

Introduction to the Course

**The Need for
Communication**

Trends and Advancements

**What is taught in this
course?**

**What is NOT taught in this
course?**

Tips and Tricks to do well

Text and References

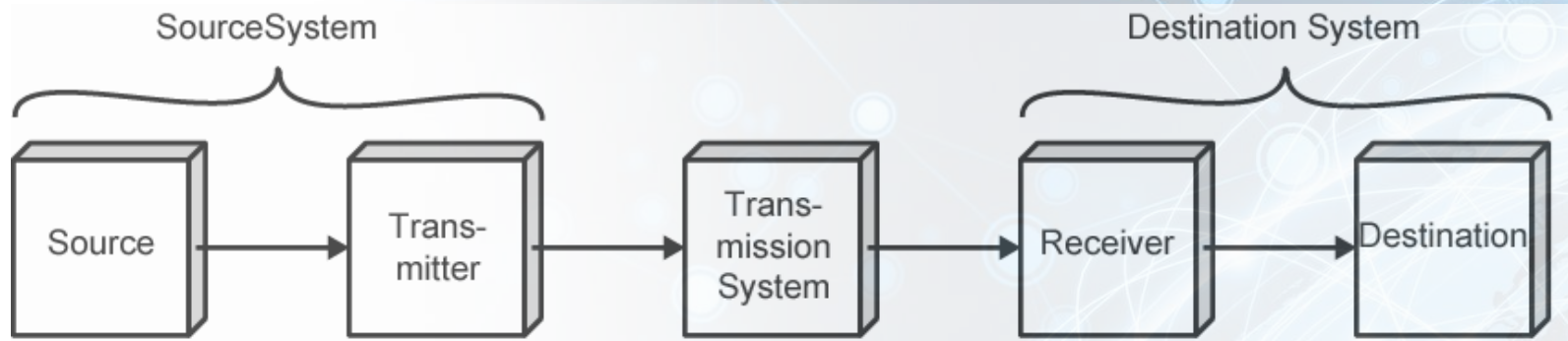
Introduction to Data Communications

Communication: Sharing of Information (Local or remote)

Telecommunications: Communication at a Distance (includes telephony, telegraph, and television etc.)

Data communications: Exchange of data between two devices via some form of transmission media

A Simple Communication Model



(a) General block diagram



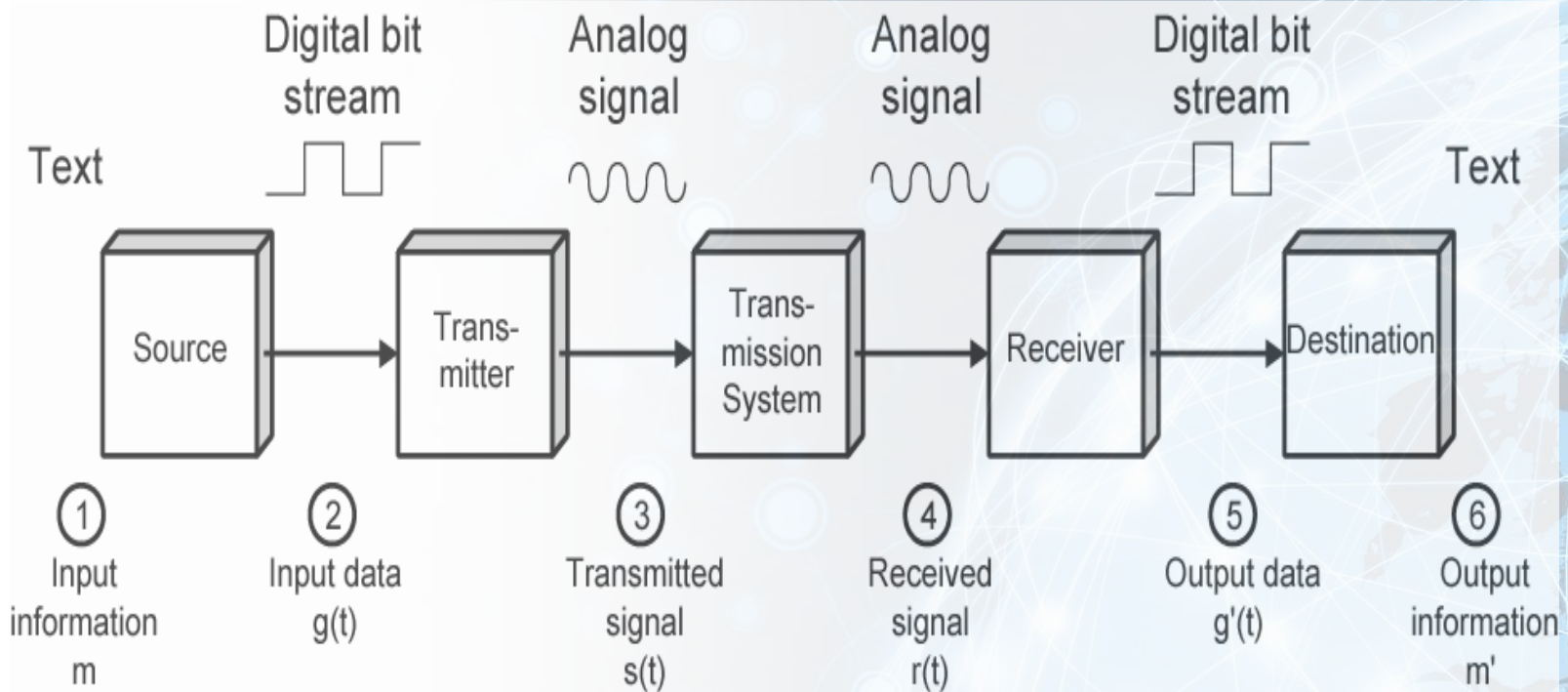
(b) Example

Characteristics of a Data Communication System

Effectiveness of a Data Communication System:

- **Delivery**
- **Accuracy**
- **Timeliness**
- **Jitter**

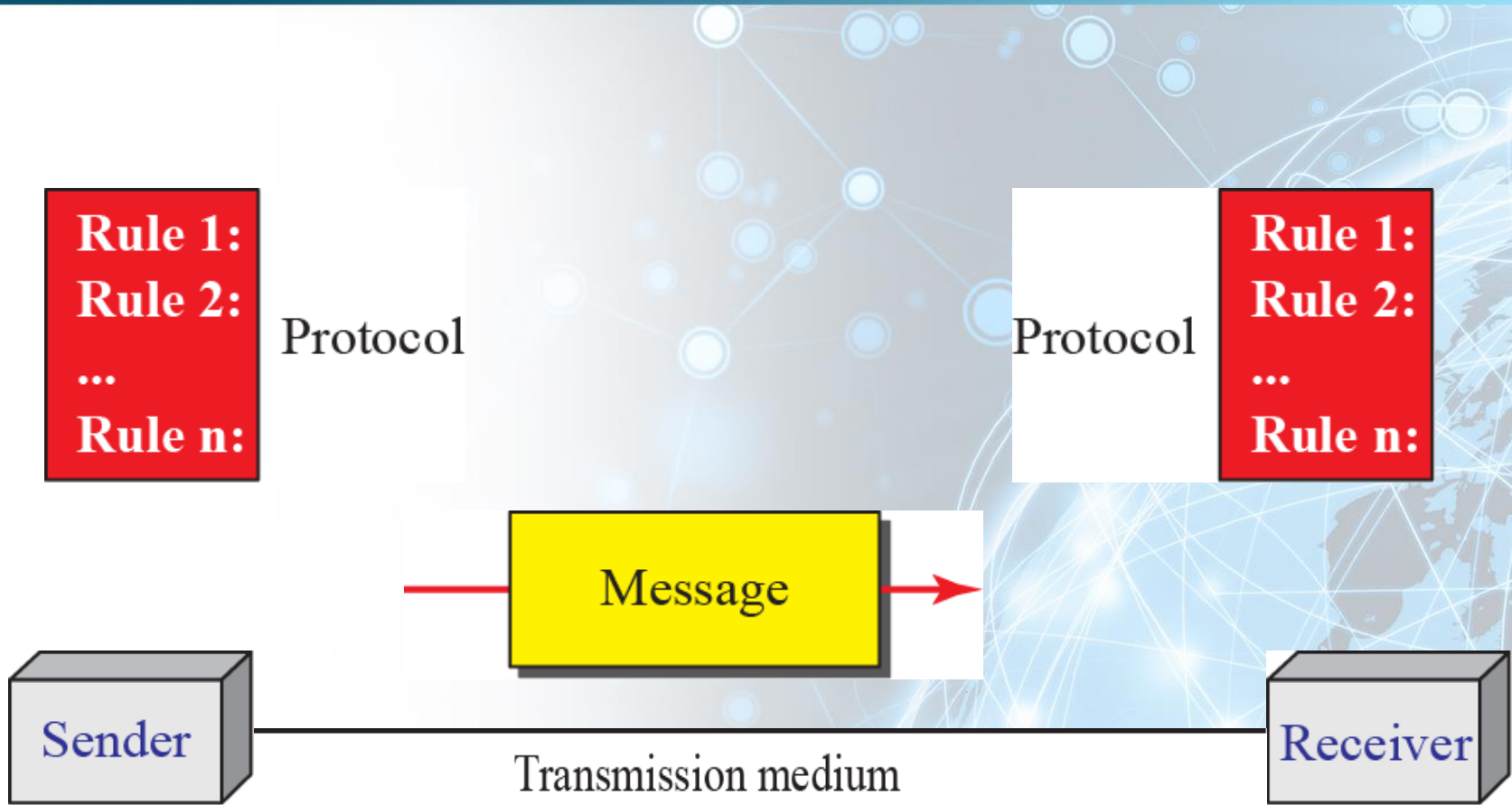
Characteristics of a Data Communication System



Components of a Data Communication system

A data communications system has five components

Components of Data Communication system



Data Representation and Data Flow

Forms of Information

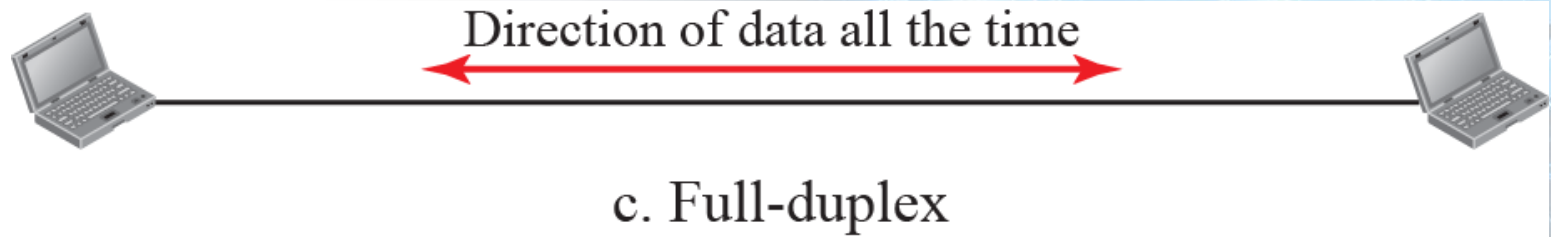
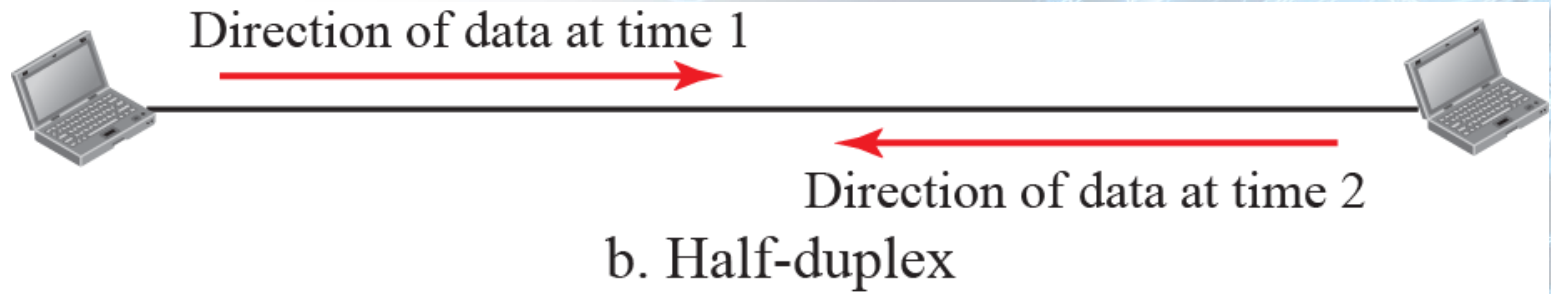
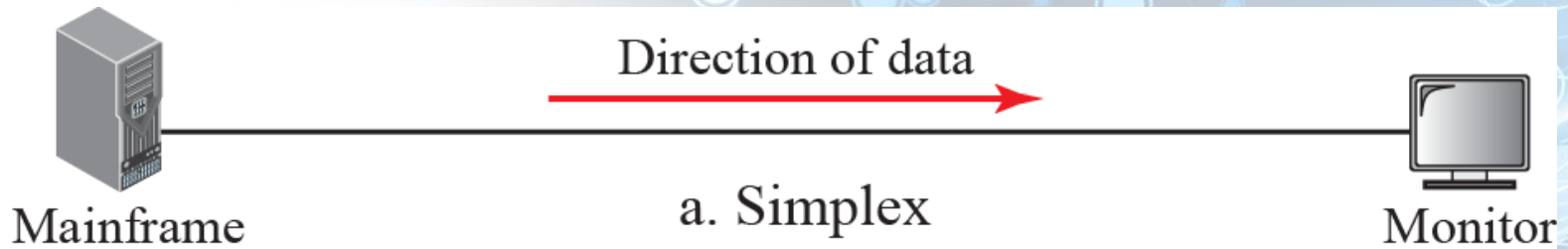
- Text
- Numbers
- Images
- Audio
- Video

Data Representation and Data Flow

Data Flow between two devices:

- **Simplex**
- **Half-Duplex**
- **Full-Duplex**

Data Flow



Networks

- **Network:**
Interconnection of a set of devices capable of communication
- **Host**
- **Connecting Device**

Network Criteria

A network must be able to meet a certain number of criteria:

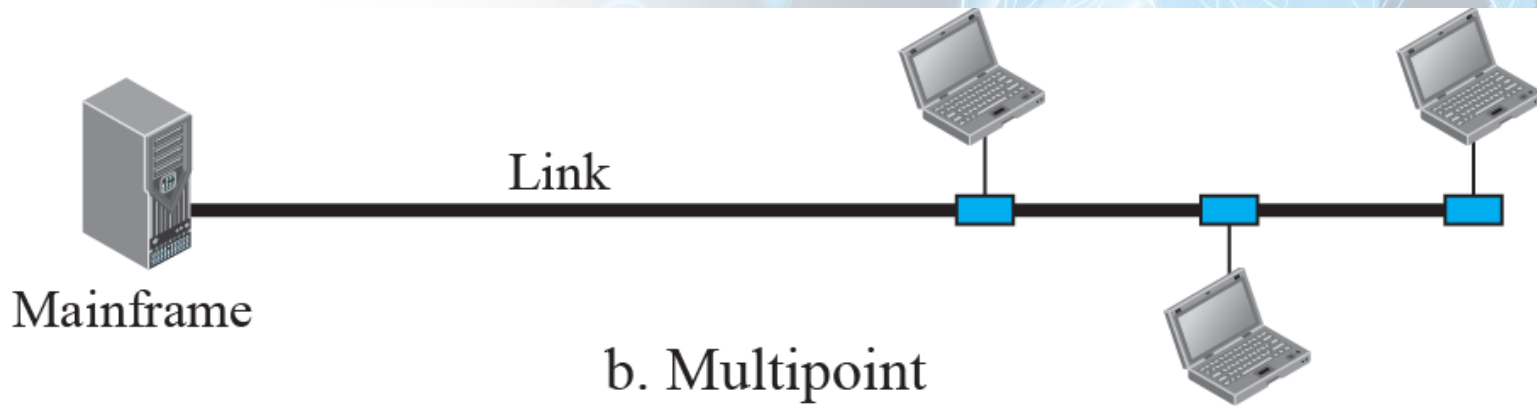
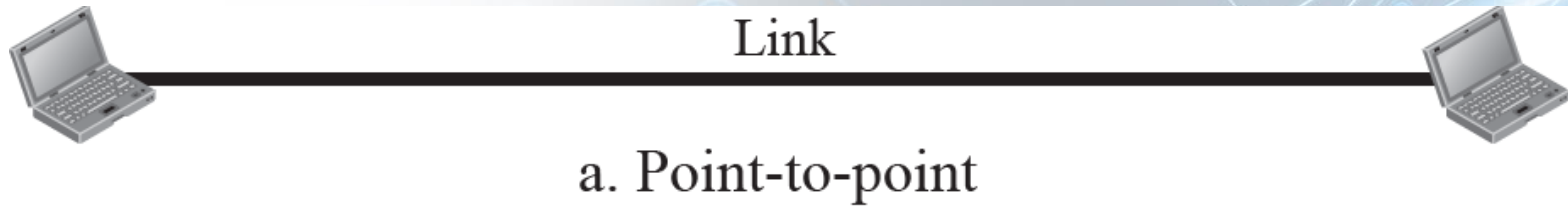
- **Performance**
 - ✓ Throughput
 - ✓ Delay
- **Reliability**
- **Security**

Physical Structures

Physical Network Attributes

- **Link**
- **Type of Connection**
 - ✓ **Point-to-Point**
 - ✓ **Multipoint**

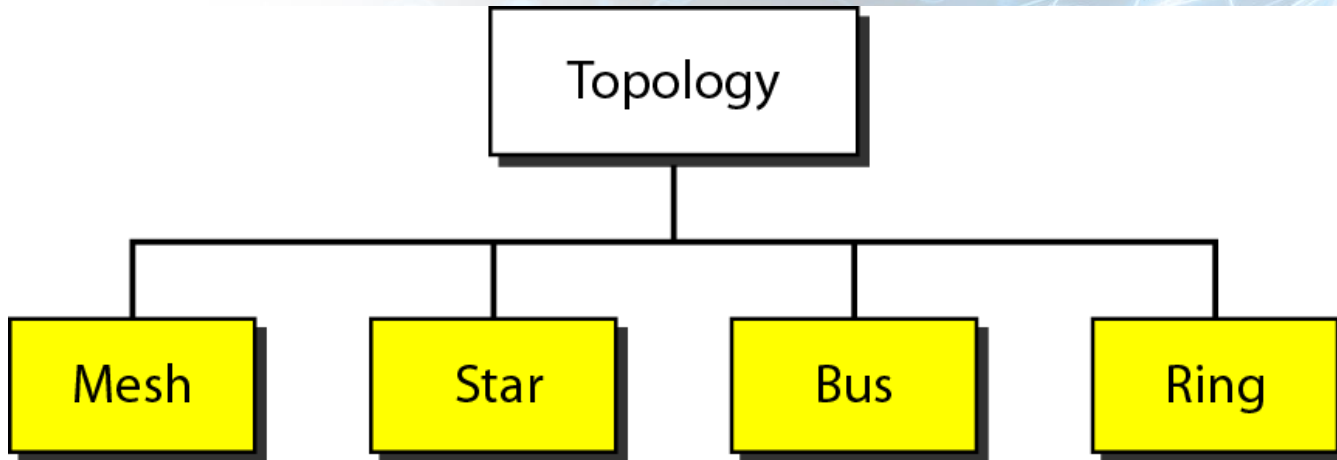
Physical Structures



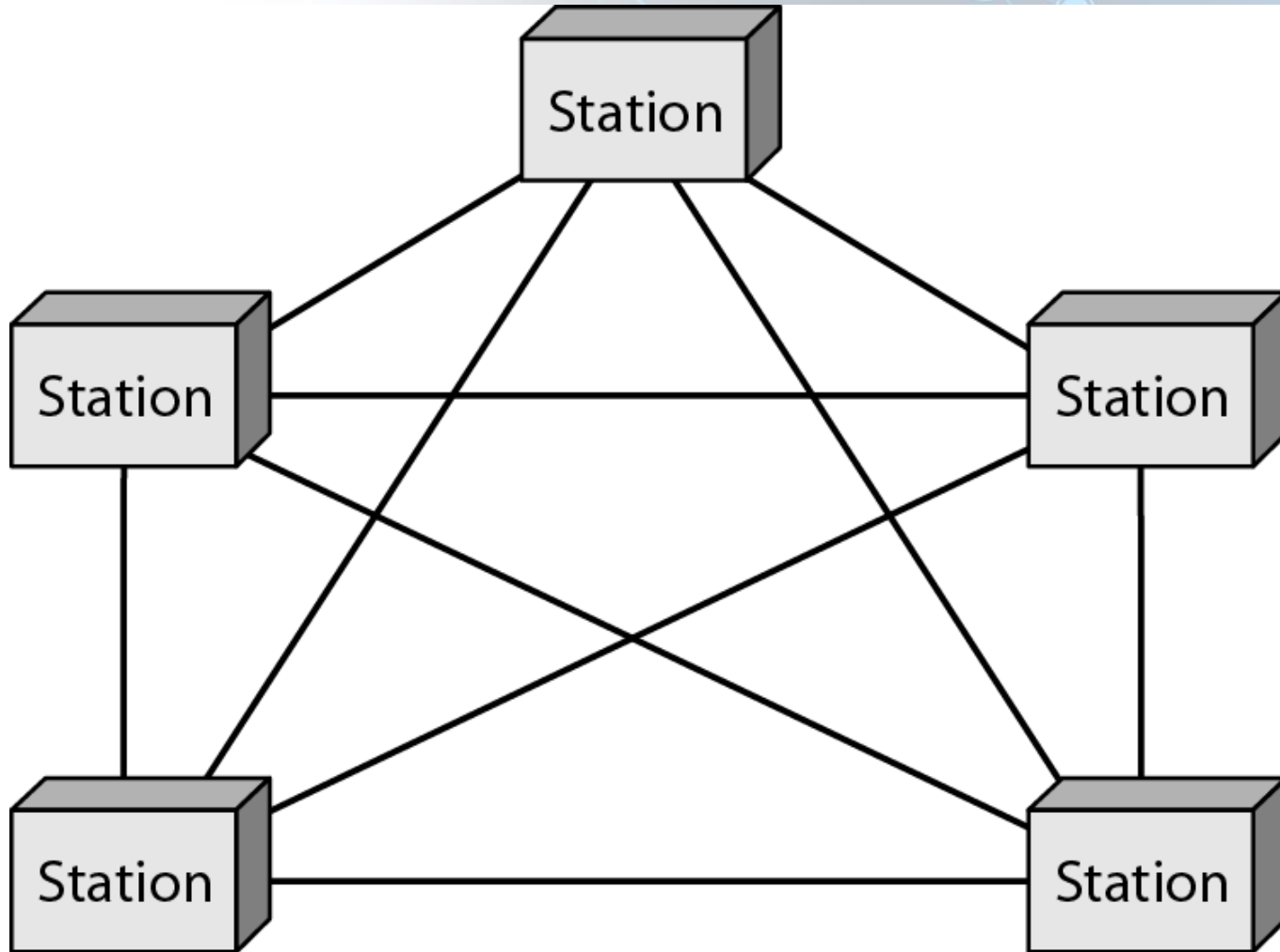
Physical Topologies

- **Physical Layout of Network**
- **Links + Nodes = Topology**
- **Physical Topologies:**
 - ✓ **Mesh**
 - ✓ **Star**
 - ✓ **Bus**
 - ✓ **Ring**

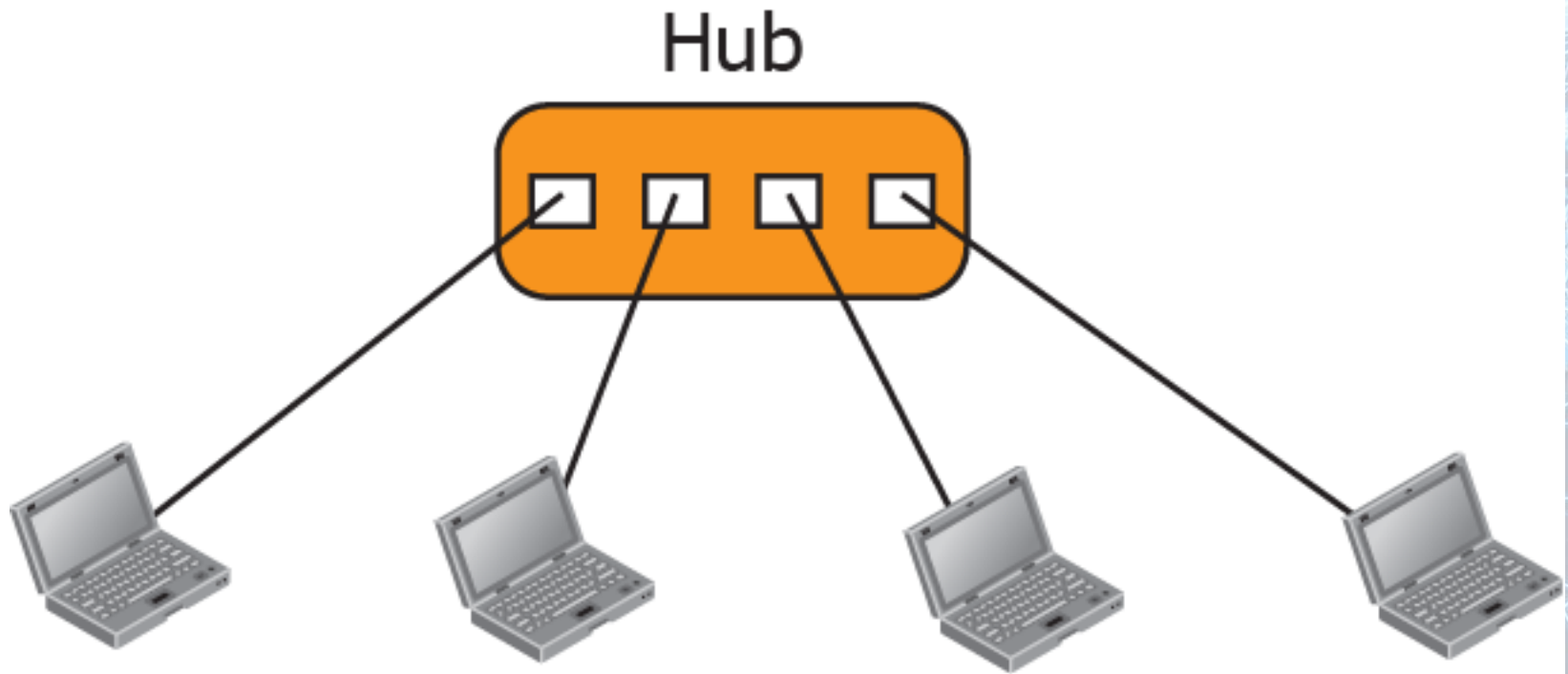
Physical Topologies



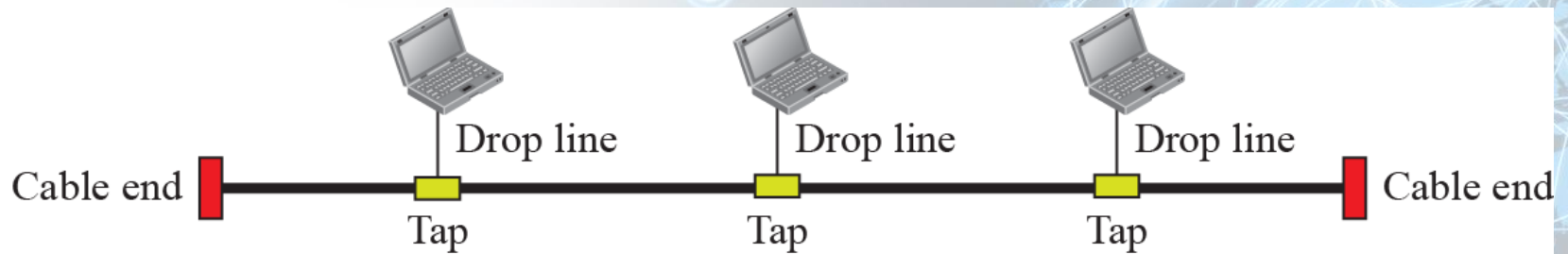
Mesh Topology



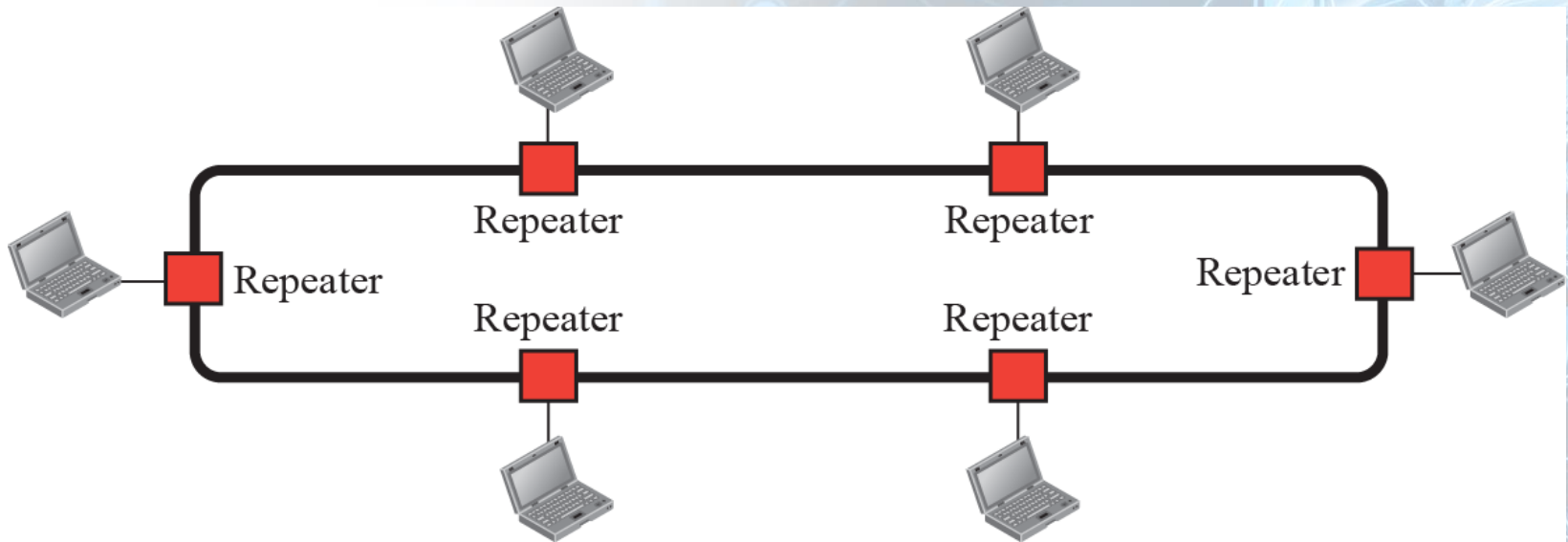
Star Topology



Bus Topology



Ring Topology



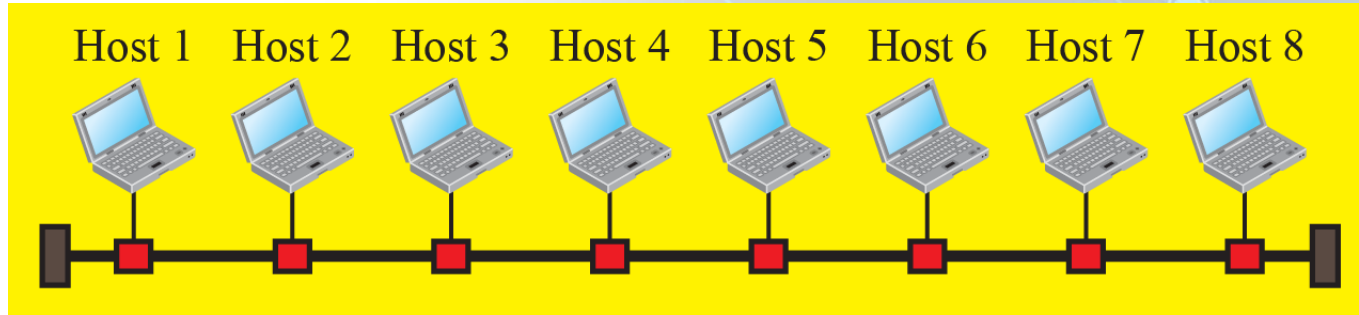
Networks Types

- **Network classification:**
 - ✓ **Size**
 - ✓ **Geographical Coverage**
 - ✓ **Ownership**
- **Local Area Networks (LANs)**
- **Wide Area Networks (WANs)**

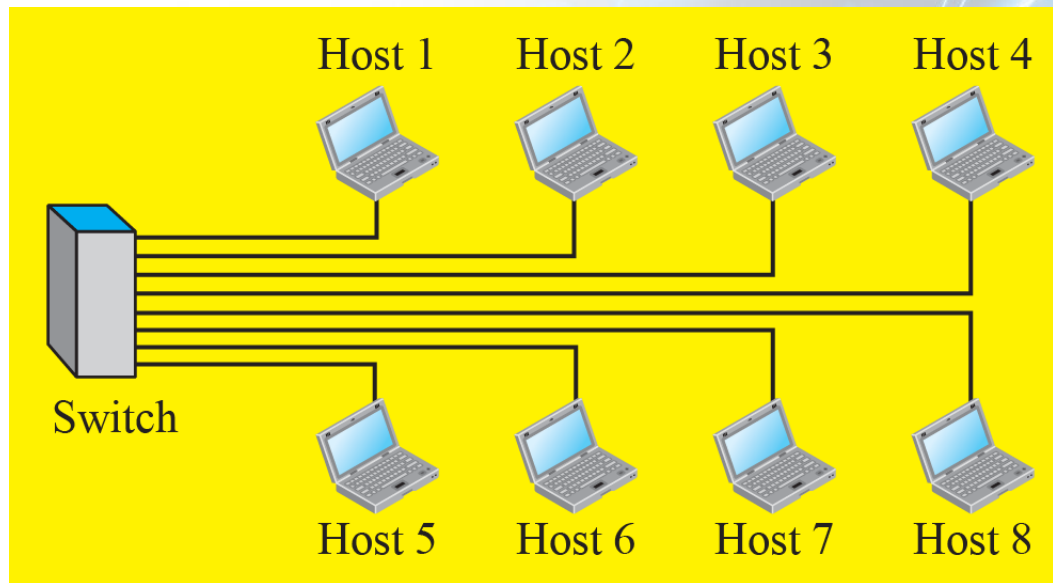
Local Area Networks

- **Usually Privately owned**
- **Connects some hosts in a single office, building, or campus**
- **Can be as simple as two PCs and a printer in someone's home office**
- **Can extend throughout a company**
- **Host Address**

Local Area Networks









a. LAN with a common cable (past)



b. LAN with a switch (today)

Legend

-  A host (of any type)
-  A switch
-  A cable tap
-  A cable end
-  The common cable
-  A connection

Wide Area Network

- **Wider geographical span than a LAN**
- **Spans a town, a state, a country, or even the world**
- **Interconnects connecting devices such as switches, routers, or modems**
- **Normally created and run by communication companies**

Wide Area Network

- **Point-to-Point WAN**
- **Switched WAN**
- **Internetwork**

Point-to-Point WANs



Legend

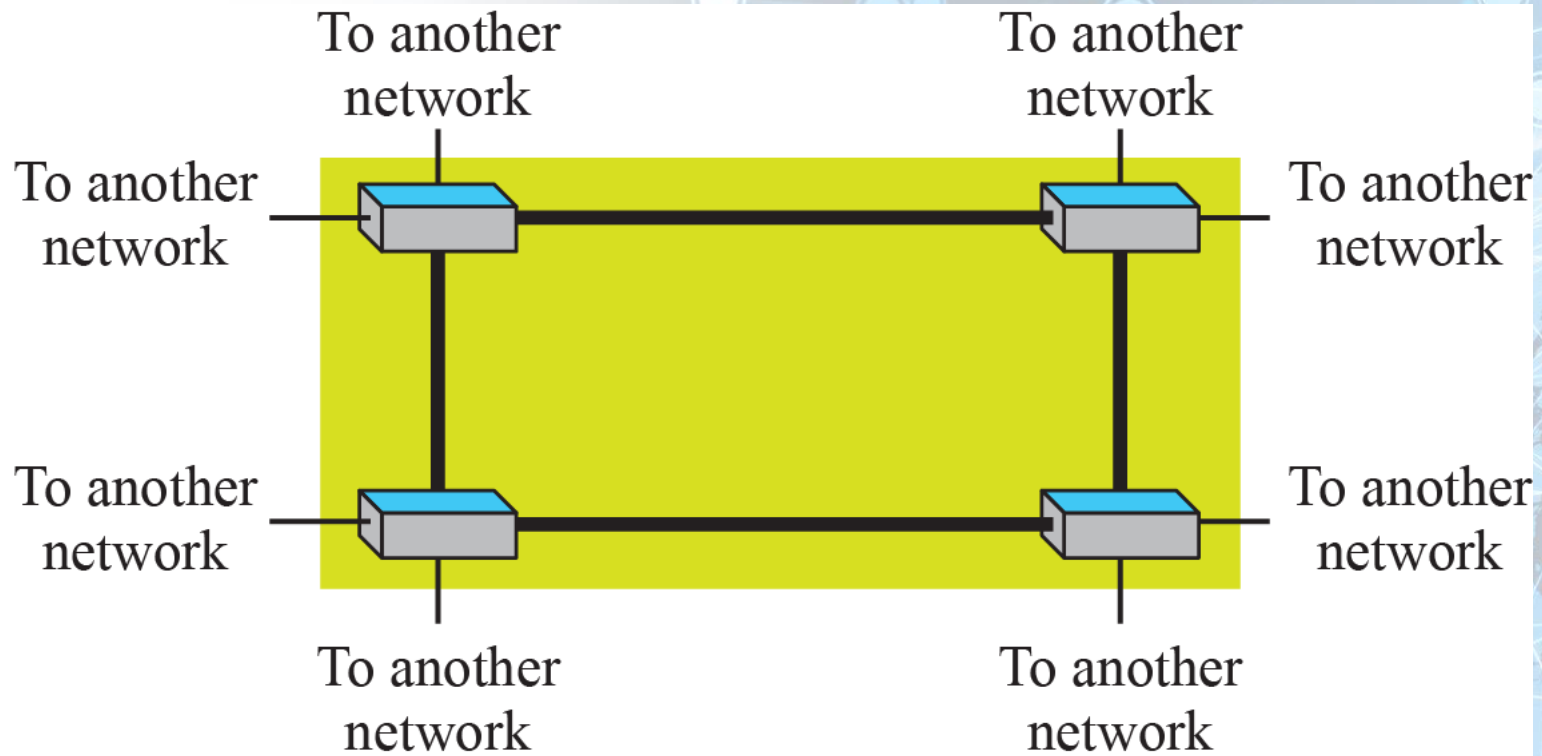


A connecting device



Connecting medium

Switched WANs



Legend

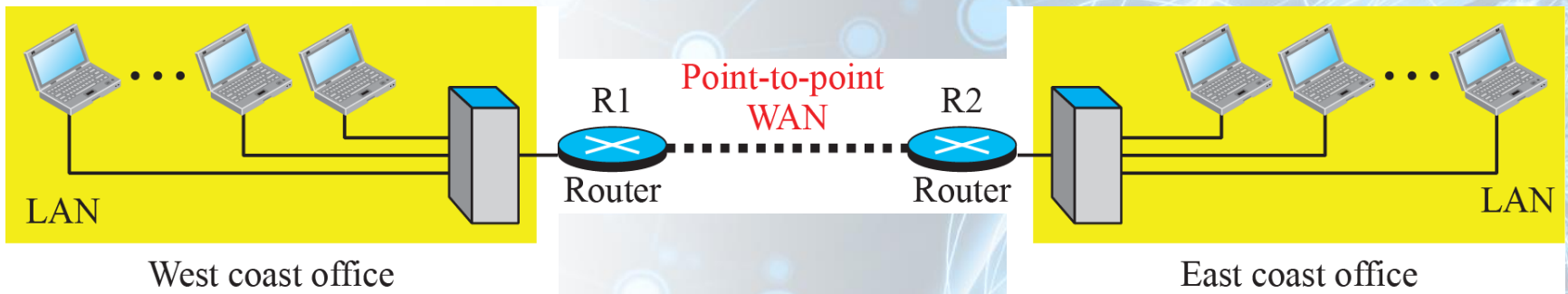


A switch



Connecting medium

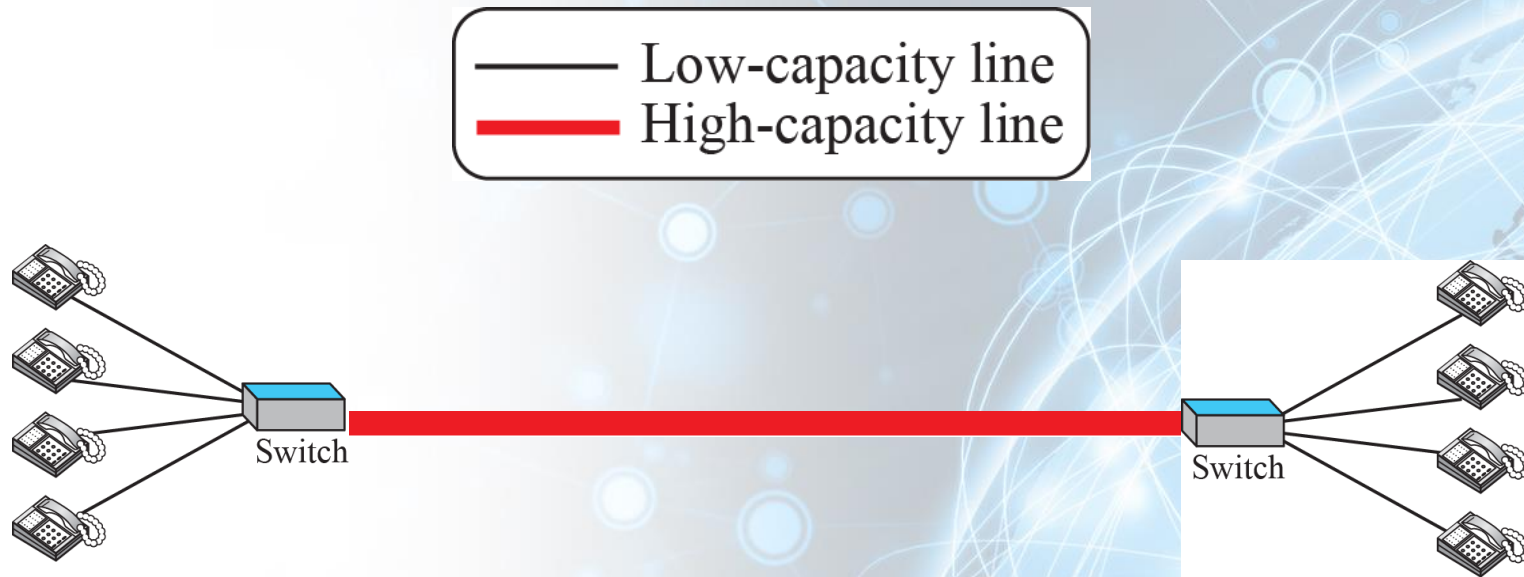
Internetwork



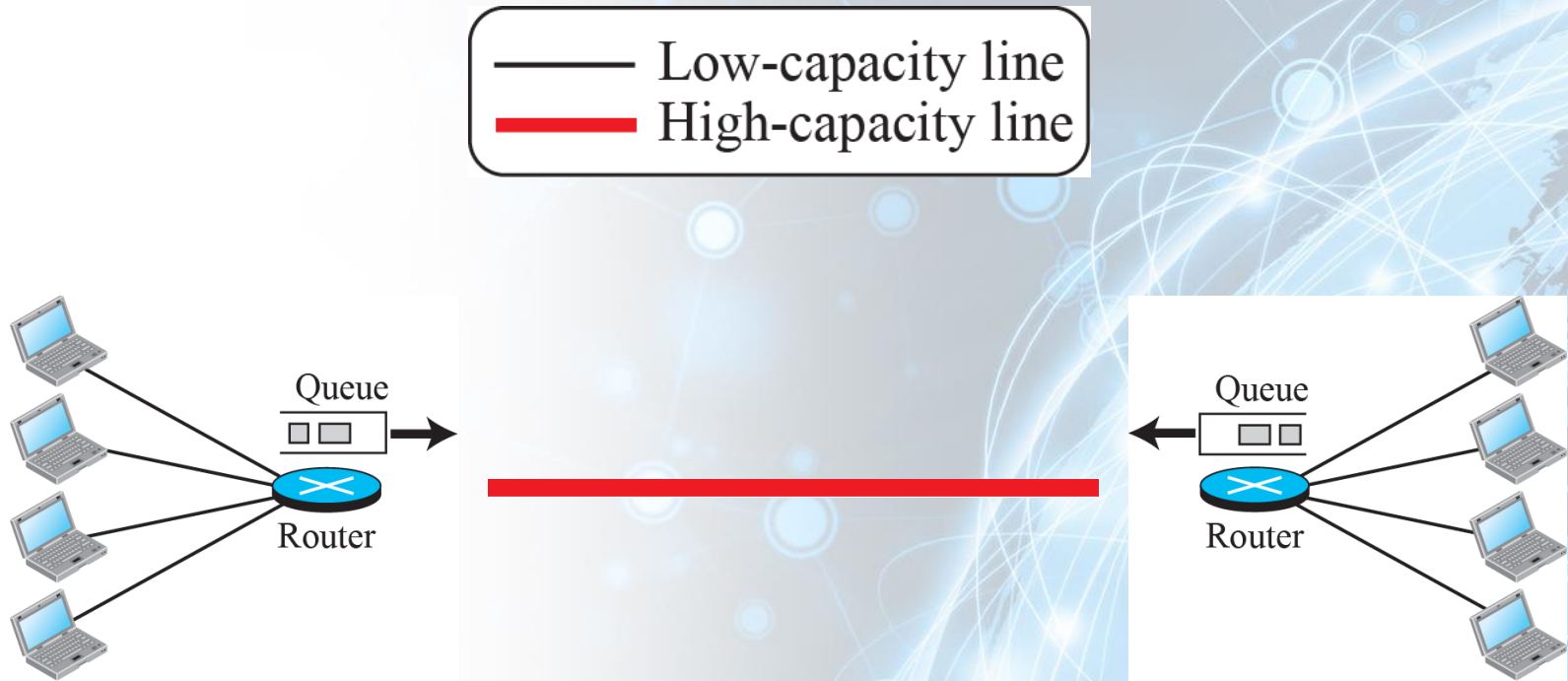
Switching

- **Switching**
 - ✓ **Circuit-Switched Network**
 - ✓ **Packet- Switched Network**

Circuit Switched Network



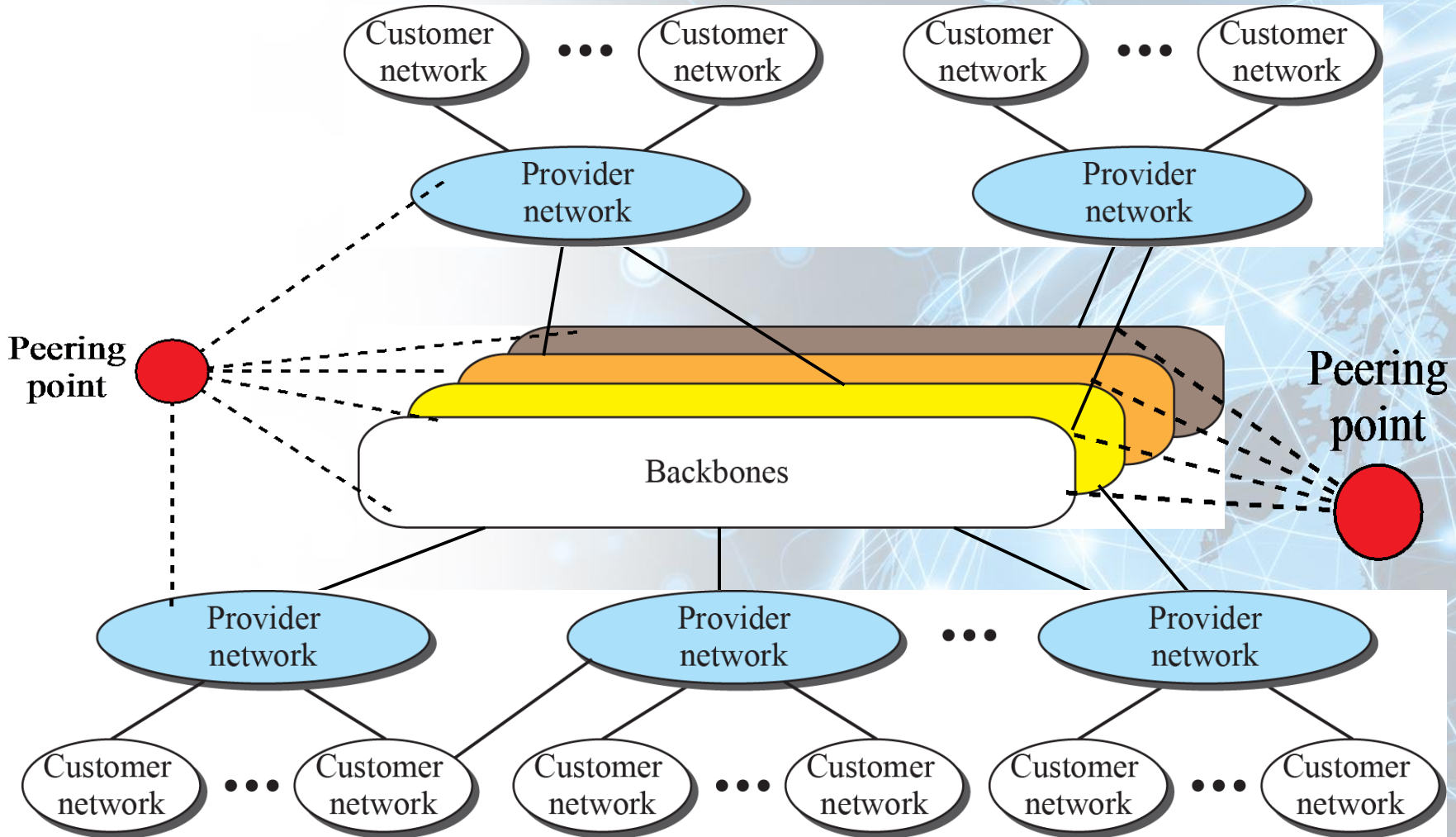
Packet Switched Network



The Internet

- An internet (note the lowercase i) is two or more networks that can communicate with each other
- The Internet (uppercase I), and is composed of thousands of interconnected networks.
- Accessing the Internet

The Internet



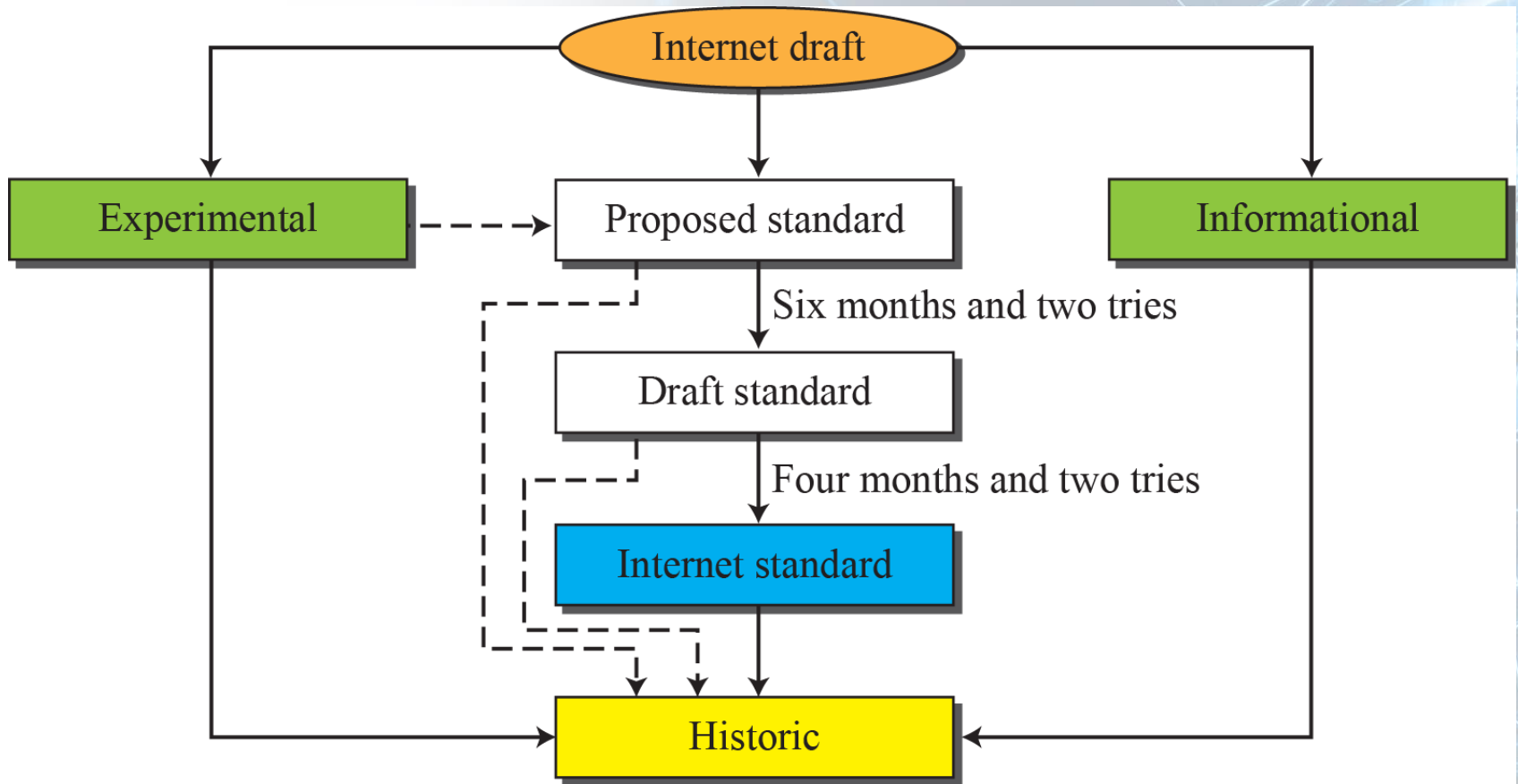
Internet History

- **Telegraph and Telephone networks, before 1960:**
 - ✓ **Constant-rate communication only**
- **ARPANET- Packet Switched**
- **Birth of the Internet &TCP/IP**
- **MILNET**
- **CSNET**
- **NSFNET**
- **Internet Today**

