_\_  $G=(V, E)$ .

**a. Directed graph page 153**

65) Line graph

66) Un-directed graph

67) Weighted graph

366. Equivalence relation partitions the vertices into \_\_\_\_\_ classes of mutually reachable

vertices and these are the strong components

a. Variance

**b. Equivalence page 136**

- c. Non equivalence
- d. Non classes

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367. Overall Running time of Prim's algorithm is \_\_\_\_\_.

- a.  $\Theta(E \log E)$
- b.  $\Theta(E \log V)$

**c.  $\Theta((V+E) \log V)$  page 152**

d.  $\Theta((V+E) \log E)$

368. For \_\_\_\_\_ graphs, there is no distinction between forward and back edges.

- a. large
- b. directed

**c. undirected page 130**

d. Medium

369. For \_\_\_\_\_ graphs, there is no distinction between forward and back edges.

**a. Undirected page 130**

- directed
- small
- large

370. As the Kruskal's algorithm runs, the edges in viable set A induce a \_\_\_\_\_ on the

vertices.

- a. Set
- b. Graph
- c. Tree

**d. Forest page 147**

371. In strong components algorithm, the form of graph is used in which all the \_\_\_\_\_ of

original graph G have been reversed in direction.

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a. Vertices

**b. Edges** **page 138**

c. Both edges & vertices

d. Trees

372. In computing the \_\_\_\_\_ components of a digraph, vertices of the digraph are partitioned into subsets.

a. weakly connected

**b. strongly connected** **page 135**

c. Best

d. Worst

373. Timestamp structure of \_\_\_\_\_ is used in determining the strong components of a digraph.

**a. DFS** **google**

b. BFS

c. Both DFS & BFS

d. MST

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374. In Prim's algorithm, if the color of a vertex is \_\_\_\_\_ then it is in S otherwise not.

- a. White
- b. Gray

**c. Black** page 151

- d. Blue

375. Digraphs \_\_\_\_\_ in communication and transportation networks.

- a. are not used

**b. are used** page 135

- c. parts are used
- d. final value is used

376. Once you enter a strong component, every vertex in the component is \_\_\_\_\_.

- a. not reachable

**b. reachable** page 137

- c. reachable some times
- d. removed

377. In Kruskal's algorithm, the next edge is added to viable set A, if its adding does not induce a/an \_\_\_\_\_.

- a. Vertex
- b. Edge

**c. Cycle** page 147

- d. Tree

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378. Problems such as the shortest route between cities can be solved efficiently by modelling the road map as a \_\_\_\_\_.

a. Tree

**b. Graph** page 153

c. Linked list

d. Stack

379. In Bellman-Ford Algorithm, relaxation applies to every edge of the graph and repeat this \_\_\_\_\_ time.

a.  $E - 1$

b.  $E + 1$

c.  $V + 1$

**d.  $V - 1$**  page 159

380. A topological sort of a DAG is a \_\_\_\_\_ ordering of the vertices of the DAG such

that for each edge  $(u, v)$ ,  $u$  appears before  $v$  in the ordering.

**a. Linear** page 134

b. Parallel

c. Sequence

d. Non-linear



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381. Adding any edge to a free tree creates a unique \_\_\_\_\_

- a. Vertex
- b. Edge

**c. Cycle** page 142

- d. Strong component

382. Back edge is:

**a.  $(u, v)$  where  $v$  is an ancestor of  $u$  in the tree.** Page 128

- b.  $(u, v)$  where  $u$  is an ancestor of  $v$  in the tree.
- c.  $(u, v)$  where  $v$  is a predecessor of  $u$  in the tree.
- d.  $(u, v)$  where  $u$  is a mid of  $v$  in the tree.

383. In Kruskal's algorithm, the next \_\_\_\_\_ is not added to viable set  $A$ , if its adding induce a/an cycle.

- a. Vertex

**b. Edge** page 147

- c. Cycle
- d. Tree

384. Which of the following statement is false about Dijkstra's Algorithm?

**a. It can be applied on graphs having a negative weight function** google

- b. It is used to solve Single-source shortest path
- c. It works on a weighted directed graph
- d. Its implementation in data structure is possible through the priority queue

385. . In strong components algorithm, first of all DFS is run for getting \_\_\_\_\_ times of

vertices.

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a. **Start** page 138

b. Finish

c. Both start & finish

d. Middle

386. . The tricky part of \_\_\_\_\_ algorithm(s) is/are, how to detect whether the addition of an edge will create a cycle in viable set A.

a. **Kruskal's** page 149

b. Prim's

c. Both Kruskal's and Prim's

d. DFS

387. . \_\_\_\_\_ components are not affected by reversal of all edges in terms of reachability.

a. **Strongly connected** page 139

b. Weakly connected

c. First two

d. Last two

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388. In Prim's algorithm, we will make use of \_\_\_\_\_.

a. Stack

**b. Priority Queue page 150**

c. Array

d. List

389. The component digraph is necessarily \_\_\_\_\_.

a. straight

b. cyclic

**c. Acyclic page 136**

d. Strong

390. A free tree with  $n$  \_\_\_\_\_ have exactly  $n - 1$  \_\_\_\_\_.

a. vertices, nodes

b. edges, vertices

c. nodes, vertices

**d. vertices, edges page 142**

391. If you find yourself in maze the better traversal approach will be:

**a. BFS google (always return with short part)**

c. Level order

d. DFS

392. Forward  
edge is :

a.  $(u, v)$  where  $u$  is proper descendent of  $v$  in the tree

**b.  $(u, v)$  where  $v$  is proper descendent of  $u$  in the tree page 129**

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- c.  $(u, v)$  where  $v$  is proper ancestor of  $u$  in the tree
- d.  $(u, v)$  where  $u$  is proper ancestor of  $v$  in the tree

393. . cross edge is :

- a.  $(u, v)$  where  $u$  and  $v$  are not ancestor of one another
- b.  $(u, v)$  where  $u$  is ancestor of  $v$  and  $v$  is not descendent of  $u$

**c.  $(u, v)$  where  $u$  and  $v$  are not ancestor or descendent of one another page 129**

- d.  $(u, v)$  where  $u$  and  $v$  are either ancestor of descendent of one another
394. . The running time of Bellman-Ford algorithm is \_\_\_\_\_.