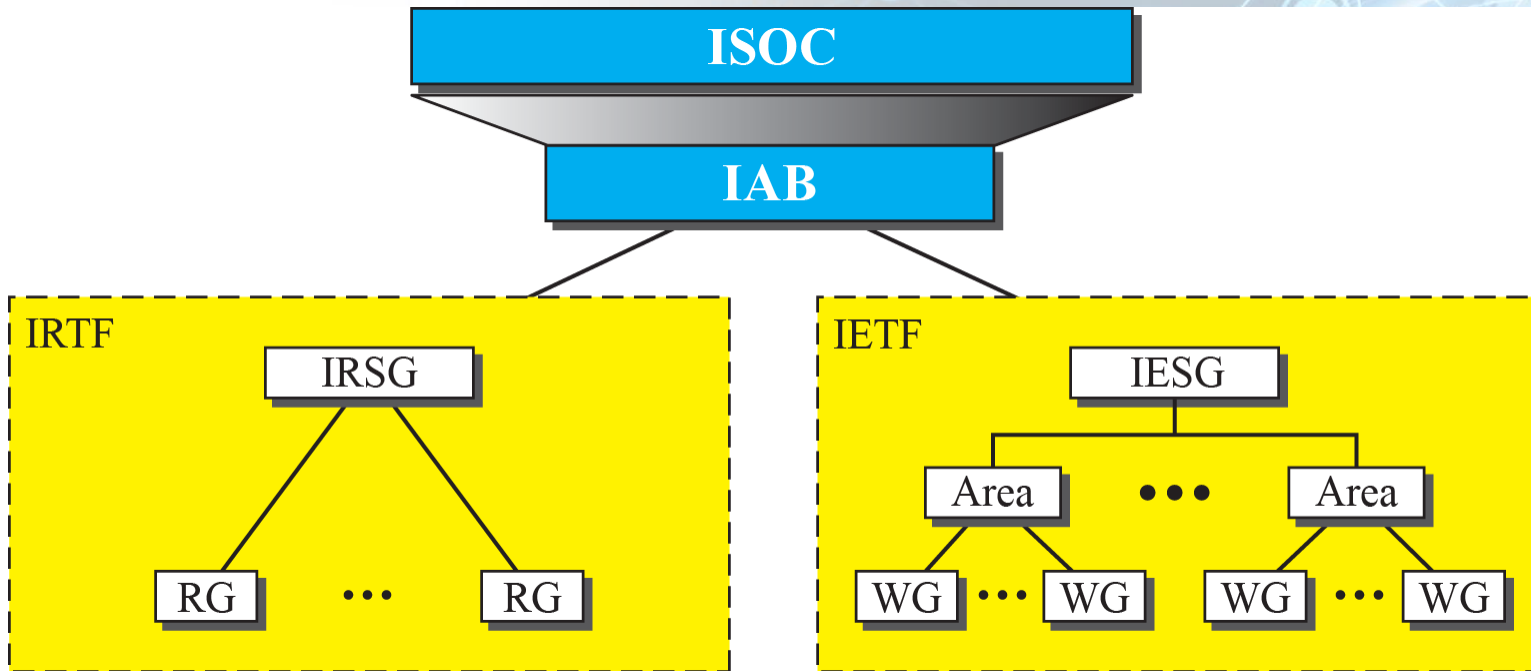
Internet Standards and Administration

- **Internet draft**
- **Request for Comments (RFC)**
 - ✓ **Proposed Standard**
 - ✓ **Draft Standard**
 - ✓ **Internet Standard**
 - ✓ **Historic**
 - ✓ **Experimental**
 - ✓ **Informational**

Internet Standards



Internet Administration

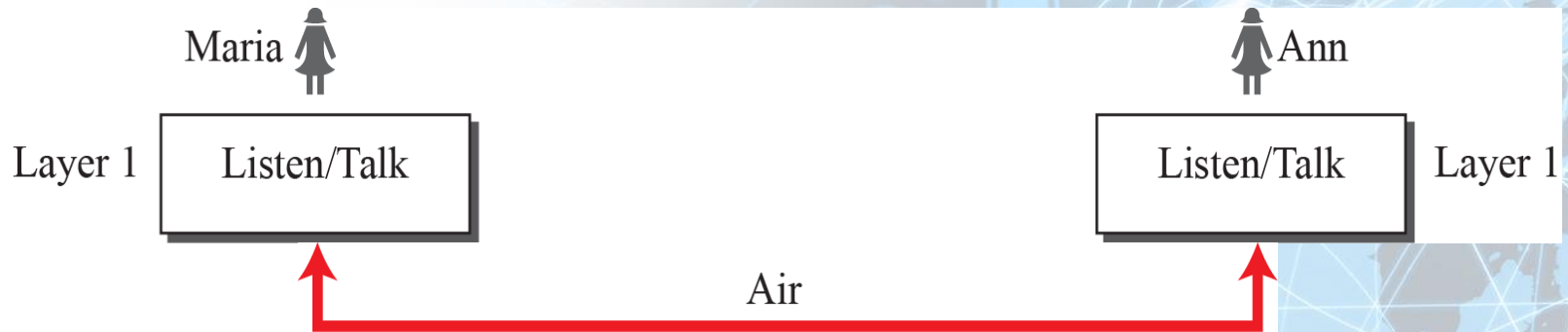


Protocol Layering - Introduction

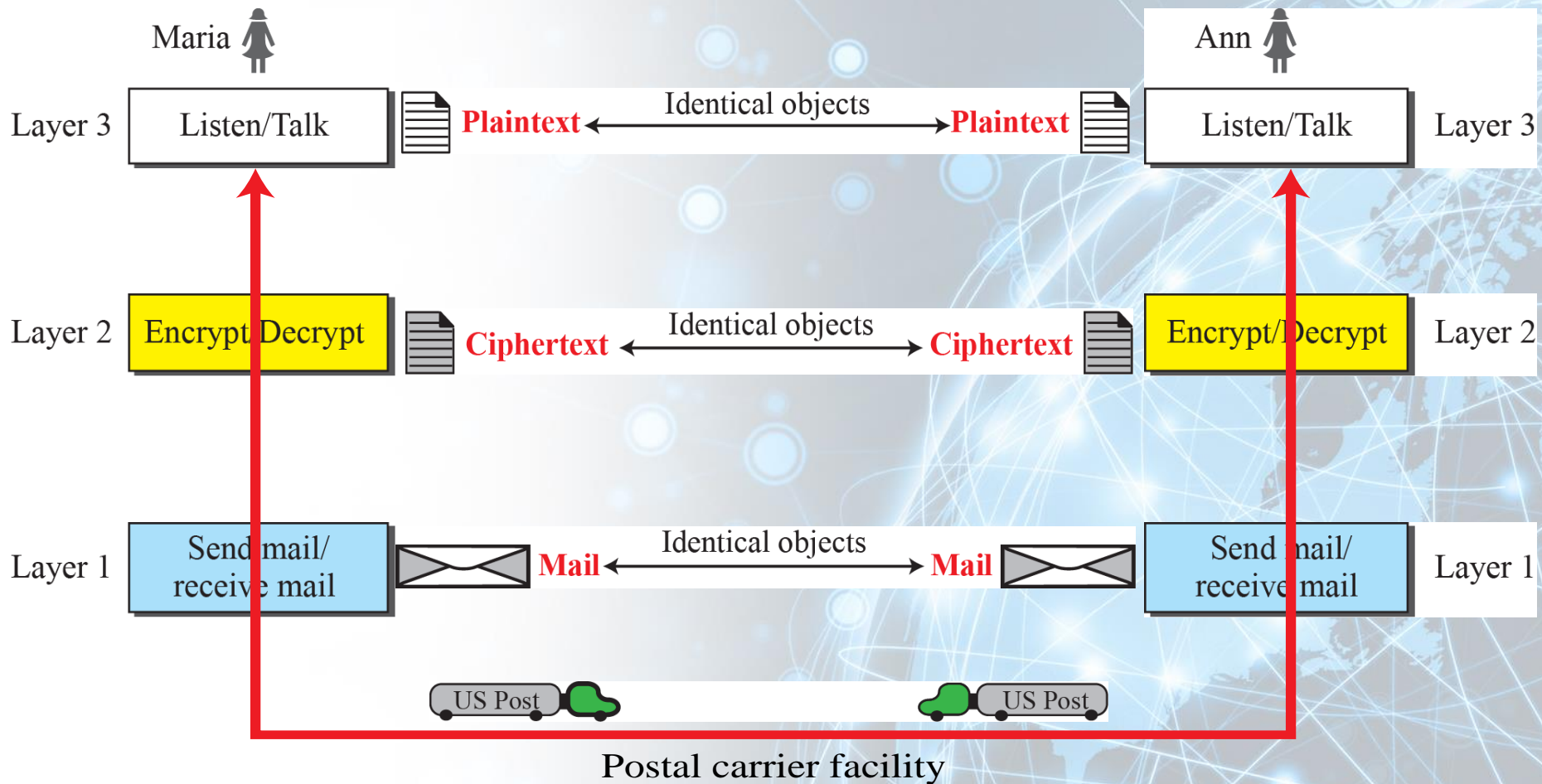
- **Protocol**
Rules that both the sender and receiver and all intermediate devices need to follow to be able to communicate effectively
- **Protocol Layering**
Simple Communication:
only one simple protocol

Complex Communication,
we need a protocol at each layer, or Protocol Layering

Protocol Layering - Example Scenario 1



Protocol Layering - Example Scenario 2



Protocol Layering - Advantages and Disadvantages

- **Advantages**
 - ✓ Modularity
 - ✓ Separation of Service & Implementation
 - ✓ Reduced Complexity & Cost
- **Disadvantages**
 - ✓ None Really!

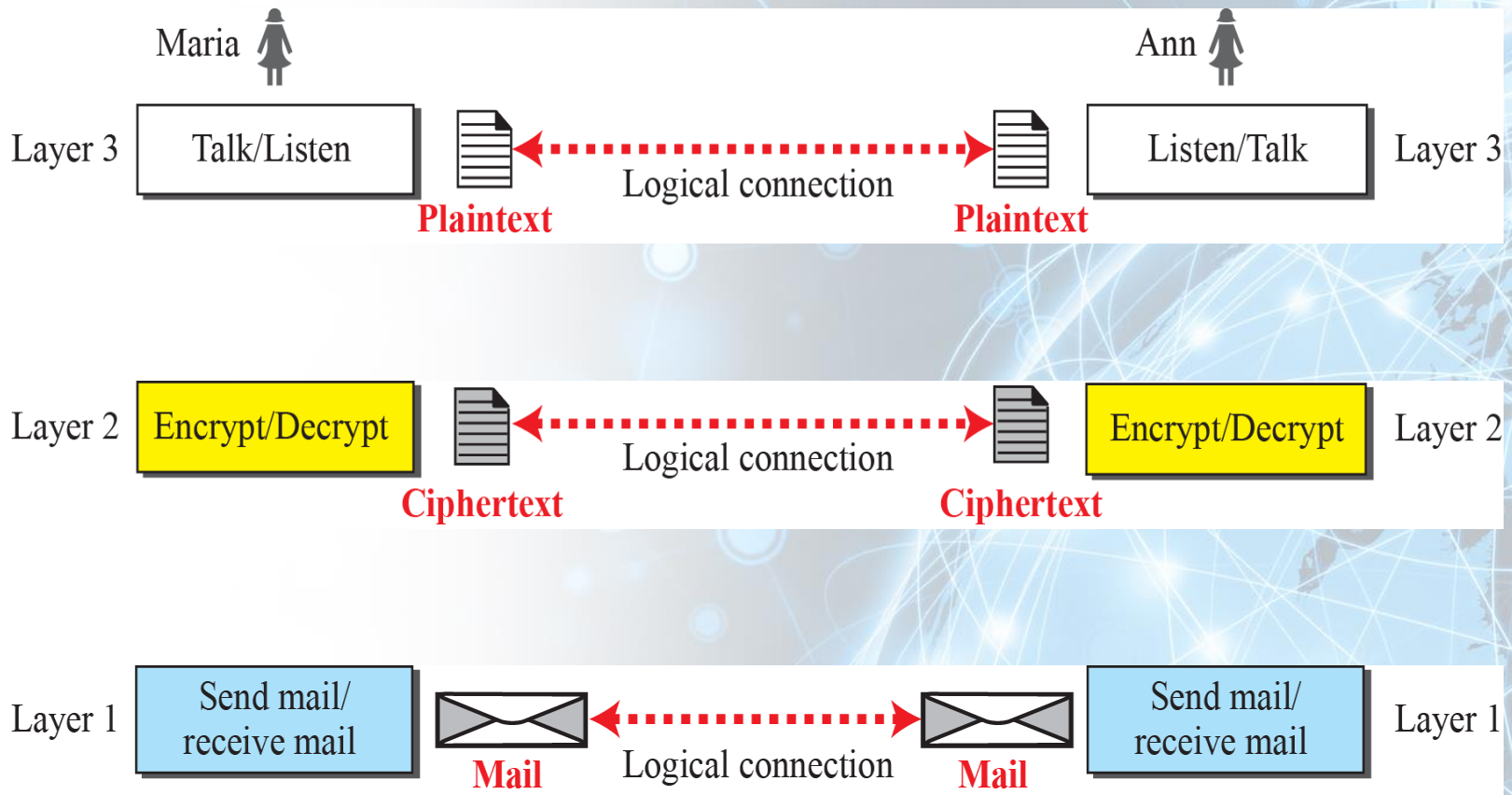
Protocol Layering - Principles

- **Two Principles**
 - ✓ Bidirectional Communication → Each Layer performs two opposite tasks in each direction
 - ✓ Two objects under each layer at both sites should be identical

Protocol Layering - Logical Connections

- **Logical Connections**
 - ✓ Imaginary connection between each layer

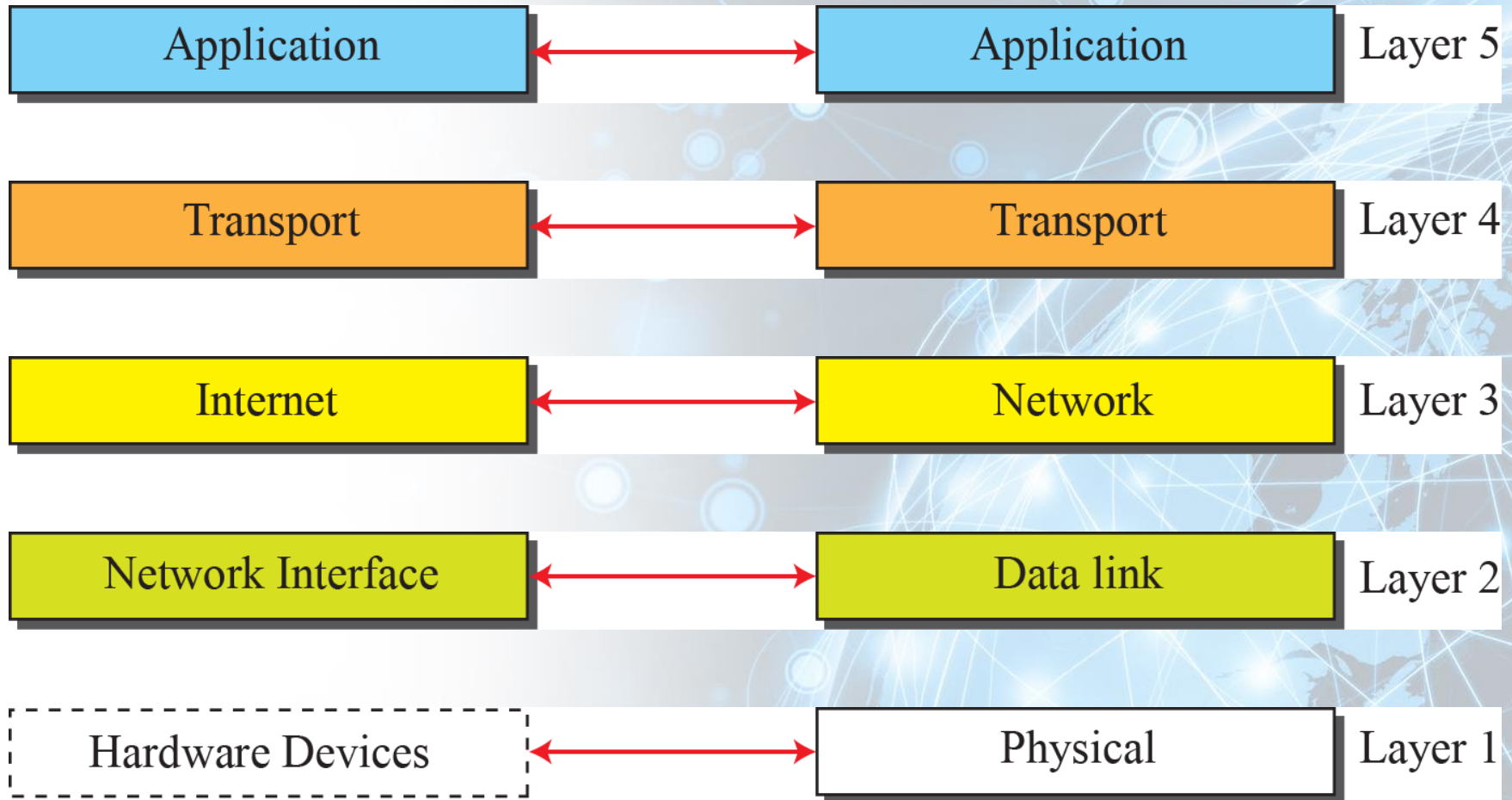
Protocol Layering



TCP/IP Protocol Suite

- **TCP/IP Protocol Suite**
 - ✓ Protocol suite used in Internet today
 - ✓ Each Layer provides specific functionality
 - ✓ Hierarchical Protocol
 - ✓ Presented in 1973 and chosen to be the official protocol of Internet in 1983

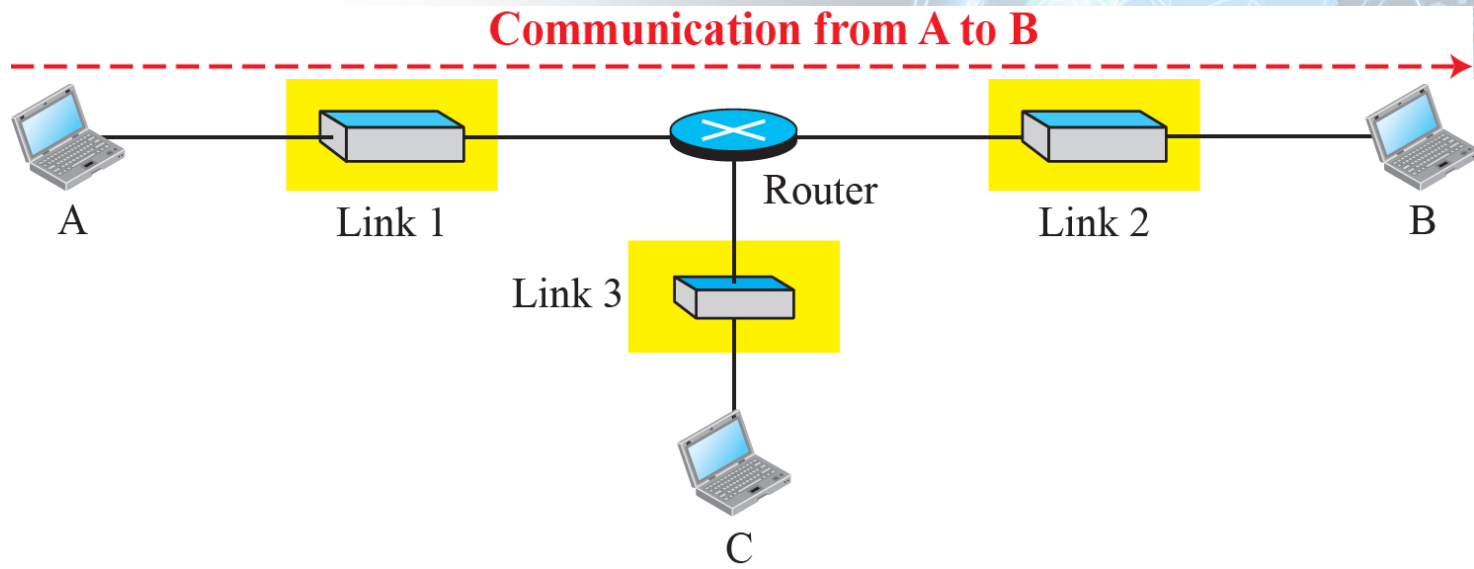
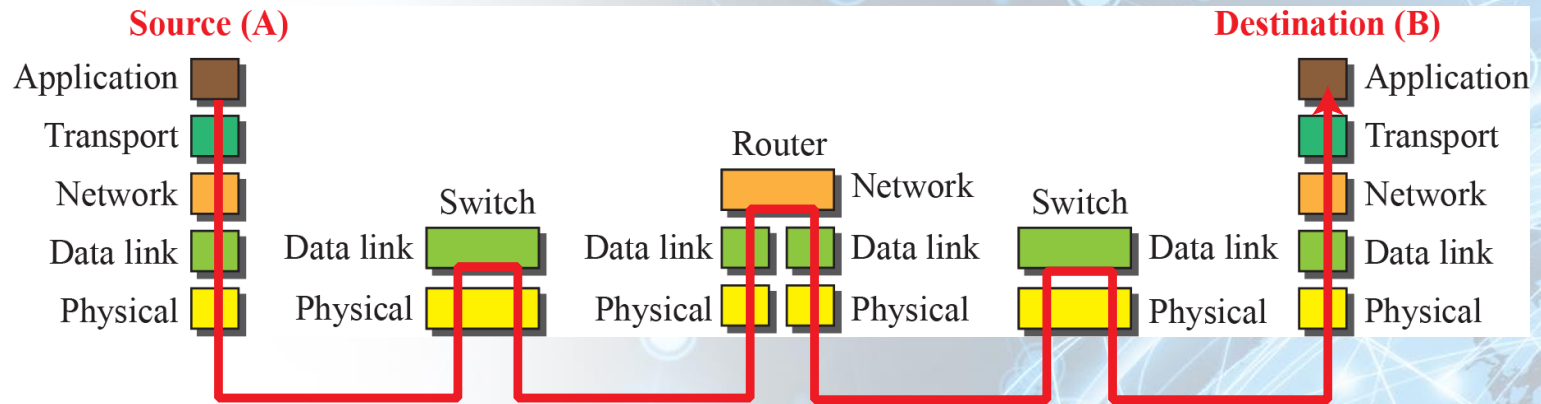
TCP/IP Protocol Suite



a. Original layers

b. Layers used in this book

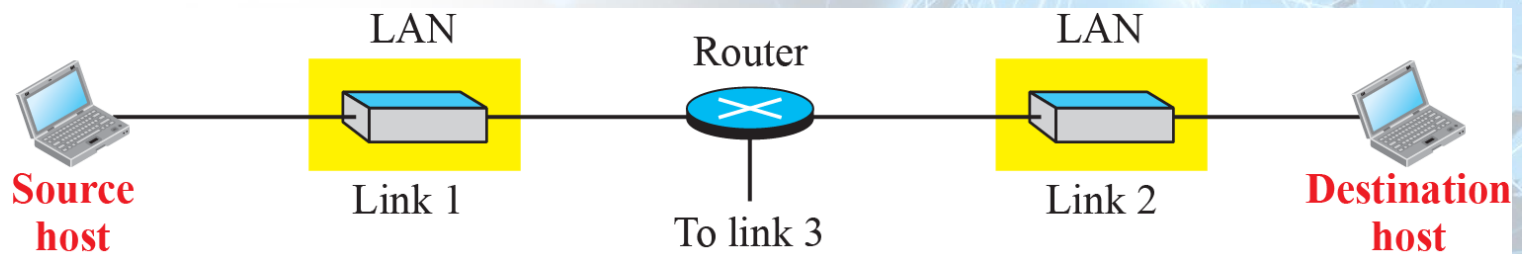
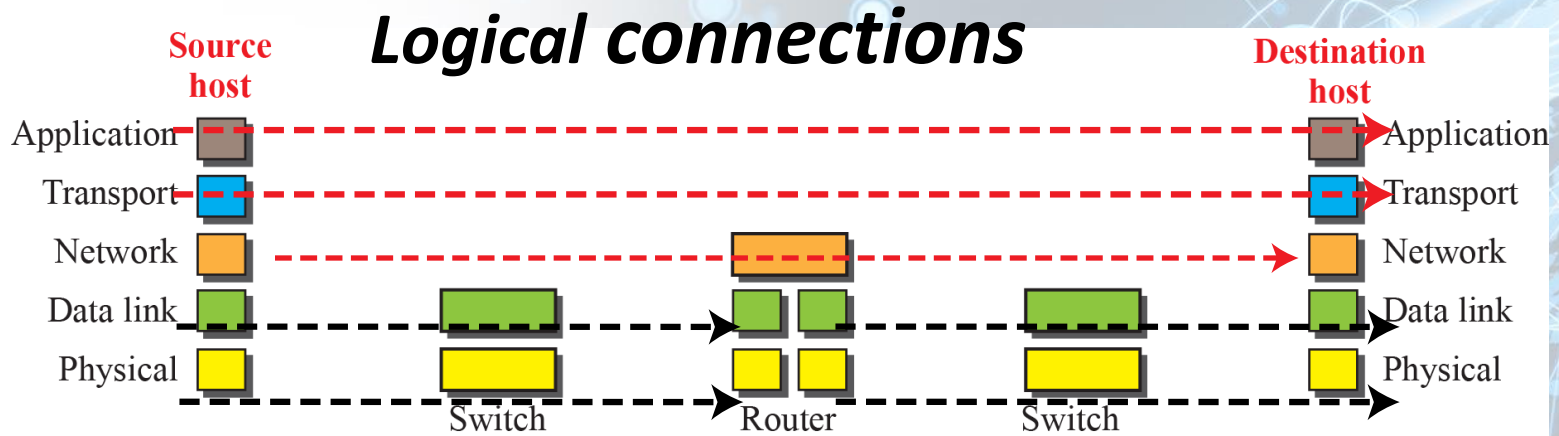
TCP/IP Protocol Suite - Layered Architecture



TCP/IP Protocol Suite – Function of Layers

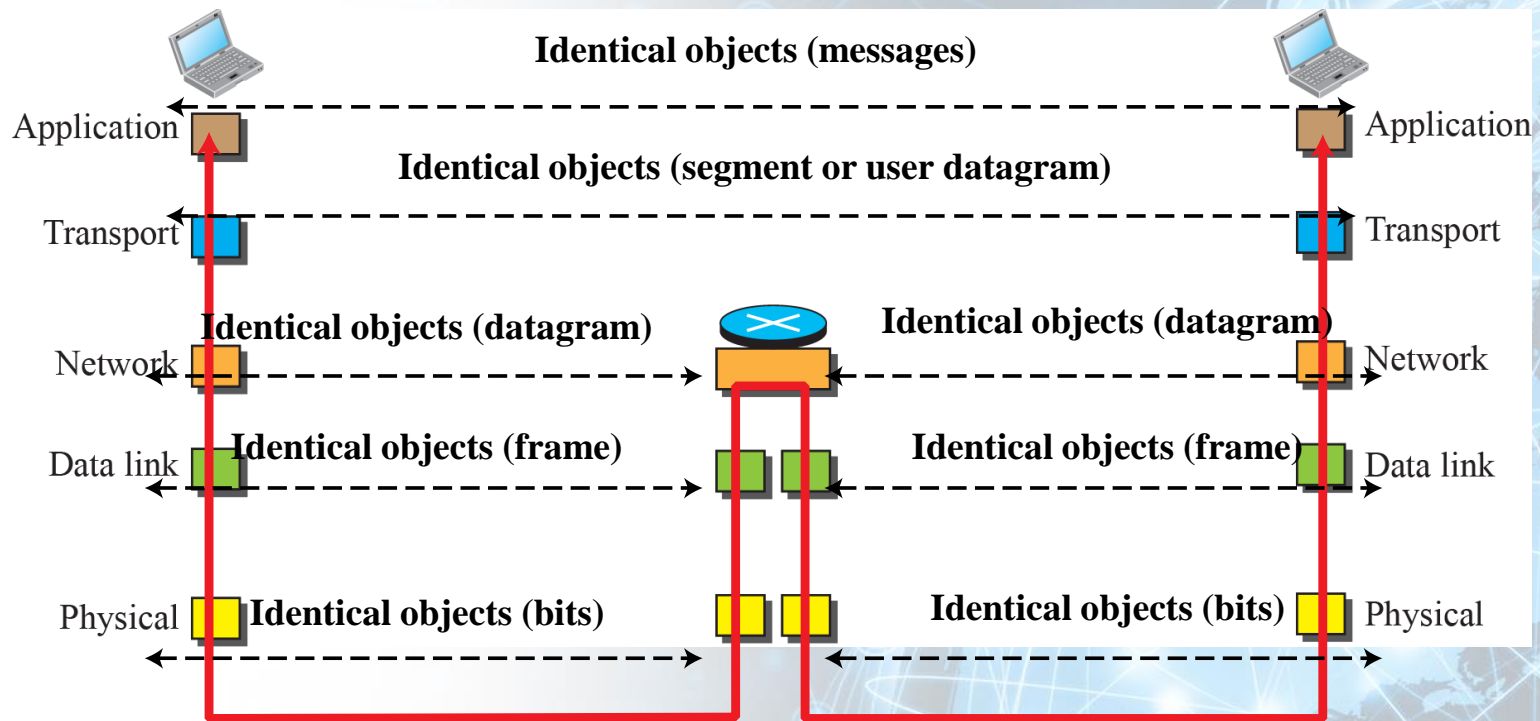
- **Logical Connections between TCP/IP Layers**

TCP/IP Protocol Suite – Function of Layers

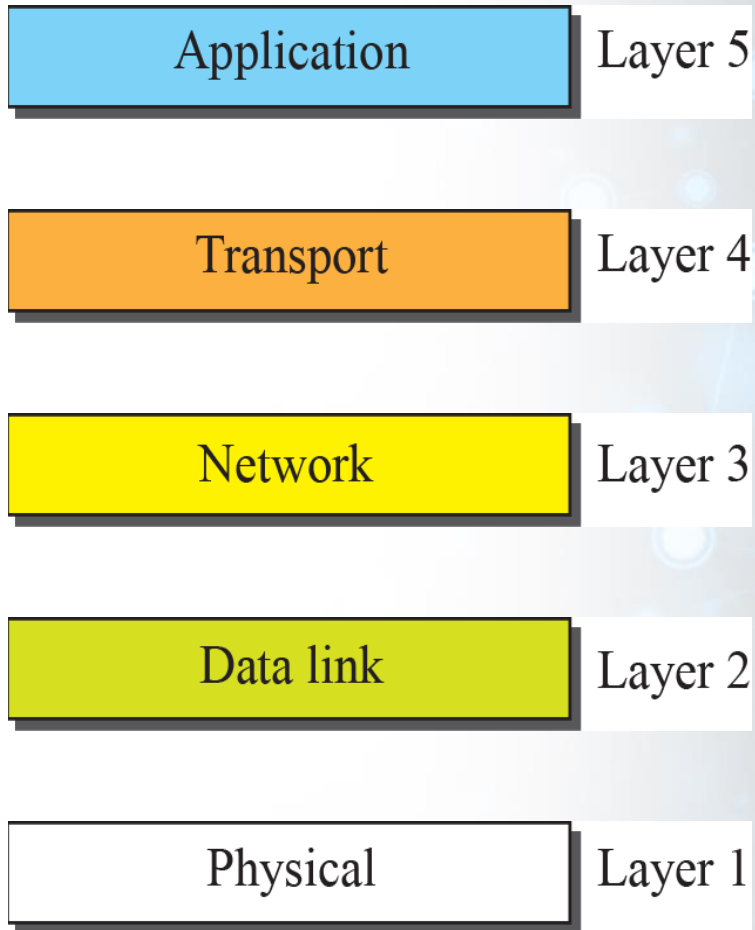


TCP/IP Protocol Suite – Function of Layers

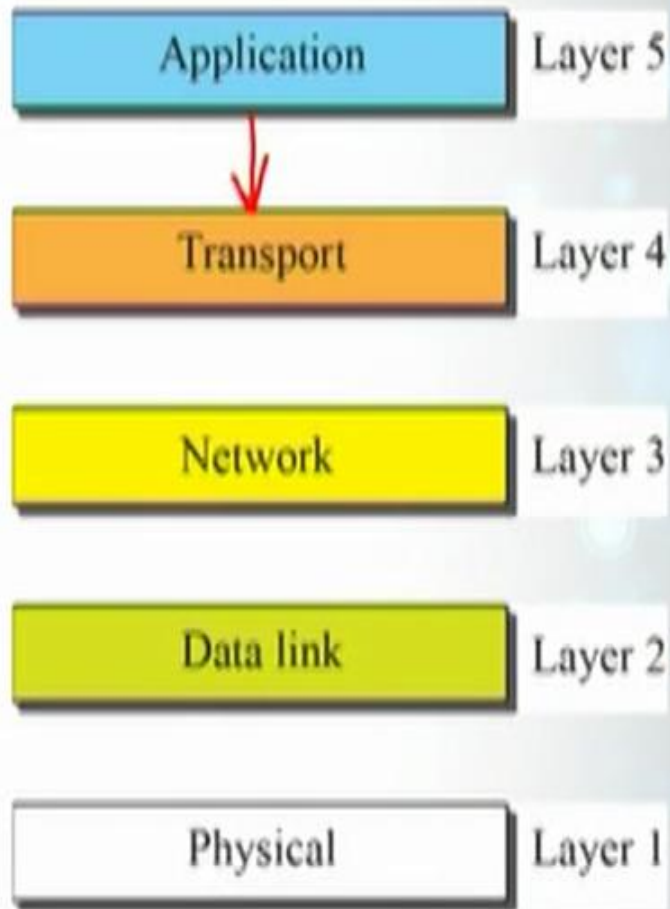
Notes: We have not shown switches because they don't change objects.



TCP/IP Protocol Suite – Layer Description



TCP/IP Protocol Suite – Layer Description



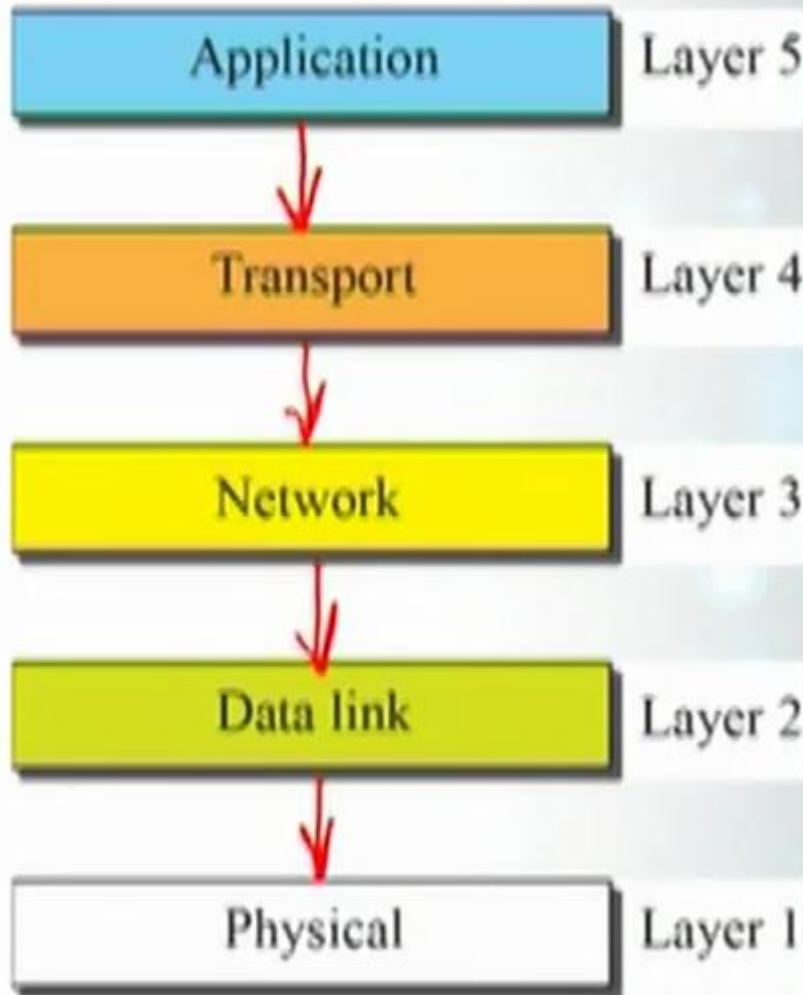
Message (object) HTTP, SMTP, FTP,

Segment (User Datagram) TCP, UDP

Datagram → Routing → IP

Double-click to go to fullscreen, ctrl+c

TCP/IP Protocol Suite – Layer Description



Message (object) HTTP, SMTP

Segment (User Datagram) TCP

Datagram → Routing →

Frame (object) Standard,

Bits (object)



TM

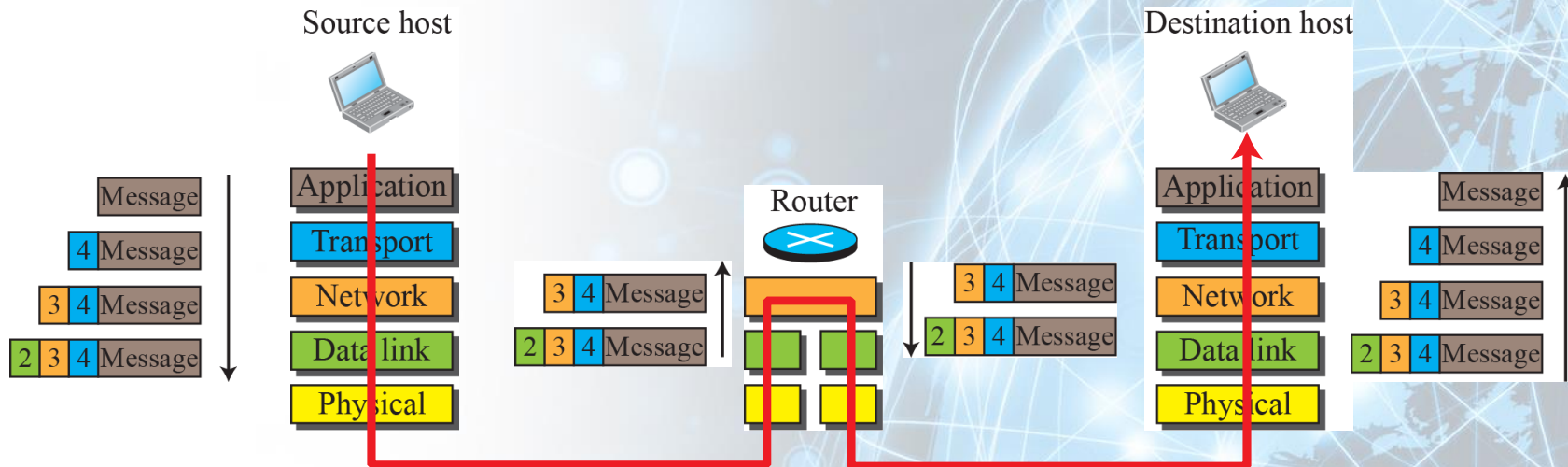
Encapsulation & Decapsulation

- **Important Concept in Internet Protocol Layering**
- **Layer Header**

Encapsulation & Decapsulation

Legend

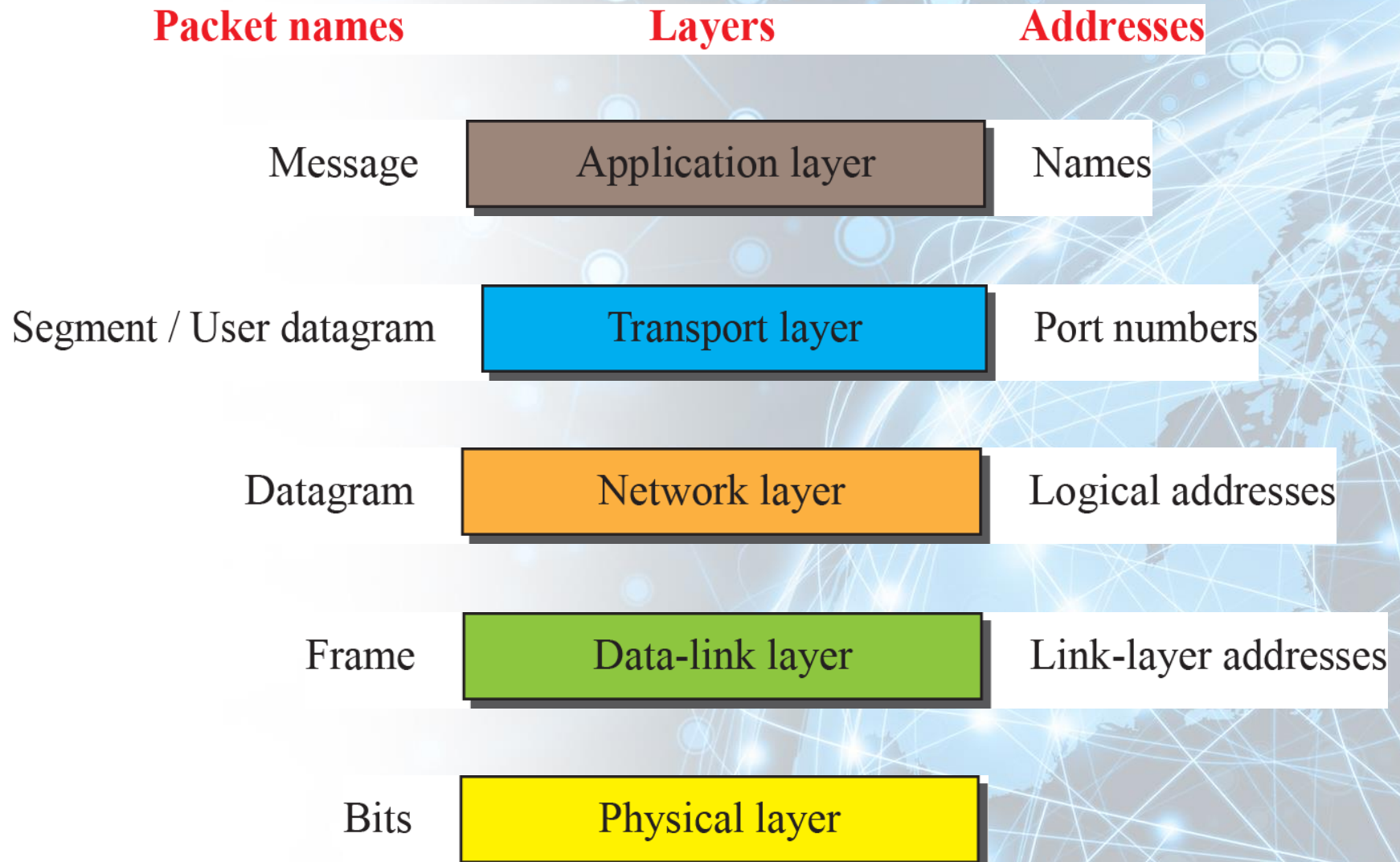
- 4 Header at transport layer ↓ Encapsulate
- 3 Header at network layer ↑ Decapsulate
- 2 Header at data-link layer



Addressing in TCP/IP Protocol Suite

- **Every communication needs at least two addresses:**
 - ✓ **Source Address &**
 - ✓ **Destination Address**
- **Addressing by Layer**
- **Physical Layer is an exception**

Addressing in TCP/IP Protocol Suite



The Open System Interconnection (OSI) Model

- **International Organization for Standardization (ISO)**
- **ISO established in 1947**
- **Close to three-fourths of countries represented**
- **Introduced OSI Model in late 1970s**
- **OSI: a 7-Layer Model**

The Open System Interconnection (OSI) Model

Layer 7

Application

Layer 6

Presentation

Layer 5

Session

Layer 4

Transport

Layer 3

Network

Layer 2

Data link

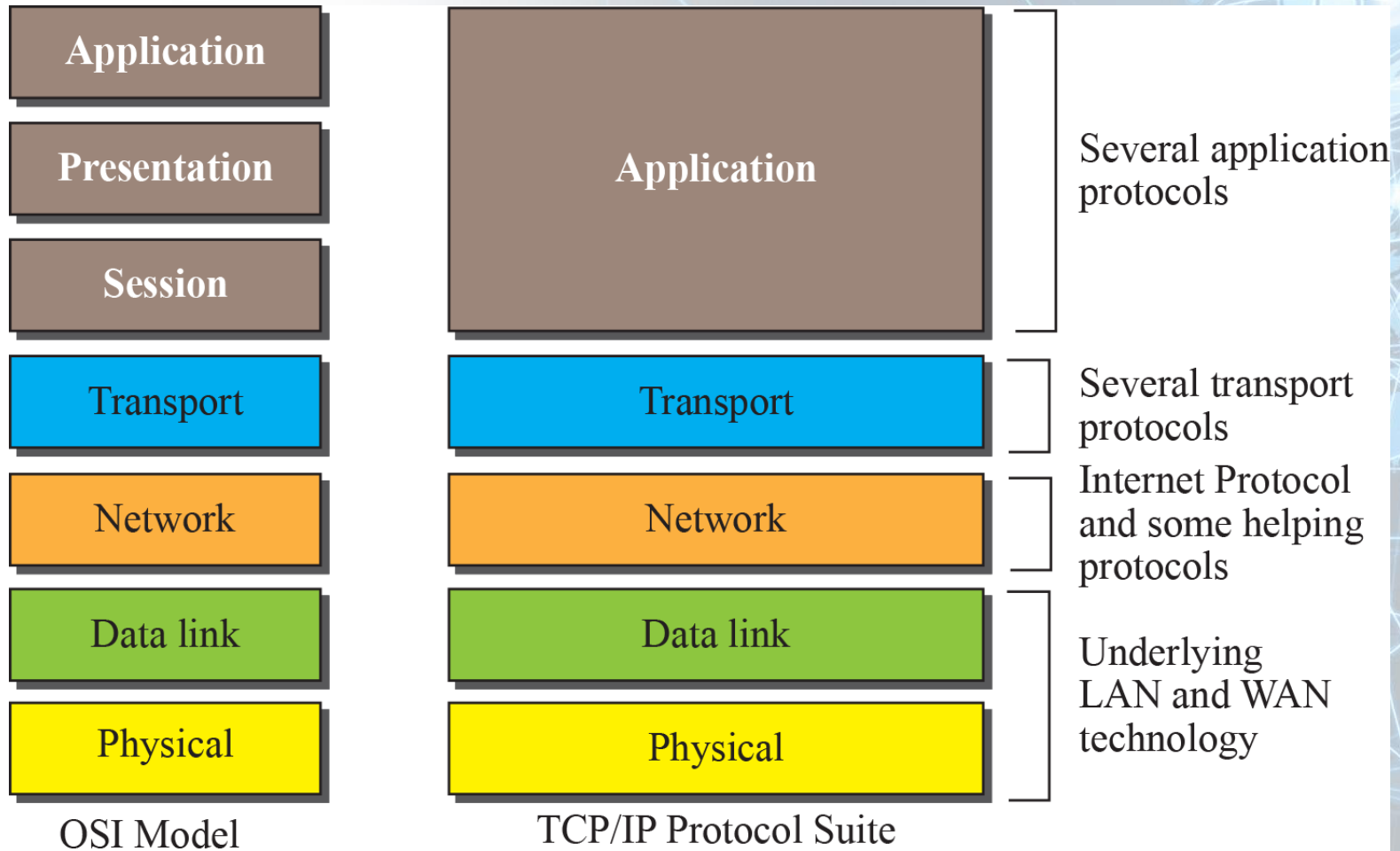
Layer 1

Physical

OSI Model vs TCP/IP Protocol suite

- **Two Layers of OSI missing from TCP/IP**
- **Application (TCP/IP) = Application + Presentation + Session (OSI)**

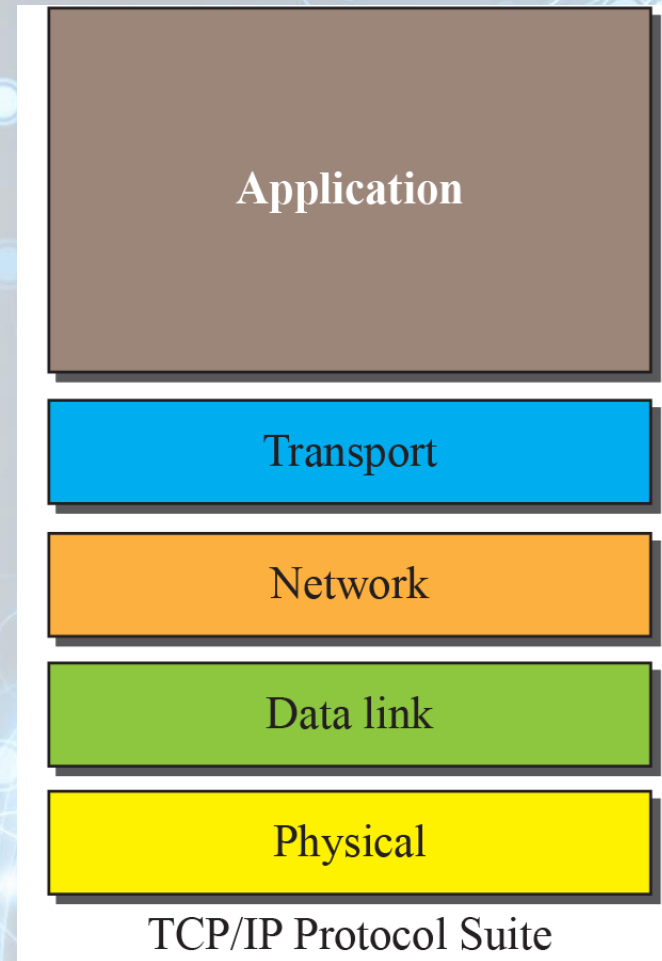
OSI Model vs TCP/IP Protocol suite



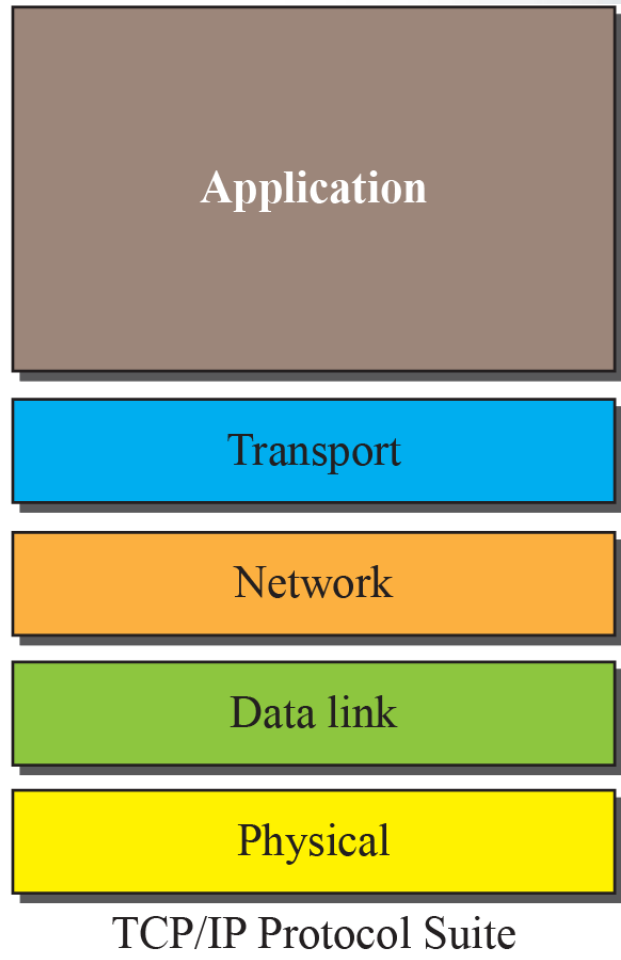
Lack of OSI Model's Success

- **Three reasons OSI did not replace TCP/IP:**
 - ✓ **OSI was completed when TCP/IP was fully in place**
 - ✓ **Some layers in OSI not fully defined**
 - ✓ **Performance of TCP/IP better than that of OSI**