- a.  $\Theta(V + E)$
- b.  $\Theta(E + E)$

**c.  $\Theta(VE)$  page 159**

- d.  $\Theta(V + V)$

395. In Bellman-Ford Algorithm, relaxation applies to \_\_\_\_\_ of the graph.

**a. Every edge page 159**

- b. Every Vertices
- c. Only First Vertices
- d. Only First edge

396. If a subset of edges  $A$  is visible for building MST, it cannot contain a/an \_\_\_\_\_

- a. Vertex
- b. Edge

**c. Cycle page 143**

- d. Graph

397. . In Timestamped DFS-cycles lemma, if edge  $(u, v)$  is a back edge, then \_\_\_\_\_.

- a.  $f[u] < f[v]$

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b.  $f[u] > f[v]$

**c.  $f[u] \leq f[v]$  page 130**

d.  $f[u] \geq f[v]$

398. In digraph  $G=(V,E)$  ;G has cycle if and only if

a. The DFS forest has forward edge.

**b. The DFS forest has back edge page 131**

c. The DFS forest has both back and forward edge

d. BFS forest has forward edge

399. . The key[u] is the weight of the \_\_\_\_\_ going from u to any vertex in S.

**a. lightest edge page 151**

b. edge

c. lighter edge

d. heavier edge

400. In Bellman-Ford Algorithm, path consists of at most \_\_\_\_\_ edges.

a.  $V + 1$

**b.  $V-1$  page 160**

c.  $E + 1$

d.  $E-1$

401. According to parenthesis lemma, vertex u is a descendent of v vertex it and only if;

**a.  $[d[u], f[u]] \subseteq [d[v], f[v]]$  page 129**

b.  $[d[u], f[u]] \supseteq [d[v], f[v]]$

c. Unrelated

d. Disjoint

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402. Edge weights can be interpreted as distance \_\_\_\_\_.

- a. in breadth-First Search
- b. in Queue's

**c. in the shortest-paths** **page 153**

- d. in depth-First Search

403. \_\_\_\_\_ algorithm allows negative weights edges and no negative cost cycles.

- a. Brute-force technique

**b. Bellman-Ford** **page 159**

- c. Dijkstra's
- d. Print

404. In Huffman encoding, the characters with smallest probabilities are placed at the-----depth of the tree.

- a. Minimum
- b. Average

**• Maximum** **page 102**

- Root

405. There are ----- ways to representing graphs.

- 3
- 1

**• 2** **page 116**

- a. 4

406. Each time we traverse graph by Breadth-first search algorithm, we count the distance from-----.

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a. Starting node

- Neighbours of the starting node page 117

- Right most node

- Left most node

407. In Activity Selection problem, intuitively-----.

- There are always short activities as input

- Short activities are not attractive

- Duration of the activities does not matter

- We do not like long activities page 105

408. The activity scheduling is a simple scheduling problem for which the greedy algorithm approach provides a/an-----solution.

a. Simple

b. Sub-optimal

- Optimal page 105

c. Non optimal

409. The ----- is a problem for which the greedy algorithm approach provides an optimal solution.

- Activity selection page 105

- Dynamic programming

- Knapsack problem

- NP complete problem

410. Which of the following ways can be used to represent a graph?

a. Adjacency list

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b. Incidence matrix

- Adjacency list , Adjacency Matrix page 116

- No way to represent

411.

Queue Data Structure work on ----- principles.

4

- FIFO(first in first out) cs301

- LIFO(last in first out)
- JLO(just in last out)
- LOFI(last out first in)

412. Graphs can be represented by an----- and -----.

- queue , stack
- adjacency list , adjacency matrix page 116

a. adjacency right , adjacency left

b. Binary , linear

413. Identify a TRUE statement about Knapsack.

- a. The Knapsack Problem does not belongs to the domain of optimization problems
- The Knapsack Problem belongs to the domain of optimization problems page 91

i. The Knapsack Problem cannot be solved by using Dynamic programming

- The Knapsack Problem is optimally solved by using Brute force algorithm

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414. Which of the following is true about graph?

- a. A graph may contain no edges and many vertices
- A graph may contain many edges and no vertices

415. Which type of algorithm is harder to prove the correctness?

- Greedygoogle
- Brute force
- Dynamic programming
- Divide and Conquer

416. The running time of brute-force algorithm to solve Knapsack problem is-----

- $O(h1)$
- $O(n3)$
- $O(n!)$
- $O(2^n)$  pg#92

417. If a matrix has three rows and two columns, the dimension of matrix will be:

- 3x2 Conceptual
- 2x3
- 3x3
- 2x2

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418. The Probability in Huffman encoding is the number of occurrences of a character divided by the total-

-----in the message.

- c. Numbers
- d. Frequencies
- e. Strings
- f. Characters pg#100

419. In recursive formulation of Knapsack Problem:  $V$   
 $[0, j] = \text{-----}$  for  
 $j \geq 0$

- -1
- 0 pg#93
- 1
- 2

420. The Knapsack Problem belongs to the domain of-----problem.

- g. Optimization pg#91
- h. Sorting
- i. Linear solution
- j. Searching

421. An optimization problem is one in which you want to find the-----solution.

- k. Simple
- l. Good
- m. Best pg#97

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- Worst

422. Huffman algorithm generates an optimum----- co  
de.

- Prefix page 102

- Postfix
- Infix
- None of the above

423. Which of the following algorithms solves the Fractional Knapsack Problem more effectively?

- Divide and Conquer
- Greedy algorithm page 109
- Dynamic programming
- Backtracking

424. One of the limitation in 0/1 Knapsack is that an item can either be-----in the bag or not.

- Use
- Put page 91
- Move
- Store

425. In Dynamic Programming based solution of Knapsack Problem, if we decide to take an object 'i' then we gain-----.

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a.  $W$ (Total weight of Knapsack)

b.  $V$ (Total value of all items)

- $v_i$ (value of object  $i$ ) page 93

- None of the given option

426. An activity scheduling algorithm, the width of a rectangle-----.

n. Is always ignored

o. Direct toward recursion

p. Should be maximized

- Indicates the duration of an activity page 106

427. The prefix code generated by Huffman algorithm----- the expected length of the encoded string.

- Minimizes page 102

- Balances

- Maximizes

- Keeps constant

428. An optimization problem is one in which you want to find,

- ▶ Not a solution

- ▶ An algorithm

- ▶ Good solution

- ▶ The best solution (Page 97)

429. Although it requires more complicated data structures, Prim's algorithm for a minimum spanning tree is better than Kruskal's when the graph has a large number of vertices.

- ▶ True

- ▶ False

430. If a problem is in NP, it must also be in P.

- ▶ True

- ▶ False

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▶ unknown (Page 173)

431. What is generally true of Adjacency List and Adjacency Matrix representations of graphs?

▶ Lists require less space than matrices but take longer to find the weight of an edge  $(v_1, v_2)$

▶ Lists require less space than matrices and they are faster to find the weight of an edge  $(v_1, v_2)$

▶ Lists require more space than matrices and they take longer to find the weight of an edge  $(v_1, v_2)$

▶ Lists require more space than matrices but are faster to find the weight of an edge  $(v_1, v_2)$

432. If a graph has  $v$  vertices and  $e$  edges then to obtain a spanning tree we have to delete

▶  $v$  edges.

▶  $v - e + 5$  edges

▶  $v + e$  edges.

▶ None of these

433. Maximum number of vertices in a Directed Graph may be  $|V_2|$

▶ True

▶ False

434. The Huffman algorithm finds a  $(n)$  \_\_\_\_\_ solution.

▶ Optimal

▶ Non-optimal

▶ Exponential

▶ Polynomial

435. The Huffman algorithm finds an exponential solution

▶ True

▶ False

436. The greedy part of the Huffman encoding algorithm is to first find two nodes with larger frequency.

▶ True

▶ False (Page 100)

437. The codeword assigned to characters by the Huffman algorithm have the property that no codeword is the postfix of any other.

▶ True (Page 101)

▶ False

438. Huffman algorithm uses a greedy approach to generate a postfix code  $T$  that minimizes the expected length  $B(T)$  of the encoded string.

▶ True

▶ False (Page 102)

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439. Shortest path problems can be solved efficiently by modeling the road map as a graph.
- ▶ True (Page 153)
  - ▶ False
440. Dijkstra's single source shortest path algorithm works if all edges weights are non-negative and there are negative cost cycles.
- ▶ True
  - ▶ False (Page 159)
441. Bellman-Ford allows negative weights edges and negative cost cycles.
- ▶ True
  - ▶ False (Page 159)
442. The term "coloring" came form the original application which was in architectural design.
- ▶ True
  - ▶ False (Page 176)
443. In the clique cover problem, for two vertices to be in the same group, they must be adjacent to each other.
- ▶ True (Page 176)
  - ▶ False
444. Dijkstra's algorithm is operates by maintaining a subset of vertices
- ▶ True (Page 155)
  - ▶ False
445. The difference between Prim's algorithm and Dijkstra's algorithm is that Dijkstra's algorithm uses a different key.
- ▶ True ( Page 156)
  - ▶ False
446. We do sorting to,
- ▶ keep elements in random positions
  - ▶ keep the algorithm run in linear order
  - ▶ keep the algorithm run in (log n) order
  - ▶ keep elements in increasing or decreasing order (Page 40)
447. After partitioning array in Quick sort, pivot is placed in a position such that
- ▶ Values smaller than pivot are on left and larger than pivot are on right (Page 48)
  - ▶ Values larger than pivot are on left and smaller than pivot are on right
  - ▶ Pivot is the first element of array
  - ▶ Pivot is the last element of array
448. Merge sort is stable sort, but not an in-place algorithm
- ▶ True (Page 54)
  - ▶ False

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449. In counting sort, once we know the ranks, we simply \_\_\_\_\_ numbers to their final positions in an output array.
- ▶ Delete
  - ▶ **copy (Page 57)**
  - ▶ Mark
  - ▶ arrange
450. one Dynamic programming algorithms need to store the results of intermediate sub-problems.
- ▶ **True (Page 75)**
  - ▶ False
451. A  $p \times q$  matrix A can be multiplied with a  $q \times r$  matrix B. The result will be a  $p \times r$  matrix C. There are  $(p \cdot r)$  total entries in C and each takes \_\_\_\_\_ to compute.
- ▶  **$O(q)$  (Page 84)**
  - ▶  $O(1)$
  - ▶  $O(n^2)$
  - ▶  $O(n^3)$  –
452. \_\_\_\_\_ is a graphical representation of an algorithm
- ▶  $\Sigma$  notation
  - ▶  $\Theta$  notation
  - ▶ **Flowchart**
  - ▶ Asymptotic notation
453. one Which of the following is calculated with big o notation?
- ▶ Lower bounds
  - ▶ **Upper bounds (Page 25)**
  - ▶ Both upper and lower bound
  - ▶ Medium bounds
454. Merge sort makes two recursive calls. Which statement is true after these recursive calls finish, but before the merge step?
- ▶ The array elements form a heap
  - ▶ **Elements in each half of the array are sorted amongst themselves**
  - ▶ Elements in the first half of the array are less than or equal to elements in the second half of the array
  - ▶ None of the above
455. Who invented Quick sort procedure?
- ▶ **Hoare**
  - ▶ Sedgewick
  - ▶ Mellroy
  - ▶ Coreman
456. What is the solution to the recurrence  $T(n) = T(n/2) + n$ ,  $T(1) = 1$

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- ▶  $O(\log n)$
- ▶  $O(n)$  (Page 37)
- ▶  $O(n \log n)$
- ▶  $O(2n)$

457. one Consider the following Huffman Tree The binary code for the string TEA is

- ▶ 10 00 010
- ▶ 011 00 010
- ▶ 10 00 110
- ▶ 11 10 110

458. A greedy algorithm does not work in phases.

- ▶ True
- ▶ False (Page 97)

459. Can an adjacency matrix for a directed graph ever not be square in shape?

- ▶ Yes
- ▶ No

460. One of the clever aspects of heaps is that they can be stored in arrays without using any \_\_\_\_\_.

- ▶ Pointers (Page 40)
- ▶ constants
- ▶ variables
- ▶ functions

461. Merge sort requires extra array storage, •

- ▶ True (Page 54) •
- ▶ False

462. Non-optimal or greedy algorithm for money change takes \_\_\_\_\_

- ▶  $O(k)$  (Page 99)
- ▶  $O(kN)$
- ▶  $O(2k)$
- ▶  $O(N)$

463. The Huffman codes provide a method of encoding data inefficiently when coded using ASCII standard.

- ▶ True
- ▶ False (Page 99)