Data Communication versus Computer Networks

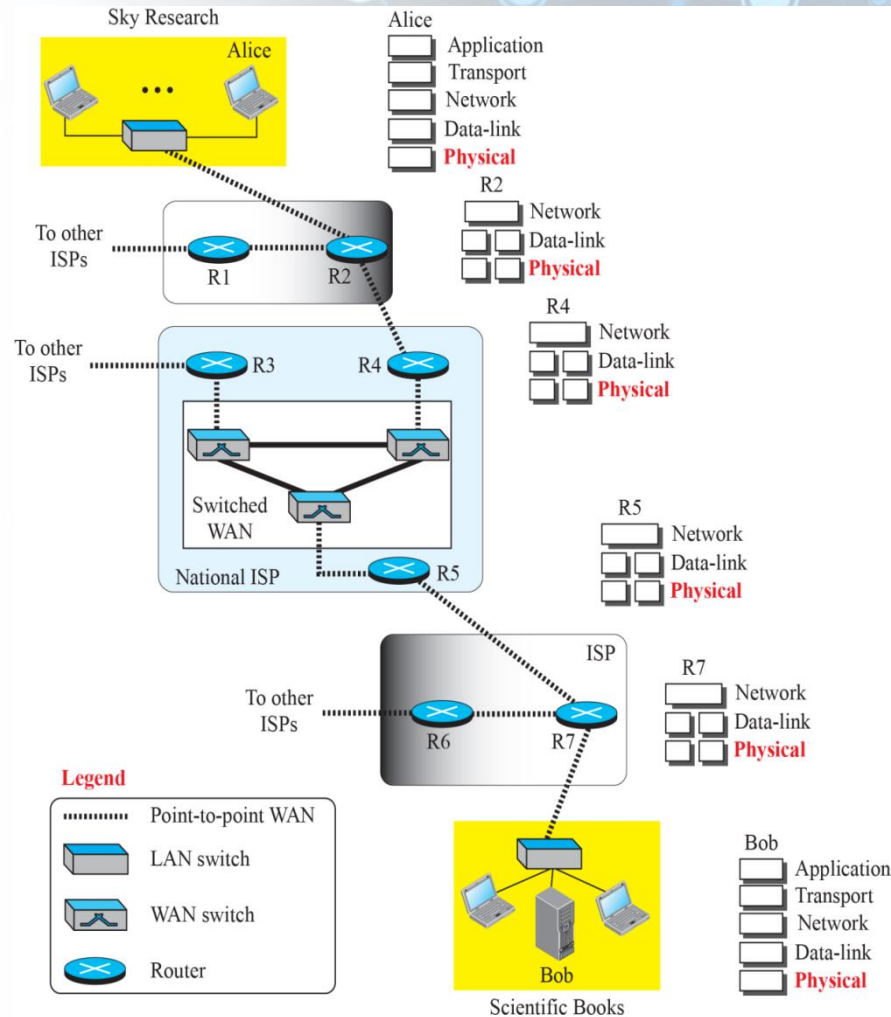


Data Communication versus Computer Networks



- Analog & Digital Transmission
- Transmission Media
- Switching
- Error Detection and Correction
- Media Access and Data Link Control
- Wired and Wireless LANs

Communication at Physical Layer



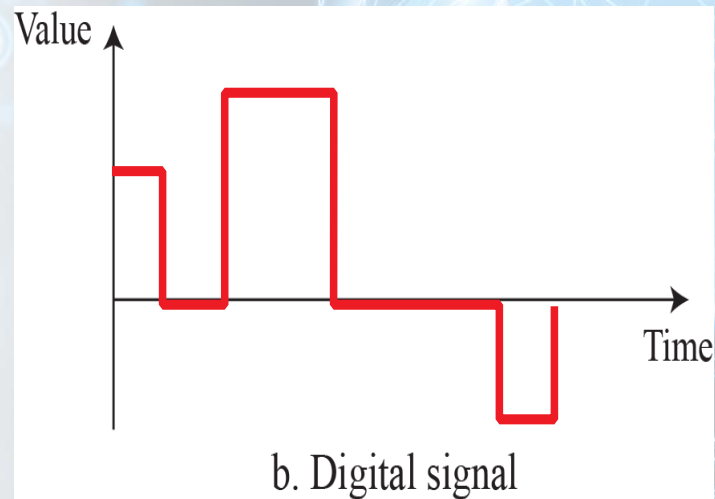
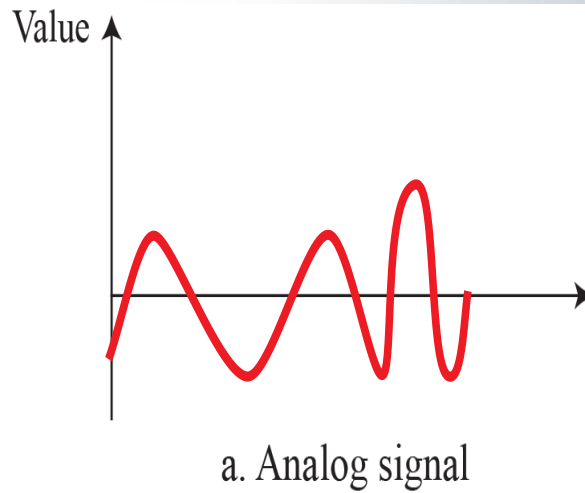
Analog & Digital Data

- **Data → Analog or Digital**
- **Analog Data → Continuous**
- **Digital Data → Discrete**
- **Examples: Analog Clock vs. Digital Clock**
- **Human voice vs. Data in Computer**

Analog & Digital Signals

- **Signals represent Data**
- **Signals → Analog or Digital**
- **Analog Signal → Infinite Levels of Intensity over time**
- **Digital Signal → Limited number of defined values**

Analog & Digital Signals



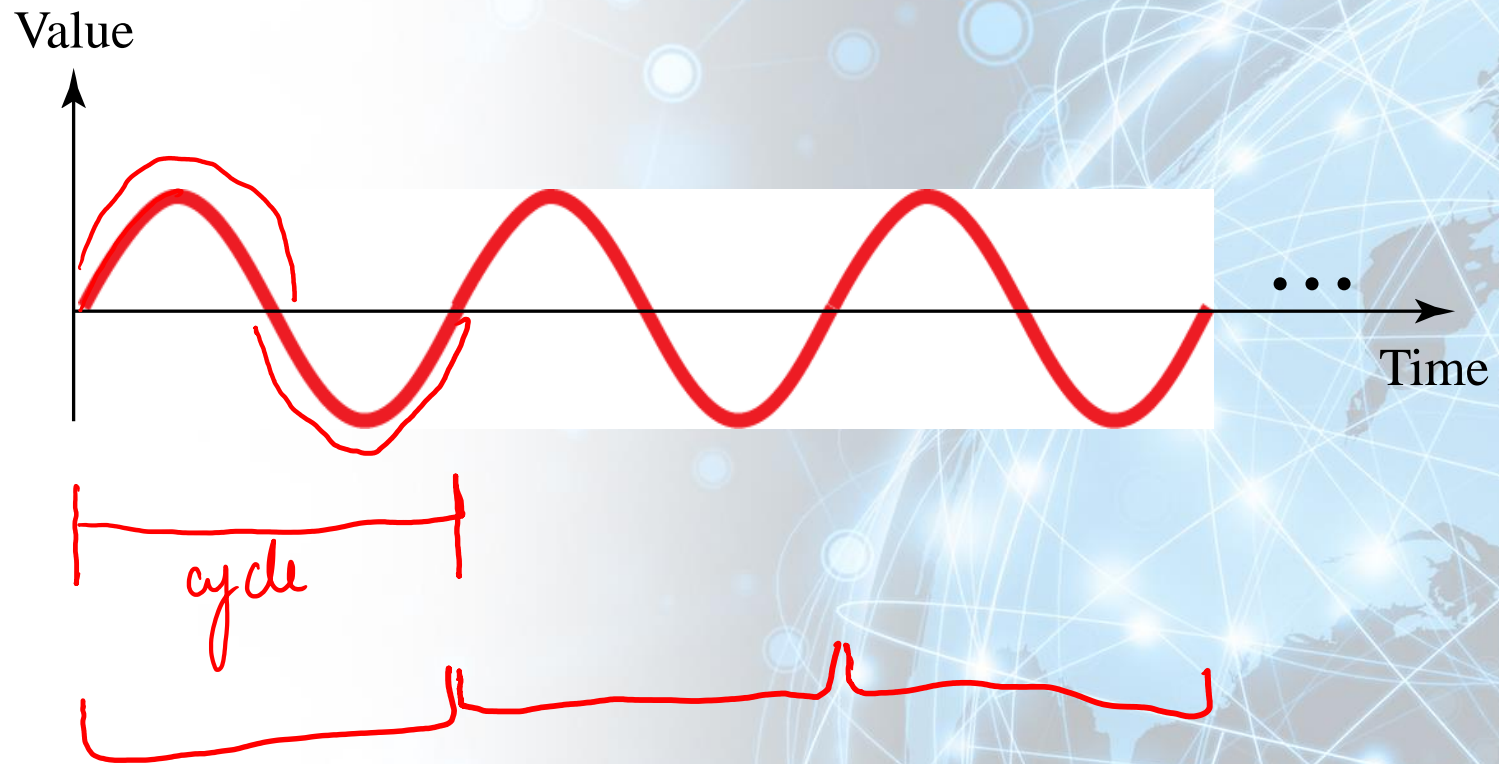
Periodic & Non-periodic Signals

- **Analog/Digital Signal → Periodic or Non-periodic**
- **Periodic Signal → Pattern**
- **Period and Cycle**
- **Non-Periodic → No Pattern**
- **Periodic ANALOG Signals and Non-periodic DIGITAL Signals**

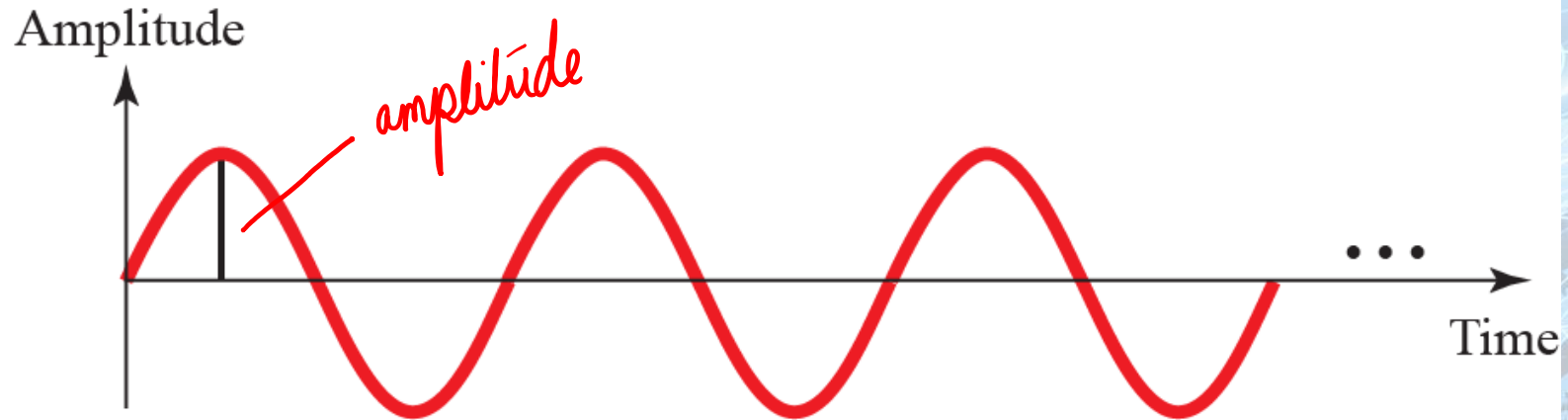
Periodic Analog Signals

- **Periodic Analog Signals**
→ **Simple or Composite**
- **Simple Periodic Analog signal** → **Sine wave**
- **Composite Periodic Analog signal** → **Composed of multiple sine waves**

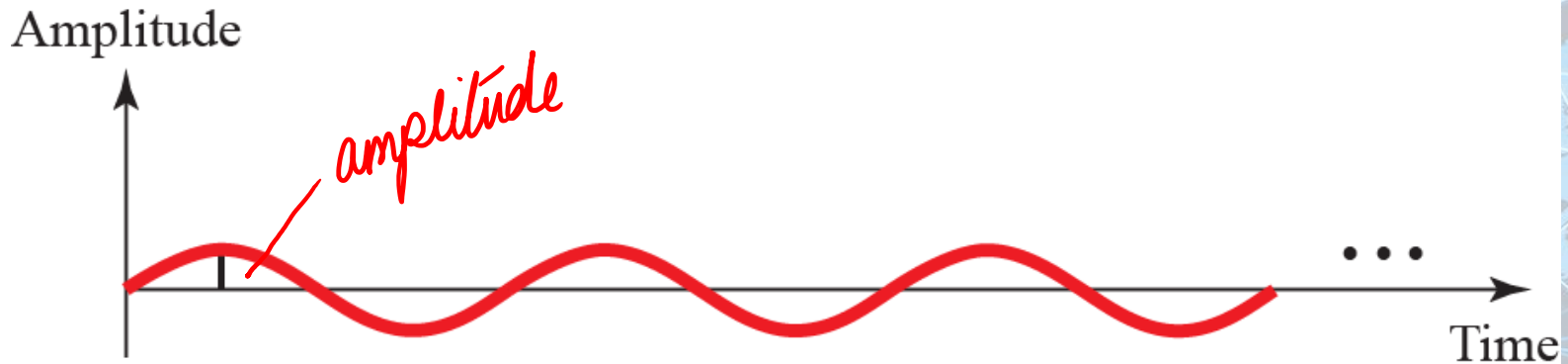
Sine Wave



Sine Wave – Peak Amplitude



a. A signal with high peak amplitude



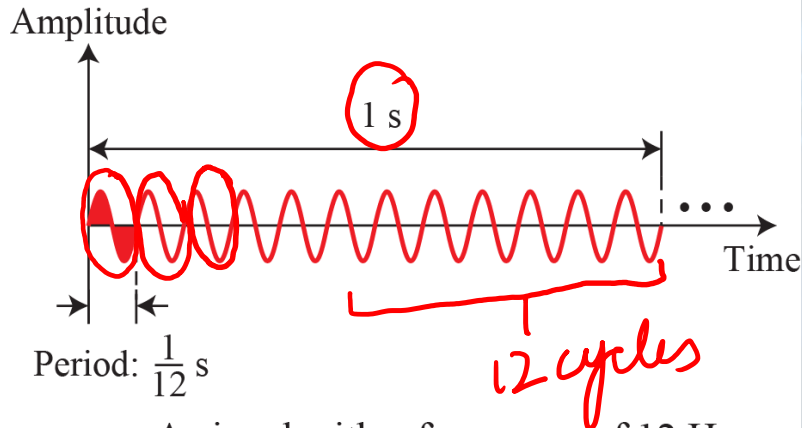
b. A signal with low peak amplitude

Sine Wave –Frequency

- **Period (T) → Amount of time required to complete 1 cycle**
- **Frequency (f) → No. of Periods in 1 sec**
- **$f = 1/T$ or $T = 1/f$**

Sine Wave – Frequency

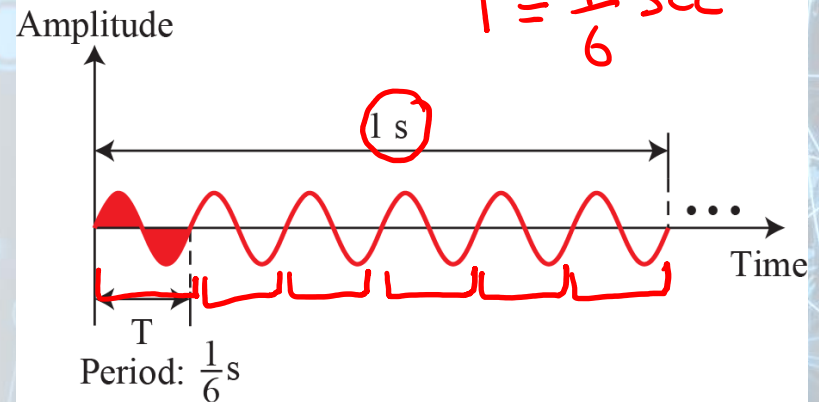
12 periods in 1 s → Frequency is 12 Hz



a. A signal with a frequency of 12 Hz

$$\text{Hz} = \text{cycles/sec}$$
$$T = \frac{1}{f} = \frac{1}{12} \text{ sec}$$

6 periods in 1 s → Frequency is 6 Hz



b. A signal with a frequency of 6 Hz

$$T = \frac{1}{6} \text{ sec}$$

Sine Wave –Frequency

<i>Period</i>		<i>Frequency</i>	
<i>Unit</i>	<i>Equivalent</i>	<i>Unit</i>	<i>Equivalent</i>
Seconds (s) ✓	1 s	Hertz (Hz) ✓	1 Hz
Milliseconds (ms)	10^{-3} s ✓	Kilohertz (kHz)	10^3 Hz ✓
Microseconds (μ s)	10^{-6} s ✓	Megahertz (MHz)	10^6 Hz ✓
Nanoseconds (ns)	10^{-9} s ✓	Gigahertz (GHz)	10^9 Hz ✓
Picoseconds (ps)	10^{-12} s ✓	Terahertz (THz)	10^{12} Hz ✓

Example

The power we use at home has a frequency of 60 Hz. The period of this sine wave can be determined as follows:

$$T = \frac{1}{f} = \frac{1}{60} = 0.0166 \text{ sec} \\ = 16.6 \text{ msec}$$

Example

The period of a signal is 100 ms. What is its frequency in kilohertz?.

$$T = 100 \text{ ms} \Rightarrow 100 \times 10^{-3} \text{ Sec} = 10^{-1} \text{ Sec}$$

$$f = \frac{1}{T} = \frac{1}{10^{-1}} = 10 \text{ Hz}$$

$$10 \times 10^{-3} \text{ kHz}$$

$$= 10^{-2} \text{ kHz}$$

Phase (or Phase Shift)

- **Position of waveform relative to time 0**
- **Phase describes the amount of shift of the wave**
- **Indicates start of the first cycle**

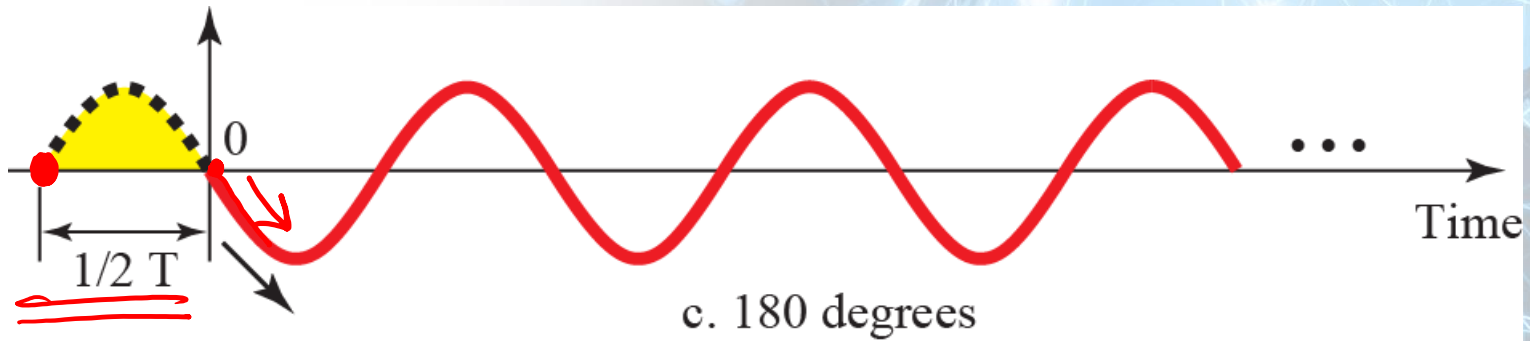
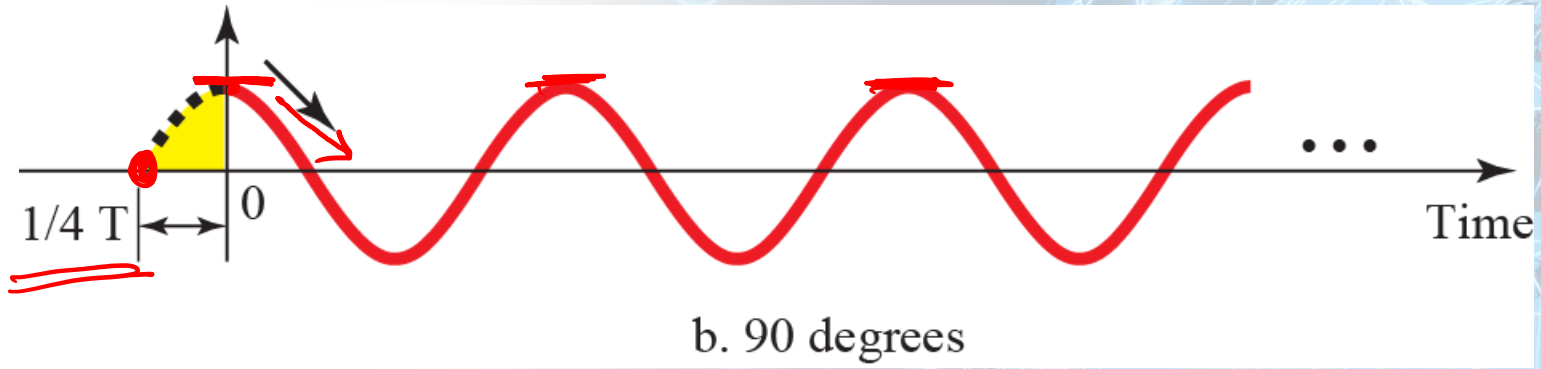
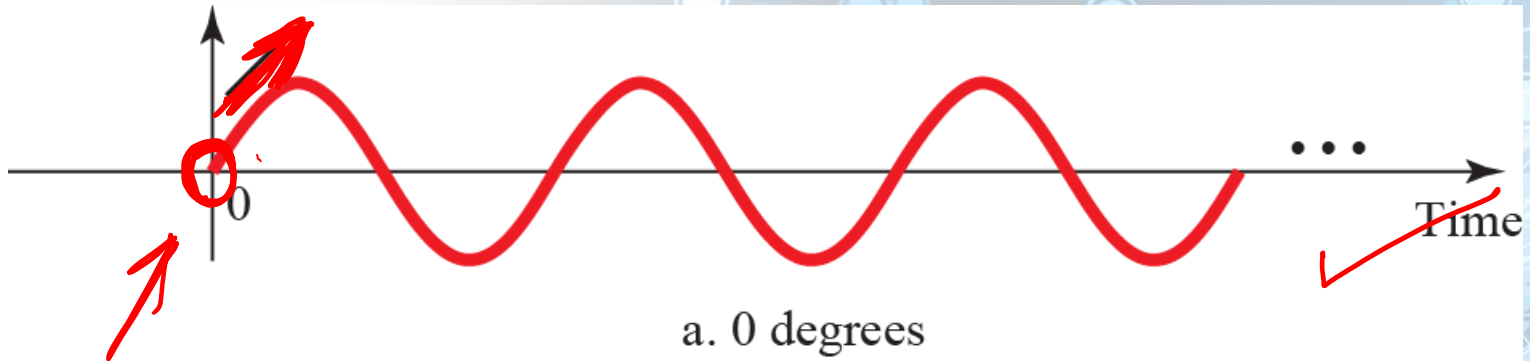
Phase

$$360^\circ = 2\pi \text{ radians}$$

$$1^\circ = \frac{2\pi}{360} \text{ rad}$$



Phase



Example

A sine wave is offset $1/6$ cycle with respect to time 0. What is its phase in degrees and radians?

$$\frac{1}{6} \times 360^\circ = \underline{\underline{60^\circ}}$$

$$60 \times \frac{2\pi}{360} = 1.046 \text{ rad}$$

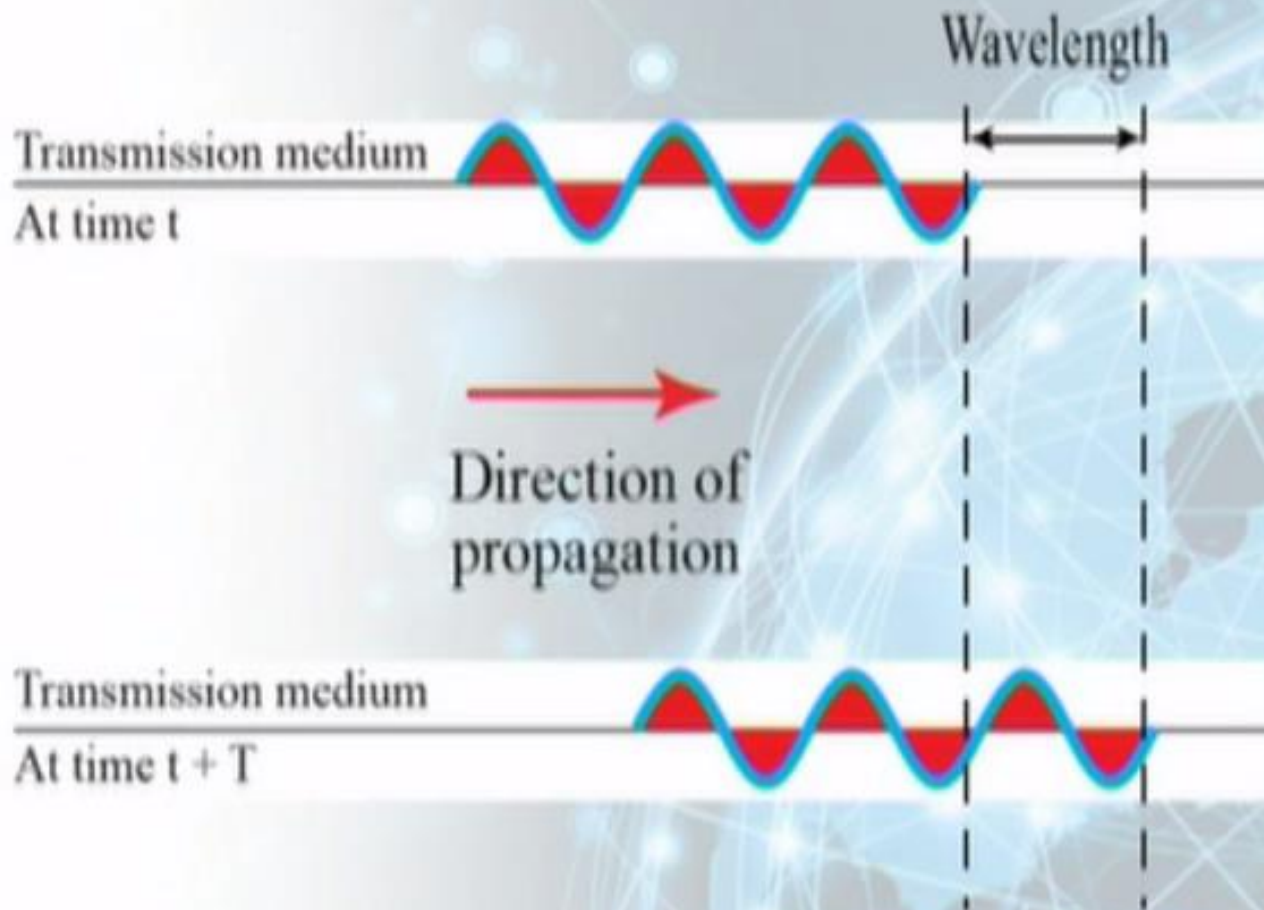
$$1^\circ = \frac{2\pi}{360} \text{ rad}$$

Wavelength

Wavelength is another characteristic of a signal traveling through a transmission medium. Wavelength binds the period or the frequency of a simple sine wave to the propagation speed of the medium (see Figure 3.7).

Wavelength

Figure 3.7



Wavelength

Prop. Speed = c = Light (speed)

frequency = f

Wavelength = λ

$$\lambda = \frac{c}{f} = \frac{3 \times 10^8 \text{ m/sec}}{f}$$

$$\lambda = \frac{3 \times 10^8}{4 \times 10^{14}}$$



Wavelength

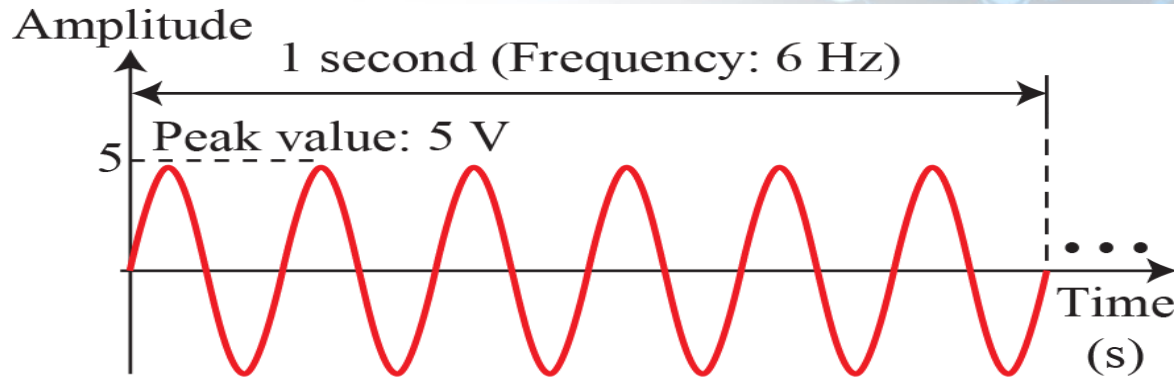
$$\begin{aligned}\lambda &= 0.75 \times 10^{-6} \text{ m} \\ &= 0.75 \mu\text{m} \\ &= \underline{\underline{\quad}}\end{aligned}$$



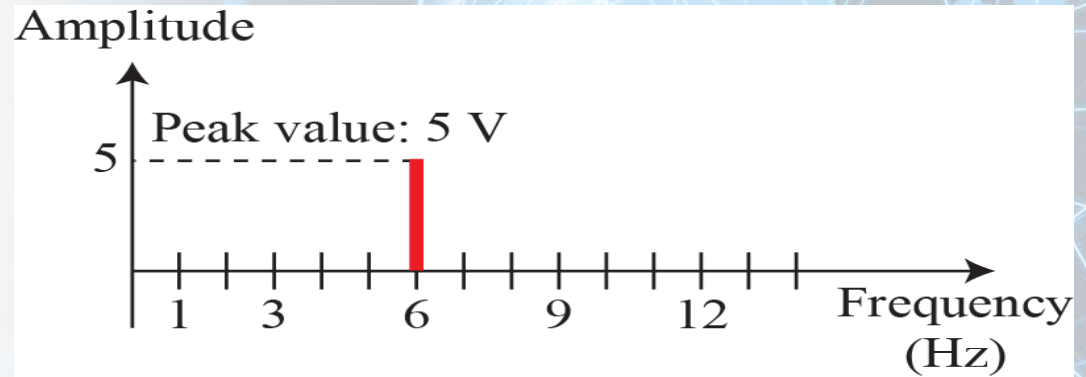
Time & Frequency Domains

A sine wave is comprehensively defined by its amplitude, frequency, and phase. We have been showing a sine wave by using what is called a time domain plot. The time-domain plot shows changes in signal amplitude with respect to time (it is an amplitude-versus-time plot). Phase is not explicitly shown on a time-domain plot.

Time & Frequency Domains



a. A sine wave in the time domain



b. The same sine wave in the frequency domain

Example 3.7

The frequency domain is more compact and useful when we are dealing with more than one sine wave. For example, Figure 3.9 shows three sine waves, each with different amplitude and frequency. All can be represented by three spikes in the frequency domain.

Time & Frequency Domains

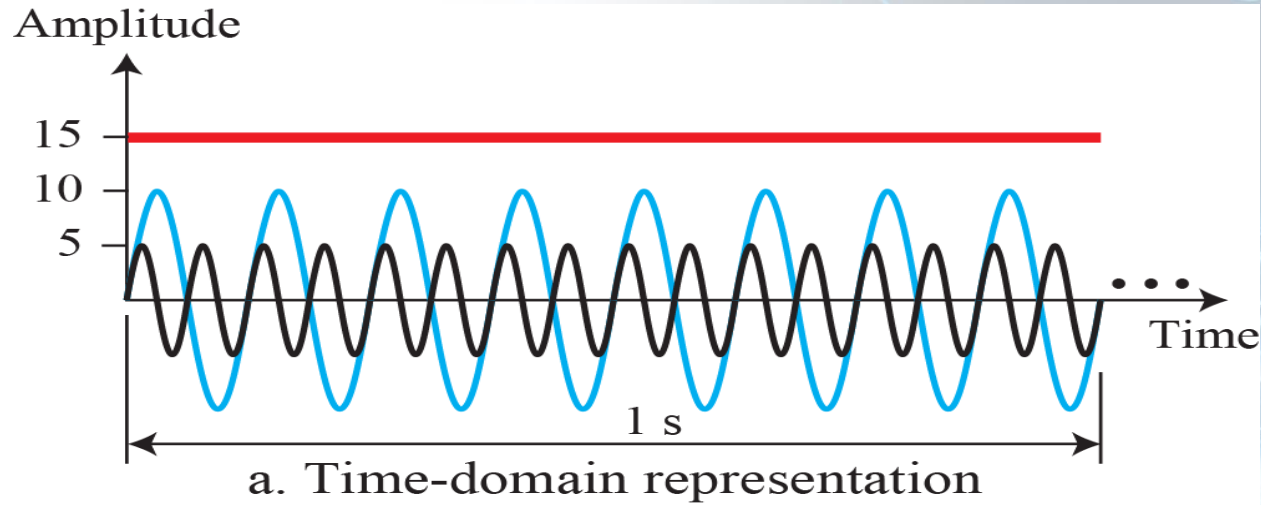


Figure 3.9



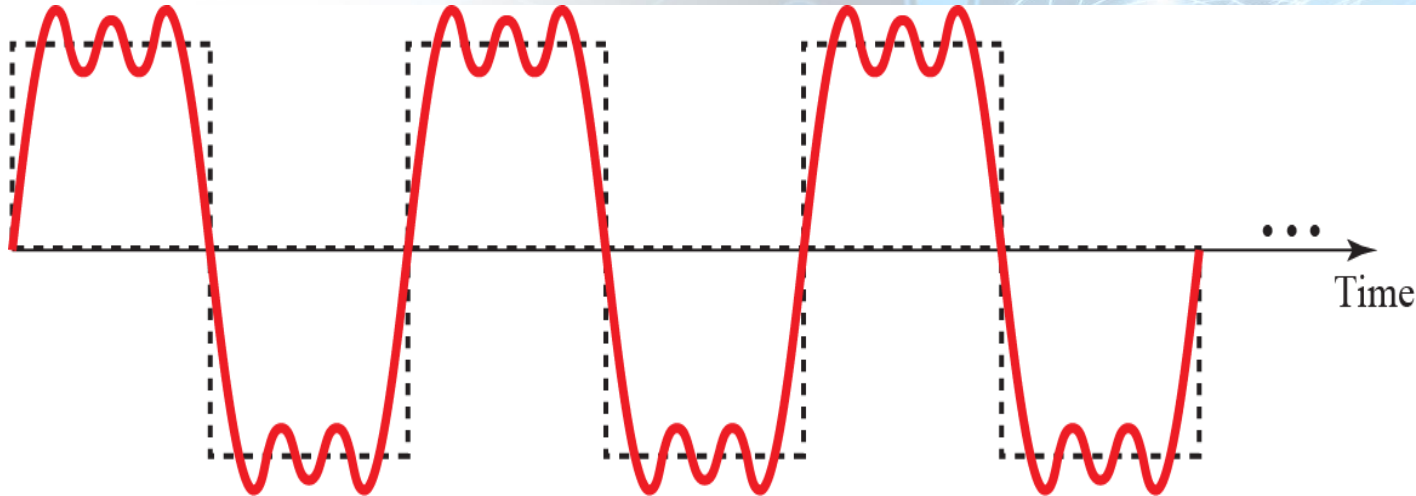
Composite Signals

So far, we have focused on simple sine waves. Simple sine waves have many applications in daily life. We can send a single sine wave to carry electric energy from one place to another. For example, the power company sends a single sine wave with a frequency of 60 Hz to distribute electric energy to houses and businesses.

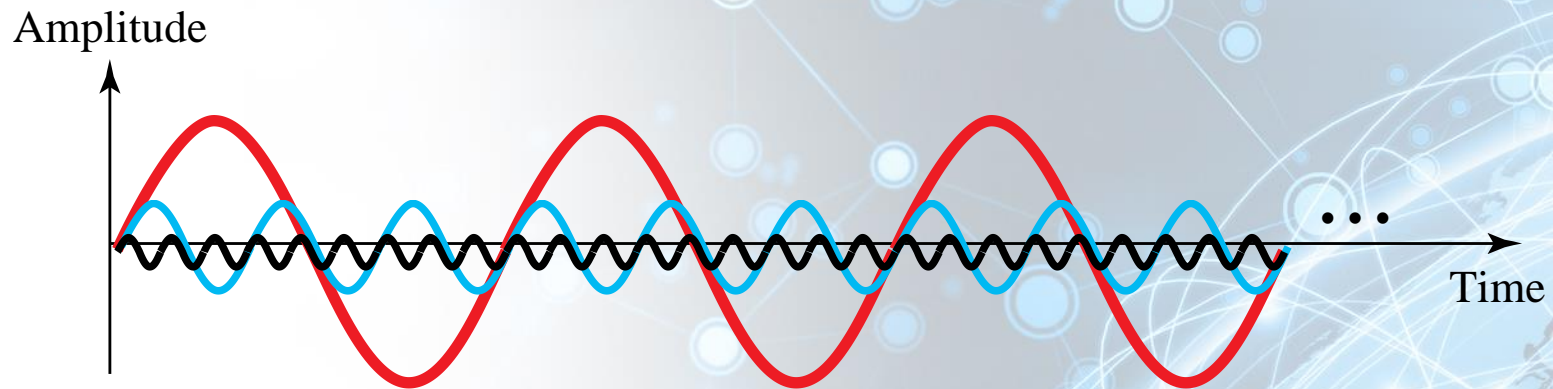
Composite Signals

- **Single Sine Wave can only carry limited information**
- **Composite Signal is made up of multiple simple sine waves**
- **Can be periodic or non-periodic**

A Composite Periodic Signal



Decomposition of Composite Periodic Signal

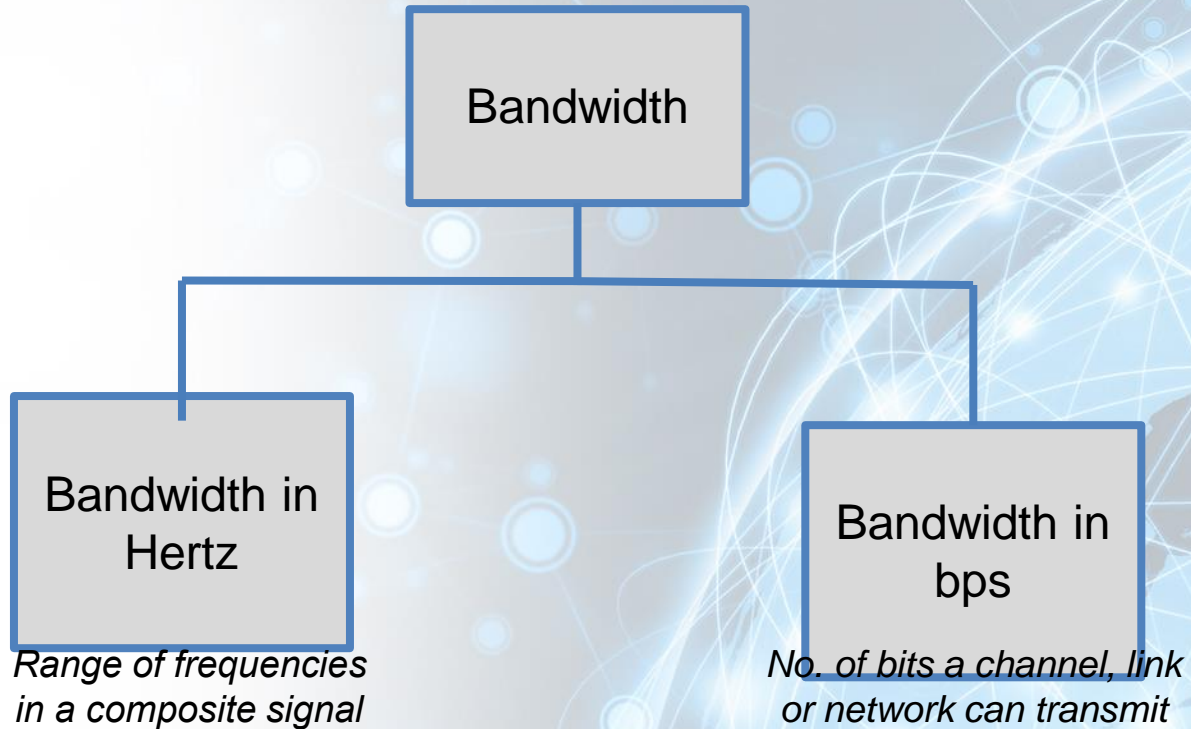


b. Frequency-domain decomposition of the composite signal

Bandwidth

- **An important characteristic that measures Network Performance**
- **Bandwidth can be used in two different contexts with two different measuring values:**
 - **Bandwidth in Hertz**
 - **Bandwidth in bits per second**

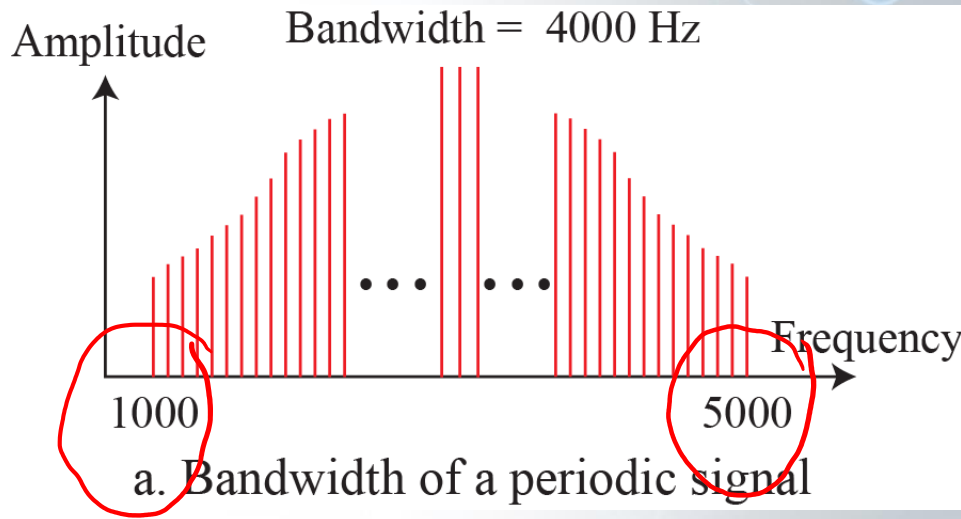
Bandwidth



Bandwidth

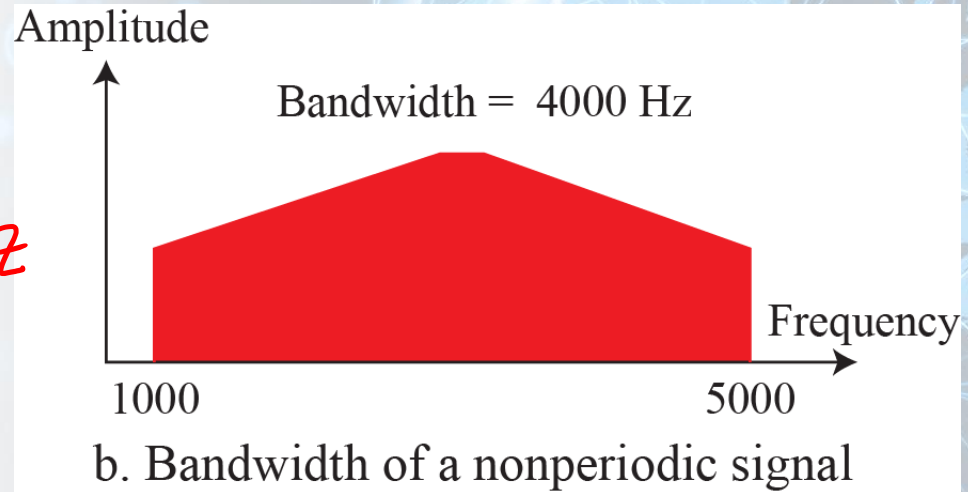
- **Range of frequencies contained in a Composite Signal**
- **The bandwidth is normally a difference between two frequencies (the highest and the lowest)**

Bandwidth of a composite signal



$$B = f_h - f_l$$
$$= 5000 - 1000$$
$$= 4000 \text{ Hz}$$

$$5000 - 1000$$
$$B = 4000 \text{ Hz}$$

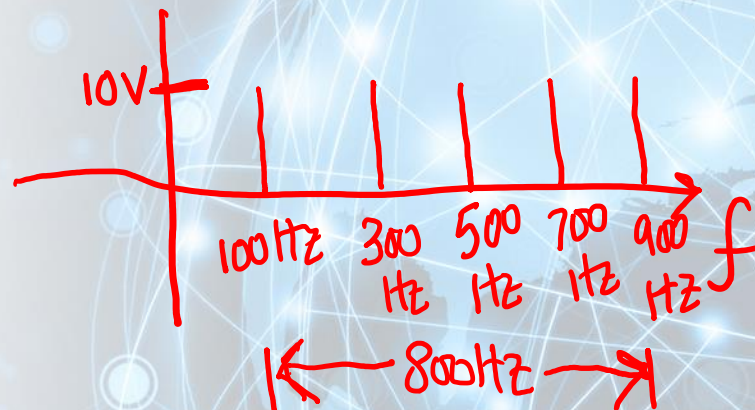


Example

If a periodic signal is decomposed into five sine waves with frequencies of 100, 300, 500, 700, and 900 Hz, what is its bandwidth? Draw the spectrum, assuming all components have a maximum amplitude of 10 V.

$$B = f_h - f_l$$
$$= 900 - 100$$

$$\underline{B = 800 \text{ Hz}}$$



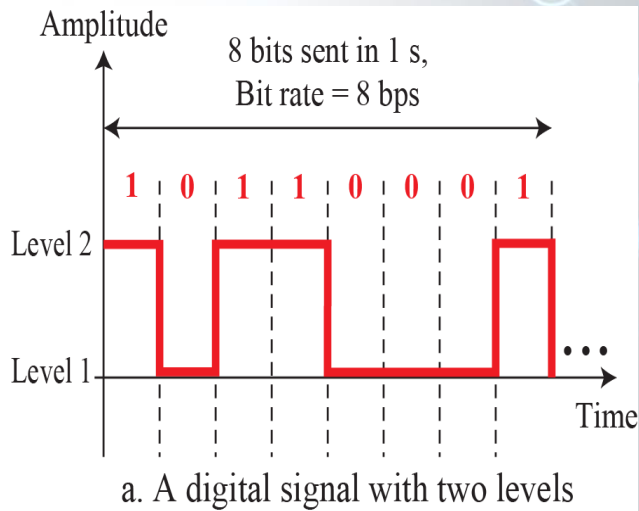
Digital Signals

In addition to being represented by an analog signal, information can also be represented by a digital signal. For example, a 1 can be encoded as a positive voltage and a 0 as zero voltage. A digital signal can have more than two levels.

Digital Signals

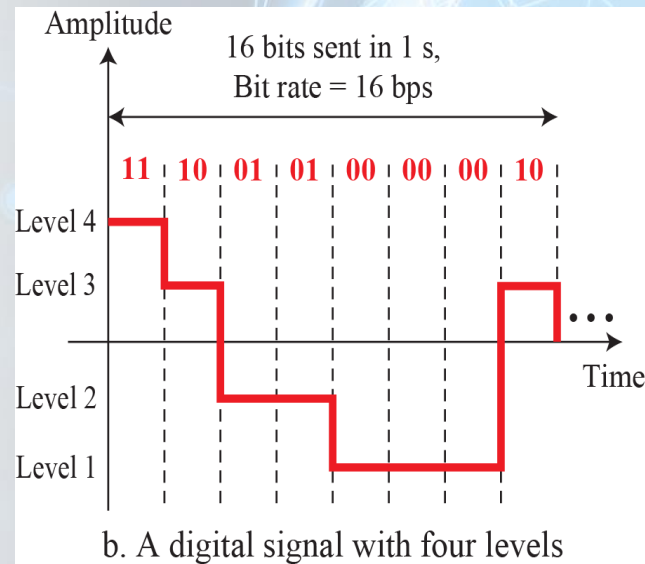
- Information can also be represented by a digital signal
- For example, a 1 can be encoded as a positive voltage and a 0 as zero voltage
- A digital signal can have more than two levels so that we can send more than one bit for each level

Digital Signals



In general, if a signal has L levels, each level needs $\log_2 L$ bits. So, we can send $\log_2 2 = 1$ bit per level

$$\log_2 4 = 2 \text{ bits}$$



Digital Signals

In this case, we can send more than 1 bit for each level. Figure 3.17 shows two signals, one with two levels and the other with four.

Example 3.16

A digital signal has eight levels. How many bits are needed per level?

We calculate the number of bits from the following formula. Each

Number of bits per level

bits. = $\log_2 8 = 3$

Example

A digital signal has eight levels. How many bits are needed per symbol?

$$\begin{aligned}\text{No of bits} &= \log_2 L \\ &= \log_2 8 \\ &= 3 \text{ bits}\end{aligned}$$

Example 3.17

A digital signal has nine levels. How many bits are needed per level? We calculate the number of bits by using the formula. Each signal level is represented by 3.17 bits. However, this answer is not realistic. The number of bits sent per level needs to be an integer as well as a power of 2. For this example, 4 bits can represent one level.

Example

A digital signal has nine levels. How many bits are needed per level? We calculate the number of bits by using the formula.