464. Using ASCII standard the string abacdaacac will be encoded with \_\_\_\_\_ bits.

- ▶ 80 (Page 99)
- ▶ 160
- ▶ 320

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- ▶ 100
465. Using ASCII standard the string abacdaacac will be encoded with 160 bits.
- ▶ True
  - ▶ False (Page 99)
466. one Using ASCII standard the string abacdaacac will be encoded with 320 bits.
- ▶ True
  - ▶ False (Page 99)
467. Using ASCII standard the string abacdaacac will be encoded with 100 bits.
- ▶ True
  - ▶ False (Page 99)
468. Using ASCII standard the string abacdaacac will be encoded with 32 bytes
- ▶ True
  - ▶ False (Page 99)
469. The greedy part of the Huffman encoding algorithm is to first find two nodes with smallest frequency.
- ▶ True (Page 100)
  - ▶ False
470. The greedy part of the Huffman encoding algorithm is to first find two nodes with character frequency
- ▶ True
  - ▶ False (Page 100)
471. Huffman algorithm uses a greedy approach to generate an antefix code T that minimizes the expected length  $B(T)$  of the encoded string.
- ▶ True
  - ▶ False (Page 102)
472. Depth first search is shortest path algorithm that works on un-weighted graphs.
- ▶ True
  - ▶ False (Page 153)
473. one Dijkstra s single source shortest path algorithm works if all edges weights are non negative and there are no negative cost cycles.
- ▶ True (Page 159)
  - ▶ False
474. Dijkestra s single source shortest path algorithm works if all edges weights are negative and there are no negative cost cycles.
- ▶ True •
  - ▶ False (Page 159)
475. Floyd-Warshall algorithm is a dynamic programming algorithm; the genius of the algorithm is in the clever recursive formulation of the shortest path problem.

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- ▶ True (Page 162)
- ▶ Flase

476. Floyd-Warshall algorithm, as in the case with DP algorithms, we avoid recursive evaluation by generating a table for

- ▶ k

- ▶ k ij d (Page 164)

- ▶ True

- ▶ Flase

477. The term coloring came from the original application which was in map drawing.

- ▶ True (Page 176)

- ▶ False

478. In the clique cover problem, for two vertices to be in the same group, they must be \_\_\_\_\_ each other.

- ▶ Apart from

- ▶ Far from

- ▶ Near to

- ▶ Adjacent to (Page 176)

479. Fixed-length codes may not be efficient from the perspective of \_\_\_\_\_ the total quantity of data. Select correct option:

- ▶ Minimizing (Page 99)

- ▶ Averaging

- ▶ Maximizing

- ▶ Summing

480. In greedy algorithm, at each phase, you take the \_\_\_\_\_ you can get right now, without regard for future consequences.

- ▶ Worst

- ▶ Minimum

- ▶ Good

- ▶ Best (Page 97)

481. one The difference between Prim s algorithm and Dijkstra s algorithm is that Dijkstra s algorithm uses a same key.

- ▶ True

- ▶ False ( Page 156)

482. If a problem is in NP-complete, it must also be in NP.

- ▶ True (Page 178)

- ▶ False

483. If there are n items, there are \_\_\_\_\_ possible combinations of the items.

- ▶ 2

- ▶ n

- ▶  $2^n$  (Page 92)

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▶  $3^n$

484. Using ASCII code, each character is represented by a fixed-length code word of \_\_\_\_\_ bits per character.

▶ 4

▶ 6

▶ 8 (Page 99)

▶ 10

485. In Knapsack Problem, the thief's goal is to put items in the bag such that the \_\_\_\_\_ of the items does not exceed the limit of the bag.

▶ Value (Page 91)

▶ Weight

▶ Length

▶ Balance

486. one The knapsack problem does not belong to the domain of optimization problems. ▶ True

▶ False (Page 91)

487. In Huffman encoding, for a given message string, the frequency of occurrence (relative probability) of each character in the message is determined last.

▶ True

▶ False (Page 100)

488. Fixed-length codes are known for easy break up of a string into its individual characters.

▶ True (Page 99)

▶ False

489. Question No: 8 ( Marks: 1 ) - Please choose one In \_\_\_\_\_ Knapsack Problem, limitation is that an item can either be put in the bag or not-fractional items are not allowed.

▶ 0

▶ 1

▶ 0/1 (Page 91)

▶ Fractional

490. one The term "coloring" came from the original application which was in architectural design.

▶ True

▶ False (Page 173)

491. In Knapsack Problem, value and weight both are to be under consideration.

▶ True (page 91)

▶ False

492. Time complexity of DP based algorithm for computing the minimum cost of chain matrix Multiplication is \_\_\_\_\_ .

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▶ log n

▶ n

▶ n<sup>2</sup>

▶ n<sup>3</sup> (Page 90)

493. Question No: 12 ( Marks: 1 ) - Please choose one In DP based solution of knapsack problem, to compute entries of V we will imply a/an \_\_\_\_\_ approach.

▶ Subjective

▶ Inductive (Page 93)

▶ Brute force

▶ Combination

494. A greedy algorithm sometimes works well for optimization problems.

▶ True (Page 97)

▶ False

495. In Huffman encoding, frequency of each character can be determined by parsing the message and \_\_\_\_\_ how many times each character (or symbol) appears. ▶ Printing

▶ Incrementing

▶ Counting (Page 100)

▶ Deleting

496. Greedy algorithm can do very poorly for some problems.

▶ True (Page 97)

▶ False 14

497. one The Huffman codes provide a method of \_\_\_\_\_ data efficiently.

▶ Reading

▶ Encoding (Page 99)

▶ Decoding

▶ Printing

498. In \_\_\_\_\_ based solution of knapsack problem, we consider 2 cases, Leave object Or Take object.

▶ Brute force

▶ Dynamic programming (Page 93)

499. Those problems in which Greedy finds good, but not always best is called a greedy \_\_\_\_\_.

▶ Algorithm

▶ Solution

▶ Heuristic (Page 97)

▶ Result

500. one In brute force based solution of knapsack problem, we consider 2 cases, Leave object Or Take object.

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▶ TRUE

▶ FALSE (Page 97)

501. \_\_\_\_\_ problem, we want to find the best solution.