$\log_2 L = \log_2 9 = 3.17 \text{ bits}$

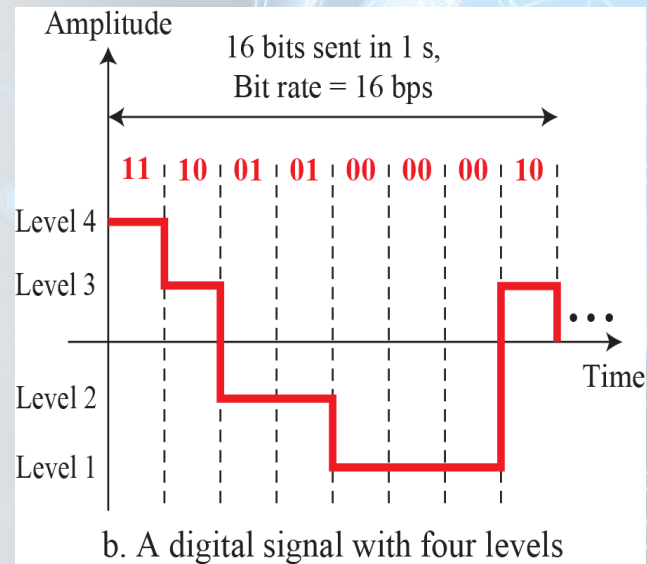
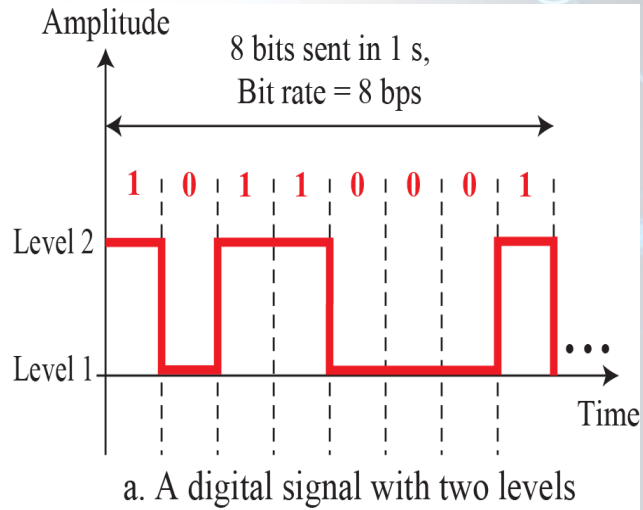
integer power of 2

4 bits

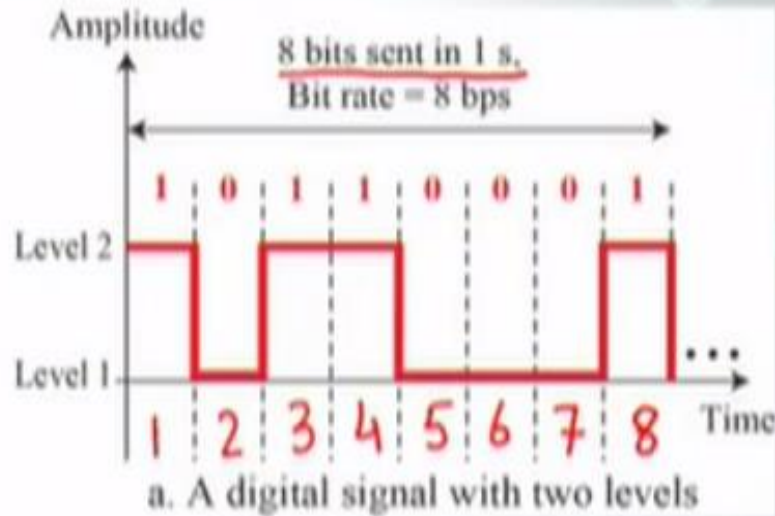
Bit Rate

- **Number of bits sent in 1 second**
- **Bit Rate is expressed in bits per second (bps)**
- **Most digital signals are non-periodic, and thus period and frequency are not appropriate characteristics**

Bit Rate

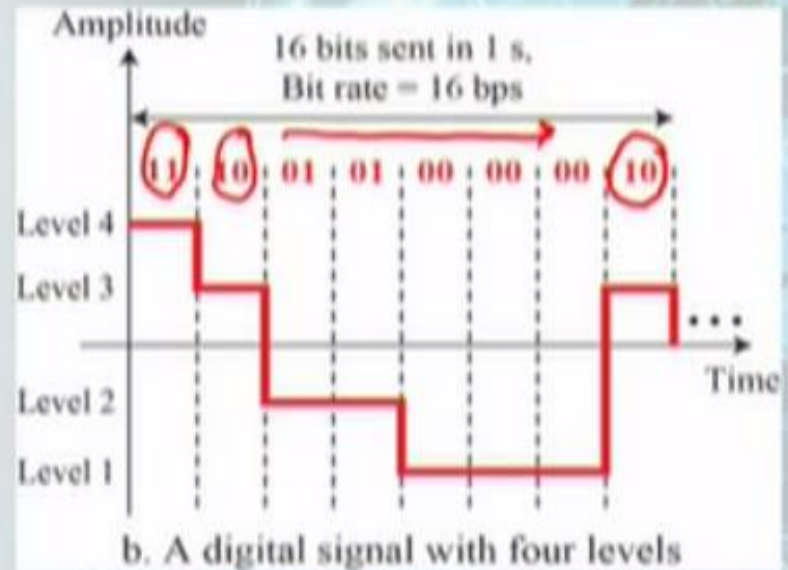


Bit Rate



Bit Rate = 8 bps

BR = 1



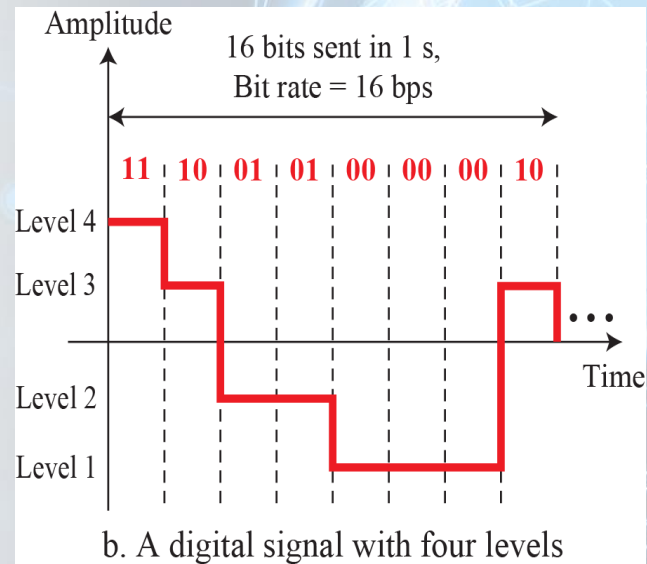
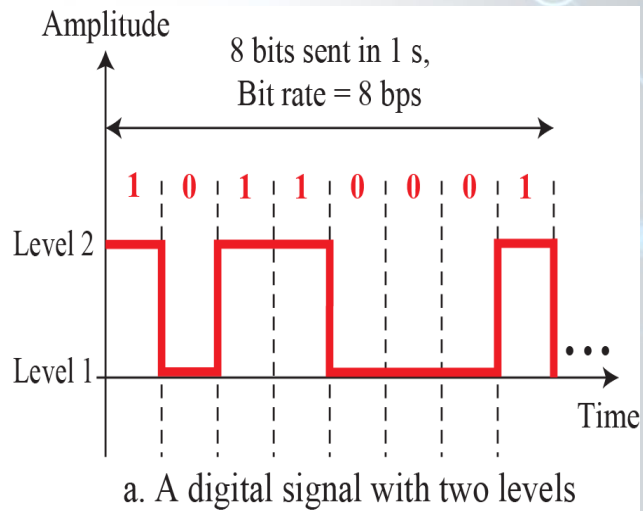
Bit Rate

Most digital signals are nonperiodic, and thus period and frequency are not appropriate characteristics. Another term—bit rate (instead of frequency)—is used to describe digital signals. The bit rate is the number of bits sent in 1s, expressed in bits per second (bps). Figure 3.17 shows the bit rate for two signals.

Bit Rate

- **Number of bits sent in 1 second**
- **Bit Rate is expressed in bits per second (bps)**
- **Most digital signals are non-periodic, and thus period and frequency are not appropriate characteristics**

Bit Rate



Example

Assume we need to download text documents at the rate of 100 pages per second. What is the required bit rate of the

$$1 \text{ page} = 24 \text{ lines}$$

$$1 \text{ line} = 80 \text{ characters}$$

$$1 \text{ ch} = 8 \text{ bits}$$

$$\text{Bit Rate} = 100 \times 24 \times 80 \times 8$$

$$= \underline{\underline{1.536 \text{ Mbps}}}$$

Example 3.18

Solution

From Table 3.1 we find the equivalents of 1 ms (1 ms is 10^{-3} s) and 1 s (1 s is $10^6 \mu\text{s}$).

We make the

$$100 \times 24 \times 80 \times 8 = 1,536,000 \text{ bps}$$

$$\text{subst} = 1.536 \text{ Mbps ;}$$

Example

A digitized voice channel is made by digitizing a 4-kHz bandwidth analog voice signal. We need to sample the signal at twice the highest frequency (two samples per hertz). We assume that each sample requires 8 bits. What is the required bit rate?

$$\begin{aligned} &2 \times 4000 \times 8 \\ &= \underline{\underline{64 \text{ kbps}}} \\ &\quad (64,000 \text{ bps}) \end{aligned}$$

Example 3.19

Solution

A page is an average of 24 lines with 80 characters in each line. If we assume that one character requires

$$2 \times 4000 \times 8 = 64,000 \text{ bps}$$

$$= 64 \text{ kbps}$$

Example 3.20

What is the bit rate for high-definition TV (HDTV)?

Solution

HDTV uses digital signals to broadcast high quality video signals. The HDTV screen is normally a ratio of 16 : 9 (in contrast to 4 : 3 for regular TV), which means the screen is wider. There are 1920 by 1080 pixels per screen, and the screen is renewed 30 times per second.

Example 3.20

Solution

Twenty-four bits represents one color pixel. We can calculate the bit rate

$$\begin{aligned} & 1920 \times 1080 \times 30 \times 24 \\ & = 1,492,992,000 \approx 1.5 \text{ Gbps} \end{aligned}$$

The TV stations reduce this rate to 20 to 40 Mbps through compression.

Bit Length

We discussed the concept of the wavelength for an analog signal: the distance one cycle occupies on the transmission medium. We can define something similar for a digital signal: the bit length. The bit length is the distance one bit occupies on the transmission medium.

$$\text{Bit length} = \text{propagation speed} \times \text{bit duration}$$

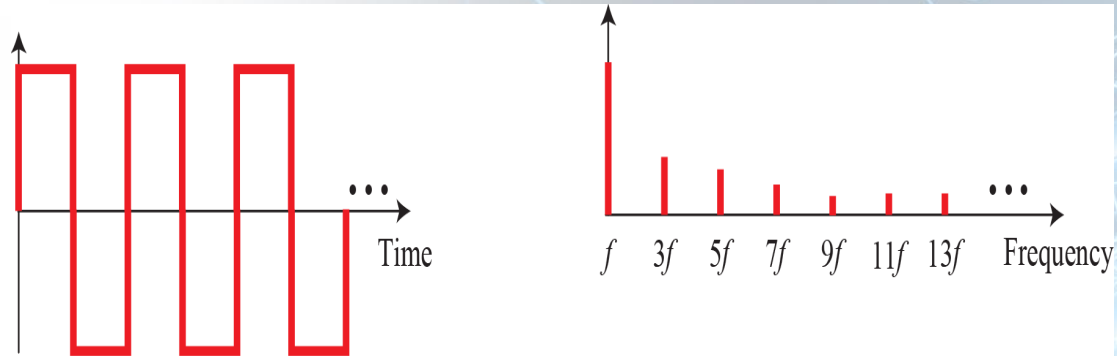
Digital Signal as Composite Analog Signal

- Based on Fourier analysis, a digital signal is a composite analog signal
- A digital signal, in the time domain, comprises connected vertical and horizontal line segments
- Infinite Bandwidth

Digital As Composite Analog

A vertical line in the time domain means a frequency of infinity: a horizontal line in the time domain means a frequency of zero. Going from a frequency of zero to a frequency of infinity implies all frequencies in between are part of the domain.

Digital Signal as Composite Analog Signal



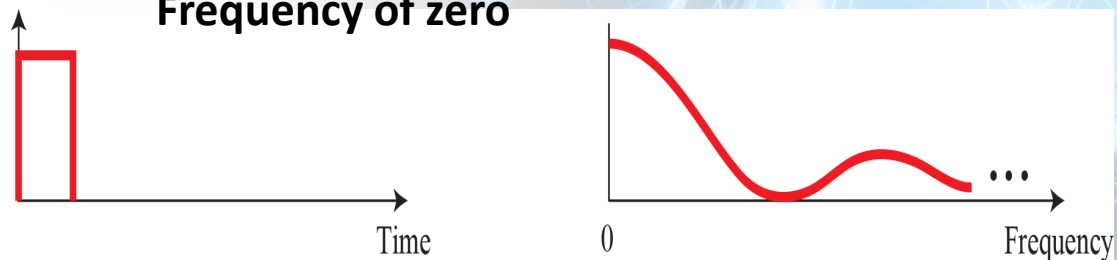
a. Time and frequency domains of periodic digital signal

Vertical line in the time domain:

Frequency of infinity

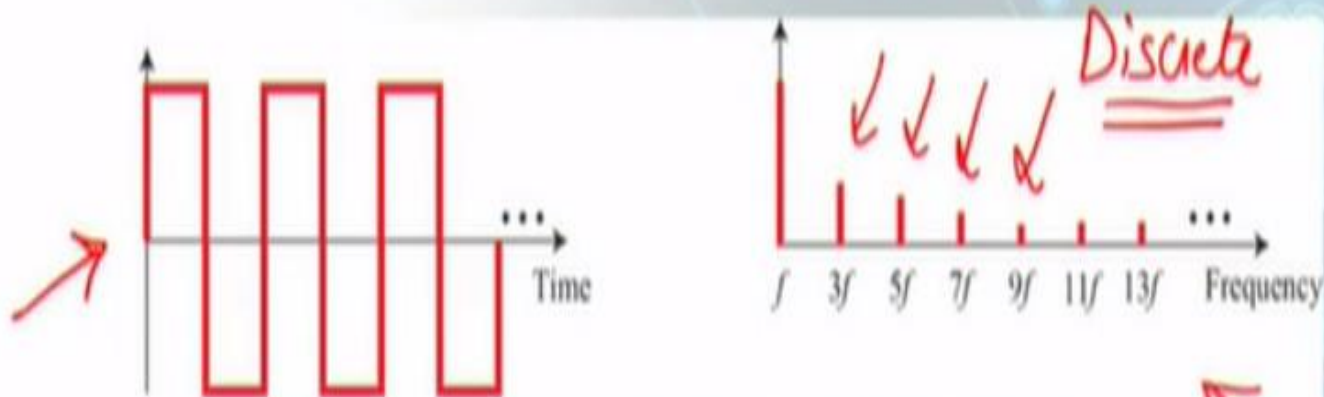
Horizontal line in the time domain:

Frequency of zero



b. Time and frequency domains of nonperiodic digital signal

Digital Signal as Composite Analog Signal



a. Time and frequency domains of periodic digital signal

→ Vertical line in the time domain: Frequency of infinity
→ Horizontal line in the time domain: Frequency of zero

$f = \frac{1}{T}$

for f_0



b. Time and frequency domains of nonperiodic digital signal



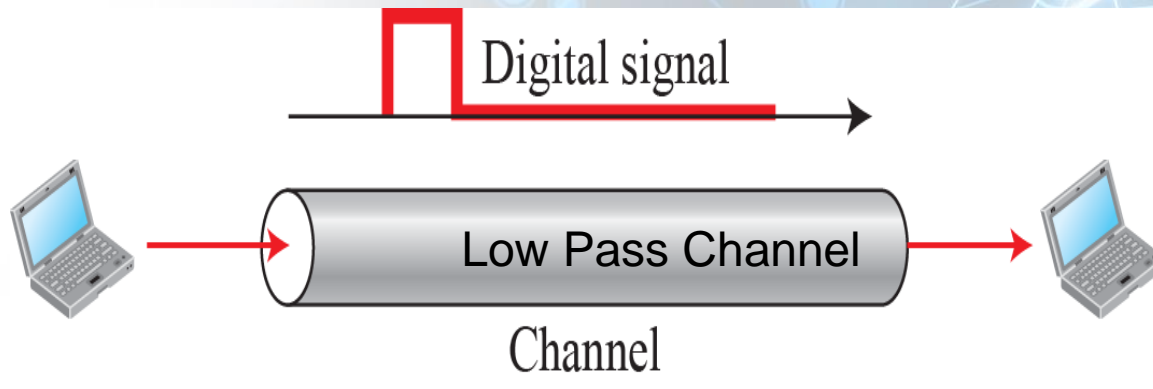
Transmission of Digital Signals

- **Digital signal, periodic or non-periodic, is a composite analog signal with frequencies between zero and infinity (Infinite Bandwidth)**
- **Two approaches for transmission:**
 - ✓ **Baseband Transmission**
 - ✓ **Broadband Transmission**

Transmission of Digital Signals

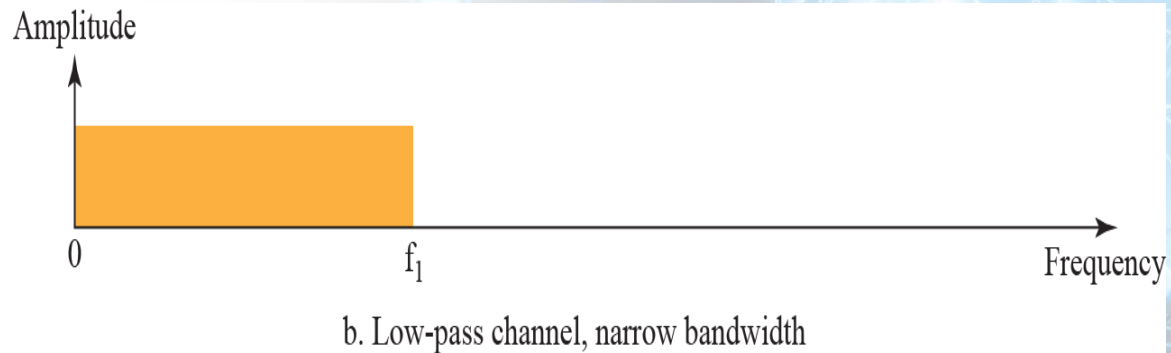
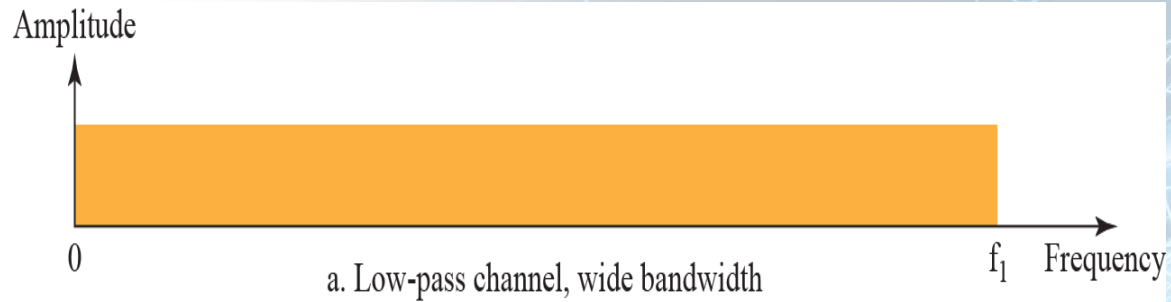
A vertical line in the time domain means a frequency of infinity: a horizontal line in the time domain means a frequency of zero. Going from a frequency of zero to a frequency of infinity implies all frequencies in between are part of the domain.

Baseband Transmission

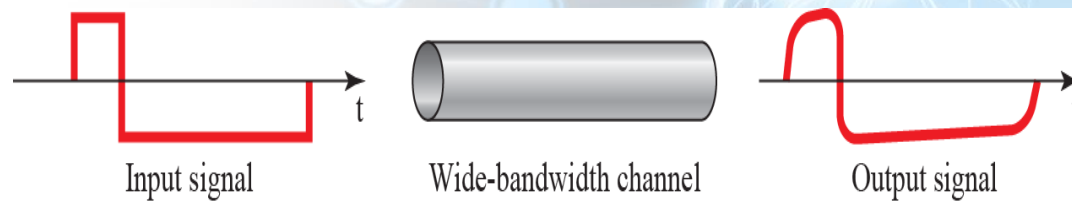
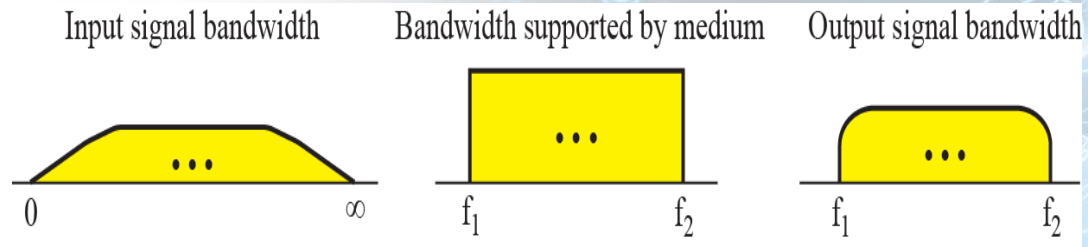


Sending a **Digital Signal** without changing it to an **Analog Signal**

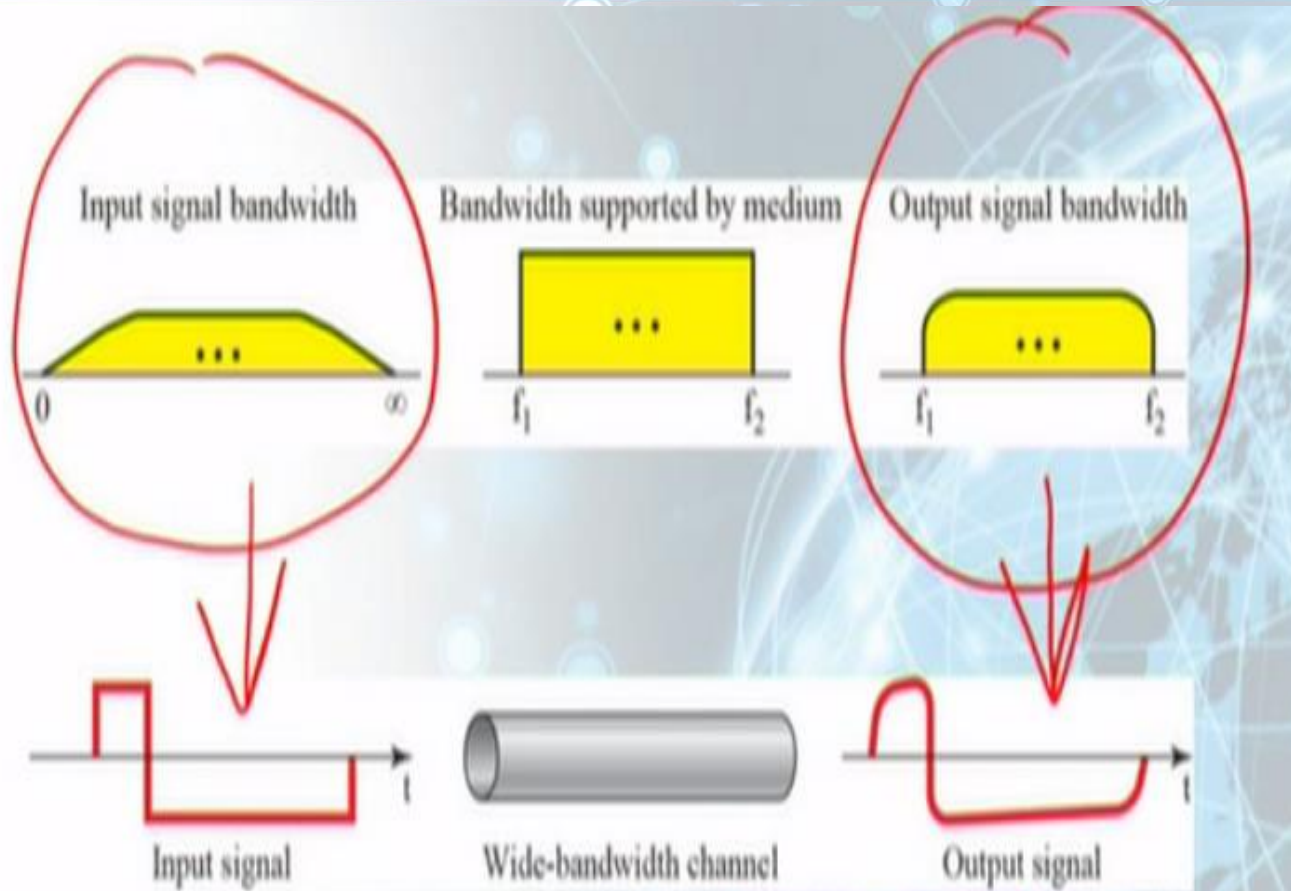
Baseband Transmission



Baseband Transmission



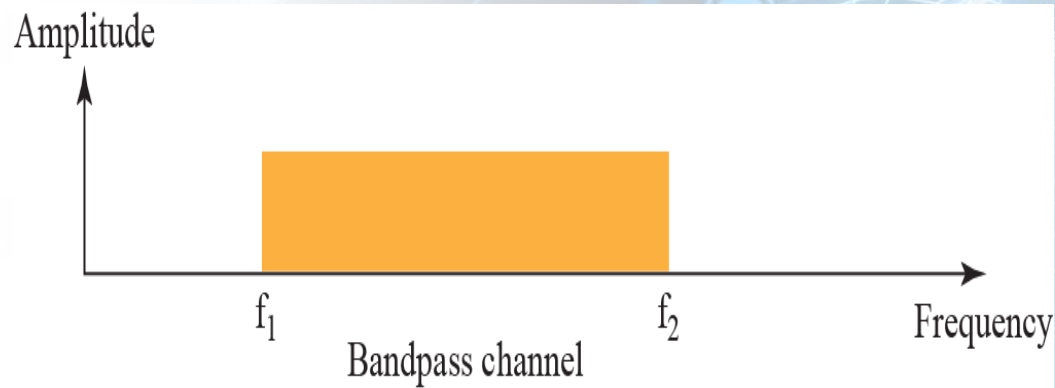
Baseband Transmission



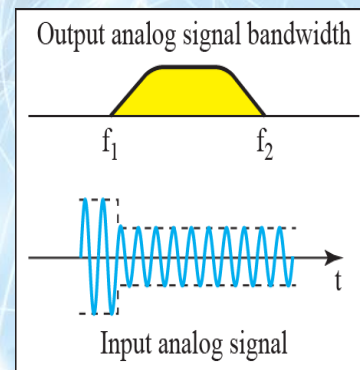
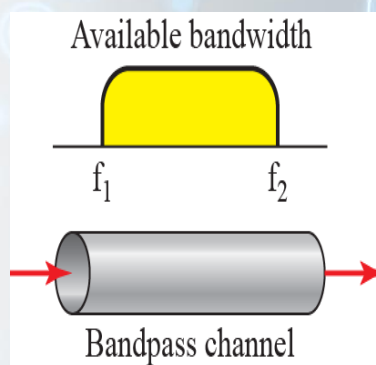
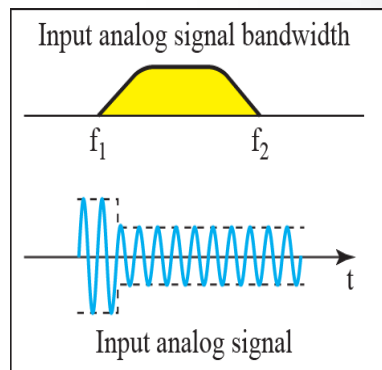
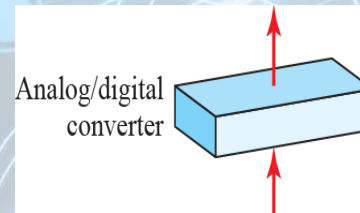
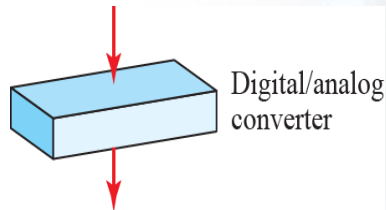
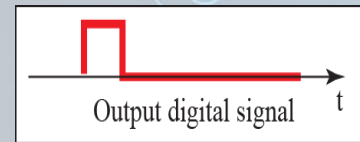
Broadband Transmission (Modulation)

- Changing the Digital signal to an Analog signal for transmission
- Modulation allows us to use a bandpass channel—a channel with a bandwidth that does not start from zero
- More available than a low pass

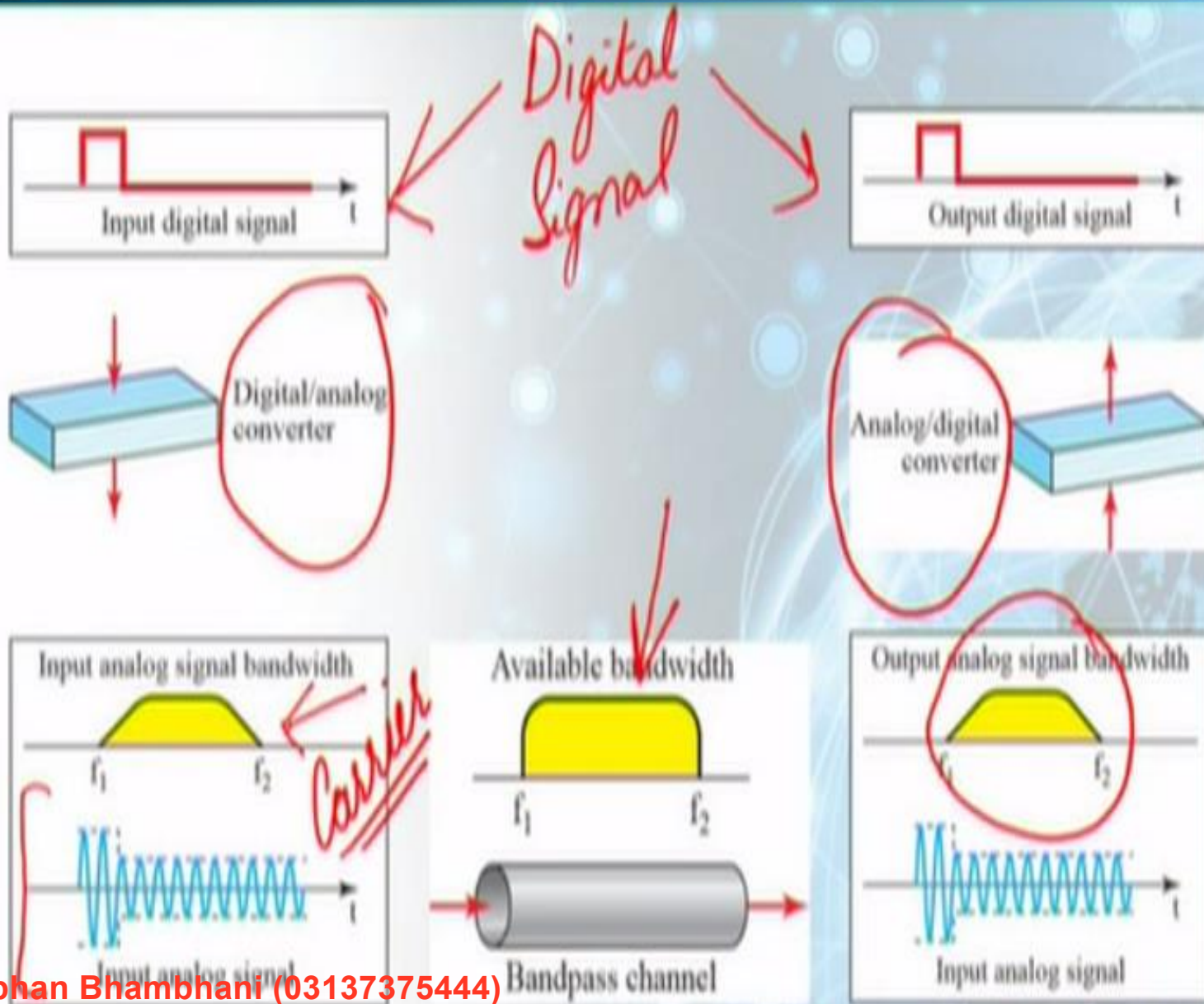
Broadband Transmission (Modulation)



Broadband Transmission (Modulation)



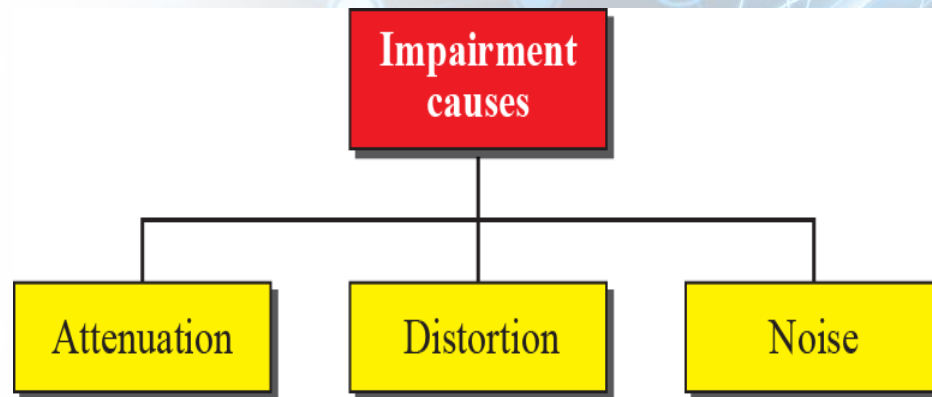
Broadband Transmission (Modulation)



Transmission Impairments

- **Transmission media are not perfect**
- **Cause Signal impairments**
- **Signal sent is not the same as the signal received**

Causes of Transmission Impairment



Transmission Impairment

What is sent is not what is received. Three causes of impairment are attenuation, distortion, and noise (see Figure 3.26).

Transmission Impairment

Signals travel through transmission media, which are not perfect. The imperfection causes signal impairment. This means that the signal at the beginning of the medium is not the same as the signal at the end of the medium.

Attenuation

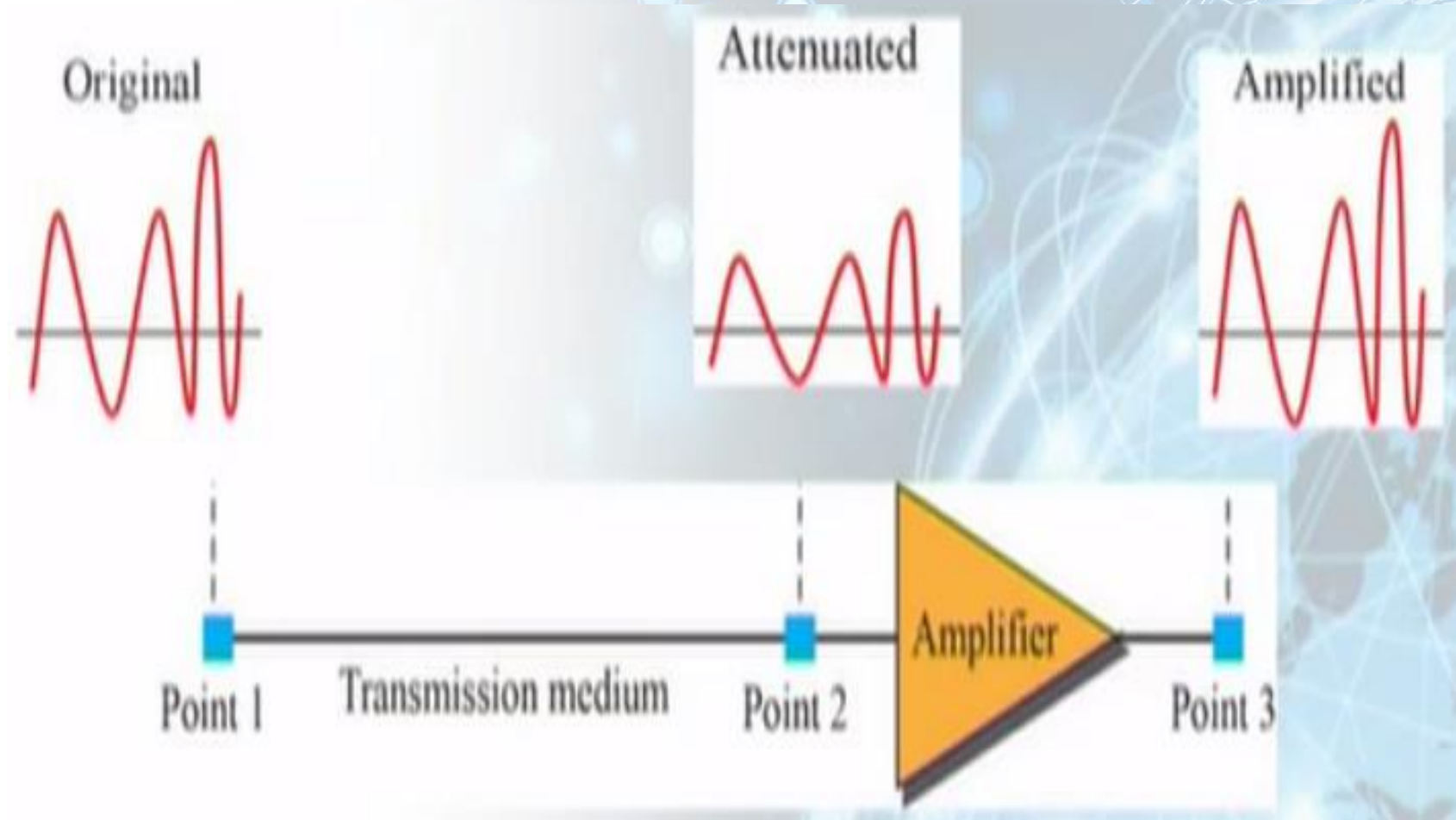
Attenuation means a loss of energy. When a signal, simple or composite, travels through a medium, it loses some of its energy in overcoming the resistance of the medium. That is why a wire carrying electric signals gets warm, if not hot, after a while. Some of the electrical energy in the signal is converted to heat.

Attenuation

To compensate for this loss, amplifiers are used to amplify the signal. Figure 3.27 shows the effect of attenuation and amplification..

Attenuation and amplification

Figure 3.27



Example 3.26

Suppose a signal travels through a transmission medium and its power is reduced to one half. This means that $P_2 = 0.5 P_1$. In this case, the attenuation (loss of power) can be calculated as

$$\begin{aligned} 10 \log_{10} P_2/P_1 &= 10 \log_{10} (0.5 P_1) / P_1 \\ &= 10 \log_{10} 0.5 = 10 \times (-0.3) = -3 \text{ dB.} \end{aligned}$$

A loss of 3 dB (–3 dB) is equivalent to losing one-half the power.

Example 3.27

A signal travels through an amplifier, and its power is increased 10 times. This means that $P_2 = 10P_1$. In this case, the amplification

$$10 \log_{10} \frac{P_2}{P_1} = 10 \log_{10} \frac{10P_1}{P_1} =$$

$$10 \log_{10} 10 = 10(1) = 10 \text{ dB}$$

Example 3.28

One reason that engineers use the decibel to measure the changes in the strength of a signal is that decibel numbers can be added (or subtracted) when we are measuring several points (cascading) instead of just two. In Figure 3.28 a signal travels from point 1 to point 4. The signal is attenuated by the time it reaches point 2.

Example 3.28

Between points 2 and 3, the signal is amplified. Again, between points 3 and 4, the signal is attenuated. We can find the resultant decibel value for the signal just by adding the decibel measurements between each set of points. In this case, the decibel value can be calculated as

$$\text{dB} = -3 + 7 - 3 = +1$$

Example 3.29

Sometimes the decibel is used to measure signal power in milliwatts. In this case, it is referred to as dB_m and is calculated as $\text{dB}_m = 10 \log_{10} P_m$, where P_m is the power in milliwatts.

Calculate the power of a signal if its $\text{dB}_m = -30$.

Example 3.29

Solution

We can calculate the power in the signal as

$$dB_m = 10 \log_{10} \longrightarrow dB_m = -30 \longrightarrow$$

$$\log_{10} P_m = -3 \longrightarrow P_m = 10^{-3} \text{ mW}$$

Example 3.30

Sometimes the decibel is used to measure signal power in milliwatts. In this case, it is referred to as dB_m and is calculated as $\text{dB}_m = 10 \log_{10} P_m$, where P_m is the power in milliwatts.

Calculate the power of a signal if its $\text{dB}_m = -30$.

Example 3.30

Solution

The loss in the cable in decibels is $5 \times (-0.3) = -1.5$ dB. We can

$$\text{dB} = 10 \log_{10} (P_2 / P_1) = -1.5 \text{ dB}$$

$$\rightarrow (P_2 / P_1) = 10^{-0.15} = 0.71$$

$$P_2 = 0.71P_1 = 0.7 \times 2 \text{ mW} = 1.4 \text{ mW}$$

Attenuation and Amplification - Decibel

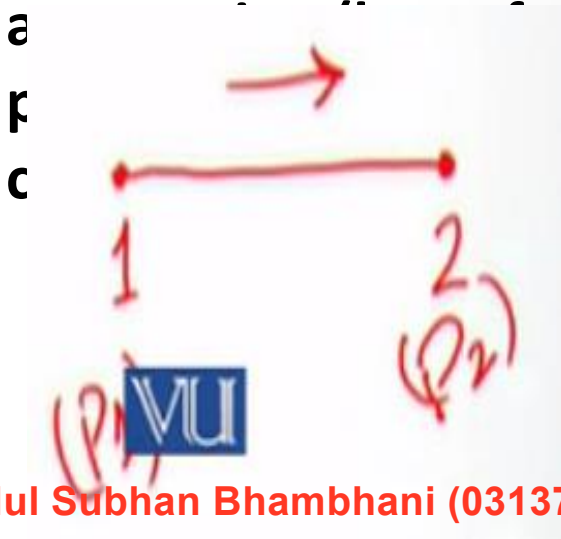
- Unit of Signal strength is Decibel or dB
- Decibel (dB) measures the relative strengths of two signals or one signal at two different points

$$10 \log_{10} P_2/P_1$$

- Decibel is negative if a signal is attenuated and positive if signal is amplified

Example

Suppose a signal travels through a transmission medium and its power is reduced to one half. This means that $P_2 = 0.5 P_1$. In this case, the



$P_2 \rightarrow$ Power at point 2

$P_1 \rightarrow$ Power at point 1

$$P_2 = 0.5 P_1$$

$$10 \log_{10} \frac{P_2}{P_1} = 10 \log_{10} \frac{0.5 P_1}{P_1}$$

Signal has lost one half the power.

$$= 10 \log_{10} 0.5$$

$$= \underline{\underline{-3 \text{ dB}}}$$

Example

A signal travels through an amplifier, and its power is increased 10 times. This means that $P_2 = 10P_1$. In this case, the **amplification** (gain of power) can be calculated as

$$\begin{aligned} P_2 &= 10 P_1 \\ 10 \log_{10} \frac{P_2}{P_1} & \\ &= 10 \log_{10} \frac{10 P_1}{P_1} \\ &= 10 \text{ dB} \end{aligned}$$

Distortion

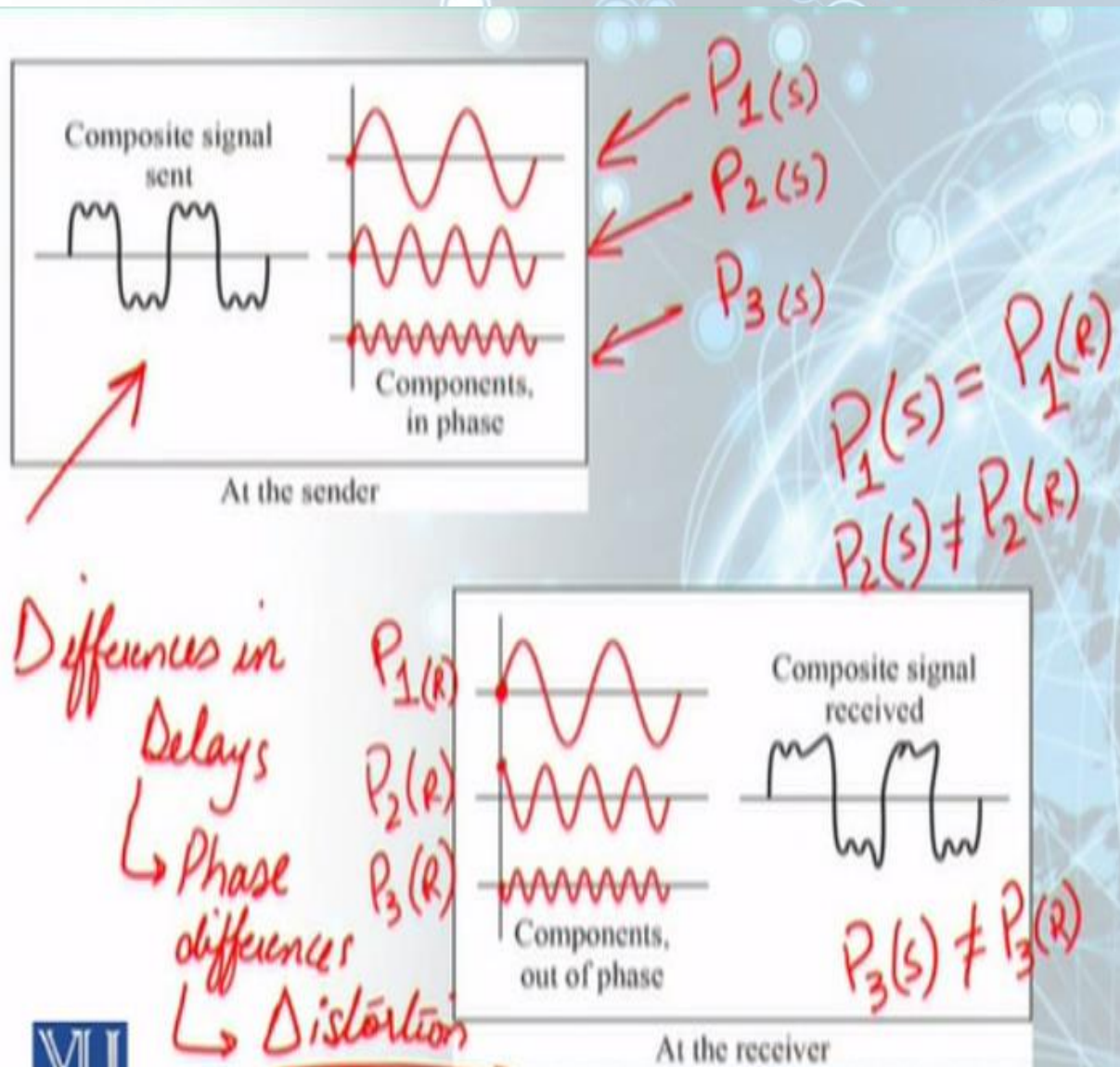
- **Distortion means that the signal changes its form or shape.**
- **Distortion can occur in a composite signal made of different frequencies.**
- **Each signal component has its own propagation speed (see the next section) through a medium and, therefore, its own delay in arriving at the final destination.**

Distortion

Differences in delay may create a difference in phase if the delay is not exactly the same as the period duration.

Distortion

Figure 3.2



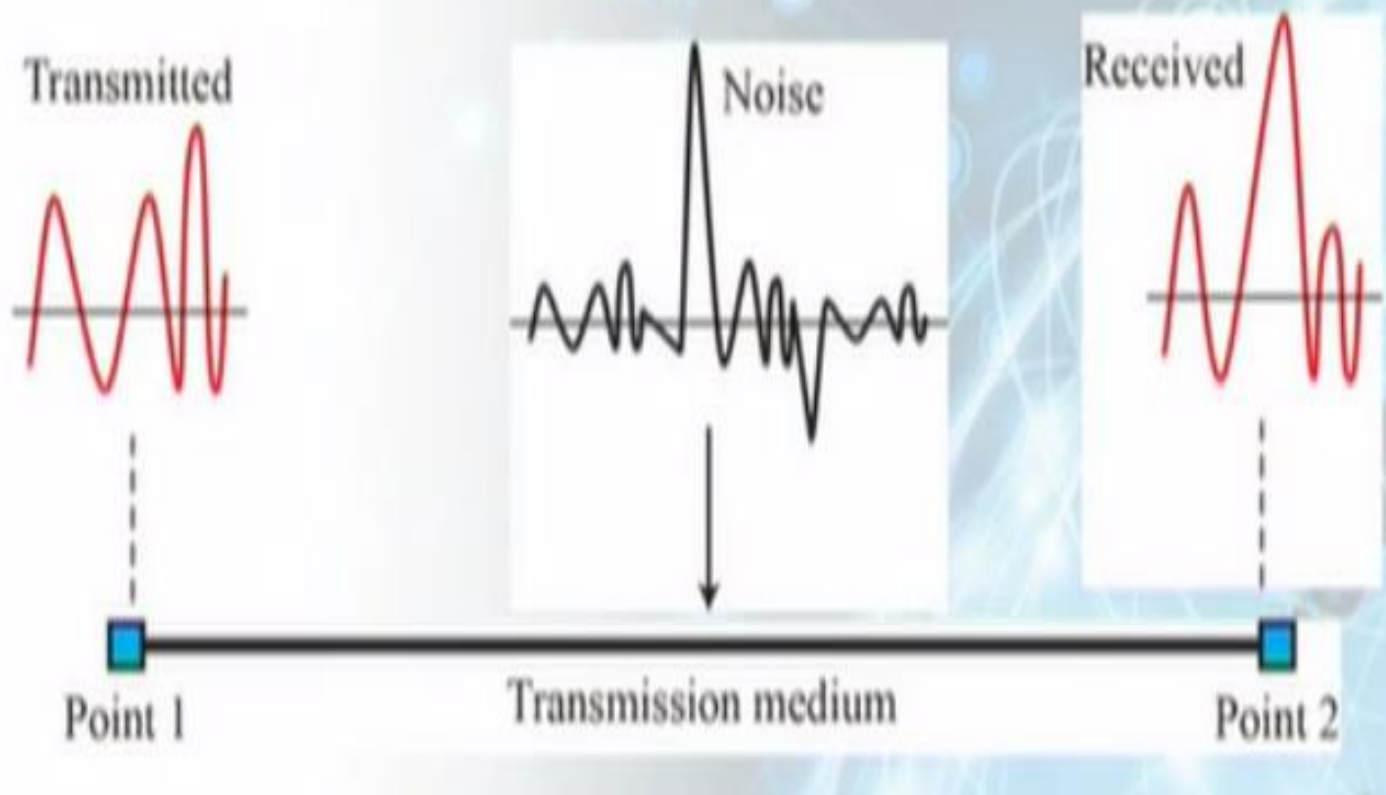
Noise

- **Noise is another cause of impairment.**
- **Several types of noise, such as thermal noise, induced noise, crosstalk, and impulse noise, may corrupt the signal.**
- **Thermal noise is the random motion of electrons in a wire, which creates an extra signal not**

Noise

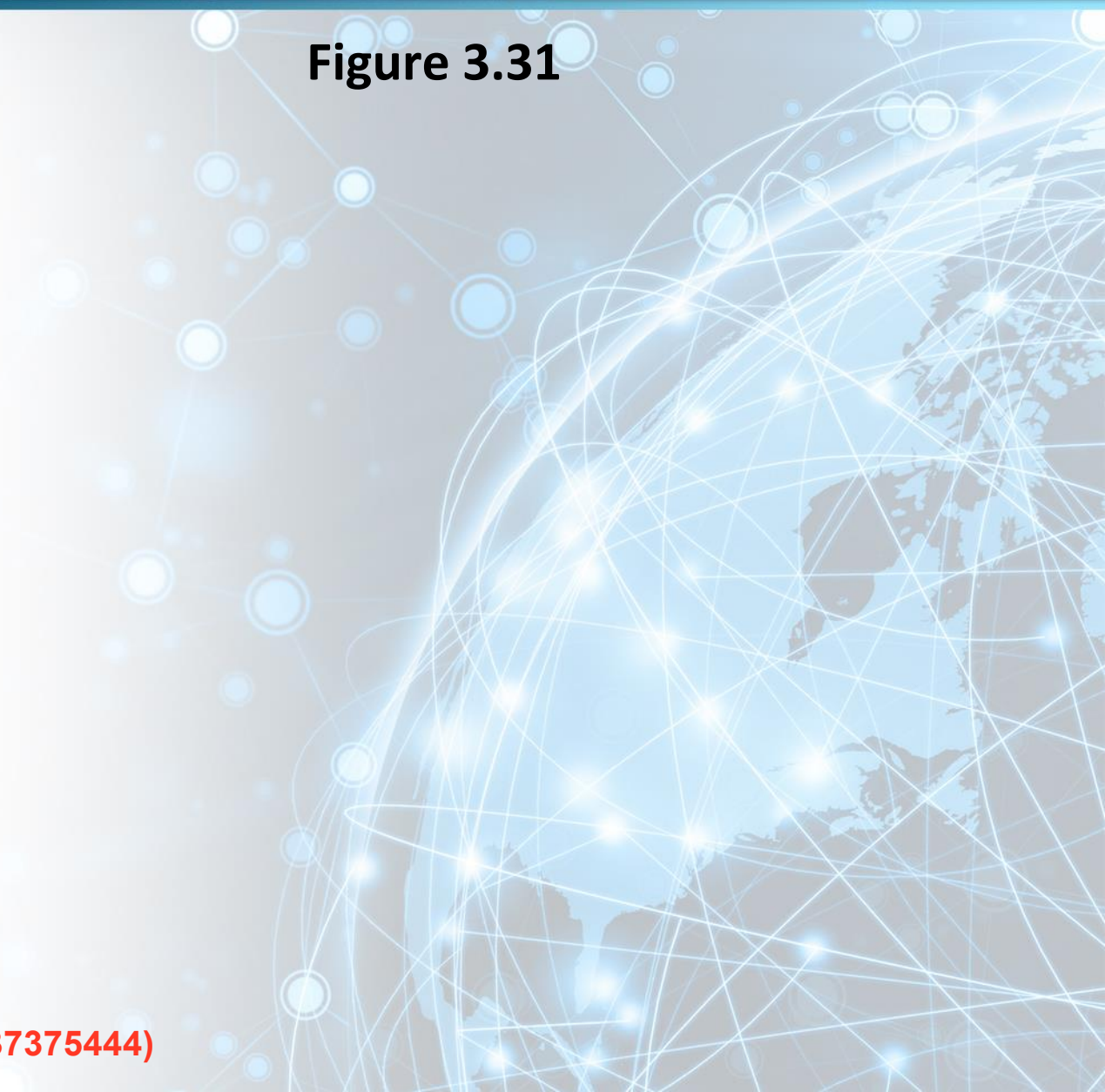
- **Induced noise comes from sources such as motors.**
- **Crosstalk is the effect of one wire on the other.**

Noise



Noise

Figure 3.31

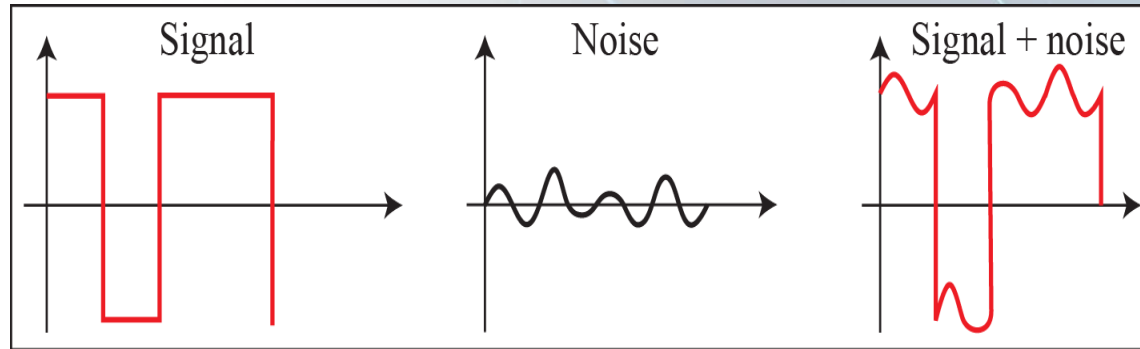


Noise – Signal to Noise Ratio (SNR)

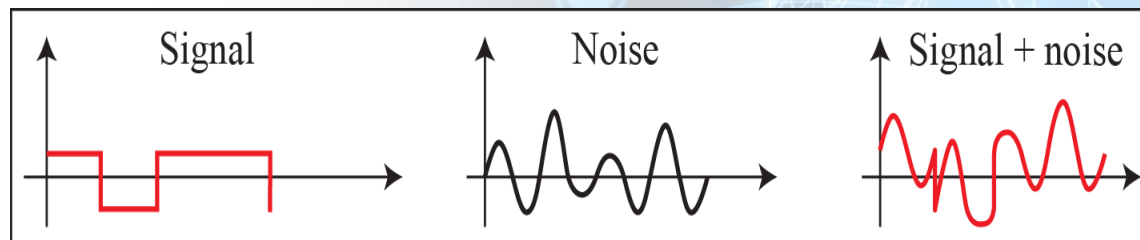
- Signal to Noise Ratio (SNR) is used to find the theoretical bit rate limit of a

$$\text{SNR} = \frac{\text{average signal power}}{\text{average noise power}}$$

Noise – Signal to Noise Ratio (SNR)



a. High SNR

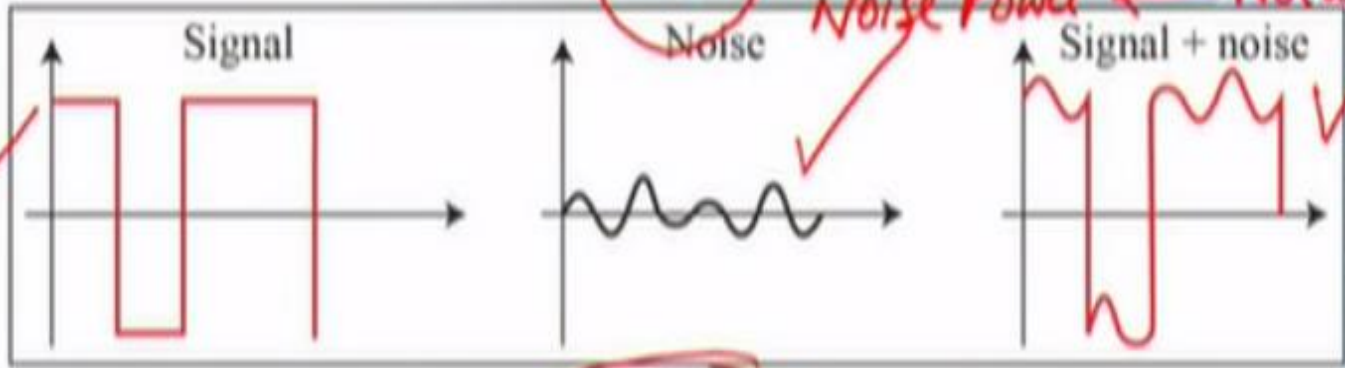


b. Low SNR

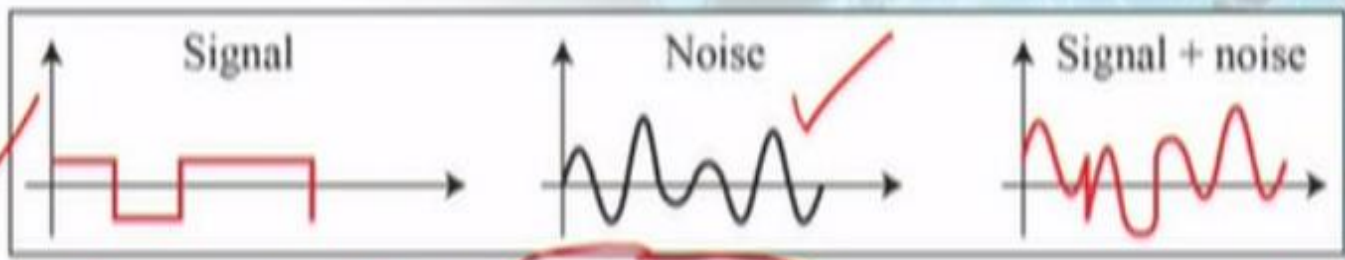
Noise – Signal to Noise Ratio (SNR)

$$SNR = \frac{\text{Signal Power}}{\text{Noise Power}}$$

← wanted
← Not wanted



a. High SNR ✓ *less corrupted*



b. Low SNR ✓ *more corrupted*

→ $SNR_{dB} = 10 \log_{10} SNR$



Example

The power of a signal is 10 mW and the power of the noise is 1 μ W; what are the values of SNR and SN

$$\text{SNR} = \frac{10 \text{ mW}}{1 \mu\text{W}} = 10,000$$
$$\text{SNR}_{\text{dB}} = 10 \log_{10} 10,000 = \underline{\underline{40 \text{ dB}}}$$

Example

The values of SNR and SNR_{dB} for a noiseless channel are calculated as

$$\underline{\text{Noise} = 0}$$

↳ NOT a real life scenario

$$\text{SNR} = \frac{(\text{Sig. Power})}{0} = \infty$$

$$= 10 \log_{10} \infty = \infty$$

Not Real

Example 3.31

The power of a signal is 10 mW and the power of the noise is 1 μ W; what are the values of SNR and SNR_{dB}?