▶ Minimization

▶ Averaging

▶ Optimization (Page 97)

▶ Maximization

502. Using ASCII standard the string abacdaacac will be encoded with 10 bytes.

• ▶ True (Page 101)

• ▶ False

503. In \_\_\_\_\_ algorithm, you hope that by choosing a local optimum at each step, you will end up at a global optimum.

▶ Simple

▶ Non Greedy

▶ Greedy (Page 97)

▶ Brute force

504. one Huffman algorithm uses a greedy approach to generate an prefix code T that minimizes the expected length B (T) of the encoded string.

• ▶ True (Page 102)

• ▶ False

505. Counting Money problem is an example which cannot be optimally solved by greedy algorithm.

▶ True (Page 97)

▶ False

506. Huffman algorithm generates an optimum prefix code.

▶ True (Page 102)

▶ False

507. If the string "lmncde" is coded with ASCII code, the message length would be \_\_\_\_\_ bits.

▶ 24

▶ 36

▶ 48 (6\*8=48)

▶ 60

508. There are \_\_\_\_\_ nested loops in DP based algorithm for computing the minimum cost of chain matrix multiplication.

▶ 2

▶ 3 (Page 90)

▶ 4

▶ 5

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509. Inductive approach to compute entries of  $V$  is implied in \_\_\_\_\_ based solution of knapsack problem.
- ▶ Brute force
  - ▶ **Dynamic programming (Page 93)**
510. A number of lectures are to be given in a single lecture hall. Optimum scheduling for this is an example of Activity selection.
- ▶ **True (Page 105)**
  - ▶ False
511. The activity scheduling is a simple scheduling problem for which the greedy algorithm approach provides a/an \_\_\_\_\_ solution.
- ▶ Simple
  - ▶ Sub optimal
  - ▶ **Optimal (Page 105)**
  - ▶ Non optimal
512. Question # 1 of 10 ( Marks: 1 ) Please choose one The string  $|xyz|$ , if coded with ASCII code, the message length would be 24 bits.
- ▶ **True**
  - ▶ False
513. An application problem is one in which you want to find, not just a solution, but the \_\_\_\_\_ solution.
- ▶ Simple
  - ▶ **Good (Page 113)**
  - ▶ Best
  - ▶ Worst
514. A dense undirected graph is:
- ▶ A graph in which  $E = O(V^2)$  [click here 4 detail](#)
  - ▶ A graph in which  $E = O(V)$
  - ▶ A graph in which  $E = O(\log V)$
  - ▶ All items above may be used to characterize a dense undirected graph
515. Suppose that a graph  $G = (V,E)$  is implemented using adjacency lists. What is the complexity of a breadth-first traversal of  $G$ ?
- ▶  $O(V^2)$
  - ▶  $O(|V| + |E|)$
  - ▶  $O(|V|^2|E|)$
  - ▶  **$O(|V| + |E|)$  pg 116**
516. Which is true statement?
- ▶ **Breadth first search is shortest path algorithm that works on un-weighted graphs (Page 153)**
  - ▶ Depth first search is shortest path algorithm that works on un-weighted graphs. ▶ Both of above are true.

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- ▶ None of above are true.
517. one Forward edge is:
- ▶ (u, v) where u is a proper descendent of v in the tree.
  - ▶ (u, v) where v is a proper descendent of u in the tree. (Page 129)
  - ▶ (u, v) where v is a proper ancestor of u in the tree.
  - ▶ (u, v) where u is a proper ancestor of v in the tree.
518. What general property of the list indicates that the graph has an isolated vertex? ▶ There is Null pointer at the end of list.
- ▶ The Isolated vertex is not handled in list.
  - ▶ Only one value is entered in the list.
  - ▶ There is at least one null list.
519. one If you find yourself in maze the better traversal approach will be :
- ▶ **BFS**
  - ▶ BFS and DFS both are valid
  - ▶ Level order
  - ▶ DFS
520. In digraph  $G=(V,E)$  ;G has cycle if and only if
- ▶ The DFS forest has forward edge.
  - ▶ **The DFS forest has back edge (Page 131)**
  - ▶ The DFS forest has both back and forward edge
  - ▶ BFS forest has forward edge
521. Back edge is:
- ▶ (u, v) where v is an ancestor of u in the tree. (Page 128)
  - ▶ (u,v) where u is an ancestor of v in the tree.
  - ▶ (u, v) where v is an predecessor of u in the tree.
  - ▶ None of above
522. Which statement is true?
- ▶ If a dynamic-programming problem satisfies the optimal-substructure property, then a locally optimal solution is globally optimal.
  - ▶ If a greedy choice property satisfies the optimal-substructure property, then a locally optimal solution is globally optimal.
  - ▶ Both of above
  - ▶ None of above
523. Cross edge is :
- ▶ (u, v) where u and v are not ancestor of one another
  - ▶ (u, v) where u is ancestor of v and v is not descendent of u.
  - ▶ (u, v) where u and v are not ancestor or descendent of one another (Page 129)
  - ▶ (u, v) where u and v are either ancestor or descendent of one another.

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524. Kruskal's algorithm (choose best non-cycle edge) is better than Prim's (choose best tree edge) when the graph has relatively few edges.
- ▶ True click here 4 detail
  - ▶ False
525. Which is true statement in the following?
- ▶ Kruskal algorithm is multiple source technique for finding MST. click here for detail
  - ▶ Kruskal's algorithm is used to find minimum spanning tree of a graph, time complexity of this algorithm is  $O(EV)$
  - ▶ Both of above
  - ▶ **Kruskal's algorithm (choose best non-cycle edge) is better than Prim's (choose best Tree edge) when the graph has relatively few edges. click here 4 detail**
526. Kruskal's algorithm (choose best non-cycle edge) is better than Prim's (choose best tree edge) when the graph has relatively few edges.
- ▶ True click here 4 detail
  - ▶ False
527. What algorithm technique is used in the implementation of Kruskal solution for the MST?
- ▶ **Greedy Technique (Page 142)**
  - ▶ Divide-and-Conquer Technique
  - ▶ Dynamic Programming Technique
  - ▶ The algorithm combines more than one of the above techniques
528. What is the time complexity to extract a vertex from the priority queue in Prim's algorithm?
- ▶  $O(\log E)$
  - ▶  $(V)$
  - ▶  $(V+E)$
  - ▶  **$O(\log V)$  (Page 152)**
529. The relationship between number of back edges and number of cycles in DFS is, ▶ Both are equal
- ▶ Back edges are half of cycles
  - ▶ Back edges are one quarter of cycles
  - ▶ **There is no relationship between no. of edges and cycles (Page 131)**
530. You have an adjacency list for  $G$ , what is the time complexity to compute Graph transpose  $G^T$ ?
- ▶  **$(V + E)$  (Page 138)**
  - ▶  $(V E)$
  - ▶  $(V)$
531. A digraph is strongly connected under what condition?

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- ▶ A digraph is strongly connected if for every pair of vertices  $u, v \in V$ ,  $u$  can reach  $v$ . ▶ A digraph is strongly connected if for every pair of vertices  $u, v \in V$ ,  $u$  can reach  $v$  and vice versa. (Page 135)
  - ▶ A digraph is strongly connected if for at least one pair of vertex  $u, v \in V$ ,  $u$  can reach  $v$  and vice versa.
  - ▶ A digraph is strongly connected if at least one third pair of vertices  $u, v \in V$ ,  $u$  can reach  $v$  and vice versa.
532. In in-place sorting algorithm is one that uses arrays for storage :
- ▶ An additional array
  - ▶ No additional array (Page 54)
  - ▶ Both of above may be true according to algorithm
  - ▶ More than 3 arrays of one dimension.
533. In stable sorting algorithm
- ▶ One array is uses
  - ▶ In which duplicating elements are not handled.
  - ▶ More then one arrays are required.
  - ▶ Duplicating elements remain in same relative position after sorting. (Page 54)
534. Which sorting algorithm is faster :
- ▶  $O(n^2)$
  - ▶  $O(n \log n)$  (Page 46)
  - ▶  $O(n+k)$
  - ▶  $O(n^3)$
535. In Quick sort algorithm, constants hidden in  $T(n \lg n)$  are
- ▶ Large
  - ▶ Medium
  - ▶ Not known
  - ▶ Small
536. Quick sort is based on divide and conquer paradigm; we divide the problem on base of pivot element and:
- ▶ There is explicit combine process as well to conquer the solution.
  - ▶ No work is needed to combine the sub-arrays, the array is already sorted
  - ▶ Merging the sub arrays
  - ▶ None of above. (Page 51)
537. Dijkstra's algorithm :
- ▶ Has greedy approach to find all shortest paths
  - ▶ Has both greedy and Dynamic approach to find all shortest paths
  - ▶ Has greedy approach to compute single source shortest paths to all other vertices (Page 154)

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- ▶ Has both greedy and dynamic approach to compute single source shortest paths to all other vertices.
538. Which may be stable sort:
- ▶ Bubble sort
  - ▶ Insertion sort
  - ▶ Both of above (page 54)
  - ▶ Selection sort
539. Question # 1 of 10 ( Marks: 1 ) Please choose one In the analysis of Selection algorithm, we eliminate a constant fraction of the array with each phase; we get the convergent \_\_\_\_\_ series in the analysis,
- ▶ linear
  - ▶ arithmetic
  - ▶ geometric (page 37)
  - ▶ exponent
540. How much time merge sort takes for an array of numbers?
- ▶  $T(n^2)$
  - ▶  $T(n)$  (Page 40)
  - ▶  $T(\log n)$
  - ▶  $T(n \log n)$
541. Counting sort has time complexity:
- ▶  $O(n)$  ▶  $O(n+k)$
  - ▶  $O(k)$
  - ▶  $O(n \log n)$
542. The analysis of Selection algorithm shows the total running time is indeed \_\_\_\_\_ in no
- ▶ arithmetic
  - ▶ geometric
  - ▶ linear (Page 37)
  - ▶ orthogonal
543. Sorting is one of the few problems where provable \_\_\_\_\_ bounds exists on how fast we can sort,
- ▶ upper
  - ▶ lower (Page 39)
  - ▶ average
  - ▶  $\log n$
544. In the analysis of Selection algorithm, we make a number of passes, in fact it could be as many as
- ▶  $T(n)$
  - ▶  $T(n / 2)$
  - ▶  $\log n$  (Page 37)

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▶  $n/2 + n/4$

545. number of nodes in a complete binary tree of height  $h$  is

▶  $2^{(h+1)} - 1$  (Page 40)

▶  $2 * (h+1) - 1$

▶  $2 * (h+1)$

▶  $((h+1)^2) - 1$  25

546. How many elements do we eliminate in each time for the Analysis of Selection algorithm?

▶  $n/2$  elements (Page 37)

▶  $(n/2) + n$  elements

▶  $n/4$  elements

▶  $2n$  elements

547. Slow sorting algorithms run in,

▶  $T(n^2)$  (Page 39)

▶  $T(n)$

▶  $T(\log n)$

▶  $T(n \log n)$

548. Counting sort is suitable to sort the elements in range 1 to  $k$ :

▶  $K$  is large

▶  $K$  is small (Page 57)

▶  $K$  may be large or small

▶ None

549. Heaps can be stored in arrays without using any pointers; this is due to the \_\_\_\_\_ nature of the binary tree,

▶ left-complete (Page 40)

▶ right-complete

▶ tree nodes

▶ tree leaves

550. Sieve Technique can be applied to selection problem?

▶ True (Page 35)

▶ False

551. A heap is a left-complete binary tree that conforms to the \_\_\_\_\_

▶ increasing order only

▶ decreasing order only

▶ heap order (Page 40)

▶  $(\log n)$  order

552. Divide-and-conquer as breaking the problem into a small number of

▶ pivot

▶ Sieve

▶ smaller sub problems (Page 34)

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▶ Selection

553. In Sieve Technique we do not know which item is of interest

▶ True (Page 34)

▶ False

554. The recurrence relation of Tower of Hanoi is given below  $T(n) = \{1 \text{ if } n=1 \text{ and } 2T(n-1) \text{ if } n > 1\}$  In order to move a tower of 5 rings from one peg to another, how many ring moves are required?

▶ 16

▶ 10

▶ 32

▶ 31 Click here 4 detail

555. one For the heap sort, access to nodes involves simple \_\_\_\_\_ operations.