Solution

The values of SNR and SNR_{dB} can be calculated as

$$\text{SNR} = (10,000 \mu\text{w}) / (1 \mu\text{w}) = 10,000 \quad \text{SNR}_{\text{dB}}$$

$$= 10 \log_{10} 10,000 = 10 \log_{10} 10^4 = 40$$

Example 3.32

The values of SNR and SNR_{dB} for a noiseless channel are

Solution

The values of SNR and SNR_{dB} for a noiseless channel are

$$\text{SNR} = (\text{signal power}) / 0 = \infty$$

$$\rightarrow \text{SNR}_{\text{dB}} = 10 \log_{10} \infty = \infty$$

We can never achieve this ratio in real life; it is an ideal.

Data Rate Limits

- How fast we can send data, in bits per second, over a channel?
- Data Rate depends on 3 factors:
 - ✓ The Bandwidth available
 - ✓ The level of the signals we use
 - ✓ The level of noise

Data Rate Limits

- **Two theoretical formulas developed to calculate the data rate:**
 - ✓ **one by Nyquist for a noiseless channel**
 - ✓ **another by Shannon for a noisy channel**

Noiseless Channel : Nyquist Rate

$$\left(\begin{array}{l} \text{Bit Rate} = 2 \times \text{Bandwidth} \\ \quad \quad \quad \times \log_2 L \end{array} \right)$$

BW = BW of channel
L = No. of signal levels
BR = bps

Bit Rate \propto L

$L \uparrow \implies \text{Bit Rate} \uparrow$
| (L \Rightarrow 0, 1) L = 2 levels

- For a noiseless channel, the Nyquist bit rate formula defines the theoretical maximum bit rate
- Finding balance between Bit rate

m
/

Example

Consider a noiseless channel with a bandwidth of 3000 Hz transmitting a signal with two signal levels. The maximum bit rate can be calculated as

$$\begin{aligned} BR &= 2 \times 3000 \times \log_2 2 \\ &= \underline{6000 \text{ bps}} \end{aligned}$$

Example

Consider the same noiseless channel transmitting a signal with four signal levels (for each level, we send 2 bits). The

n
c
a

$$\underline{\underline{BR \propto L}}$$

$$BR = 2 \times 3000 \times \log_2 4$$
$$= \underline{\underline{12,000 \text{ bps}}}$$

(Reliability)

Noisy Channel : Shannon Capacity

- In reality, we cannot have a noiseless channel; the channel is always noisy
- In 1944, Claude Shannon introduced a formula, to determine the theoretical highest data rate

$$\text{Capacity} = \text{Bandwidth} \times \log_2(1 + \text{SNR})$$

(channel) $\left(\begin{array}{c} \text{Sig} \\ \text{to} \\ \text{Noise} \end{array} \right)$ Ratio

Capacity \rightarrow Capacity of Channel
 \rightarrow Bit Rate(max)

Levels $\rightarrow L \times$

Max. BR < Capacity of Channel

Example

Consider an extremely noisy channel in which the value of the signal-to-noise ratio is almost zero. In other words, the noise is so strong that the signal is faint. For this channel the capacity C is calculated as

$$\text{SNR} \approx \text{zero}$$

$$C = B \log_2(1 + \text{SNR})$$

$$= B \log_2 1$$

$$= B \times \text{zero}$$

$$C = \text{zero}$$

↳ Cannot receive any data through channel.

Example

Theoretical highest bit rate of a Telephone line with a Bandwidth of 3000 Hz assigned for data communication. SNR is usually 3162. The capacity is calculated as:

$$C = 3000 \times \log_2(1 + 3162)$$
$$= 34,860 \text{ bps}$$

Telephone line

Using Both Limits

- In practice, we need to use both methods to find the limits and signal levels
- Shannon's formula gives us the upper limit while the Nyquist formula gives us the signal levels

Example 3.37

Consider an extremely noisy channel in which the value of the signal-to-noise ratio is almost zero. In other words, the noise is so strong that the signal is faint. For this

$$C = B \log_2(1 + \text{SNR}) = B \log_2(1 + 0)$$

$$C = B \log_2 1 = B \times 0 = 0$$

capacity C is calculated as

Example 3.37

This means that the capacity of this channel is zero regardless of the bandwidth. In other words, we cannot receive any data through this channel.

Example 3.38

This means that the capacity of this channel is zero regardless of the bandwidth. In other words, we cannot

$$C = B \log_2 (1 + \text{SNR}) =$$

$$3000 \log_2 (1 + 3162) =$$

$$3000 \times 11.62 = 34,860 \text{ bps}$$

Example 3.38

This means that the highest bit rate for a telephone line is 34.860 kbps. If we want to send data faster than this, we can either increase the bandwidth of the line or improve the signal-to-noise ratio.

Example 3.39

The signal-to-noise ratio is often given in decibels. Assume that $\text{SNR}_{\text{dB}} = 36$ and the channel bandwidth is 2 MHz. The theoretical channel capacity can be calculated as

Example 3.39

$$\text{SNR}_{\text{dB}} = 10 \log_{10} \text{SNR} \longrightarrow$$

$$\text{SNR} = 10^{\text{SNR}_{\text{dB}}/10} \longrightarrow$$

$$\text{SNR} = 10^{3.6} = 3981$$

$$C = B \log_2(1 + \text{SNR}) =$$

$$2 \times 10^6 \times \log_2 3982$$

$$= 24 \text{ Mbps}$$

Example 3.40

When the SNR is very high, we can assume that $\text{SNR} + 1$ is almost the same as SNR. In these cases, the theoretical channel capacity can be simplified to $C = B \log_2(\text{SNR}_{\text{dB}})$. For example, we can calculate the $C = 2 \text{ MHz} \times (36 / 3) = 24 \text{ Mbps}$ of the previous example as

Using Both Limits

In practice, we need to use both methods to find the limits and signal levels. Let us show this with an example.

Example 3.41

We have a channel with a 1-MHz bandwidth. The SNR for this channel is 63. What are the appropriate bit rate and signal level?

Solution

First, we use the

$$C = B \log_2(1 + \text{SNR}) = \text{a to bit}$$

$$10^6 \log_2(1 + 63) = 10^6 \log_2 64 =$$

$$6 \text{ Mbps}$$

Example 3.41

The Shannon formula gives us 6 Mbps, the upper limit. For better performance we choose something lower, 4 Mbps. Then we use the Nyquist formula

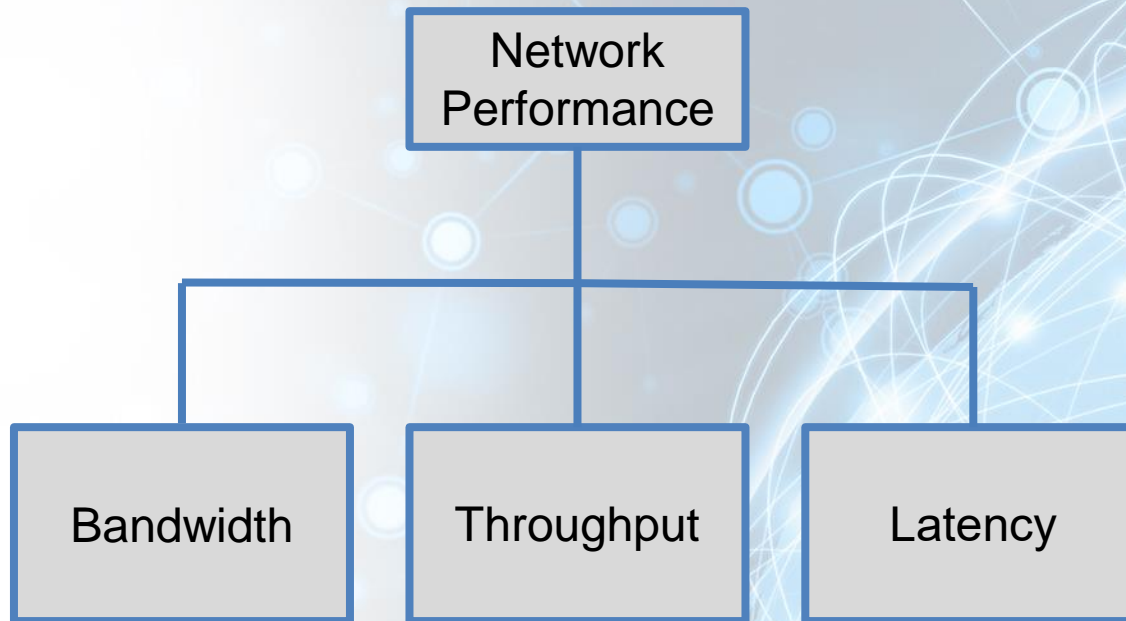
$$4 \text{ Mbps} = 2 \times 1 \text{ MHz} \times \log_2 L$$

number of levels $\rightarrow L = 4$

Network Performance

- **Data transmission (in form of Signal) over a network and how network behaves is important**
- **More important is the performance of the network**
- **How good is our network?**

Network Performance



- **There are 3 characteristics of network performance**

Bandwidth

- An important characteristic that measures Network Performance
- Bandwidth can be used in two different contexts with two different measuring values:
 - Bandwidth in Hertz
 - Bandwidth in

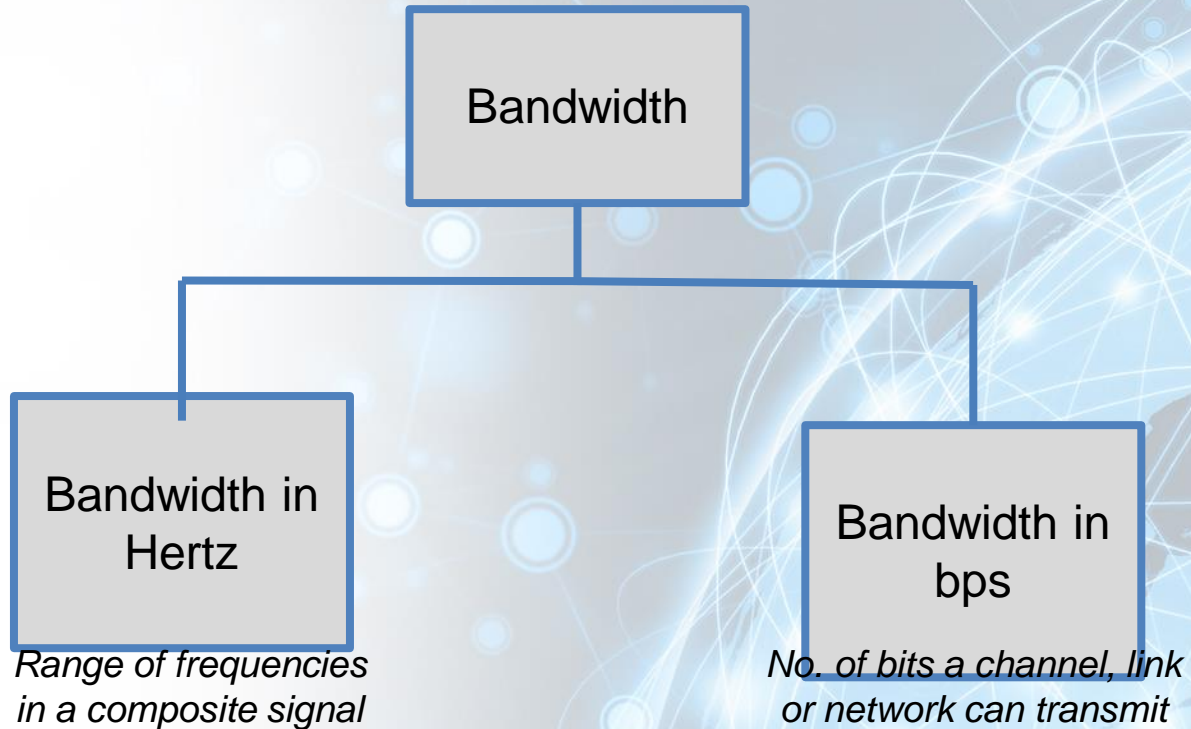
Example 3.42

The bandwidth of a subscriber line is 4 kHz for voice or data. The bandwidth of this line for data transmission can be up to 56,000 bps using a sophisticated modem to change the digital signal to analog.

Example 3.43

If the telephone company improves the quality of the line and increases the bandwidth to 8 kHz, we can send 112,000 bps by using the same technology as mentioned in Example 3.42.

Bandwidth



Throughput

- Measure of how fast we can actually send data through a network.
- Bandwidth is not the same as Throughput
- A link may have a bandwidth of B bps, but we can only send T bps through this link.

Example

A network with bandwidth of 10 Mbps can pass only an average of 12,000 frames per minute with each frame carrying an average of 10,000 bits. What is the throughput of the network?

$$T = \frac{(12,000 \times 10,000)}{60} = 2 \text{ Mbps}$$

$$T = 2 \text{ Mbps}$$
$$B = 10 \text{ Mbps}$$

Throughput

The throughput is a measure of how fast we can actually send data through a network.

Although, at first glance, bandwidth in bits per second and throughput seem the same, they are different. A link may have a bandwidth of B bps, but we can only send T bps through this link with T always less than B .

Throughput

The latency or delay defines how long it takes for an entire message to completely arrive at the destination from the time the first bit is sent out from the source.

Throughput

We can say that latency is made of four components: propagation time, transmission time, queuing time and processing delay.

Latency =
propagation time +
transmission time +
queuing time +
processing delay

Example 3.44

A network with bandwidth of 10 Mbps can pass only an average of 12,000 frames per minute with each frame carrying an average of 10,000 bits. What is the throughput of this network?

Example 3.44

Solution

We can calculate the throughput as

Throughput =

$$(12,000 \times 10,000) / 60 = 2\text{Mbps}$$

The throughput is almost one-fifth of the bandwidth in this case.

Example 3.45

What is the propagation time if the distance between the two points is 12,000 km? Assume the propagation speed to be 2.4×10^8 m/s in cable.

Solution

We can calculate the propagation time as

$$\text{Propagation time} = \frac{(12,000 \times 10,000)}{(2.4 \times 10^8)} =$$

Example 3.45

The example shows that a bit can go over the Atlantic Ocean in only 50 ms if there is a direct cable between the source and the destination.

Example 3.46

What are the propagation time and the transmission time for a 2.5-KB (kilobyte) message if the bandwidth of the network is 1 Gbps? Assume that the distance between the sender and the receiver is 12,000 km and that light travels at 2.4×10^8 m/s.

Example 3.46

Solution

We can calculate the propagation and transmission time as

$$\begin{aligned} \text{Propagation time} &= \\ &= (12,000 \times 1000) / \\ &= (2.4 \times 10^8) = 50 \text{ ms} \end{aligned}$$

$$\begin{aligned} \text{Transmission time} &= \\ &= (2500 \times 8) / 10^9 = \\ &= 0.020 \text{ ms} \end{aligned}$$

Example 3.46

Solution

Note that in this case, because the message is short and the bandwidth is high, the dominant factor is the propagation time, not the transmission time.

Example 3.47

What are the propagation time and the transmission time for a 5-MB (megabyte) message (an image) if the bandwidth of the network is 1 Mbps? Assume that the distance between the sender and the receiver is 12,000 km and that light travels at 2.4×10^8

Example 3.47

Solution

We can calculate the propagation and transmission times as

$$\text{Propagation time} = \frac{(12,000 \times 1000)}{(2.4 \times 10^8)} = 50 \text{ ms}$$

$$\text{Transmission time} = \frac{(5,000,000 \times 8)}{106} = 40 \text{ s}$$

We can calculate the propagation and transmission

Latency or Delay

- Latency or delay defines how long it takes for an entire message to completely arrive at the destination from the time the first bit is sent out from the source

$$\text{Latency} = \text{Propagation Time} + \text{Transmission Time} + \text{Queuing Time} + \text{Processing Delay.}$$

$$PT = \frac{\text{Distance}}{\text{Prop Speed}}$$

$$TT = \frac{\text{Message Size}}{BW}$$

QT → Time the message is held

Example

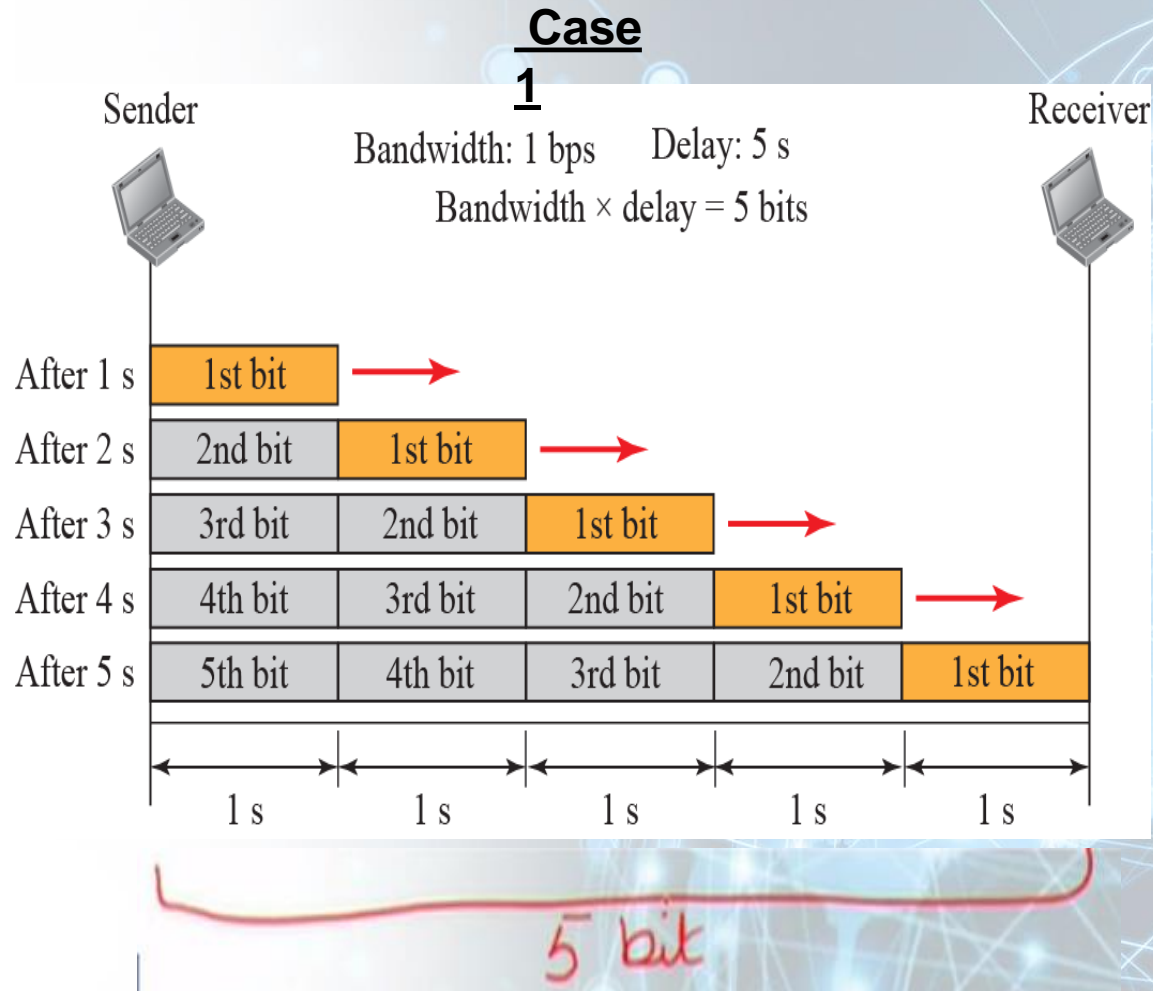
What is the propagation time if the distance between the two points is 12,000 km? Assume the propagation speed to be 2.4×10^8 m/s in cable.

$$PT = \frac{(12000 \times 1000)}{2.4 \times 10^8}$$
$$= \underline{\underline{50 \text{ m sec.}}}$$

Delay – Bandwidth Delay Product

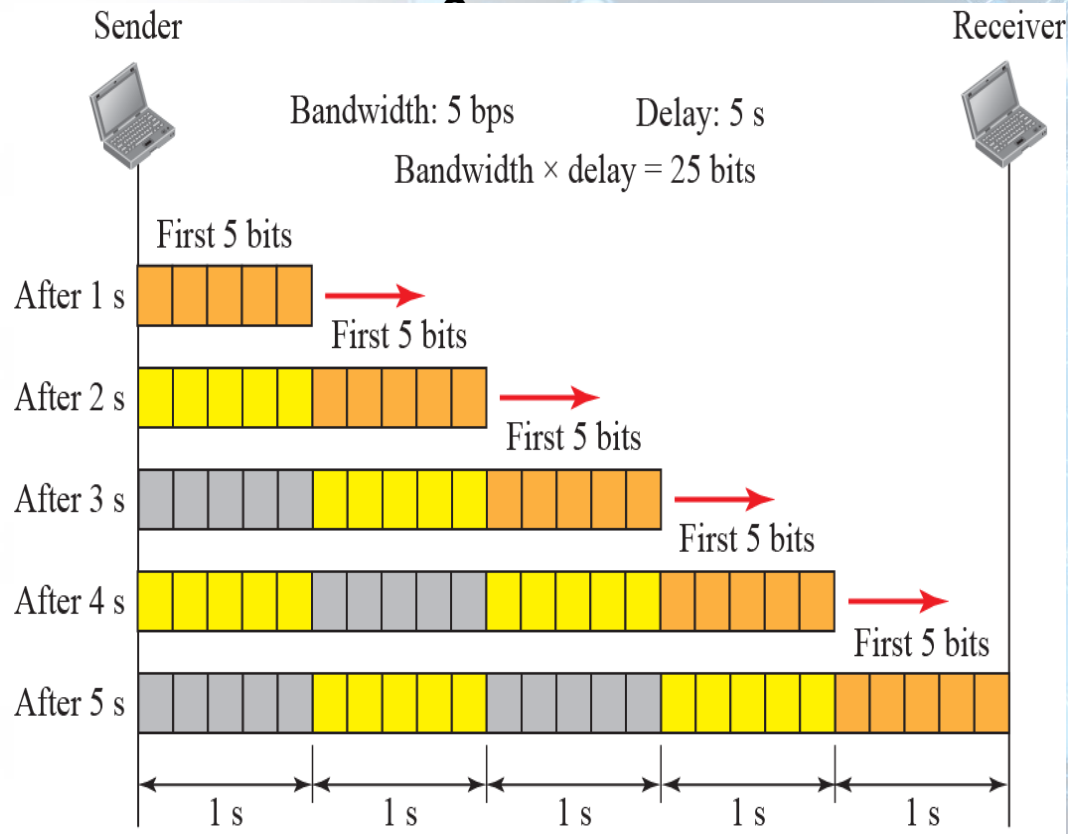
- Bandwidth and delay are two performance metrics of a link
- Product of the two, The Bandwidth-Delay Product defines the number of bits that can fill a link

Bandwidth-Delay Product

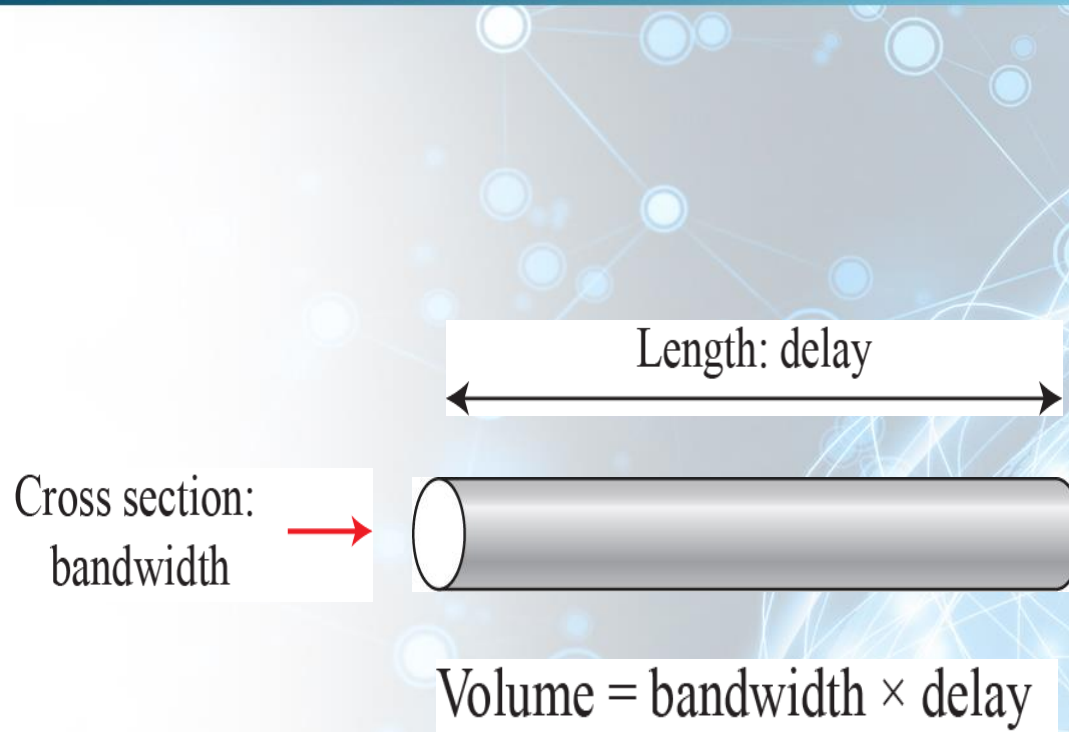


Bandwidth-Delay Product

Case



Bandwidth-Delay Product



Example 3.48

We can think about the link between two points as a pipe. The cross section of the pipe represents the bandwidth, and the length of the pipe represents the delay. We can say the volume of the pipe defines the bandwidth-delay product, as shown in Figure 3.34.

Delay - Jitter

- **Jitter is a problem if different packets of data encounter different delays and the application using the data at the receiver site is time-sensitive (audio and video data, for example)**

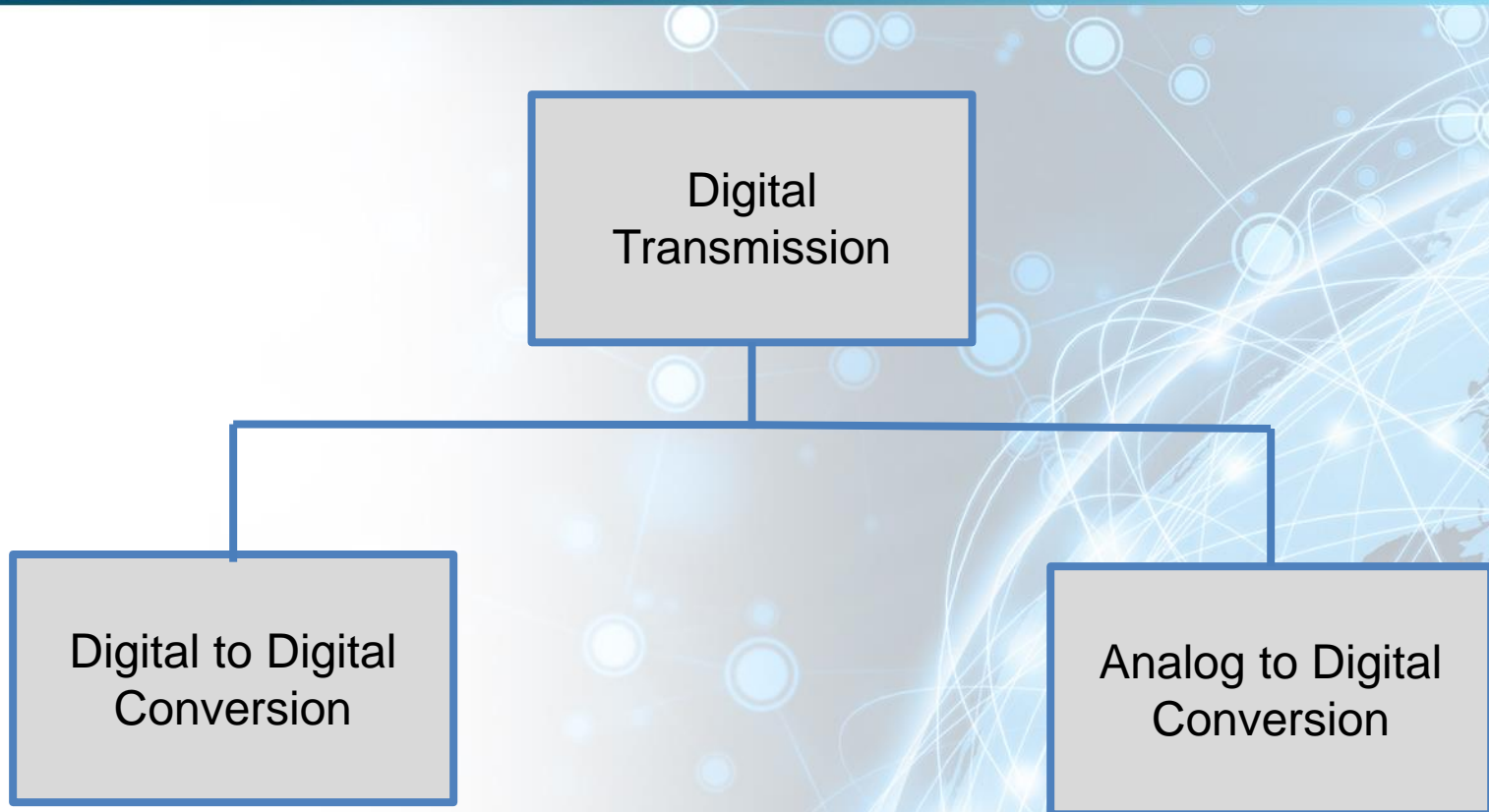
Delay - Jitter

- **Delay for first packet is 20 ms for the second is 45 ms, and for the third is 40 ms, then the real-time application that uses the packets endures jitter**

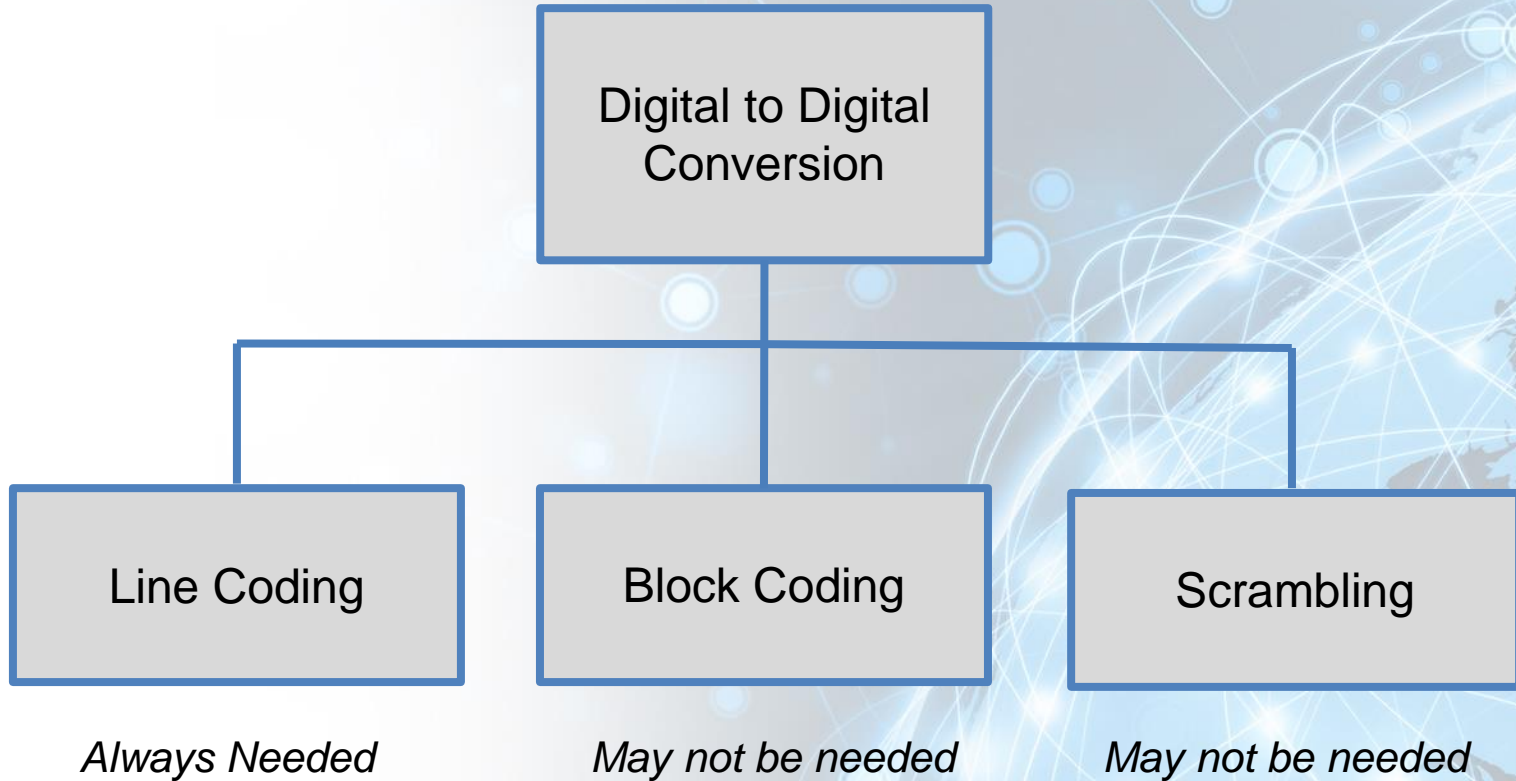
Digital-to-digital Conversion

- **Data → Analog or Digital**
- **Signals → Analog or Digital**
- **Digital Transmission**
- **Analog Transmission**

Digital Transmission



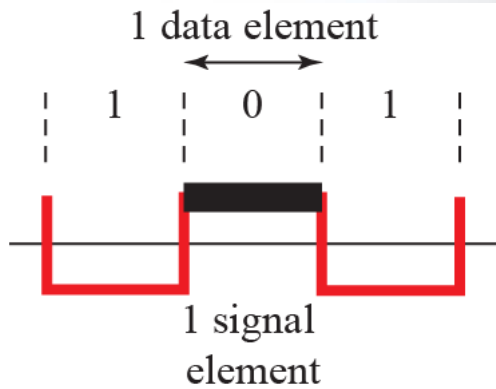
Digital to Digital Conversion



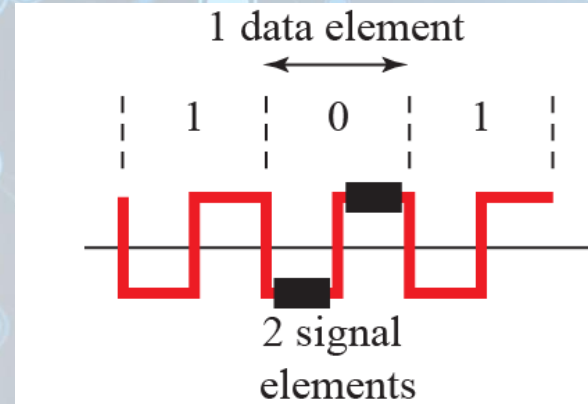
Signal Element versus Data Element

- A Data element is the smallest entity that can represent a piece of information → Bit
- A Signal element is the shortest unit of a digital signal
- Data Elements: Carried
- Signal Elements: Carriers

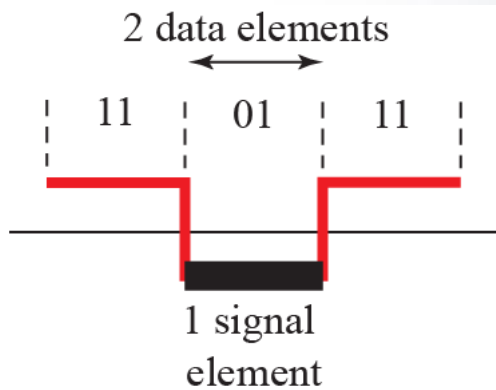
Signal Element versus Data Element



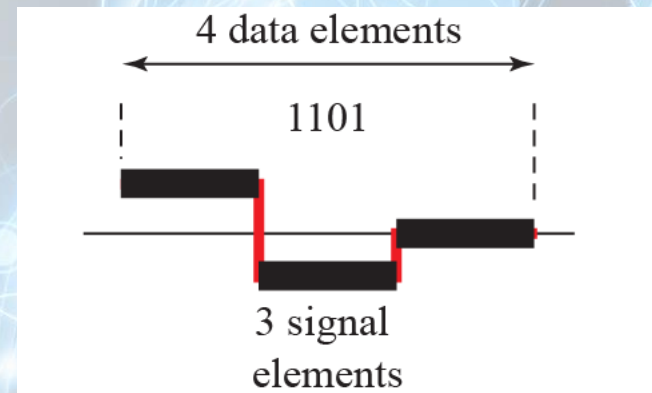
a. One data element per one signal element ($r = 1$)



b. One data element per two signal elements ($r = \frac{1}{2}$)



c. Two data elements per one signal element ($r = 2$)



d. Four data elements per three signal elements ($r = \frac{4}{3}$)



Data Rate versus Signal Rate

$S \rightarrow$ Signal Rate

$D \rightarrow$ Data Rate

$r \rightarrow$ No. of data elements
carried by signal
element

$$S = \frac{D}{r}$$

- Data Rate is number of data elements sent in 1 sec (bps)
- Signal Rate is number of signal elements sent in 1 sec (baud)
- Data Rate \rightarrow Bit Rate 
- Signal Rate \rightarrow Pulse Rate, Modulation Rate or Baud Rate 

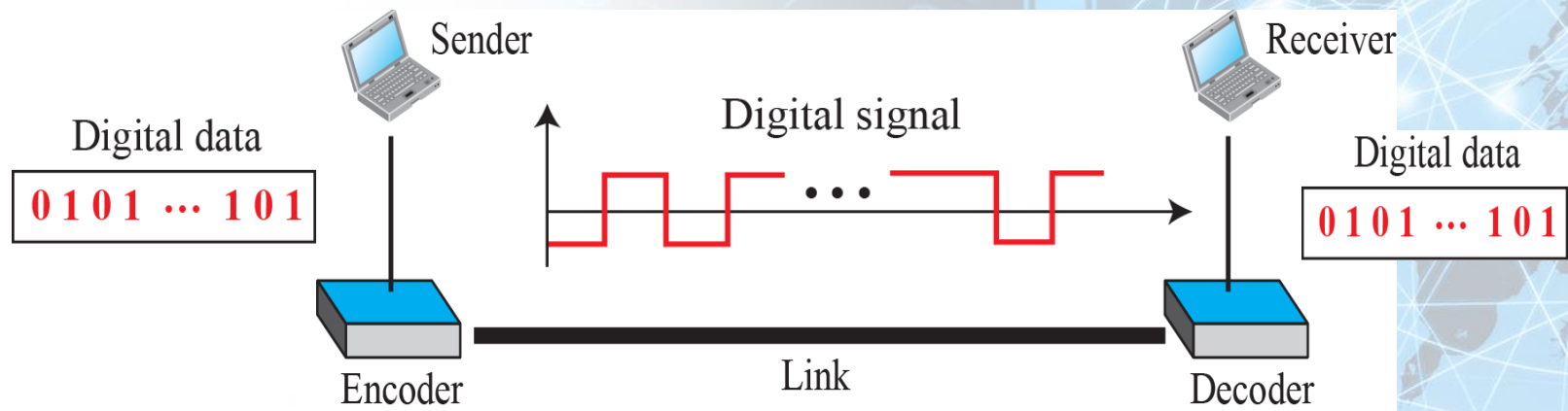
Example

A signal has a signal rate of 100 bauds. What is the Data rate if one data element is carried per signal element?

Line Coding

- **Digital data to Digital signals**
- **Data (Text, Numbers, Pictures, Audio, or Video) is stored in computer memory as sequences of bits**
- **Line coding converts a sequence of Bits to a Digital Signal**

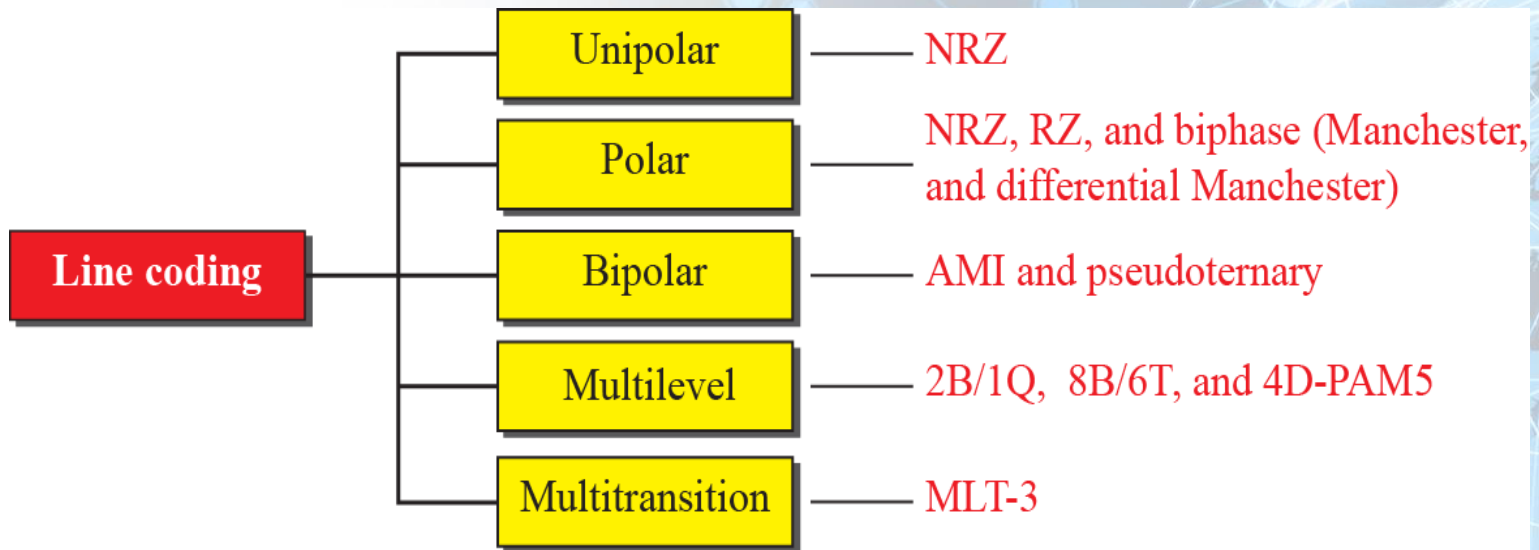
Line Coding and Decoding



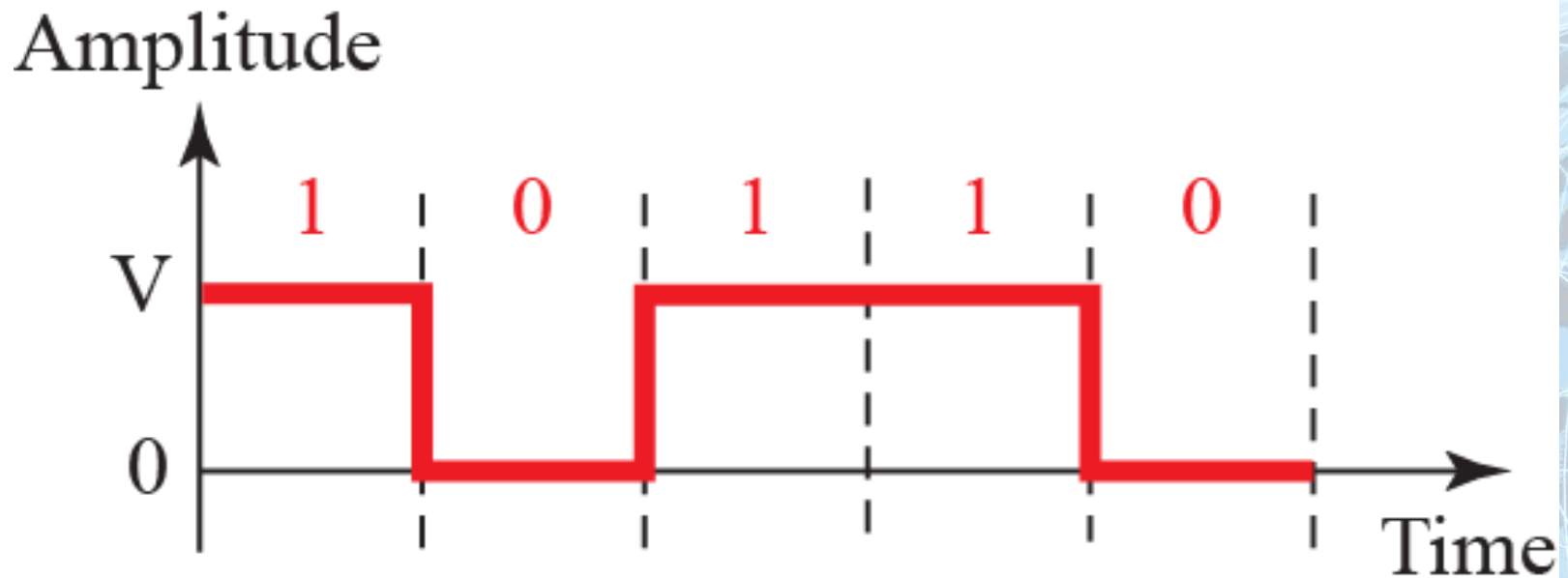
Line Coding Schemes

- We can roughly divide line coding schemes into five broad categories

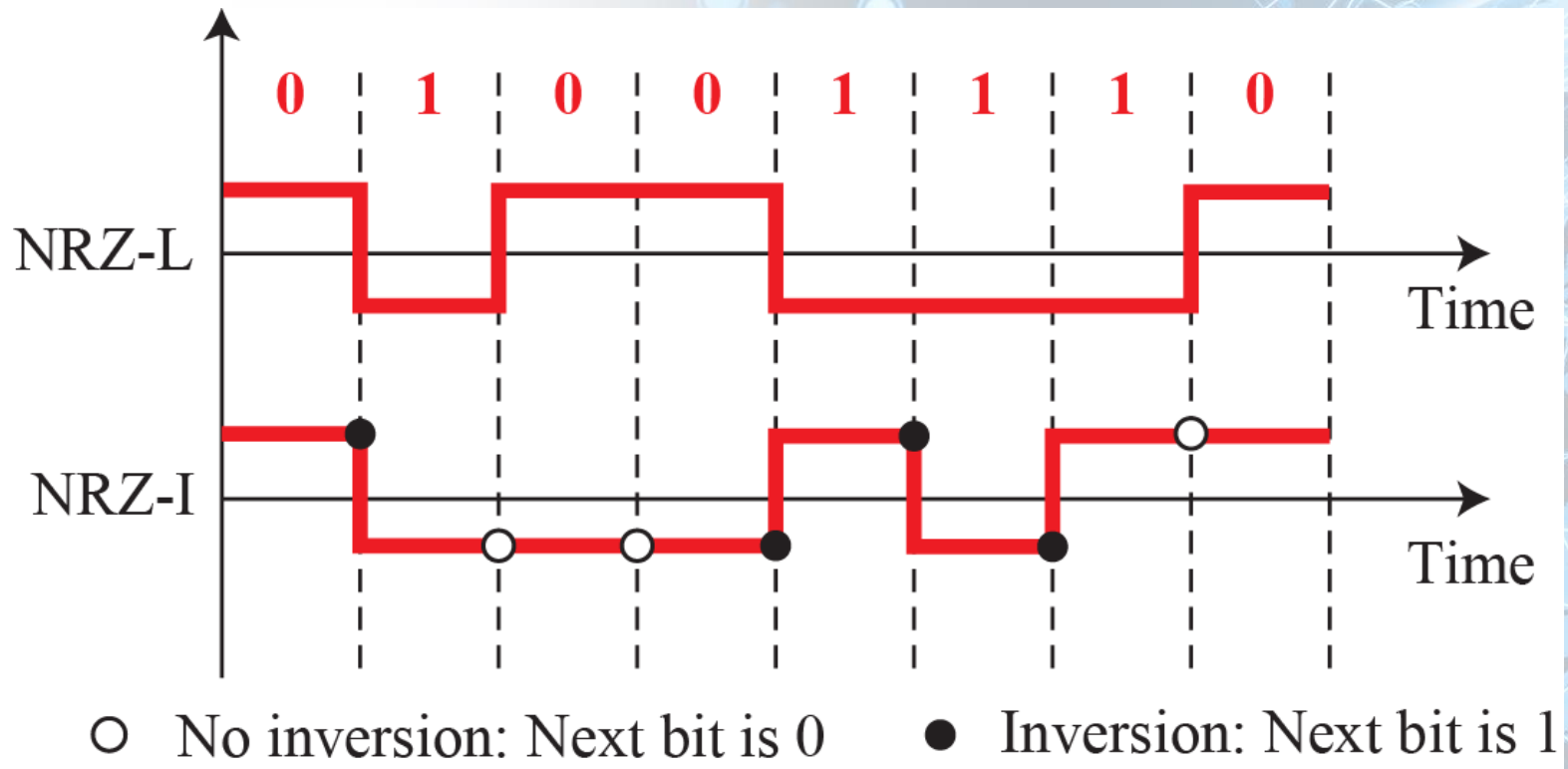
Line Coding Schemes



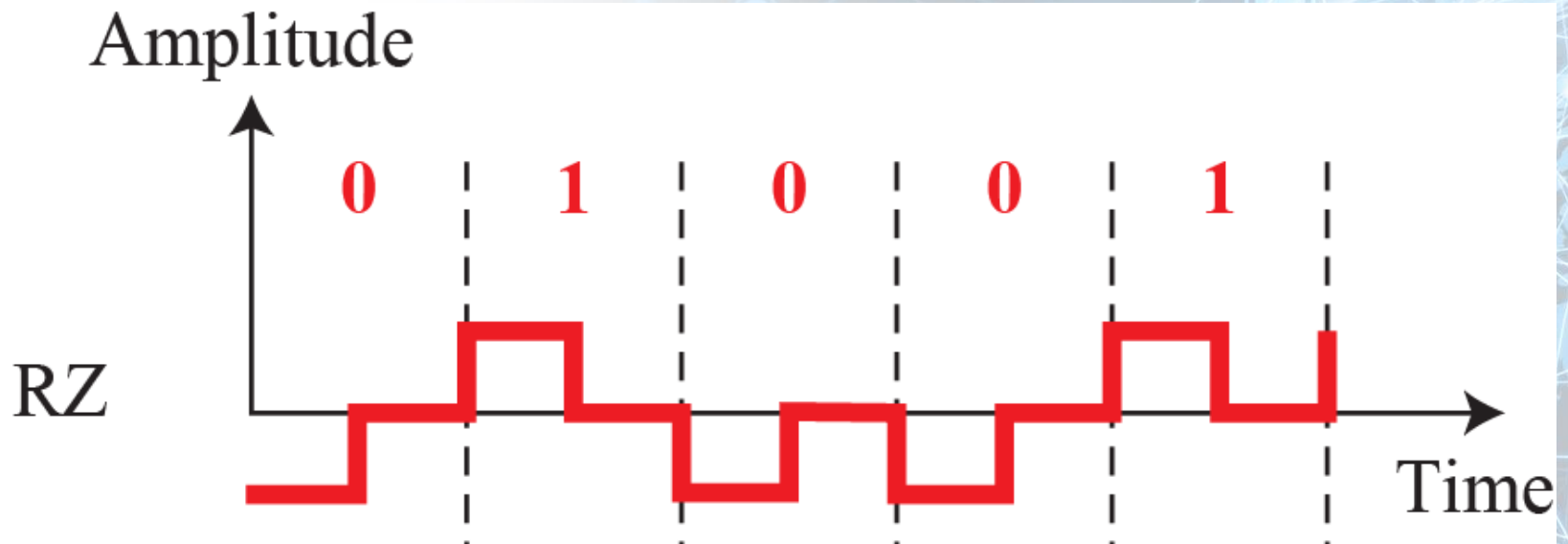
Unipolar NRZ scheme



Polar schemes (NRZ)



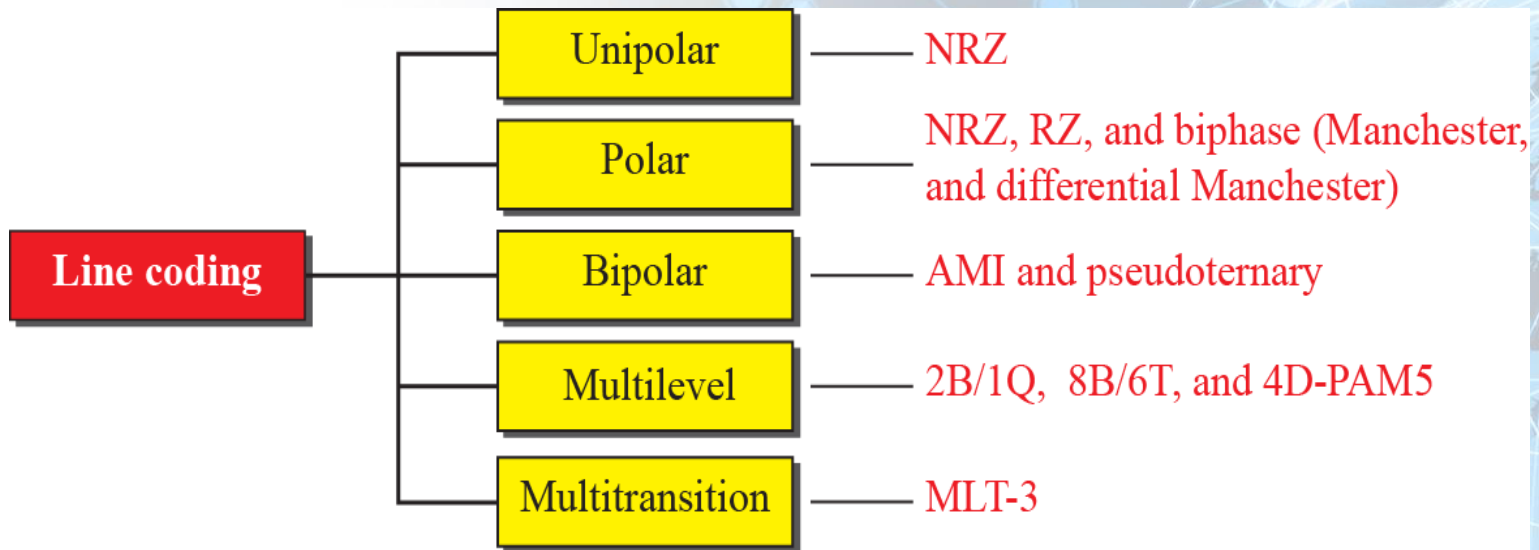
Polar schemes (RZ)



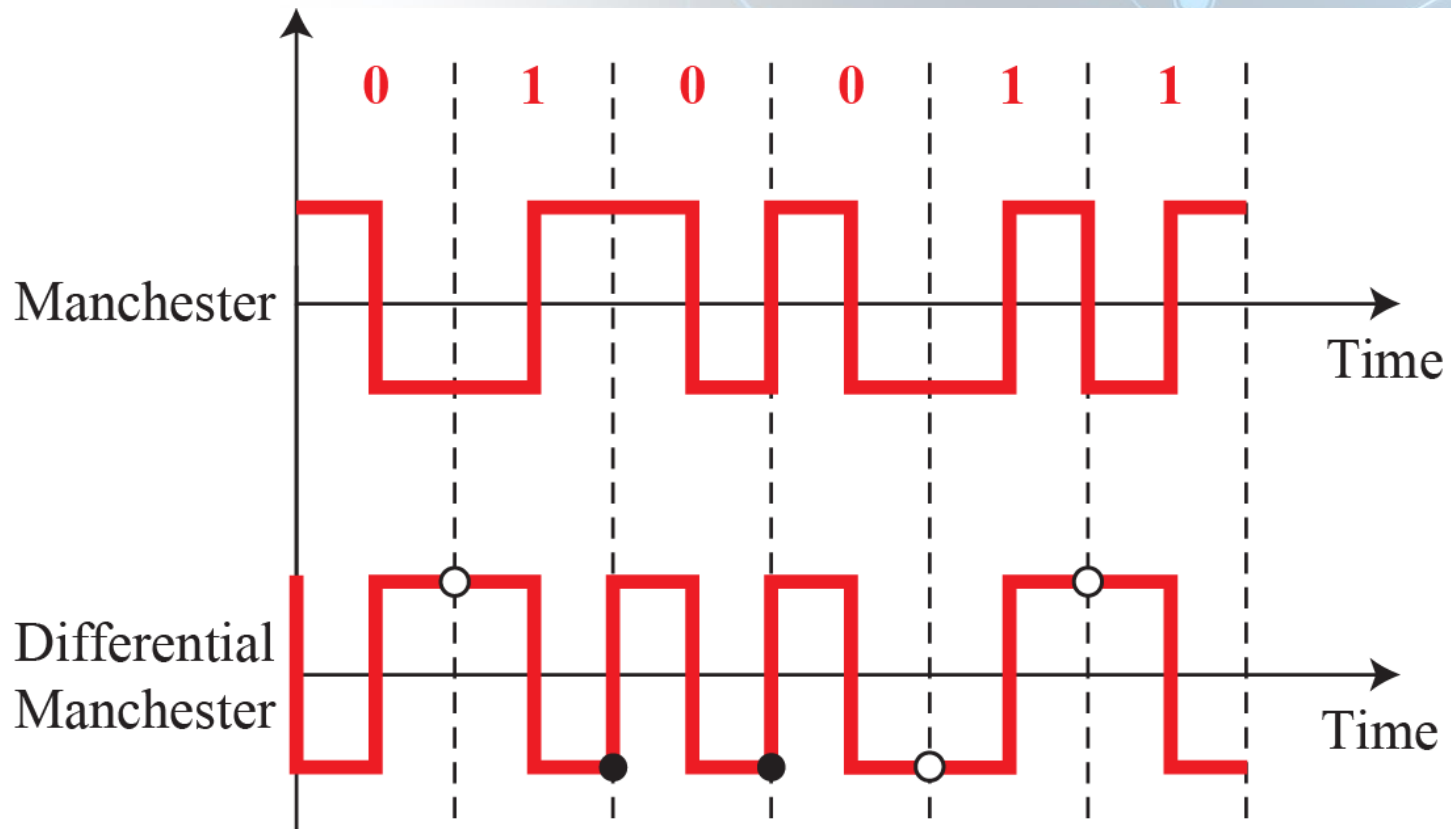
Line Coding Schemes

- We can roughly divide line coding schemes into five broad categories

Line Coding Schemes



Polar Biphasic

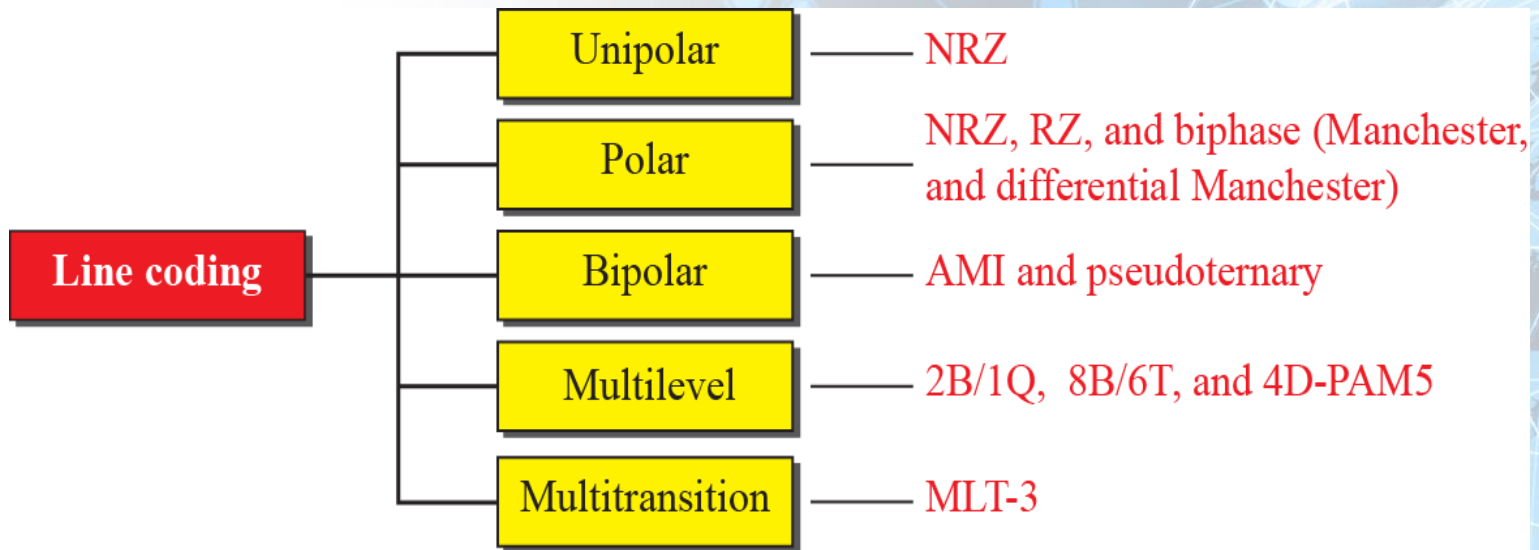


○ No inversion: Next bit is 1 ● Inversion: Next bit is 0

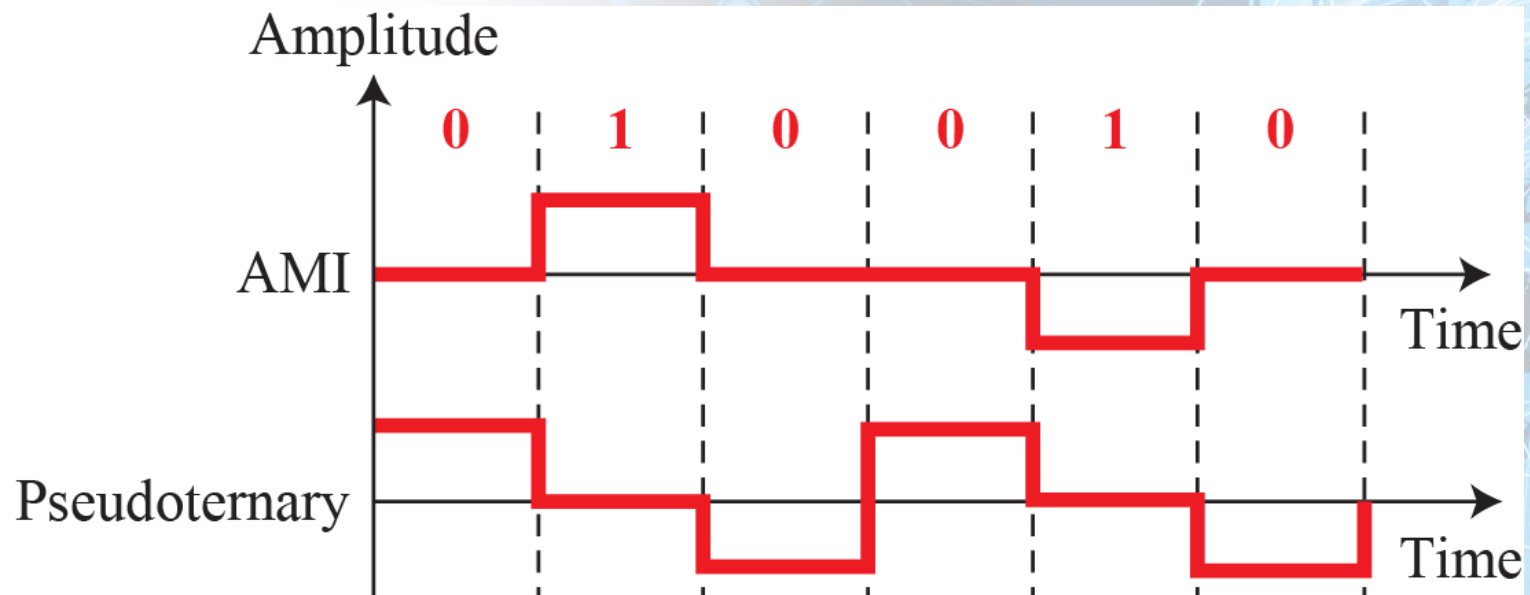
Line Coding Schemes

- We can roughly divide line coding schemes into five broad categories

Line Coding Schemes



Bipolar schemes: AMI & Pseudoternary



Multilevel: 2B1Q

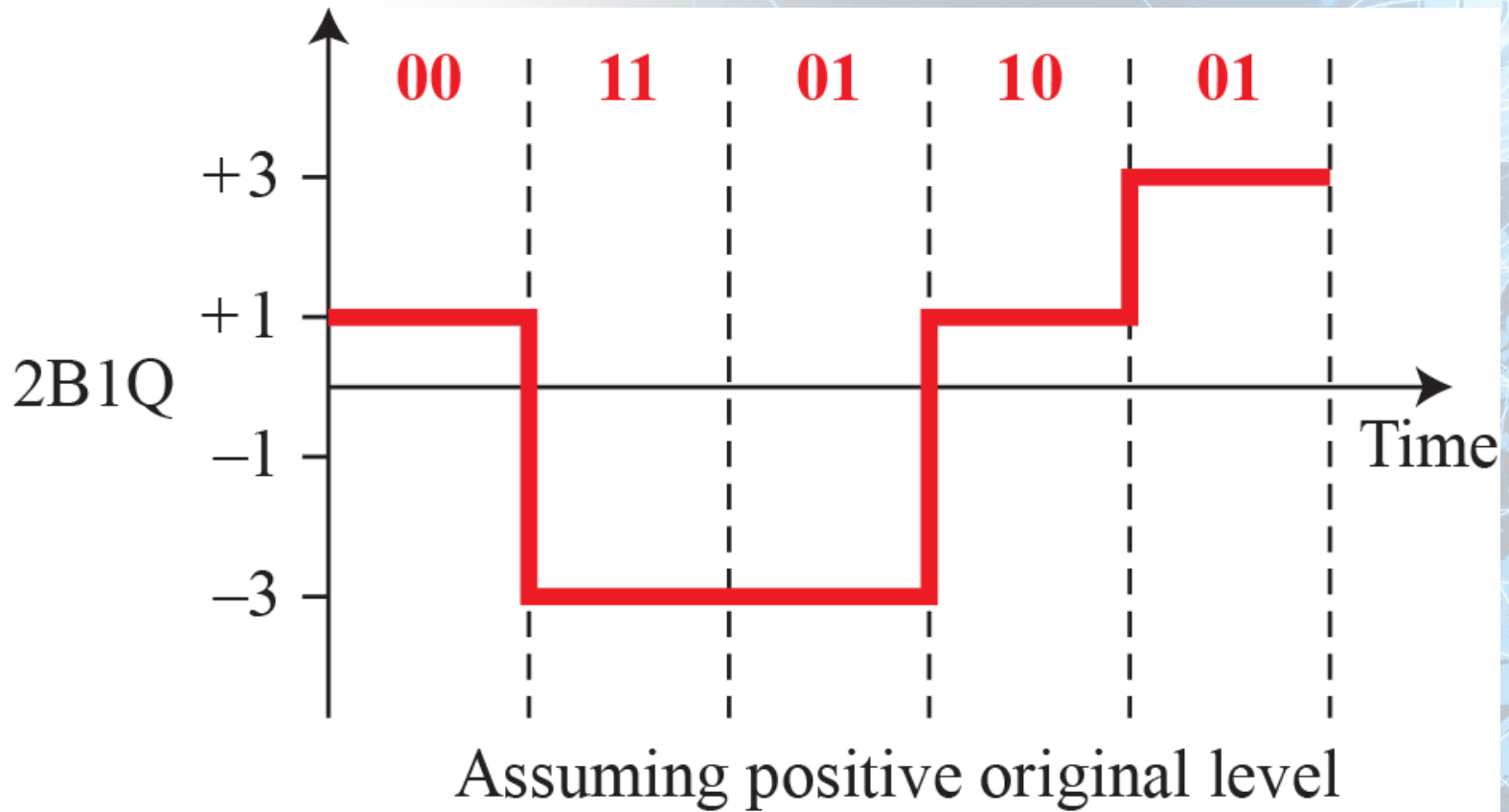


Table 4.1 : Summary of line coding schemes

<i>Category</i>	<i>Scheme</i>	<i>Bandwidth (average)</i>	<i>Characteristics</i>
Unipolar	NRZ	$B = N/2$	Costly, no self-synchronization if long 0s or 1s, DC
Polar	NRZ-L	$B = N/2$	No self-synchronization if long 0s or 1s, DC
	NRZ-I	$B = N/2$	No self-synchronization for long 0s, DC
	Biphase	$B = N$	Self-synchronization, no DC, high bandwidth
Bipolar	AMI	$B = N/2$	No self-synchronization for long 0s, DC
Multilevel	2B1Q	$B = N/4$	No self-synchronization for long same double bits
	8B6T	$B = 3N/4$	Self-synchronization, no DC
	4D-PAM5	$B = N/8$	Self-synchronization, no DC
Multitransition	MLT-3	$B = N/3$	No self-synchronization for long 0s

Block Coding

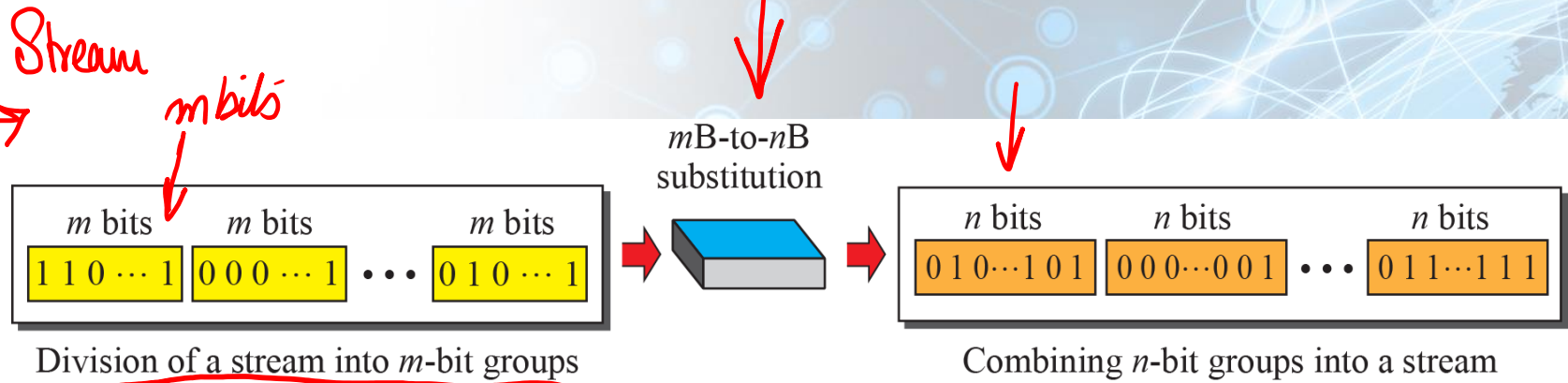
- **Block coding changes a block of 'm' bits into a block of 'n' bits ($n > m$)**
- **mB/nB encoding technique**
- **We need Redundancy to ensure Synchronization**
- **Block coding gives us redundancy and improves line coding performance**

Block coding concept

Division

Substitution

Combination



mB/nB

$n > m$

Redundant bits

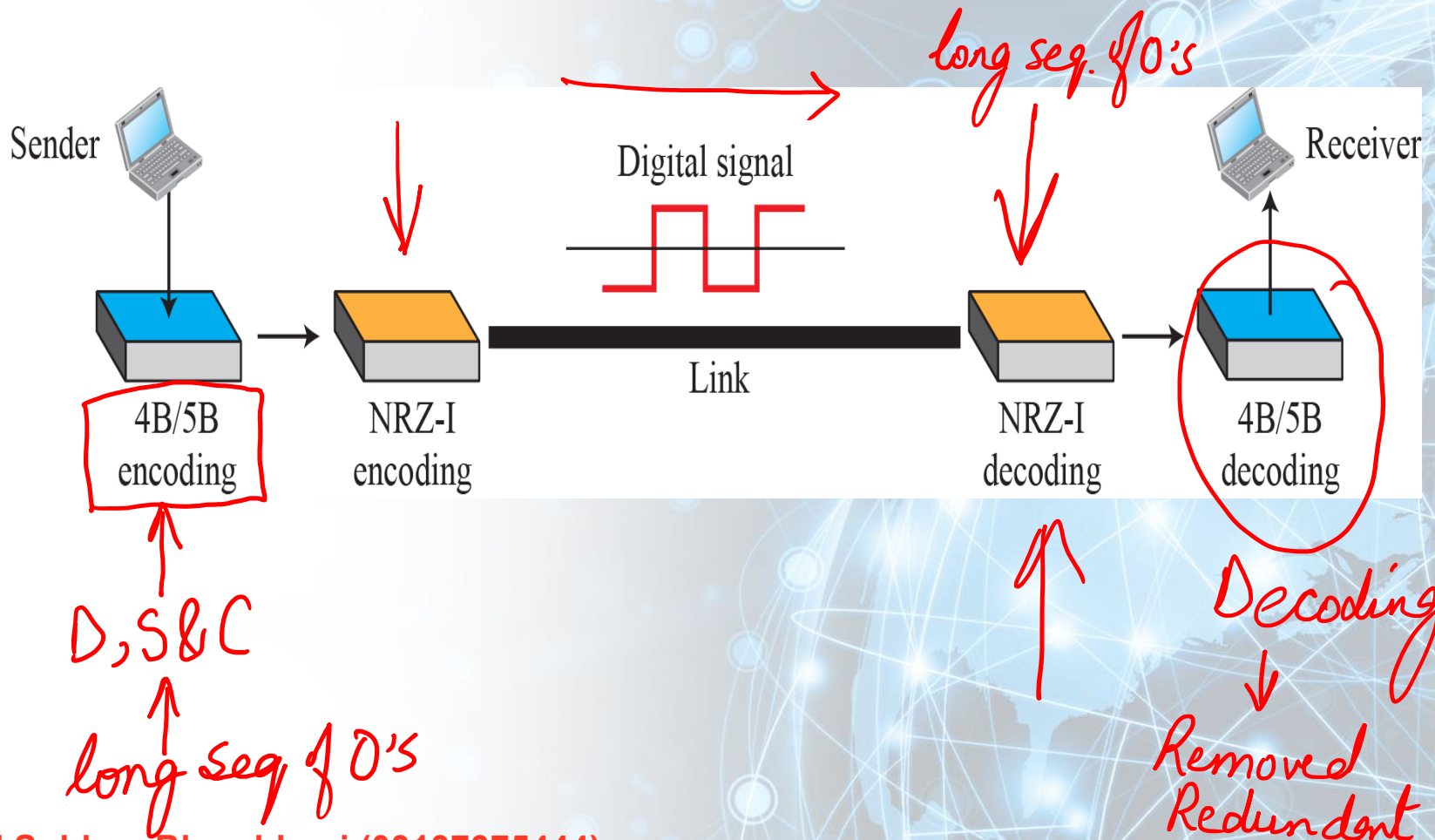
Redundancy

Block Coding

- **Block coding changes a block of 'm' bits into a block of 'n' bits ($n > m$)**
- **mB/nB encoding technique**
- **We need Redundancy to ensure Synchronization**
- **Block coding gives us redundancy and improves line coding performance**

Using block coding 4B/5B with NRZ-I line coding

$$4B/5B \Rightarrow m=4 \quad n=5 \quad (n > m)$$



Block Coding

- **Block coding changes a block of 'm' bits into a block of 'n' bits ($n > m$)**
- **mB/nB encoding technique**
- **We need Redundancy to ensure Synchronization**
- **Block coding gives us redundancy and improves line coding performance**

4B/5B mapping codes

$$2^4 = 16$$

$$2^5 = 32 \text{ groups}$$

1
2
3
.
.
.
.
.
.
.
.
.
.
.
.
.
16

Data Sequence	Encoded Sequence	Control Sequence	Encoded Sequence
<u>0000</u>	<u>11110</u>	✓ Q (Quiet)	00000
0001	01001	✓ I (Idle)	11111
0010	10100	✓ H (Halt)	00100
0011	10101	✓ J (Start delimiter)	11000
0100	01010	✓ K (Start delimiter)	10001
0101	01011	T (End delimiter)	01101
0110	01110	S (Set)	11001
0111	01111	R (Reset)	00111
1000	10010		
1001	10011		
1010	10110		
1011	10111		
1100	11010		
1101	11011		
1110	11100		
1111	11101		



Block Coding

- **Block coding changes a block of 'm' bits into a block of 'n' bits ($n > m$)**
- **mB/nB encoding technique**
- **We need Redundancy to ensure Synchronization**
- **Block coding gives us redundancy and improves line coding performance**

Example

We need to send data at a 1-Mbps rate. What is the minimum required bandwidth, using a combination of 4B/5B and NRZ-I or Manchester coding?

$$\text{NRZ-I} = \frac{N}{2} = \frac{1.25 \text{ Mbps}}{2} = 625 \text{ kHz}$$

$$\text{Manchester} \Rightarrow 1 \text{ MHz}$$

Data Rate = 1 Mbps
4B/5B Block Coding
↳ 4 bit group ↔ 5 bit group
Data Rate = 1.25 Mbps

Signal Rate ↑

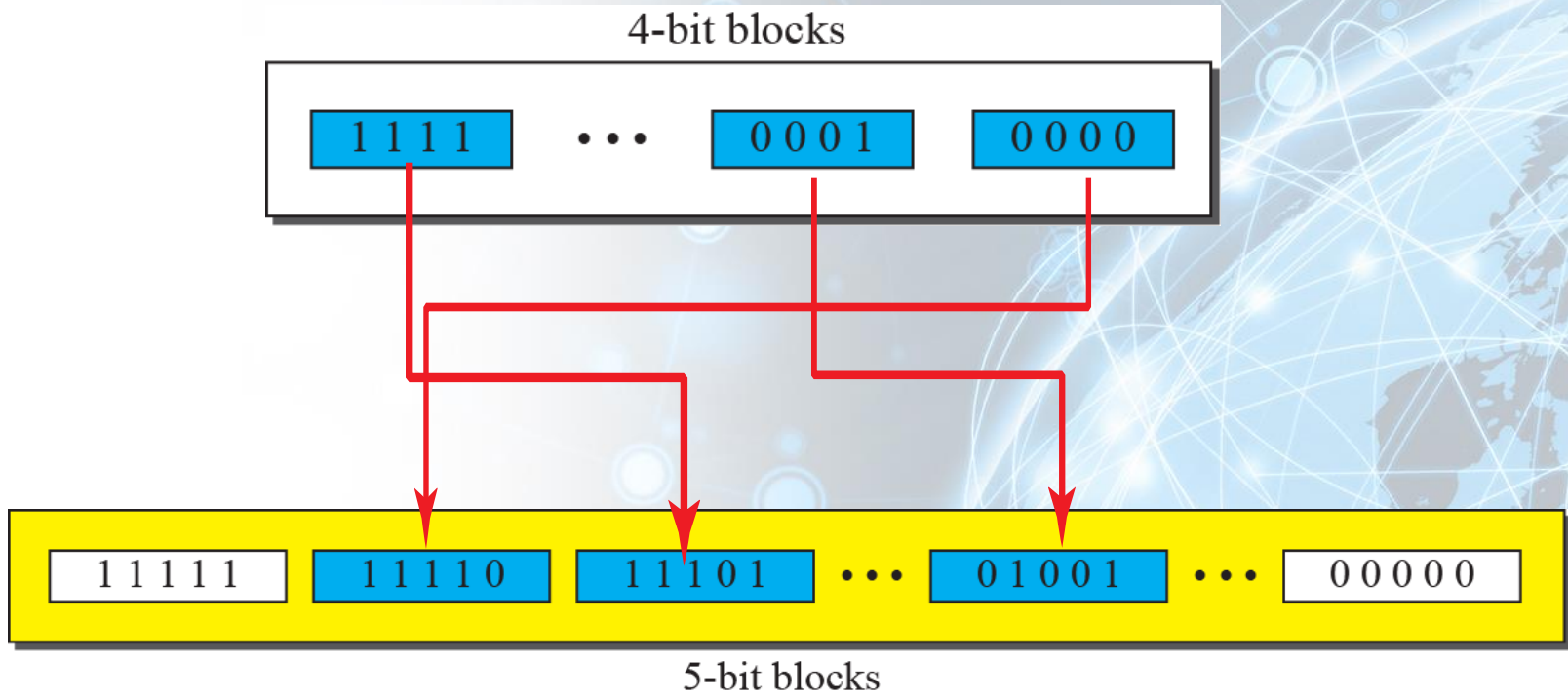
Synchronisation ⇒ ✓

Signal Rate ↑ ⇒ BW ↑ ✓

$BW_{\text{NRZ-I}} < BW_{\text{Manchester}}$

DC - component X

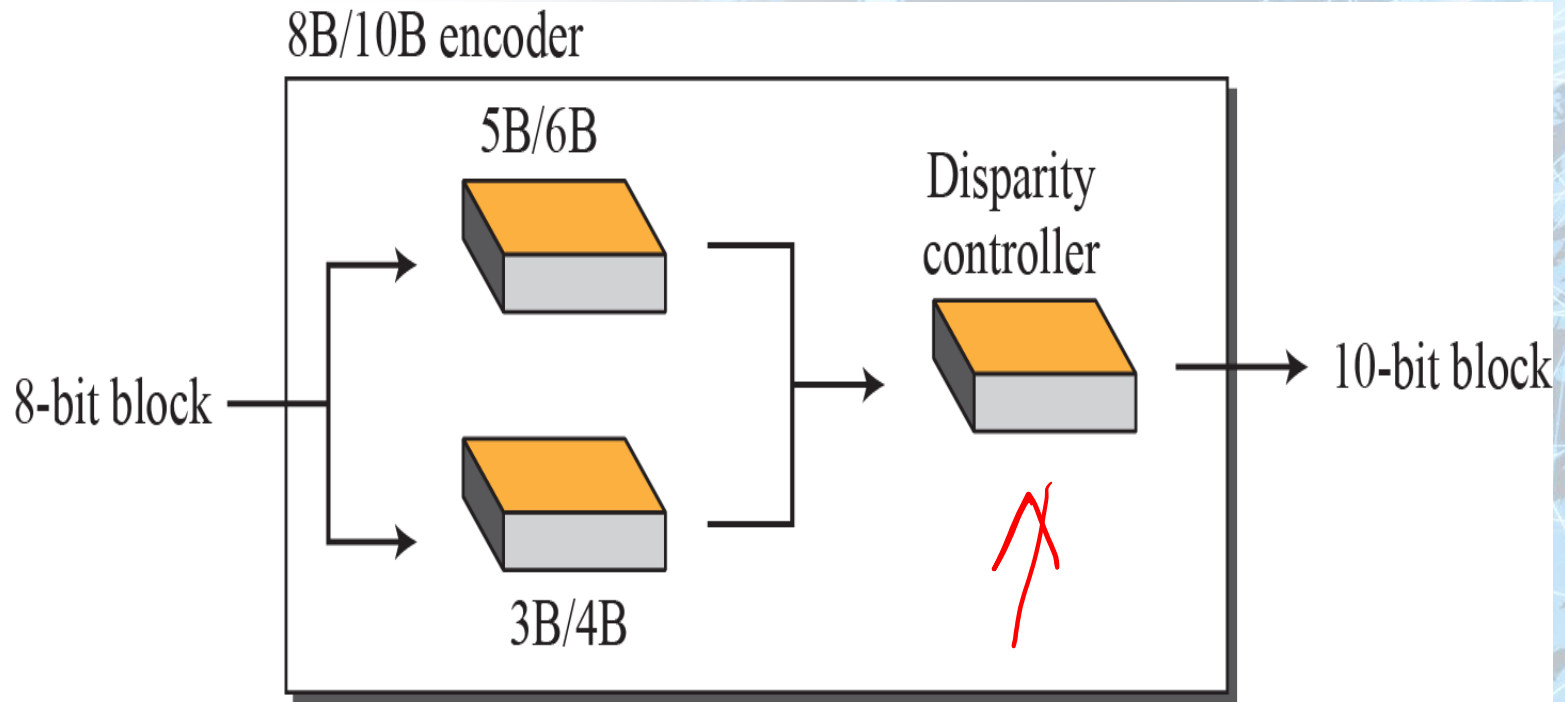
Example



8B/10B block encoding

$m=8$

$n=10$



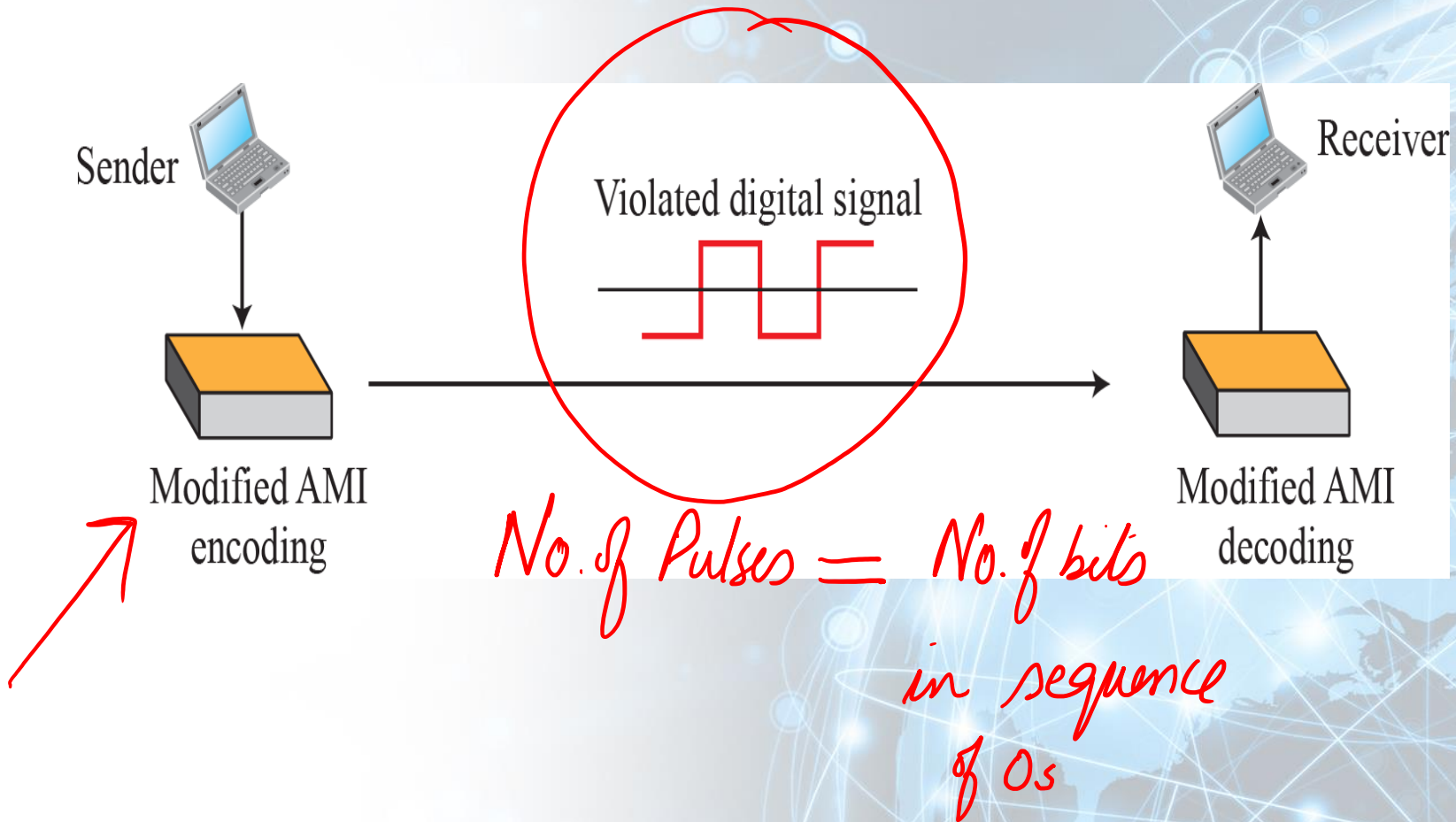
Scrambling

- **Biphase schemes suitable for LAN but not for Long Distance**
- **Block Coding + NRZ-I solves synch issue but has DC component**
- **Bipolar AMI has a narrow bandwidth (no DC Component) but synch issue (long series of 0s)**

Scrambling

- **The system needs to insert the required pulses based on the defined scrambling rules**

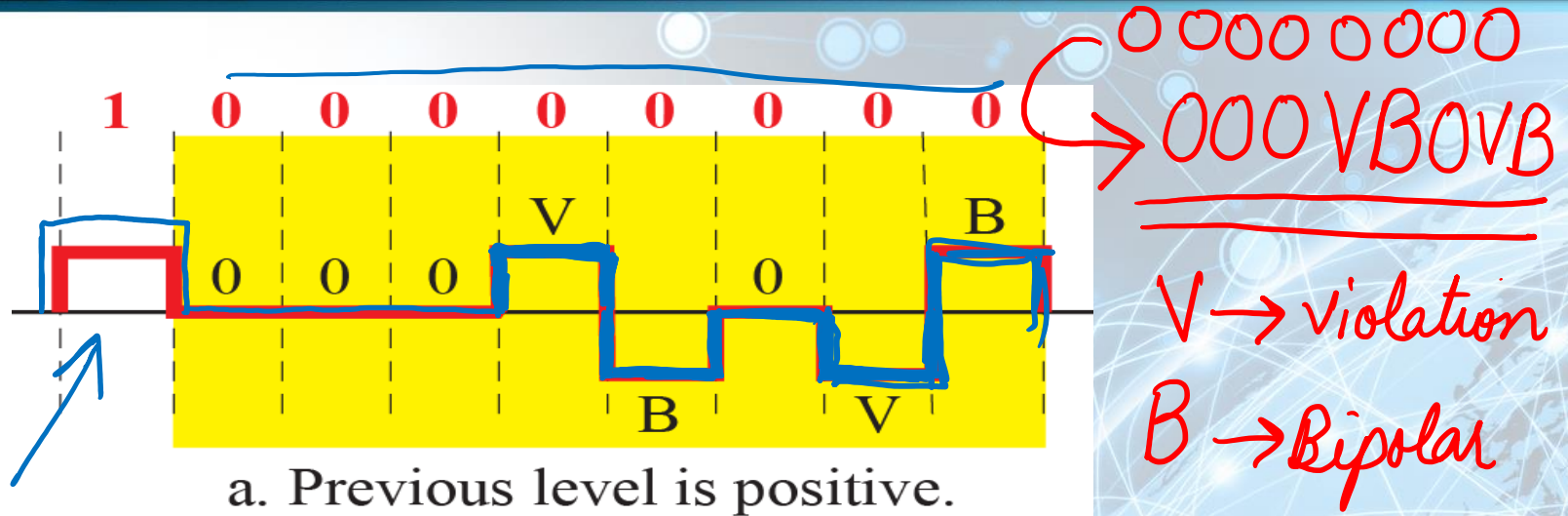
AMI used with scrambling



Types of Scrambling Techniques

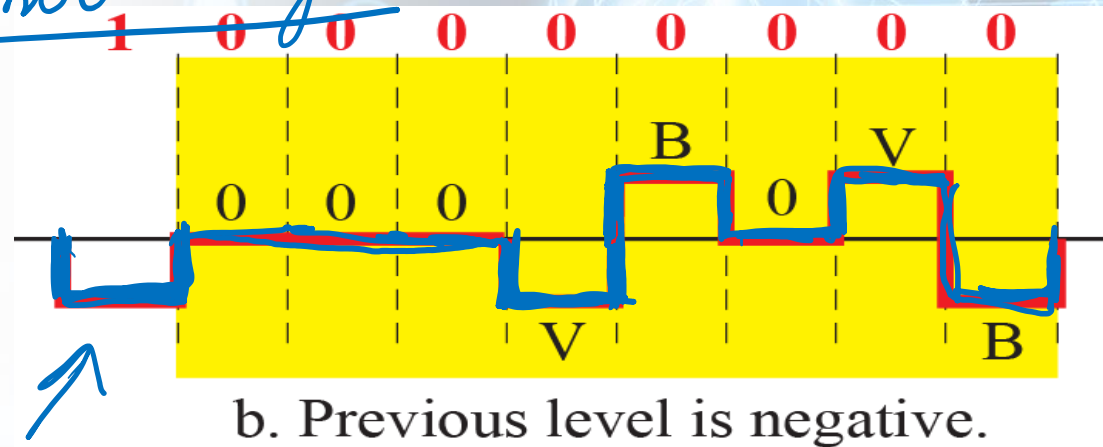
- **Two common scrambling techniques are B8ZS and HDB3**
- **Bipolar with 8-Zero Substitution (B8ZS)**
- **High-density bipolar 3-zero (HDB3)**

Two cases of B8ZS scrambling technique



Bit Rate does not change

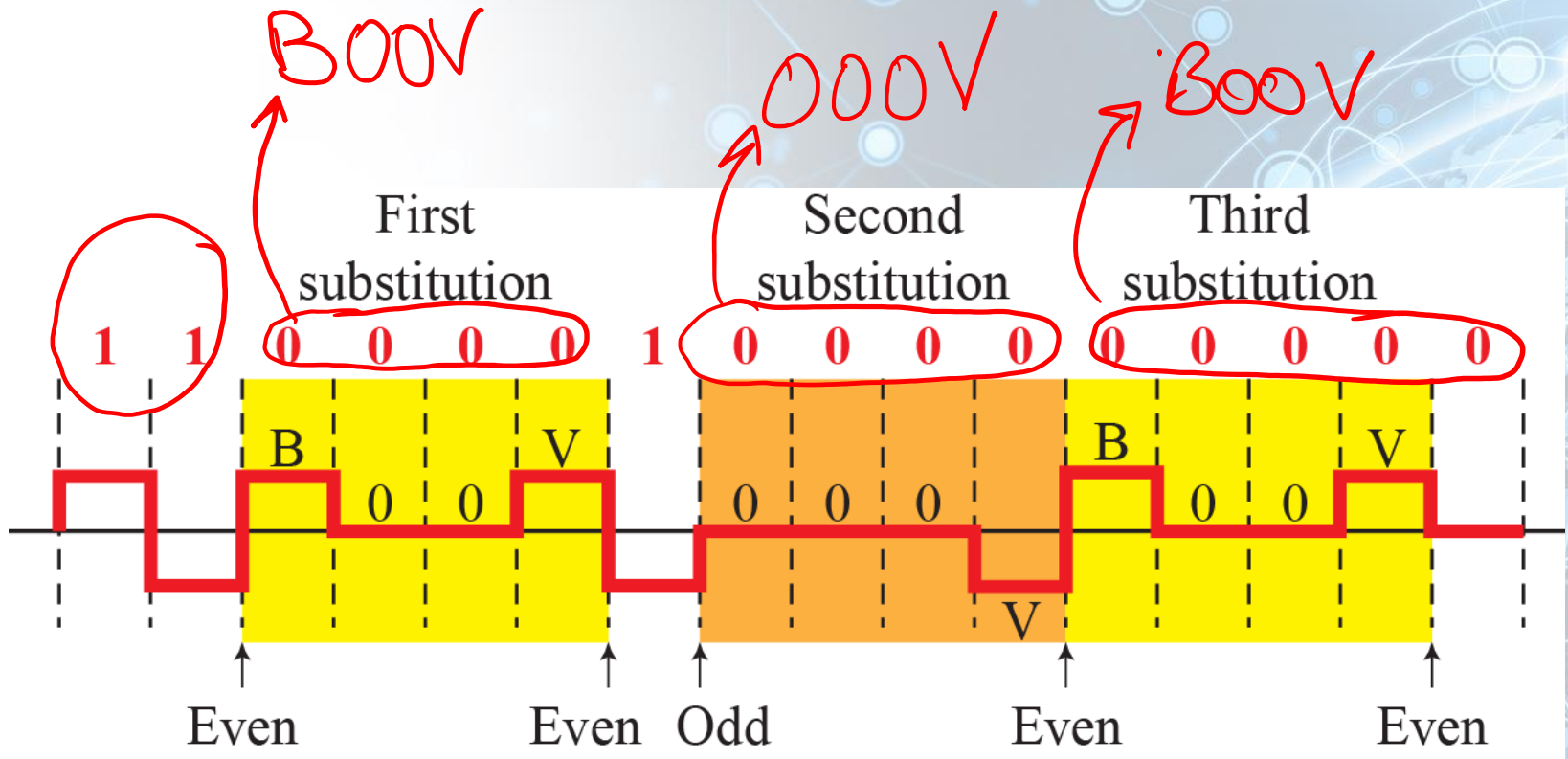
DC Balance



Types of Scrambling Techniques

- **Two common scrambling techniques are B8ZS and HDB3**
- **Bipolar with 8-Zero Substitution (B8ZS)**
- **High-density bipolar 3-zero (HDB3)**

Different situations in HDB3 scrambling technique



Rule 1: Non-zero pulses \rightarrow odd

Rule 2: Non-zero pulses \rightarrow even

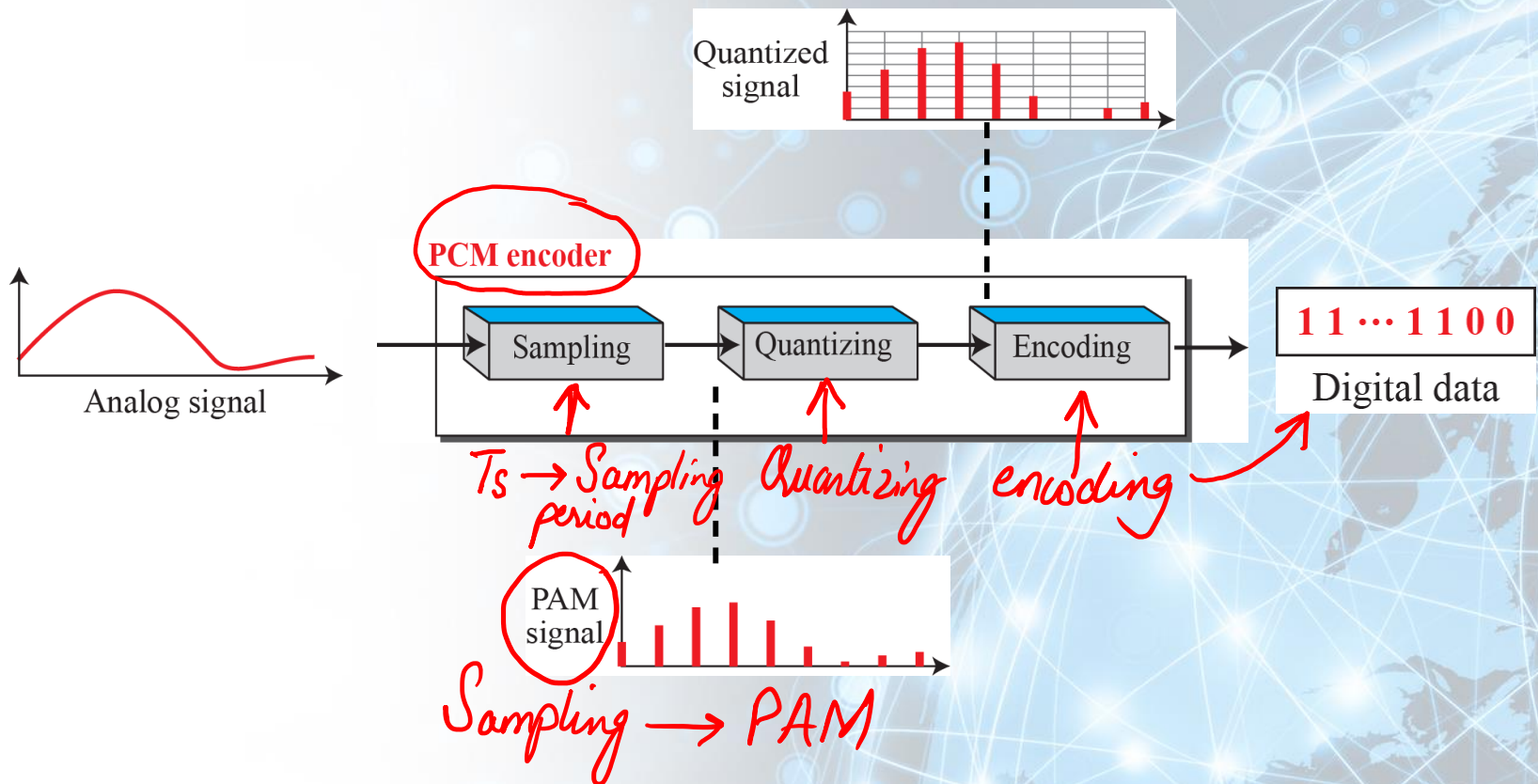
0000 \rightarrow 000V

0000 \rightarrow BOOV

Analog-to-digital Conversion

- **Analog Data to Digital Data**
- **Process of Digitization**
- **Two techniques:**
 - ✓ **Pulse Code Modulation (PCM)**
 - ✓ **Delta Modulation (DM)**