▶ arithmetic (Page 41)

▶ binary

▶ algebraic

▶ logarithmic

556. For the sieve technique we solve the problem,

▶ recursively (Page 34)

▶ mathematically

▶ precisely

▶ accurately

557. The sieve technique works in \_\_\_\_\_ as follows

▶ phases (Page 34)

▶ numbers

▶ integers

▶ routines

558. A (an) \_\_\_\_\_ is a left-complete binary tree that conforms to the heap order

▶ heap (Page 40)

▶ binary tree

▶ binary search tree

▶ array

559. The sieve technique is a special case, where the number of sub problems is just

▶ 5

▶ many

▶ 1 (Page 34)

▶ few

560. Analysis of Selection algorithm ends up with,

▶  $T(n)$

▶  $T(1 / 1 + n)$

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- ▶  $T(n/2)$
  - ▶  $T((n/2) + n)$  (Page 37)
561. For the heap sort we store the tree nodes in
- ▶ level-order traversal (Page 40)
  - ▶ in-order traversal
  - ▶ pre-order traversal
  - ▶ post-order traversal
562. The reason for introducing Sieve Technique algorithm is that it illustrates a very important special case of,
- ▶ divide-and-conquer (Page 34)
  - ▶ decrease and conquer
  - ▶ greedy nature
  - ▶ 2-dimension Maxima
563. Theta asymptotic notation for  $T(n)$  :
- ▶ Set of functions described by:  $c_1 g(n)$  Set of functions described by  $c_1 g(n) \geq f(n)$  for  $c_1 \leq c_2$
  - ▶ Theta for  $T(n)$  is actually upper and worst case comp
  - ▶ Set of functions described by:
  - ▶  $c_1 g(n)$
564. Sieve Technique applies to problems where we are interested in finding a single item from a larger set of \_\_\_\_\_
- ▶  $n$  items (Page 34)
  - ▶ phases
  - ▶ pointers
  - ▶ constant
565. Memorization is?
- ▶ To store previous results for future use
  - ▶ To avoid this unnecessary repetitions by writing down the results of recursive calls and looking them up again if we need them later (Page 47)
  - ▶ To make the process accurate
  - ▶ None of the above
566. Quick sort is
- ▶ Stable & in place
  - ▶ Not stable but in place (Page 57)
  - ▶ Stable but not in place
  - ▶ Some time stable & some times in place
567. One example of in place but not stable algorithm is
- ▶ Merger Sort
  - ▶ Quick Sort (Page 54)
  - ▶ Continuation Sort

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▶ Bubble Sort

568. Continuation sort is suitable to sort the elements in range 1 to k

▶ K is Large

▶ K is not known

▶ K may be small or large

▶ K is small (Page 57)

569. Which may be a stable sort?

▶ Merger

▶ Insertion

▶ Both above (Page 54)

▶ None of the above

570. An in place sorting algorithm is one that uses \_\_\_ arrays for storage

▶ Two dimensional arrays

▶ More than one array

▶ No Additional Array (Page 54)

▶ None of the above

571. Continuing sort has time complexity of ?

▶  $O(n)$

▶  $O(n+k)$

▶  $O(n \log n)$

▶  $O(k)$

572. single item from a larger set of \_\_\_\_\_

▶ n items (Page 34)

▶ phases

▶ pointers

▶ vconstant

573. For the Sieve Technique we take time

▶  $T(nk)$  ( Page 34)

▶  $T(n / 3)$

▶  $n^2$

▶  $n/3$

574. One Example of in place but not stable sort is

▶ Quick (Page 54)

▶ Heap

▶ Merge

▶ Bubble

575. Consider the following Algorithm: Factorial (n) { if (n=1) return 1 else return (n \* Factorial(n-1)) } Recurrence for the following algorithm is:

▶  $T(n) = T(n-1) + 1$

▶  $T(n) = nT(n-1) + 1$

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- ▶  $T(n) = T(n-1) + n$
- ▶  $T(n) = T(n(n-1)) + 1$

576. Due to left complete nature of binary tree, the heap can be stored in

- ▶ Arrays (Page 40)
- ▶ Structures
- ▶ Link Lis
- ▶ Stack

577. What type of instructions Random Access Machine (RAM) can execute?

- ▶ Algebraic and logic
- ▶ Geometric and arithmetic
- ▶ Arithmetic and logic (Page 10)
- ▶ Parallel and recursive

578. What is the total time to heapify?

- ▶  $O(\log n)$  (Page 43)
- ▶  $O(n \log n)$
- ▶  $O(n^2 \log n)$
- ▶  $O(\log^2 n)$

579. word Algorithm comes from the name of the muslim author \_\_\_\_\_

- ▶ Abu Ja'far Mohammad ibn Musa al-Khowarizmi.

580. al-Khwarizmi's work was written in a book titled \_\_\_\_\_

- ▶ al Kitab al-mukhatasar fi hisab al-jabr wa'l-muqabalah

581. Random access machine or RAM is a/an

- ▶ Machine build by Al-Khwarizmi
- ▶ Mechanical machine
- ▶ Electronics machine
- ▶ Mathematical model (Page 10)

582. A RAM is an idealized machine with \_\_\_\_\_ random-access memory.

- ▶ 256MB
- ▶ 512MB
- ▶ an infinitely large (Page 10)
- ▶ 100GB

583. What will be the total number of max comparisons if we run brute-force maxima algorithm with n elements?

- ▶  $2n$
- ▶  $2nn$
- ▶  $n$  (Page 14)
- ▶  $8n$

584. Due to left complete nature of binary tree, the heap can be stored in

- ▶ Arrays (Page 40)

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- ▶ Structures
  - ▶ Link Lis
  - ▶ Stack
585. one What type of instructions Random Access Machine (RAM) can execute?
- ▶ Algebraic and logic
  - ▶ Geometric and arithmetic
  - ▶ Arithmetic and logic (Page 10)
  - ▶ Parallel and recursive
586. What is the total time to heapify?
- ▶  $O(\log n)$  (Page 43)
  - ▶  $O(n \log n)$
  - ▶  $O(n^2 \log n)$
  - ▶  $O(\log^2 n)$
587. Random access machine or RAM is a/an
- ▶ Machine build by Al-Khwarizmi
  - ▶ Mechanical machine
  - ▶ Electronics machine
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588. A RAM is an idealized machine with \_\_\_\_\_ random-access memory.
- ▶ 256MB
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  - ▶ 100GB
589. What will be the total number of max comparisons if we run brute-force maxima algorithm with n elements?
- ▶  $2n$
  - ▶  $2nn$
  - ▶  $n$  (Page 14)
  - ▶  $8n$
590. The sieve technique works where we have to find \_\_\_\_\_ item(s) from a large input.
- ▶ Single (Page 34)
  - ▶ Two
  - ▶ Three
  - ▶ Similar
591. In which order we can sort?
- ▶ increasing order only
  - ▶ decreasing order only
  - ▶ increasing order or decreasing order (Page 39)

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- ▶ both at the same time
- 592. For the heap sort we store the tree nodes in
  - ▶ level-order traversal (Page 40)
  - ▶ in-order traversal
  - ▶ pre-order traversal
  - ▶ post-order traversal
- 593. In the analysis of Selection algorithm, we eliminate a constant fraction of the array with each phase; we get the convergent \_\_\_\_\_ series in the analysis, ▶ linear
  - ▶ arithmetic
  - ▶ geometric (Page 37)
  - ▶ exponent
- 594. How much time merge sort takes for an array of numbers?
  - ▶  $T(n^2)$
  - ▶  $T(n)$
  - ▶  $T(\log n)$
  - ▶  $T(n \log n)$  (Page 40)
- 595. Memoization is?
  - ▶ To store previous results for future use
  - ▶ To avoid this unnecessary repetitions by writing down the results of recursive calls and looking them up again if we need them later (page 74)
  - ▶ To make the process accurate
  - ▶ None of the above
- 596. Count sort is suitable to sort the elements in range 1 to k
  - ▶ K is Large
  - ▶ K is not known
  - ▶ K may be small or large
  - ▶ K is small (Page 57)
- 597. In place stable sorting algorithm.
  - ▶ If duplicate elements remain in the same relative position after sorting (Page 54)
  - ▶ One array is used
  - ▶ More than one arrays are required
  - ▶ Duplicating elements not handled
- 598. Sorting is one of the few problems where provable \_\_\_\_\_ bounds exists on how fast we can sort, ▶ upper ▶ lower (Page 39) ▶ average ▶  $\log n$
- 599. Question No: 65 ( Marks: 1 ) - Please choose one Counting sort has time complexity: ▶  $O(n)$  (Page 58)
  - ▶  $O(n+k)$
  - ▶  $O(k)$
  - ▶  $O(n \log n)$

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600. The running time of quick sort depends heavily on the selection of
- ▶ No of inputs
  - ▶ Arrangement of elements in array
  - ▶ Size o elements
  - ▶ Pivot elements (Page 49)
601. Which may be stable sort:
- ▶ Bubble sort
  - ▶ Insertion sort
  - ▶ Both of above (Page 54)
602. In Quick Sort Constants hidden in  $T(n \log n)$  are
- ▶ Large
  - ▶ Medium
  - ▶ Small
  - ▶ Not Known
603. Quick sort is based on divide and conquer paradigm; we divide the problem on base of pivot element and:
- ▶ There is explicit combine process as well to conquer the solution.
  - ▶ No work is needed to combine the sub-arrays, the array is already sorted
  - ▶ Merging the sub arrays
  - ▶ None of above. (Page 51)
604. A point  $p$  in 2-dimensional space is usually given by its integer coordinate(s)\_\_\_\_\_
- ▶ p.x only
  - ▶ p.y only
  - ▶ p.x & p.z
  - ▶ p.x & p.y (Page 10)
605. In \_\_\_\_\_ we have to find rank of an element from given input.
- ▶ Merge sort algorithm
  - ▶ Selection problem (Page 34)
  - ▶ Brute force technique
  - ▶ Plane Sweep algorithm
606. In Heap Sort algorithm, if heap property is violated \_\_\_\_\_
- ▶ We call Build heap procedure
  - ▶ We call Heapify procedure
  - ▶ We ignore
  - ▶ Heap property can never be violated
607. Upper bound requires that there exist positive constants  $c_2$  and  $n_0$  such that  $f(n) \_\_\_ c_2 n$  for all  $n \leq n_0$ (ye question ghalat lag raha hai mujhae
- ▶ Less than
  - ▶ Equal to or Less than (Page 25)

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▶ Equal or Greater than

▶ Greater than

608. A RAM is an idealized algorithm with takes an infinitely large random-access memory. ▶ True

▶ False (Page 10)

609. \_\_\_\_\_ is one of the few problems, where provable lower bounds exist on how fast we can sort.

▶ Searching

▶ Sorting

▶ Both Searching & Sorting

▶ Graphing

610. Floor and ceiling are \_\_\_\_\_ to calculate while analyzing algorithms.

▶ Very easy

▶ Usually considered difficult (Page 31)

611. In Heap Sort algorithm, the maximum levels an element can move upward is \_\_\_\_\_

▶ Theta ( $\log n$ ) (Page 43)

▶ Order ( $\log n$ )

▶ Omega ( $\log n$ )

▶ O (1) i.e. Constant time

612. A point p in 2-dimensional space is usually given by its integer coordinate(s)\_\_\_\_\_

▶ p.x only p.y

▶ only p.x & p.z

▶ p.x & p.y (Page 17)

613. In Heap Sort algorithm, the total running time for Heapify procedure is \_\_\_\_\_

▶ Theta ( $\log n$ ) (Page 43)

▶ Order ( $\log n$ )

▶ Omega ( $\log n$ )

▶ O (1) i.e. Constant time

614. Algorithm is a mathematical entity, which is independent of a specific machine and operating system.

▶ True

▶ False (Page 7)

615. While Sorting, the ordered domain means for any two input elements x and y \_\_\_\_\_ satisfies only.

▶  $x < y$

▶  $x > y$

▶  $x = y$

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▶ All of the above (Page 39)

616. Quick sort is best from the perspective of Locality of reference.

▶ True (Page 9)

▶ False

617. In Heap Sort algorithm, we build \_\_\_\_\_ for ascending sort.

▶ Max heap (Page 41)

▶ Min heap

618. In Sieve Technique, we know the item of interest.

▶ True

▶ False (Page 34)

619. While solving Selection problem, in Sieve technique we partition input data

▶ In increasing order

▶ In decreasing order

▶ According to Pivot (Page 35)

▶ Randomly

620. In pseudo code, the level of details depends on intended audience of the algorithm.

▶ True (Page 12)

▶ False

621. If the indices passed to merge sort algorithm are \_\_\_\_\_, then this means that there is only one element to sort. ▶ Small

▶ Large

▶ Equal (Page 28)

▶ Not Equal

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