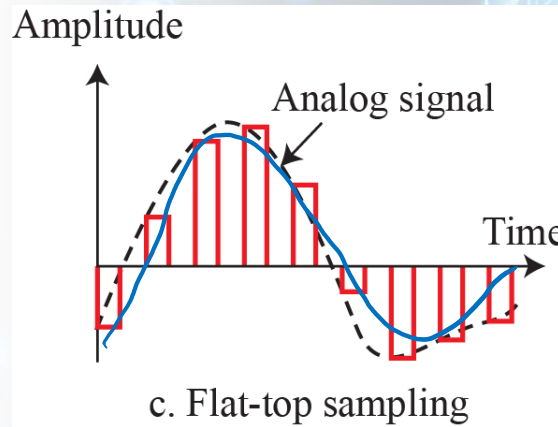
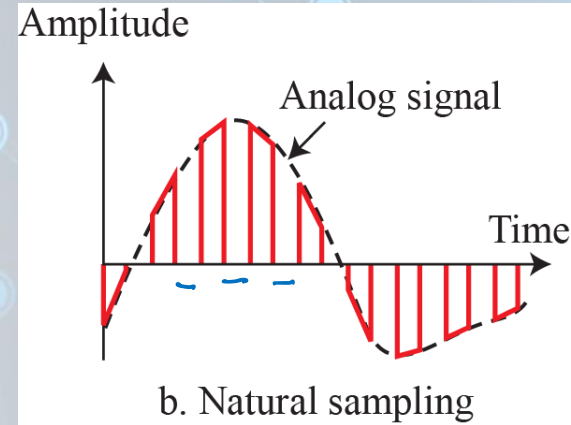
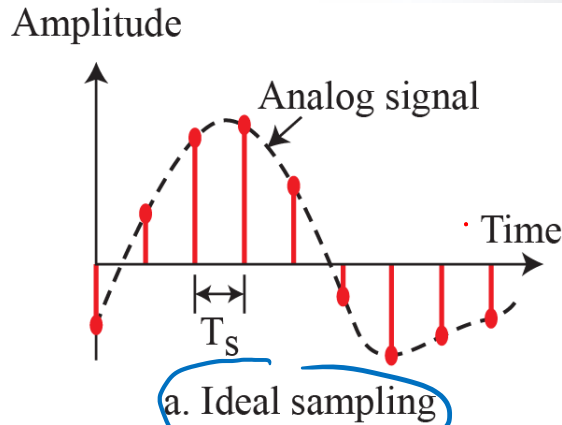
Pulse Code Modulation (PCM)



Pulse Code Modulation (PCM)

- Sampling
- Quantization
- Encoding

Three different sampling methods for PCM



Sampling
↳ Pulse
Amplitude
Modulation

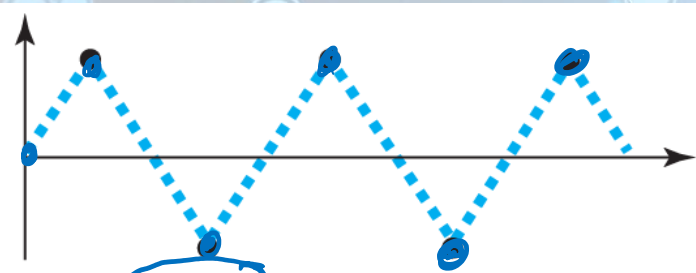
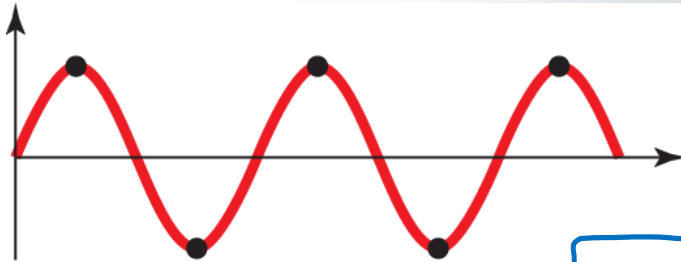
T_s → Sampled
interval
or
Sample
period

Sample and Hold

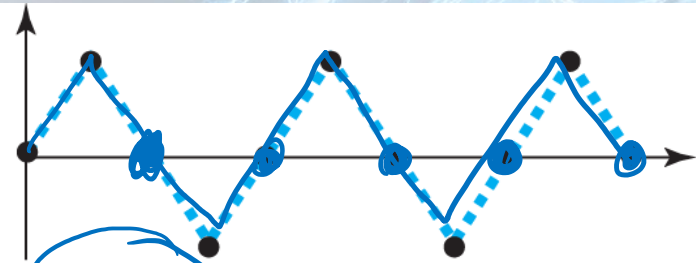
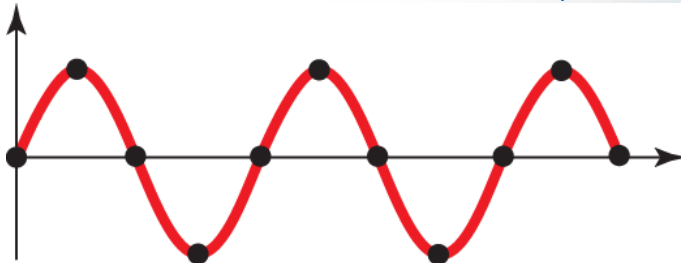
Nyquist Sampling Rate

- Nyquist $\rightarrow f_s = 2f_h$
- Sampling sine wave at three sampling rates:
 - ✓ $f_s = 4f$ (2 times the Nyquist rate)
 - ✓ $f_s = 2f$ (Nyquist rate)
 - ✓ $f_s = f$ (one-half the Nyquist rate)

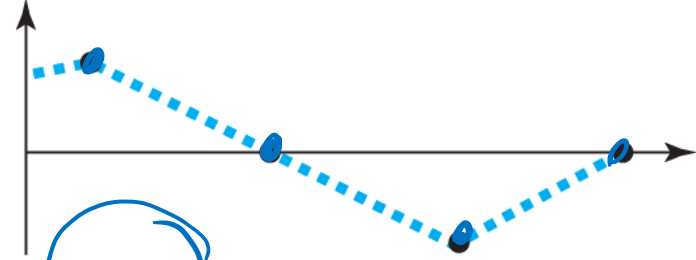
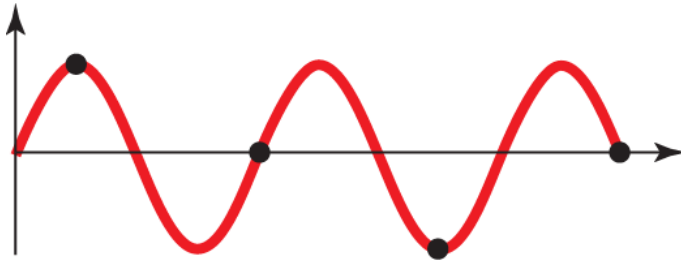
Nyquist Sampling Rate



a. Nyquist rate sampling: $f_s = 2 f$



b. Oversampling: $f_s = 4 f$ *Double Nyquist rate*

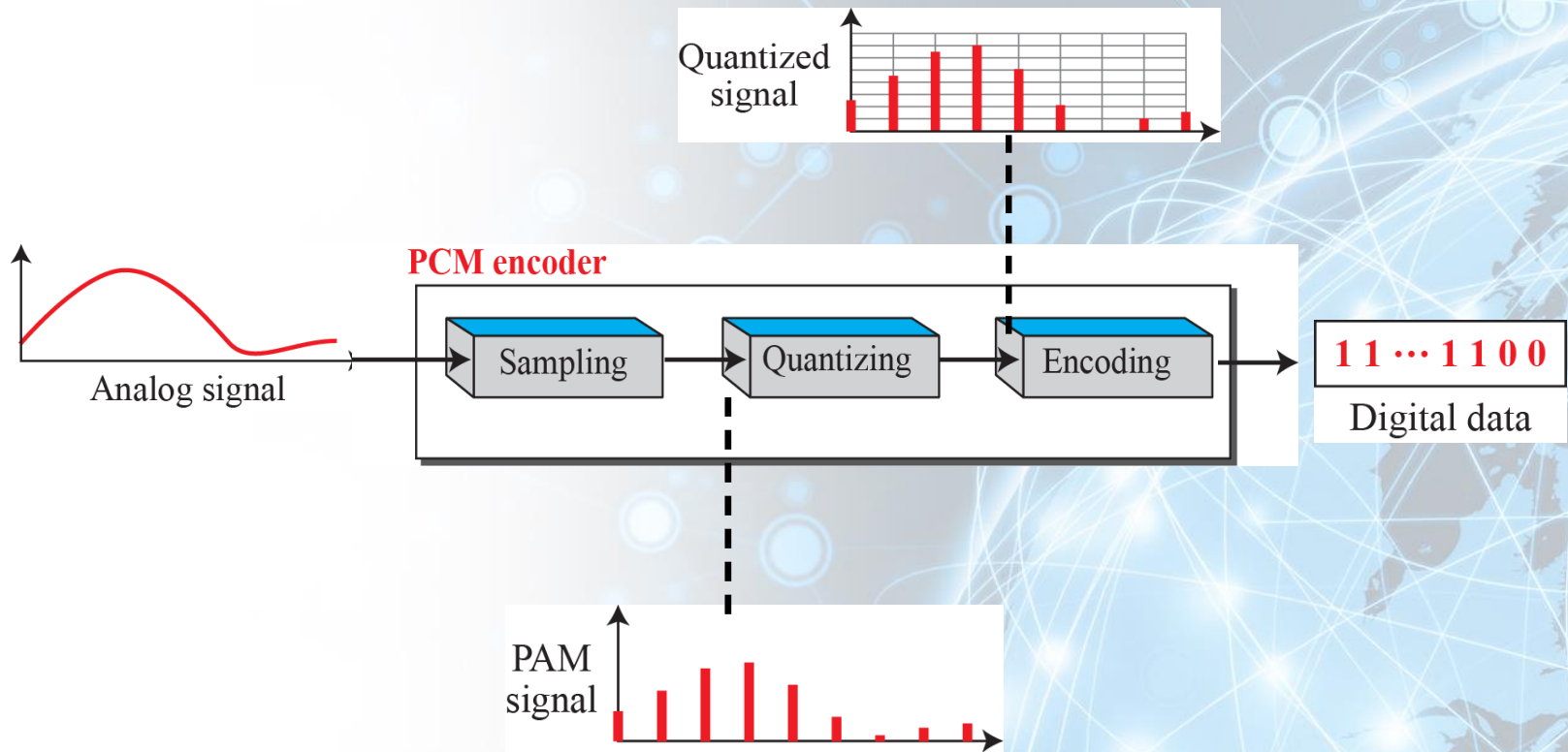


c. Undersampling: $f_s = f$ *Half the Nyquist rate*

Pulse Code Modulation (PCM)

- **Most common technique**
- **Employs a PCM Encoder**
- **A PCM encoder has three processes:**
 - ✓ **Sampling**
 - ✓ **Quantization**
 - ✓ **Encoding**

Components of PCM encoder



Pulse Code Modulation (PCM)

- **Sampling**
- **Quantization**
- **Encoding**

Quantization & encoding of a sampled signal

- Sampling → Series of pulses with amplitude values between min and max signal amplitude
- Infinite set with non-integral values not suitable for encoding
- We quantize the sampling output into certain levels based on range of amplitudes and how much accuracy is needed

Quantization & encoding of a sampled signal

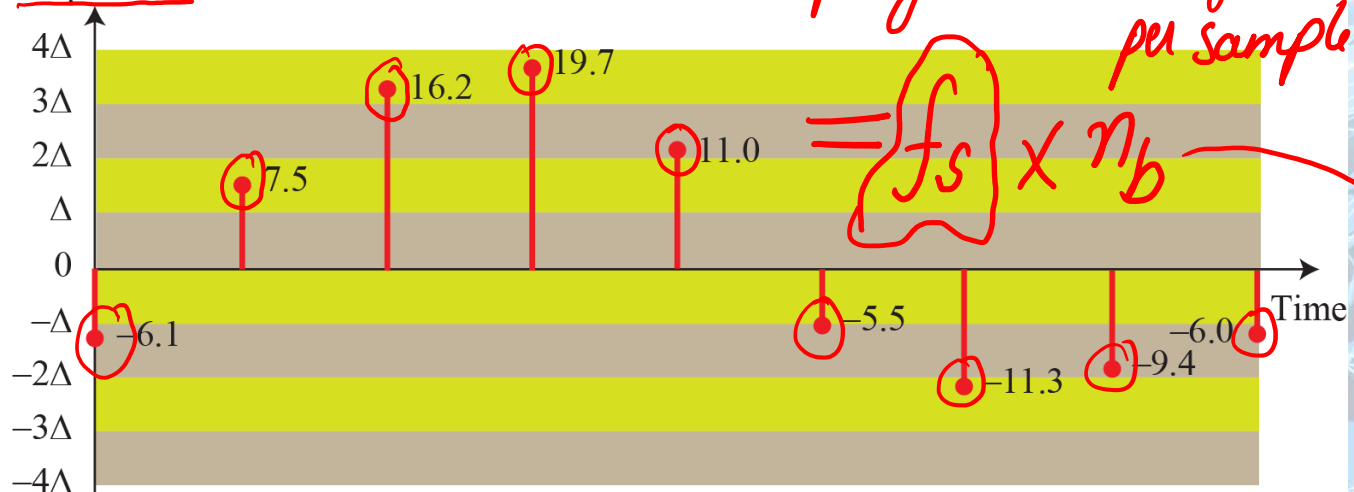
Bit Rate = Sampling rate \times No. of bits per sample

$= f_s \times n_b$

Quantization codes

- 7
- 6
- 5
- 4
- 3
- 2
- 1
- 0

Normalized amplitude



Normalized PAM values

-1.22 1.50 3.24 3.94 2.20 -1.10 -2.26 -1.88 -1.20

Normalized quantized values

-1.50 1.50 3.50 3.50 2.50 -1.50 -2.50 -1.50 -1.50

Normalized error

-0.28 0 +0.26 -0.44 +0.30 -0.40 -0.24 +0.38 -0.30

Quantization code

2 5 7 7 6 2 1 2 2

Encoded words

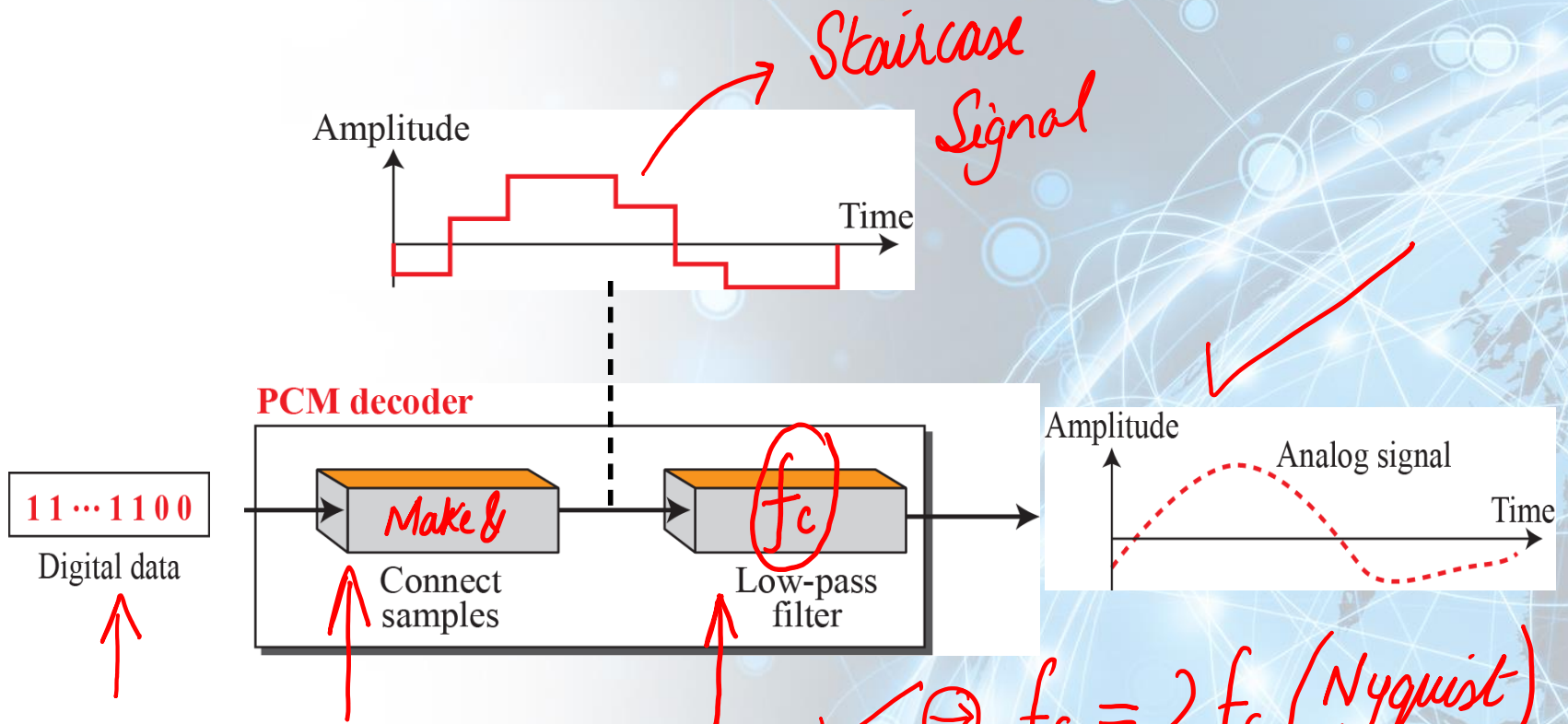
010 101 111 111 110 010 001 010 010

$n_b = \log_2 L$ $L \rightarrow$ Quantization Level.

Pulse Code Modulation (PCM)

- **Encoding**
 - ✓ **Sampling**
 - ✓ **Quantization**
 - ✓ **Encoding**
- **Decoding**

Original Signal Recovery- PCM Decoder



- ✓ $\Rightarrow f_s = 2f_c$ (Nyquist Rate)
- ✓ $\Rightarrow L \rightarrow$ Quantization Levels
- ✓ \Rightarrow Amplification

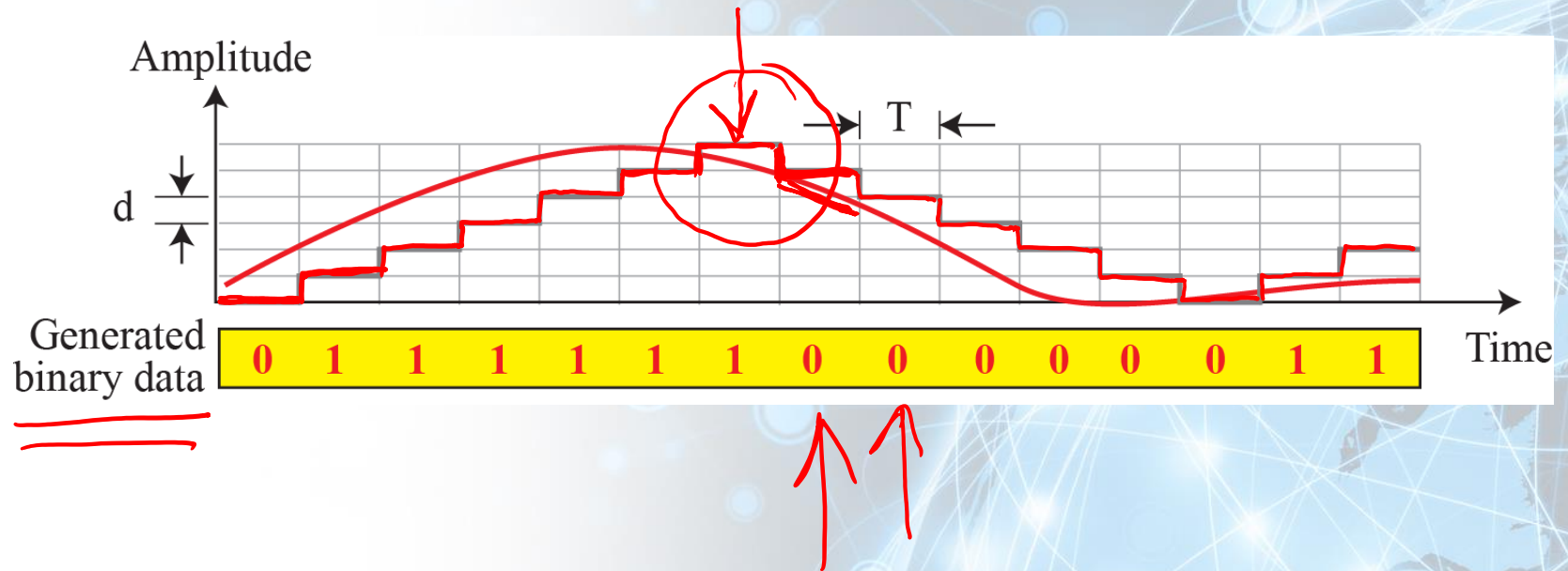
Analog-to-digital Conversion

- **Analog Data to Digital Data**
- **Process of Digitization**
- **Two techniques:**
 - ✓ **Pulse Code Modulation (PCM)**
 - ✓ **Delta Modulation (DM)**

Delta Modulation (DM)

- PCM is a very complex technique
- Delta modulation is a simpler technique
- PCM finds the value of the signal amplitude for each sample; DM finds the change from the previous sample
- No code words

The process of delta modulation

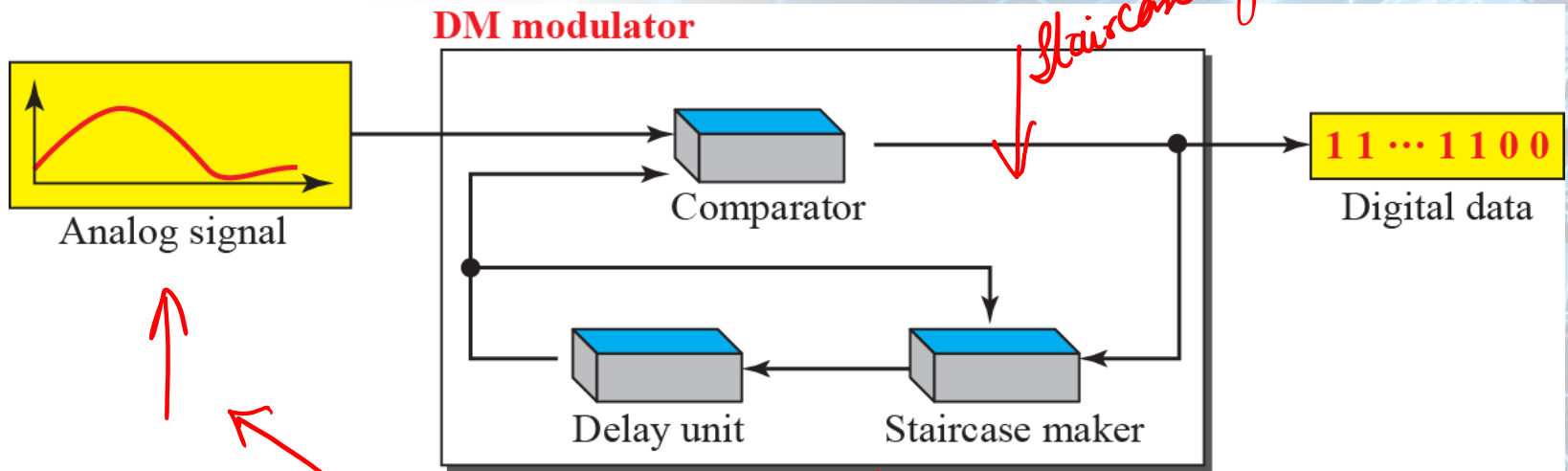


Delta Modulation (DM)

- Delta modulation is a simpler technique
- DM finds the change from the previous sample
- No code words

Delta Modulation Components

Delta $\rightarrow \delta$ $+\delta \rightarrow 1$
 $-\delta \rightarrow 0$

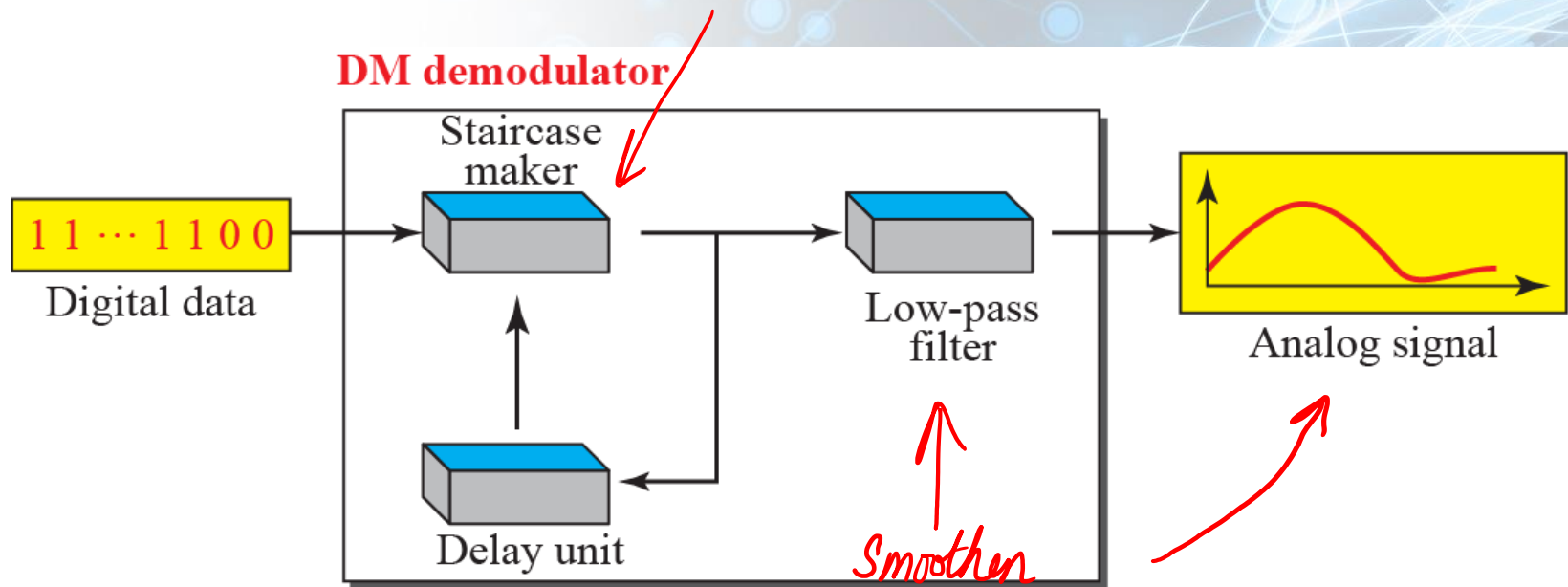


Compare
↳ Comparator

Staircase signal

Delta Demodulation Components

Adaptive DM $\rightarrow \delta$ is not fixed \rightarrow Performance \uparrow

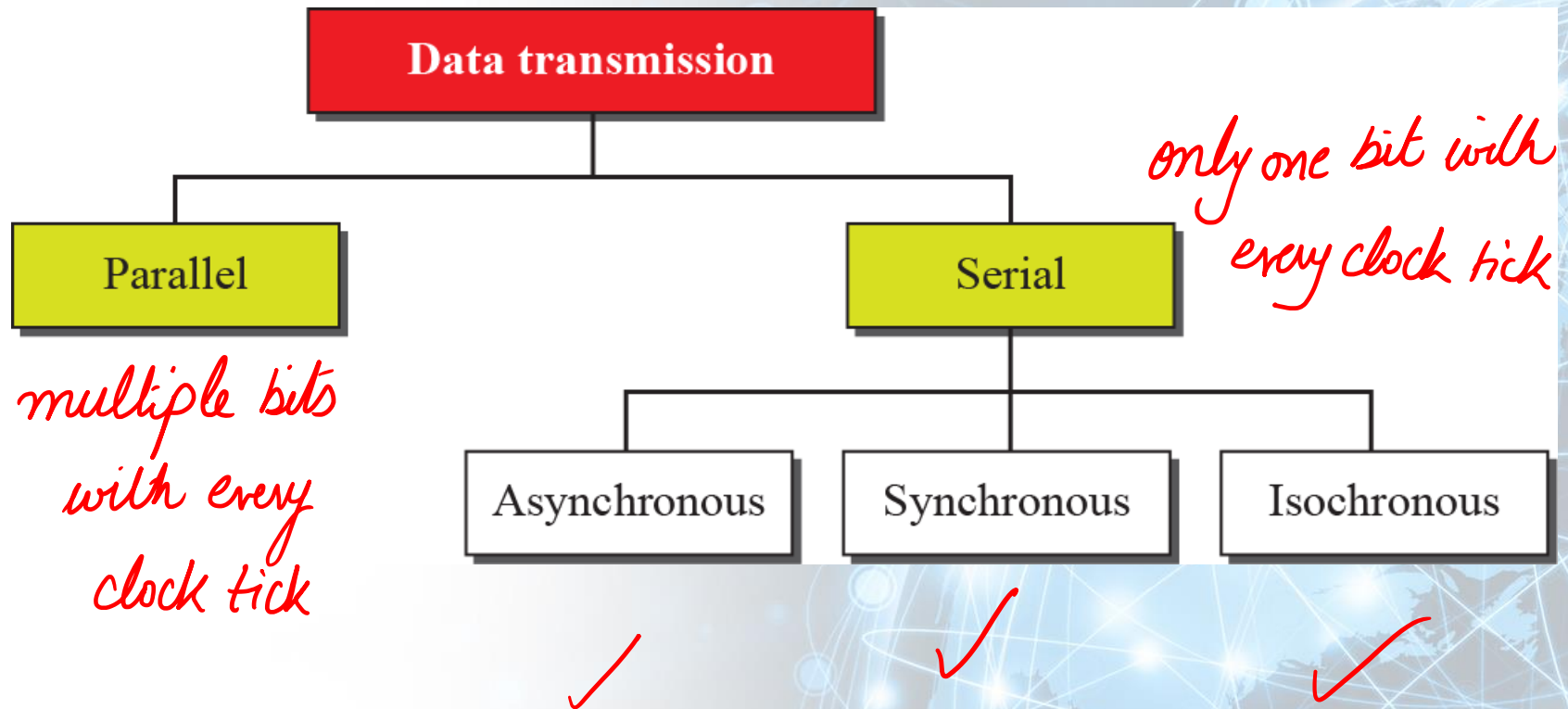


Quantization Error (QE)
 $QE_{DM} < QE_{PCM}$

Transmission Modes

- **Transmission of Data:**
 - ✓ **Wiring**
 - **Data Stream**
- **Do we send 1 bit at a time; or do we group bits into larger groups and, if so, how?**
- **Parallel or Serial Transmission**

Data transmission modes

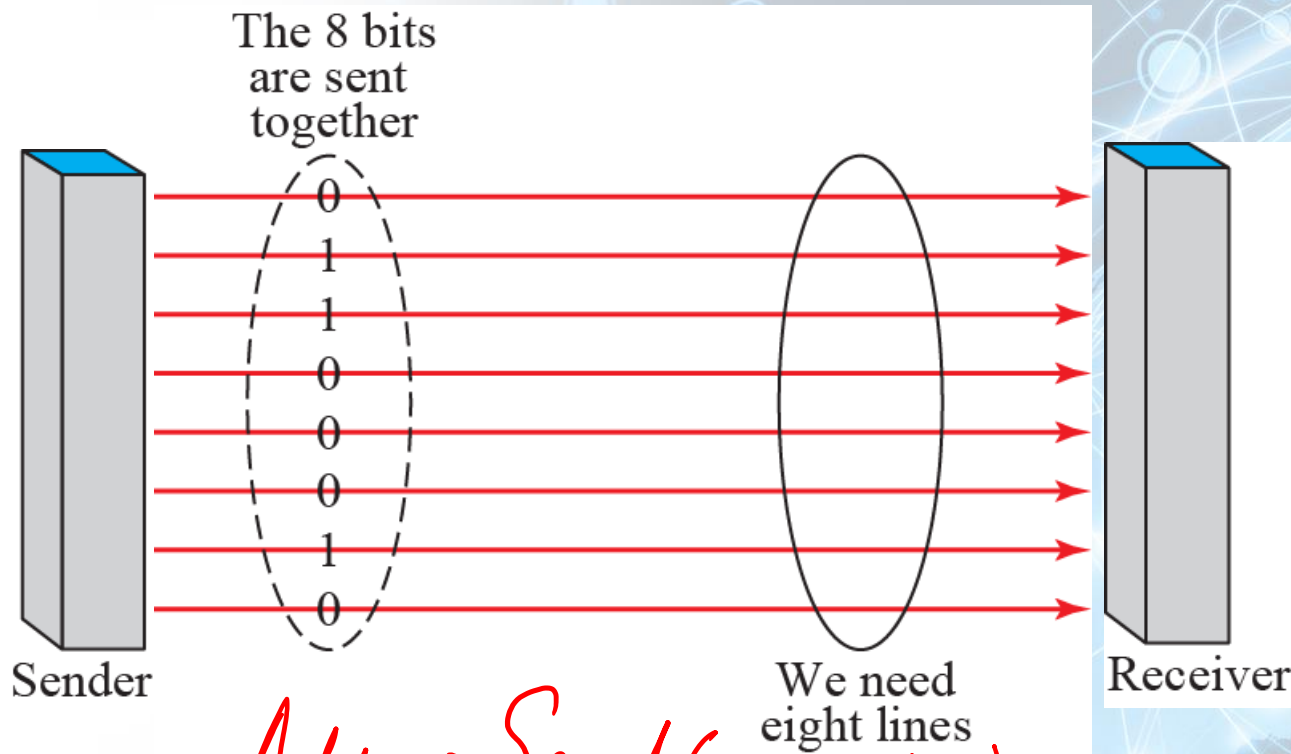


Parallel Transmission

- Binary data (1s and 0s) organized in groups of 'n' bits
- We send 'n' bits at a time instead of just one
- 'n' wires required to send 'n' bits at one time

Parallel Transmission

$$n = 8$$



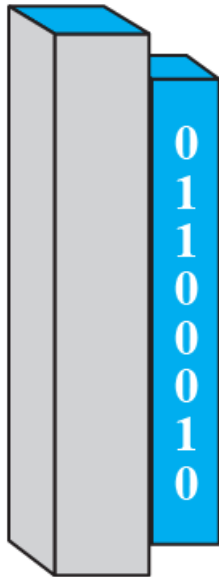
Adv → Speed (factor of n)
Disadv → Cost (n wires) → Short Distances

Serial Transmission

- In serial transmission one bit follows another
- Only one communication channel rather than 'n' to transmit data

Serial Transmission

Parallel serial
converter



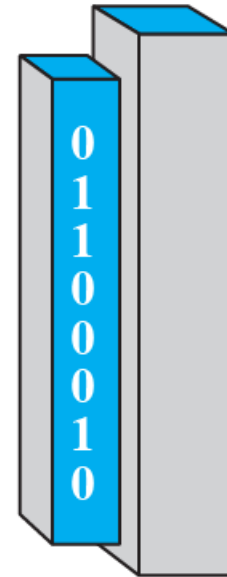
Sender

The 8 bits are sent
one after another.

0 1 1 0 0 0 1 0

We need only
one line (wire).

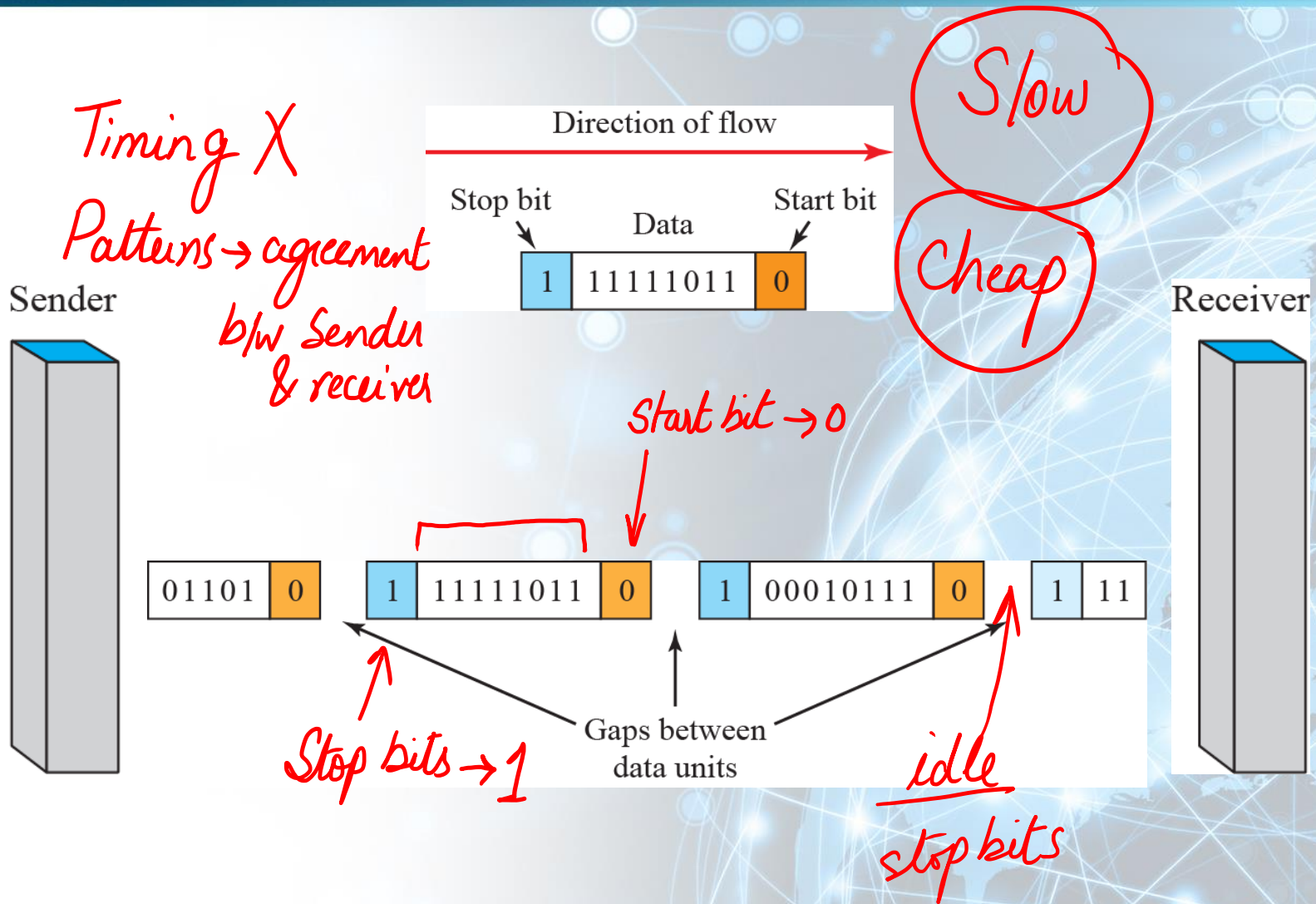
Serial/parallel
converter



Receiver

Adv → Cost (n) ↓
Disadv → Speed ↓

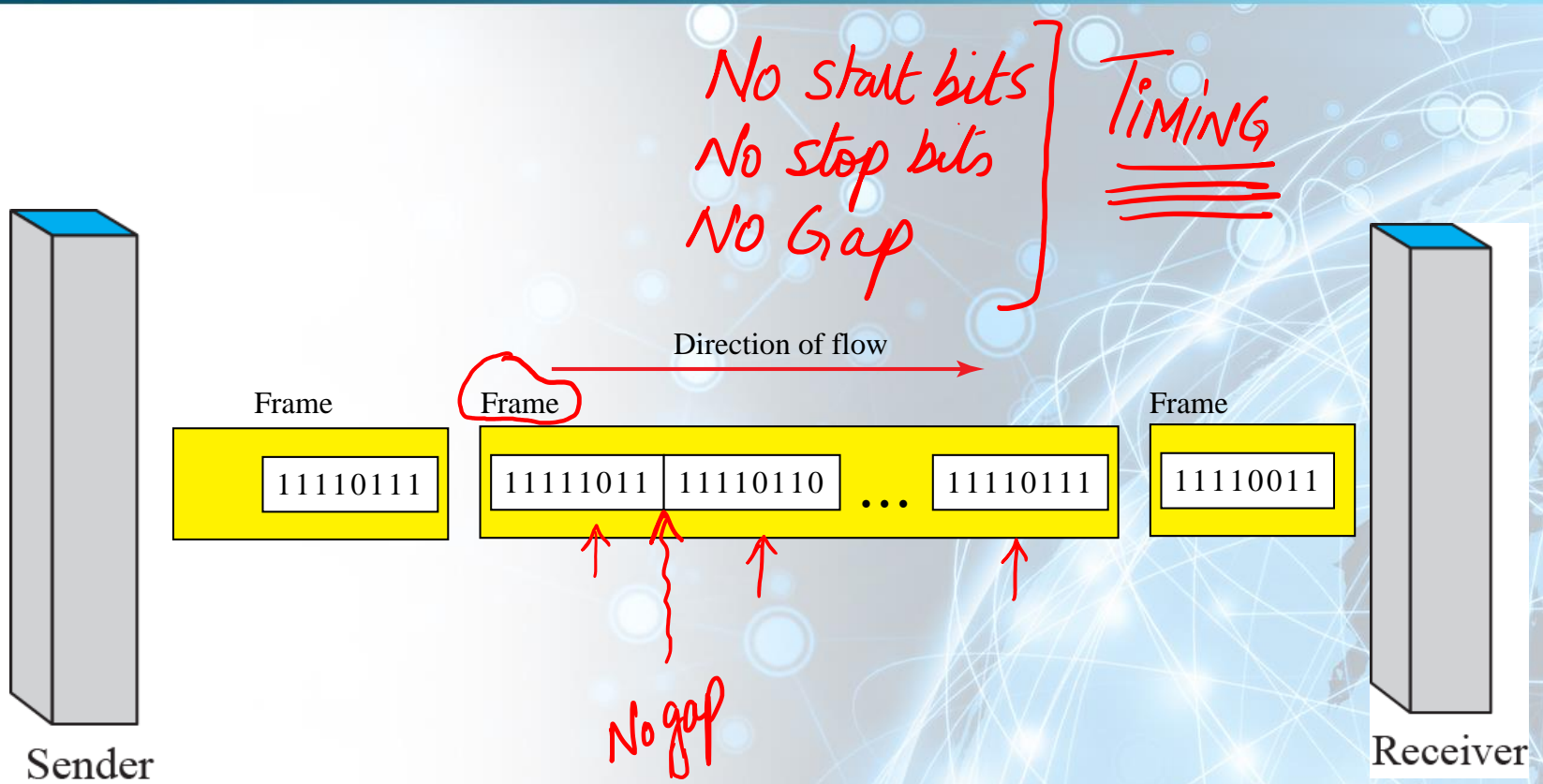
Asynchronous Transmission



Serial Transmission

- In serial transmission one bit follows another
- Only one communication channel rather than 'n' to transmit data

Synchronous Transmission



Adv → Speed

Accurate count of bits

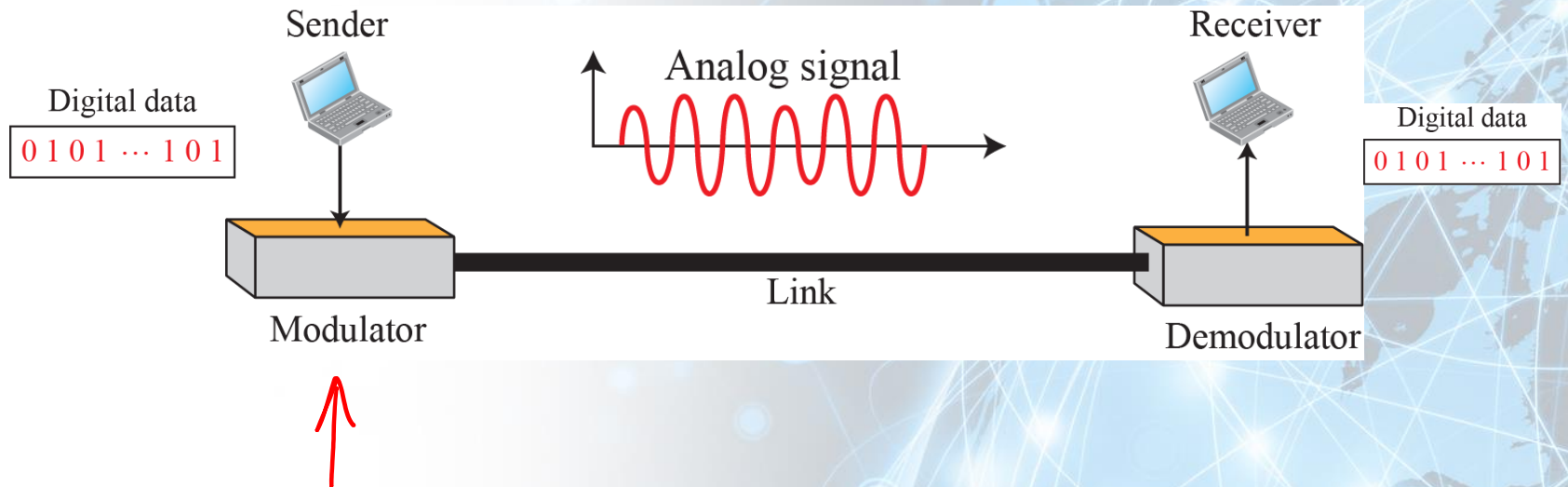
Isochronous Transmission

- **Real time Audio and Video**
- **Synchronization between characters is not enough**
- **Entire stream should be synchronized**
- **Isochronous guarantees fixed rate data**

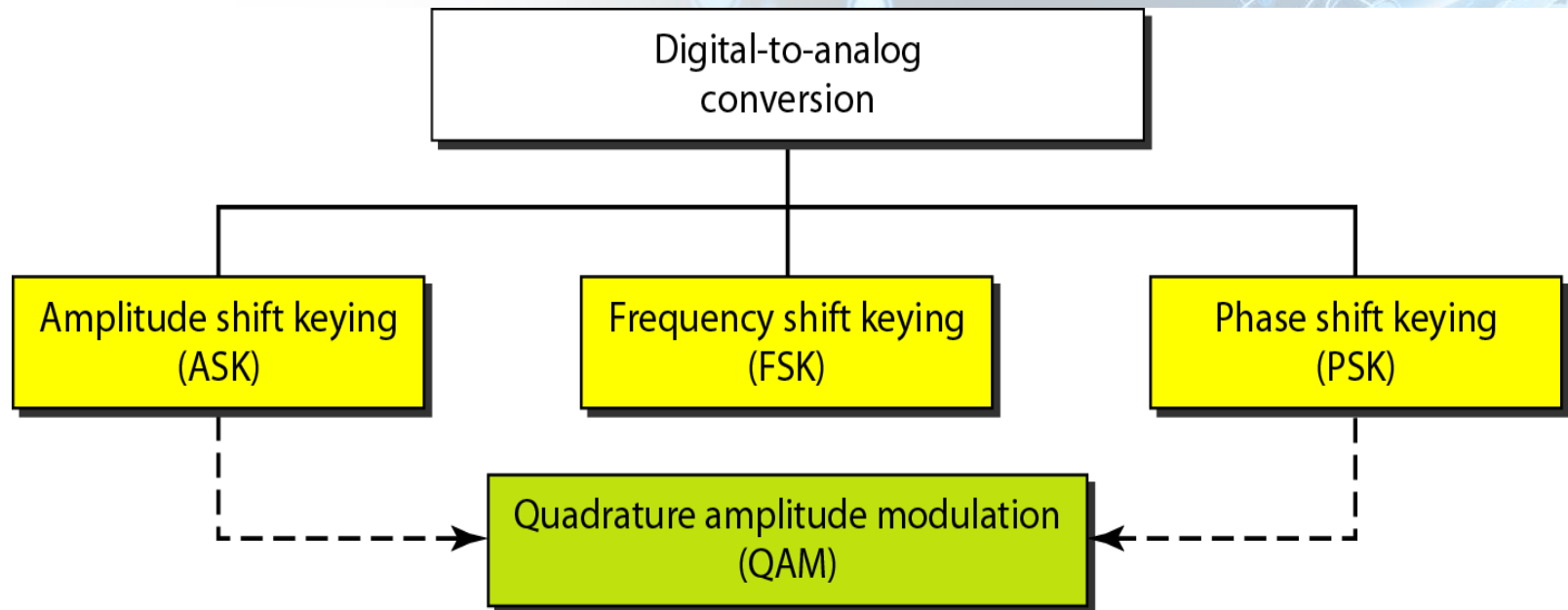
Digital-to-Analog Conversion

- Process of changing one of the characteristics of analog signal based on the information in digital data
- A sine wave is defined by 3 characteristics:
 - ✓ Amplitude
 - ✓ Frequency
 - ✓ Phase
- By changing one of these characteristics, we can use it to represent a digital signal

Digital-to-Analog Conversion



Types of Digital to Analog Conversion



Aspects of Digital to Analog Conversion

- Before we discuss specific methods of digital-to-analog modulation, two basic issues must be reviewed:
 - ✓ Bit and Baud rates and
 - ✓ The Carrier Signal

Aspects of Digital to Analog Conversion

- In Analog Transmission of Digital Data, Baud Rate is less than or equal to the Bit Rate

- ✓ Data Element vs. Signal Element ✓
- ✓ Data Rate vs. Signal Rate

- Bandwidth Required \propto Signal Rate (except FSK)

- Carrier Signal / Modulation (Shift Keying)

Data Element \rightarrow bit

Signal Element \rightarrow smallest unit of signal (constant)

$$S = \frac{N}{r} \Rightarrow r = \log_2 L$$

Carrier Signal

Sender \rightarrow high freq. signal
 \rightarrow base of information signal

Aspects of Digital to Analog Conversion

- Before we discuss specific methods of digital-to-analog modulation, two basic issues must be reviewed:
 - ✓ Bit and Baud rates and
 - ✓ The Carrier Signal

Example

An analog signal carries 4 bits per signal element. If 1000 signal elements are sent per second, find the bit rate?

$$r = 4 \quad S = 1000$$

$$N = ?$$

$$S = \frac{N}{r} \Rightarrow N = S \times r$$

$$\begin{aligned} N &= 1000 \times 4 \\ &= 4000 \text{ bps} \end{aligned}$$

Example

An analog signal has a bit rate of 8000 bps and a baud rate of 1000 baud. How many data elements are carried by each signal element? How many signal elements do we need?

$$N = 8000 \text{ bps}$$

$$S = 1000 \text{ baud}$$

$$L = ?$$

$$r = ?$$

$$S = \frac{N}{r} \Rightarrow r = \frac{N \text{ (bits)}}{S \text{ (bauds)}}$$

$$\rightarrow r = 8 \text{ bits/ baud}$$

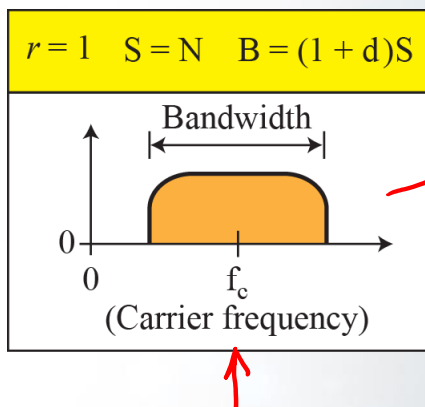
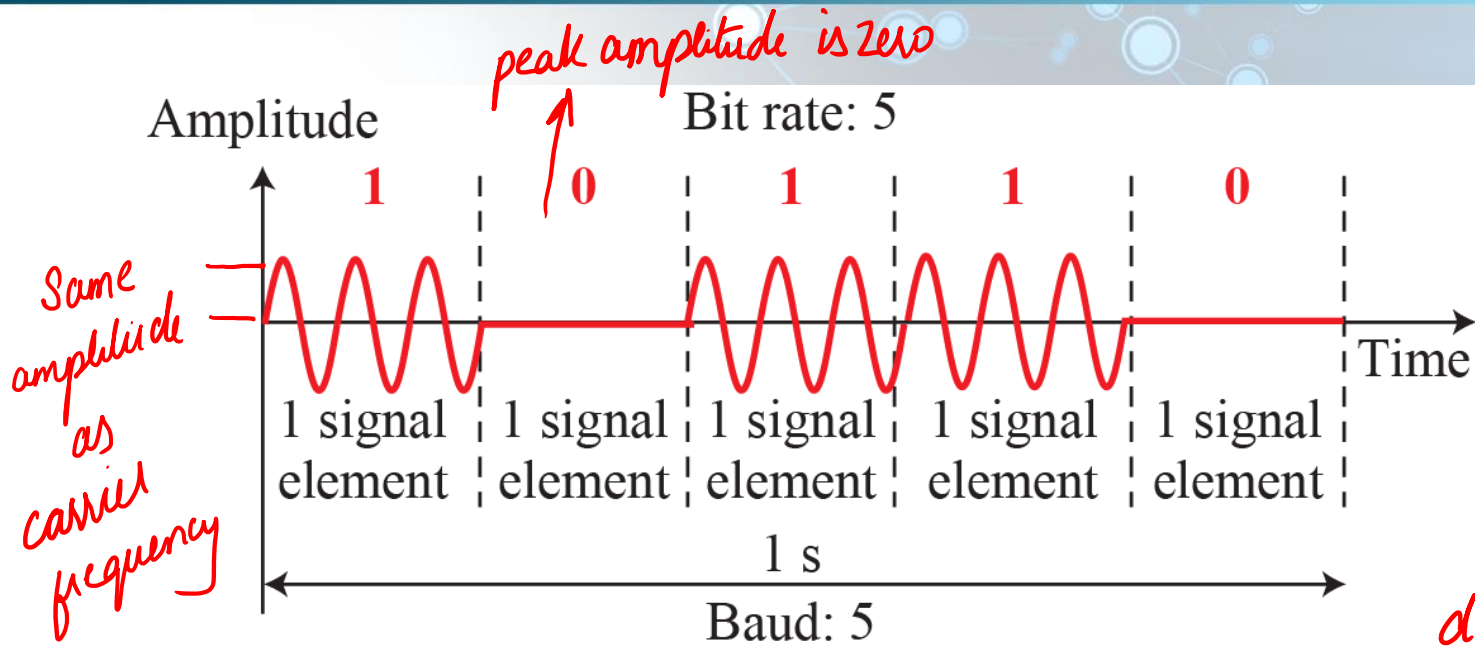
$$r = \log_2 L$$

$$\rightarrow L = 2^r = 2^8 = 256$$

Amplitude Shift Keying (ASK)

- The amplitude of the carrier signal is varied to create signal elements
- Both frequency and phase remain constant while the amplitude changes
- Binary ASK or On-Off Keying (OOK)

Binary Amplitude Shift Keying (Binary ASK)



$$B = (1 + d)S$$

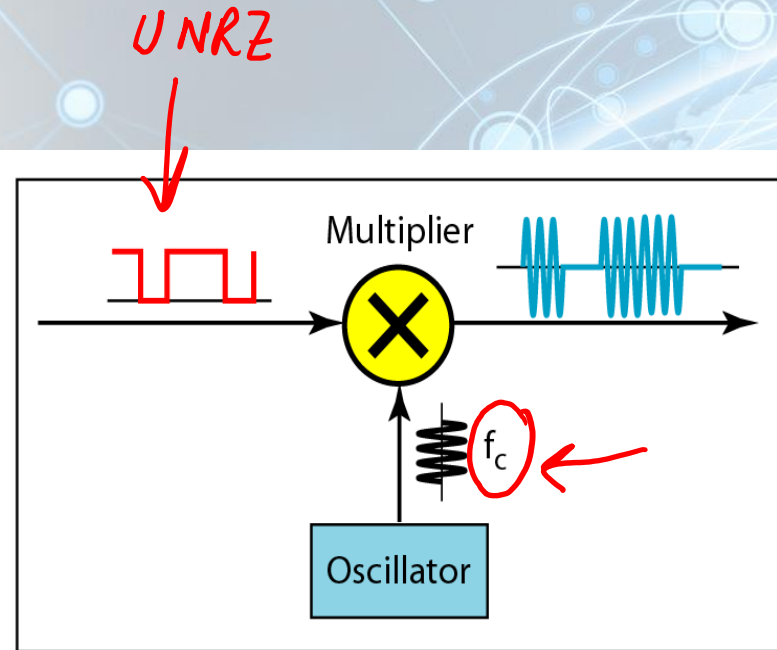
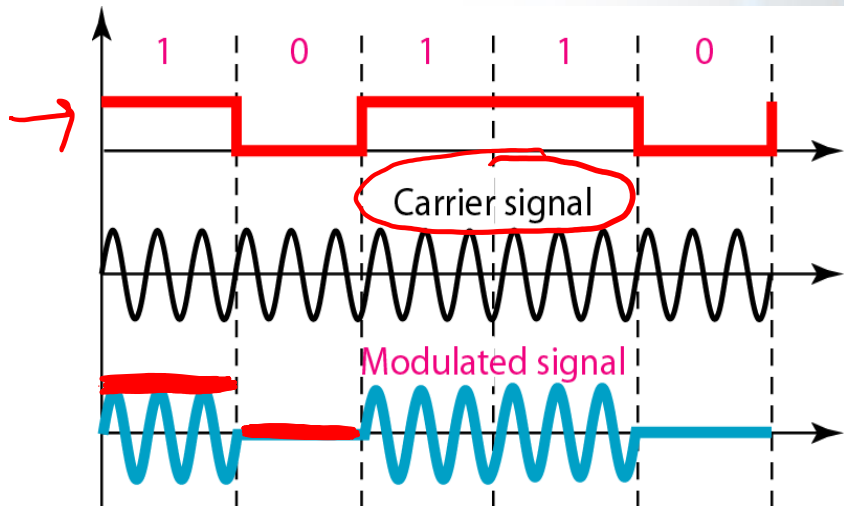
$d = 0 \rightarrow \min$
 $d = 1 \rightarrow \max$
 $d \rightarrow$ modulation & filtering process
 $(0 \rightarrow 1)$

Amplitude Shift Keying (ASK)

- The amplitude of the carrier signal is varied to create signal elements
- Both frequency and phase remain constant while the amplitude changes
- Binary ASK or On-Off Keying (OOK)

Implementation of Binary ASK

Unipolar NRZ \rightarrow HV = 1
LV = 0



\uparrow
1 \rightarrow maintaining amplitude of carrier
0 \rightarrow zero amplitude

Example

We have an available bandwidth of 100 kHz which spans from 200 to 300 kHz. What are the carrier frequency and the bit rate if we modulated our data by using ASK with $d = 1$?

$$r = 1$$

$$f_c = 250 \text{ kHz}$$

$$B = (1+d)S$$

$$B = (1+1)S$$

$$B = 2S$$

$$B = 2 \left(\frac{N}{r} \right)$$

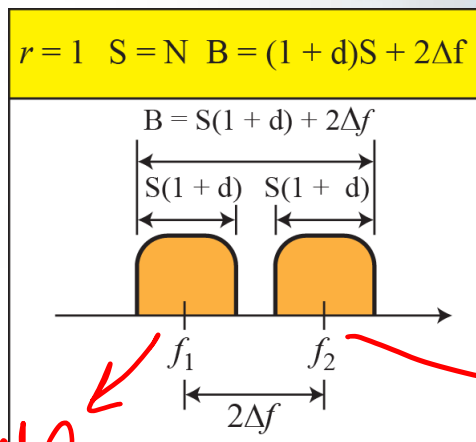
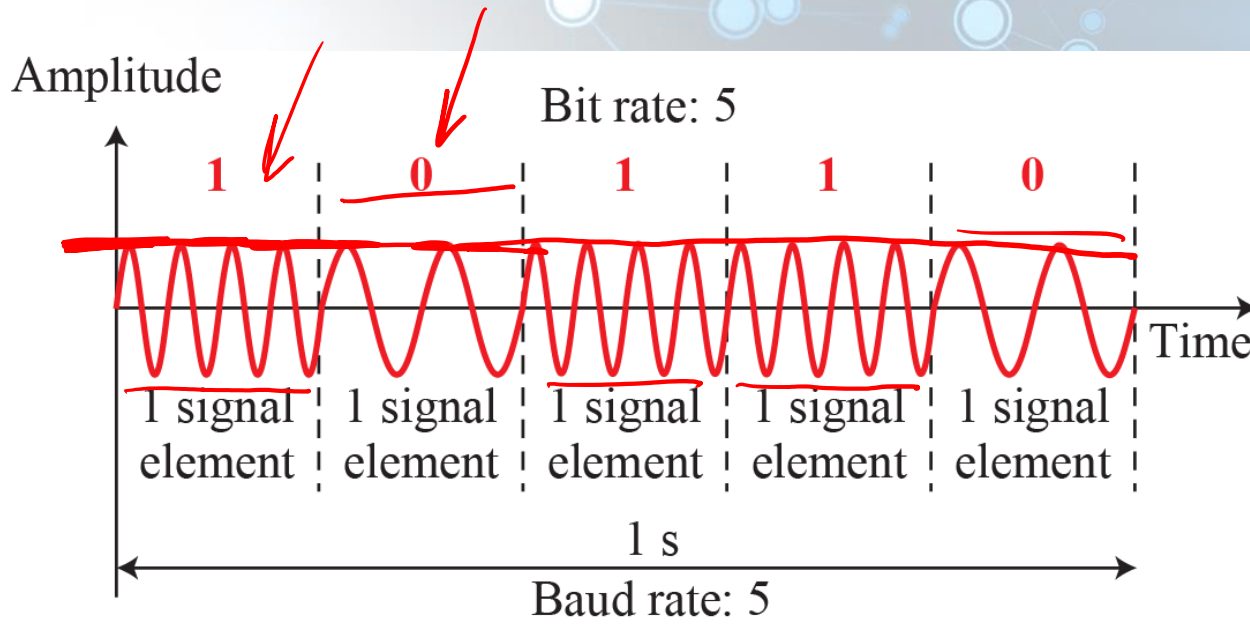
$$B = 2N \quad (r=1)$$

$$N = \frac{B}{2} = \frac{100 \text{ kHz}}{2} = 50 \text{ kbps}$$

Frequency Shift Keying (FSK)

- The frequency of the carrier signal is varied to represent data
- The frequency of the modulated signal is constant for the duration of one signal element, but changes for the next signal element if the data element changes
- Both peak amplitude and phase remain constant

Binary Frequency Shift Keying



$$f_2 - f_1 = 2\Delta f$$

$$B = (1 + d)S + 2\Delta f$$

$B \propto S$

Frequency Shift Keying (FSK)

- The frequency of the carrier signal is varied to represent data
- Both peak amplitude and phase remain constant

Example

We have an available bandwidth of 100 kHz which spans from 200 to 300 kHz. What should be the carrier frequency and the bit rate if we modulated our data by using FSK with $d = 1$?

$$B = (1+d) \times S + 2\Delta f$$

$$\Delta f = 50 \text{ kHz}$$

$$\underline{B} = 2S + 50$$

$$2S + 50 = 100$$

$$2S = 50 \text{ kHz}$$

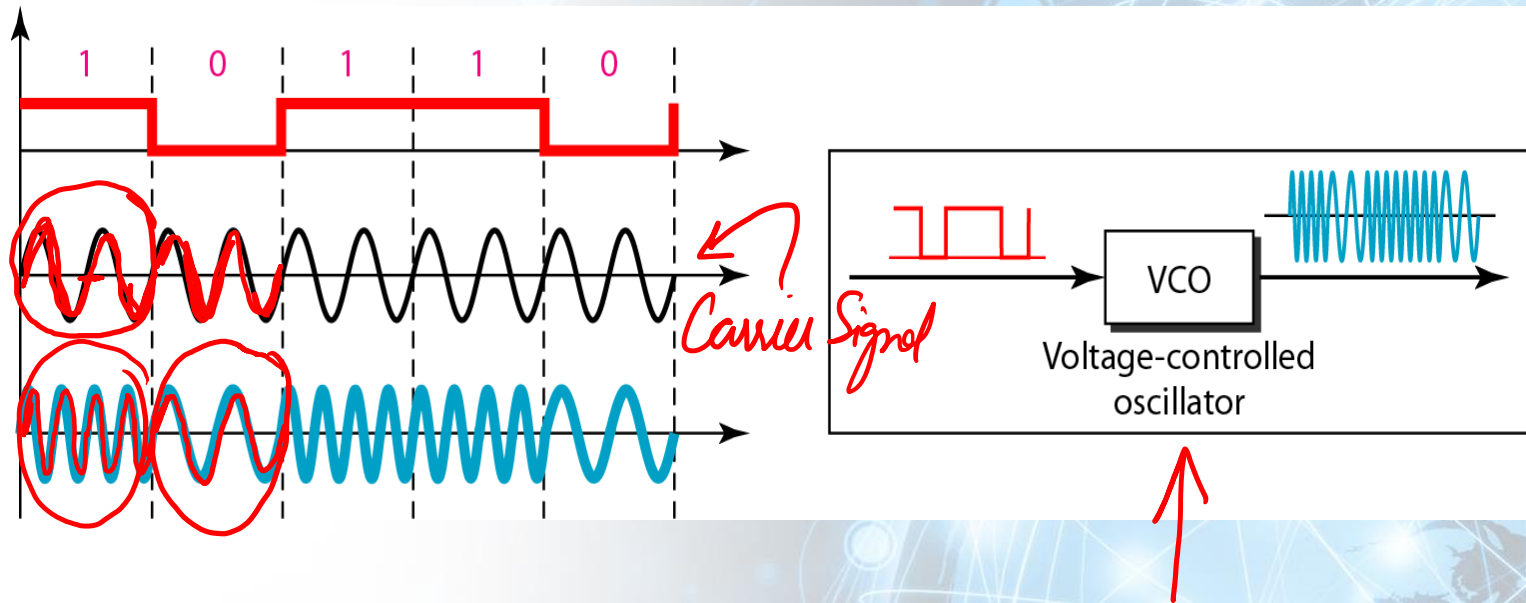
$$S = 25 \text{ kbaud}$$

$$N = S$$

$$\underline{N = 25 \text{ kbps}}$$

Implementation of BFSK

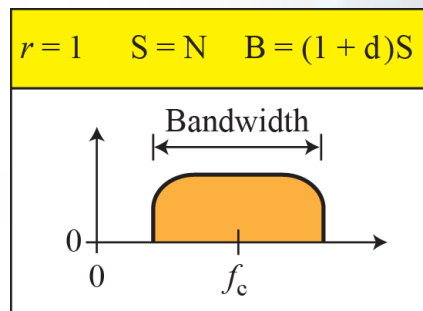
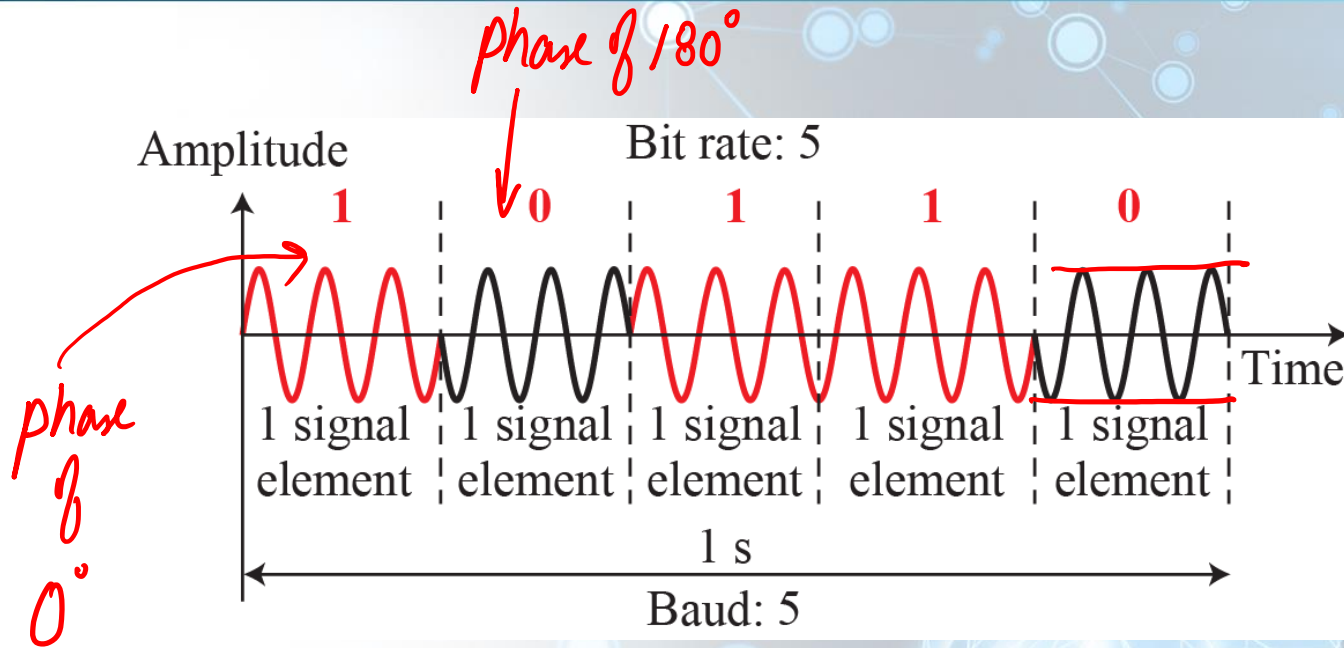
Unipolar NRZ



Phase Shift Keying (PSK)

- The phase of the carrier is varied to represent two or more different signal elements
- Both peak amplitude and frequency remain constant
- PSK is relatively common than ASK or FSK

Binary Phase Shift Keying

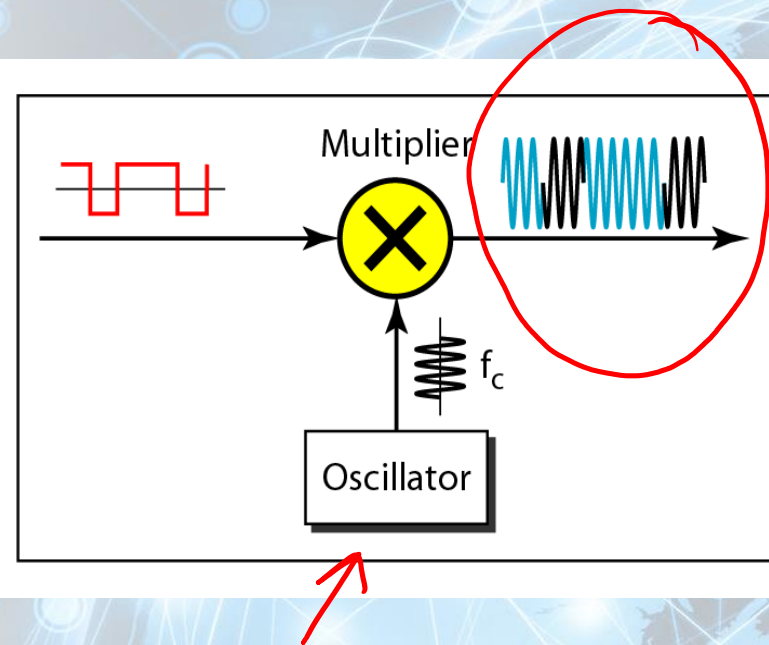
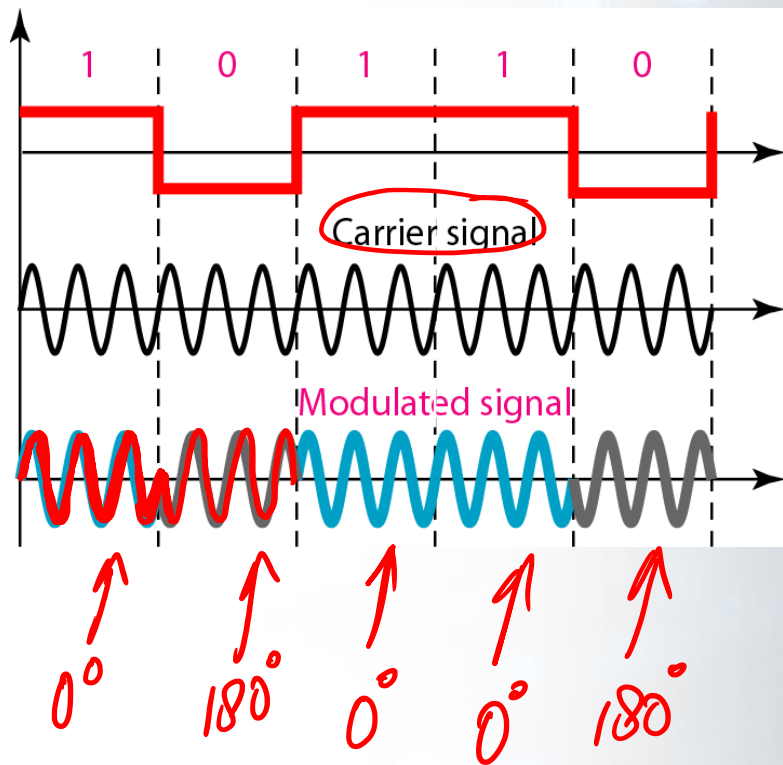


$$B = (1 + d)S$$

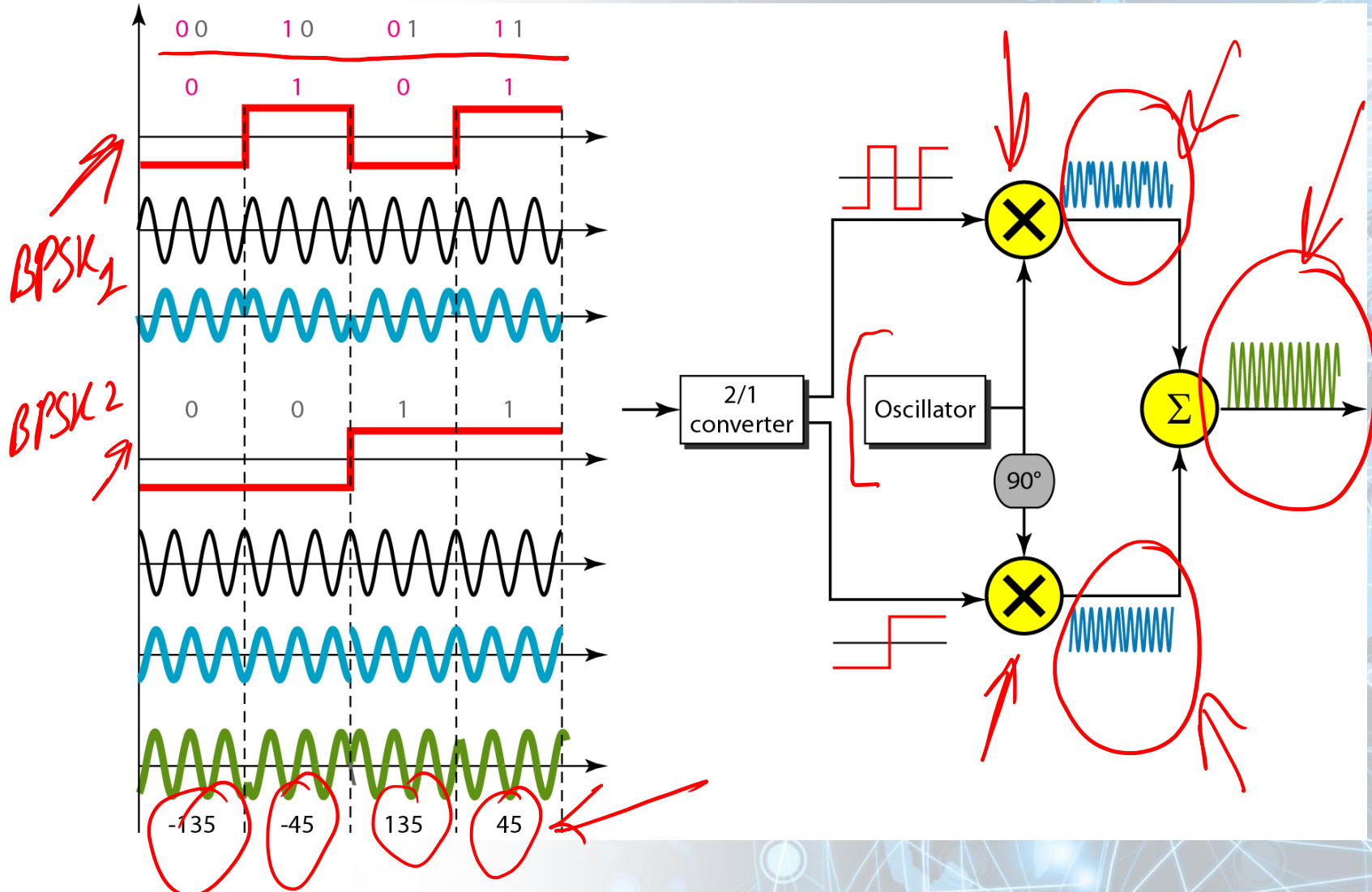
$$B_{PSK} = B_{ASK}$$

Implementation of BPSK

Polar NRZ



QPSK and its Implementation



Example

Find the bandwidth for a signal transmitting at 12 Mbps for QPSK. The value of $d = 0$.

$$r = 2$$

$$S = \frac{N}{r}$$

$$= \frac{12 \text{ Mbps}}{2}$$

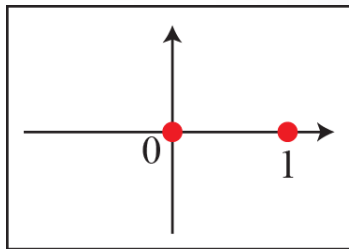
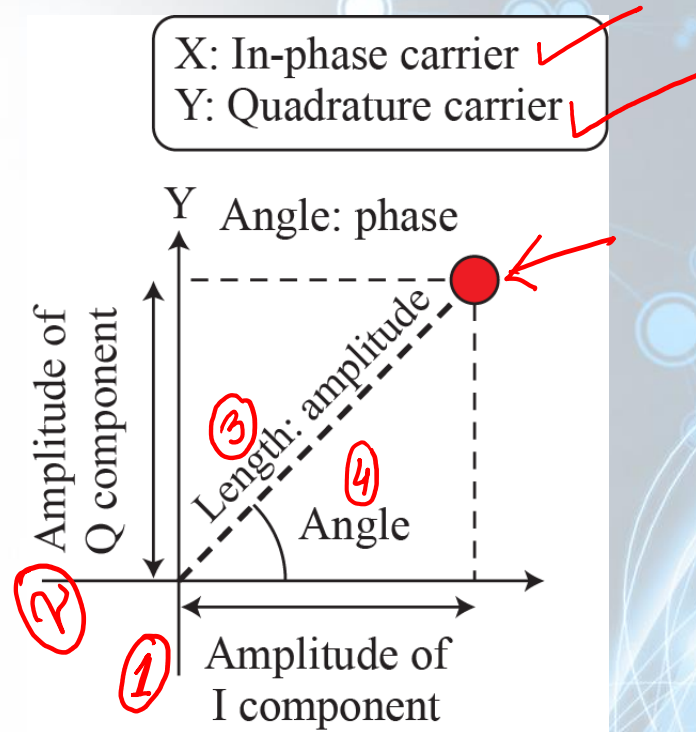
$$= 6 \text{ Mbaud.}$$

$$d=0 \rightarrow B = S = \underline{\underline{6 \text{ MHz}}}$$

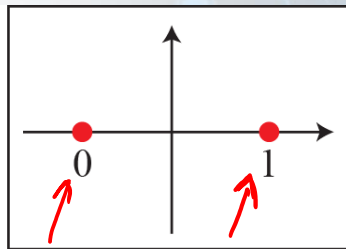
Constellation Diagram

- **Helps us define the phase and amplitude of a signal element when we are using two carriers (one in phase and other in quadrature)**
- **Signal element is represented as a dot**

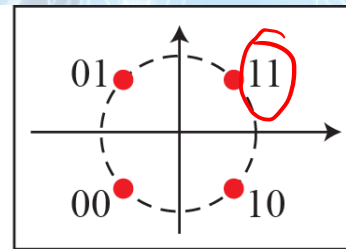
Constellation Diagram



a. BASK (OOK)



b. BPSK

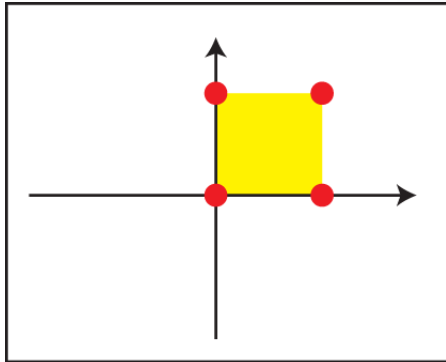


c. QPSK

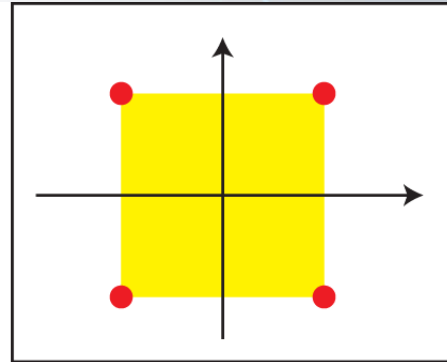
Quadrature Amplitude Modulation (QAM)

- PSK is limited by the ability of the equipment to distinguish small differences in phase which limits its potential bit rate
- We have been altering only one of the three characteristics of a sine wave at a time; but what if we alter two?
- Why not combine ASK and PSK?

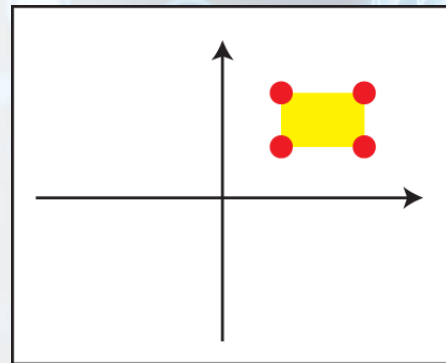
Constellation diagrams for some QAMs



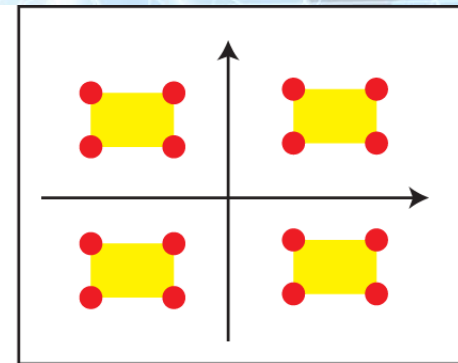
a. 4-QAM



b. 4-QAM



c. 4-QAM

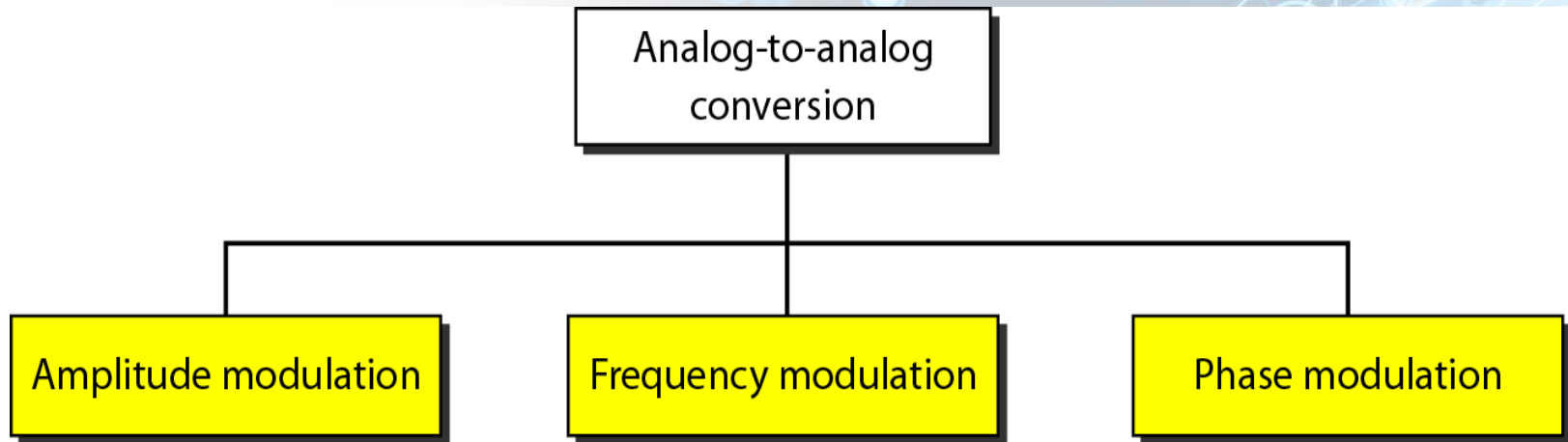


d. 16-QAM

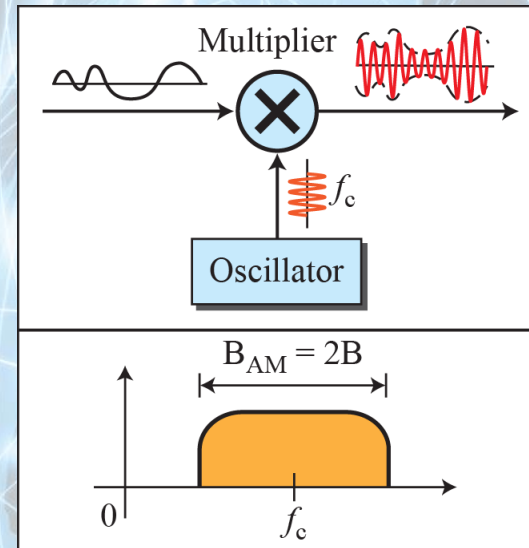
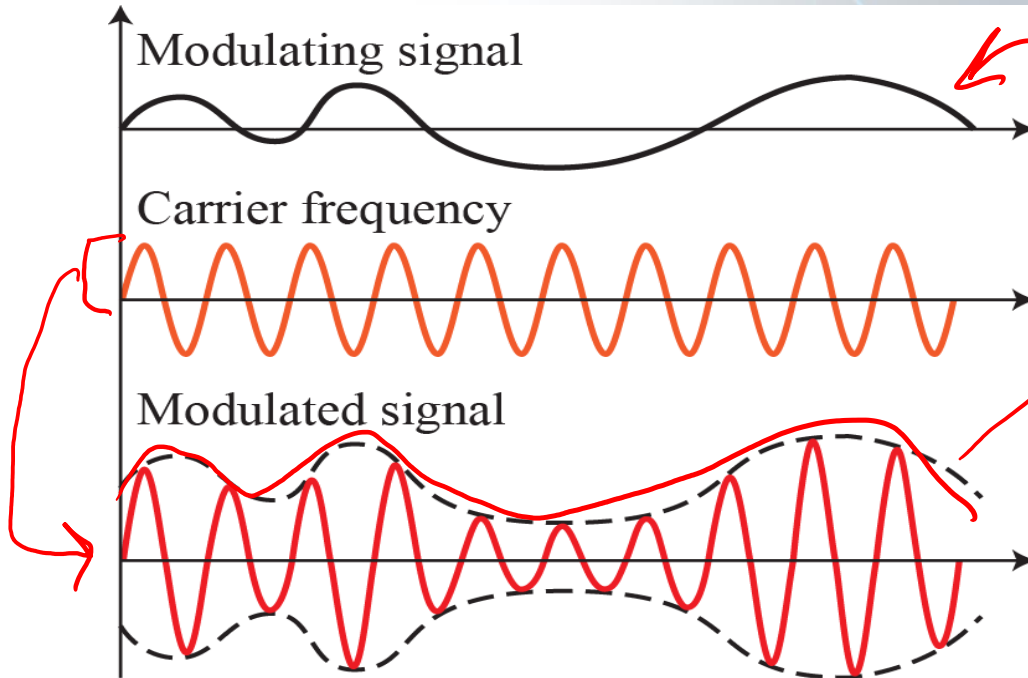
Analog-to-Analog Conversion

- **Representation of Analog information by an Analog signal**
- **Amplitude Modulation (AM)**
- **Frequency Modulation (FM)**
- **Phase Modulation (PM)**

Types of Analog-to-Analog Modulation



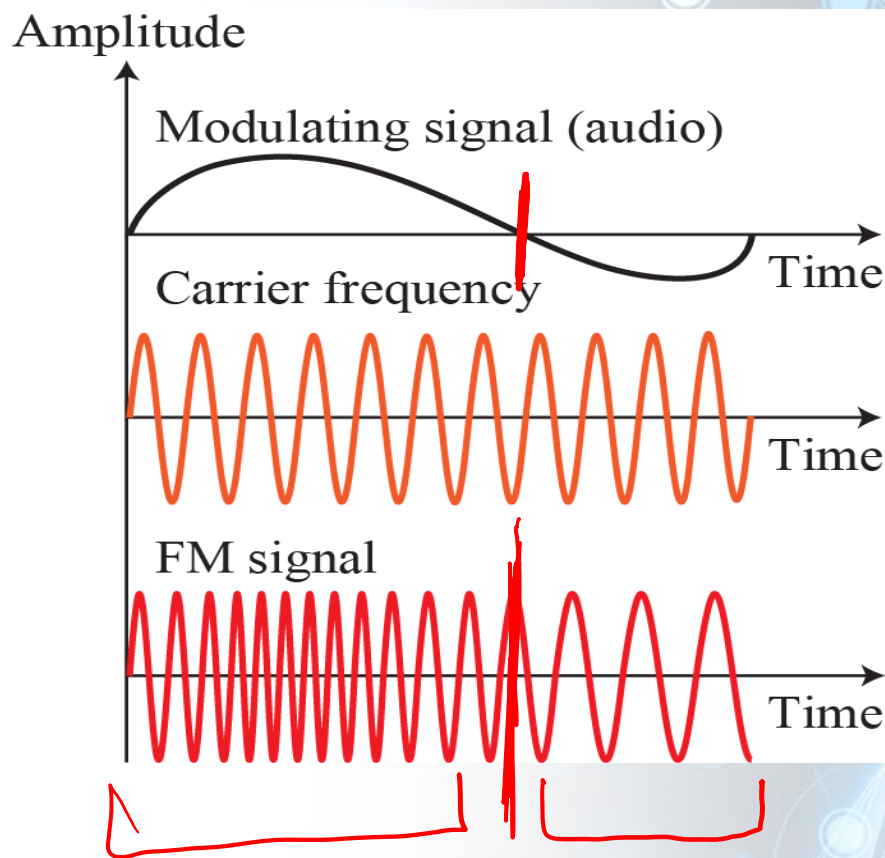
Amplitude modulation



$$B_{AM} = 2B$$

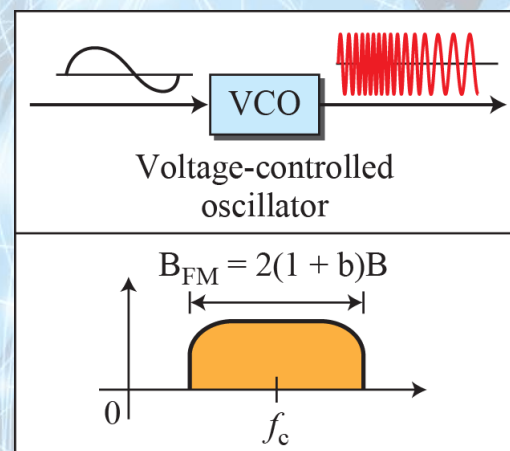
f_c

Frequency Modulation



$$B_{FM} = 2(1 + \beta)B$$

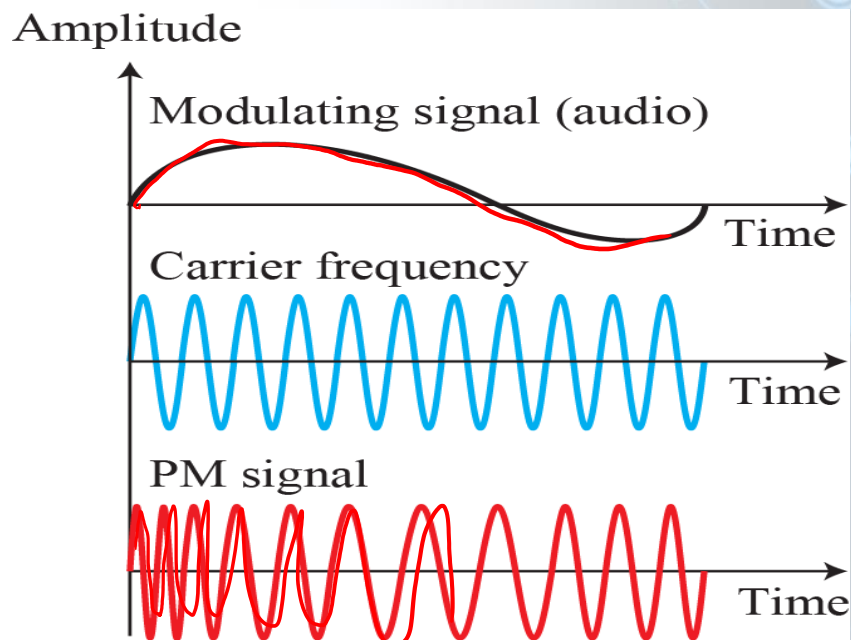
\hookrightarrow Beta = 4



Analog-to-Analog Conversion

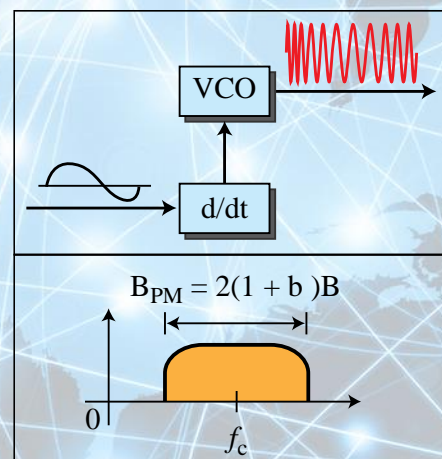
- **Representation of Analog information by an Analog signal**
- **Amplitude Modulation (AM)**
- **Frequency Modulation (FM)**
- **Phase Modulation (PM)**

Phase Modulation



$$B_{PM} = 2(1 + \beta)B$$

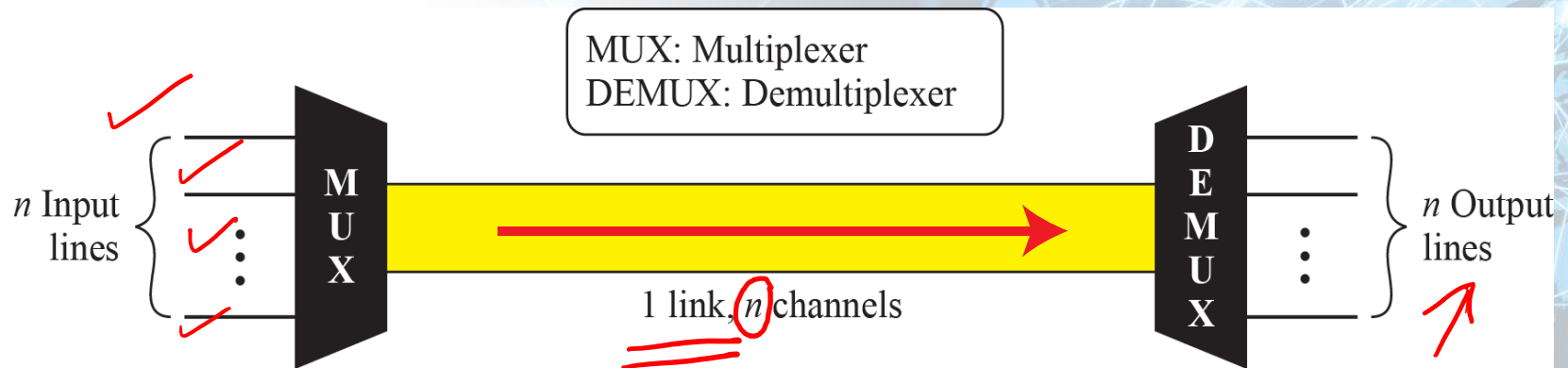
$\beta = 1$ narrowband
 $\beta = 3$ wideband



Multiplexing

- **Simultaneous transmission of multiple signals across a single data link**
- **As data & telecomm use increases, so does traffic**
 - ✓ **Add individual links each time a new channel is needed**
 - ✓ **Install higher-bandwidth links and use each to carry multiple signals**

Dividing a Link into Channels



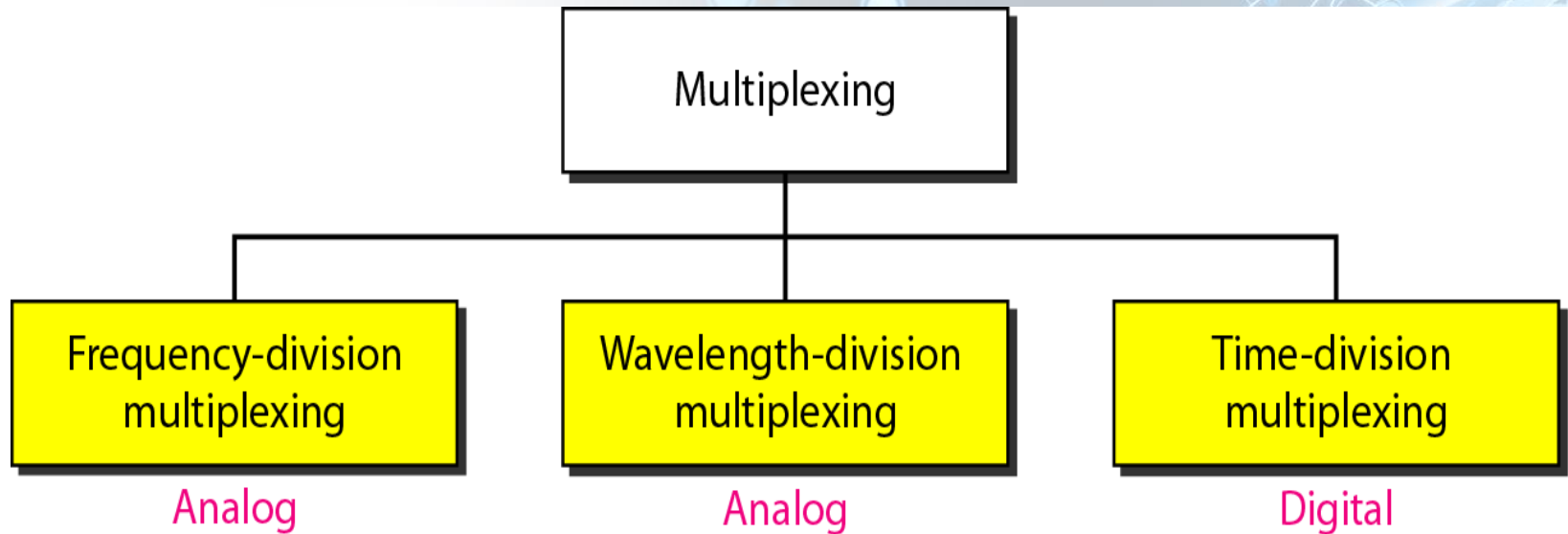
*Multiplexer
(many to one)*

*Demultiplexer
(one to many)*

Multiplexing

- **Simultaneous transmission of multiple signals across a single data link**

Categories of Multiplexing



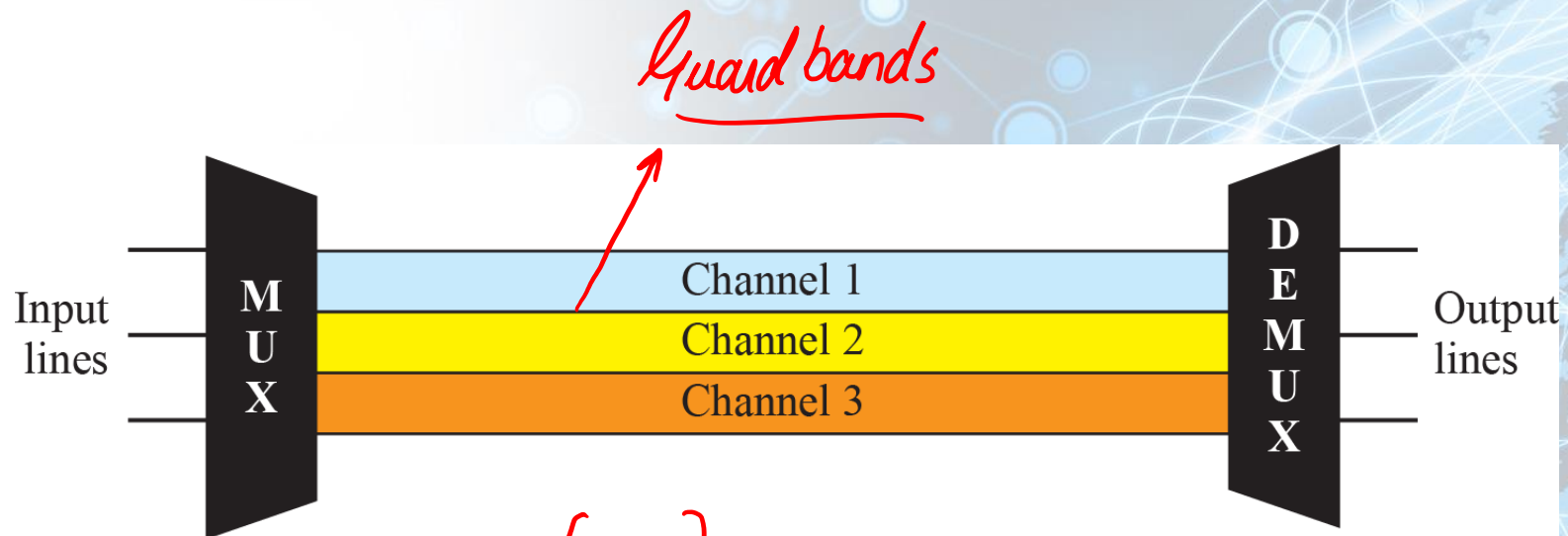
Frequency-Division Multiplexing

- An analog technique that can be applied when the bandwidth of a link (in hertz) is greater than the combined bandwidths of the signals to be transmitted
- Signals generated by each sending device modulate different carrier frequencies

Frequency-Division Multiplexing

These modulated signals are then combined into a single composite signal that can be transported by the link

Frequency-Division multiplexing

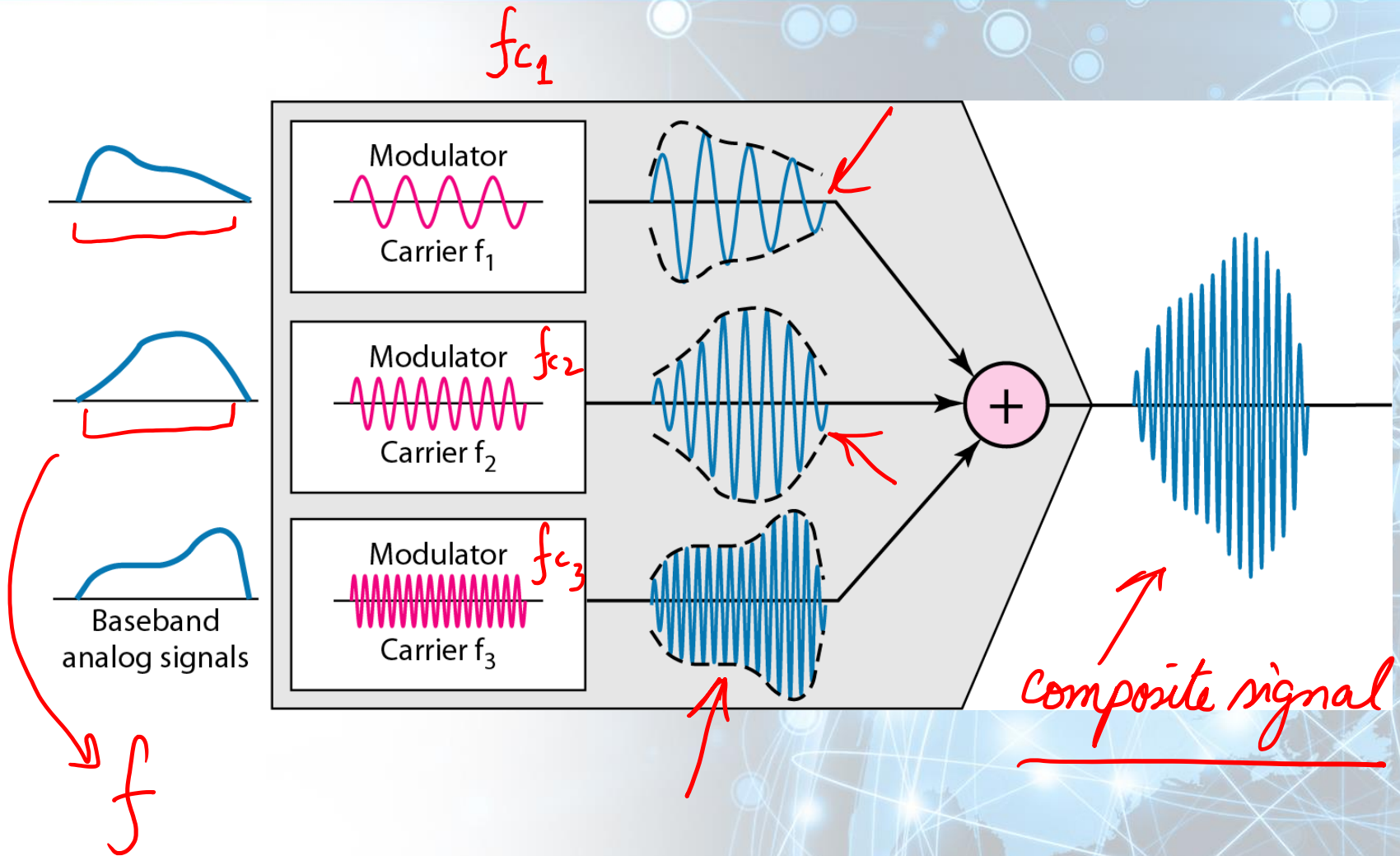


f_{c_1}
 f_{c_2}
 f_{c_3} } must not interfere
with original frequencies.

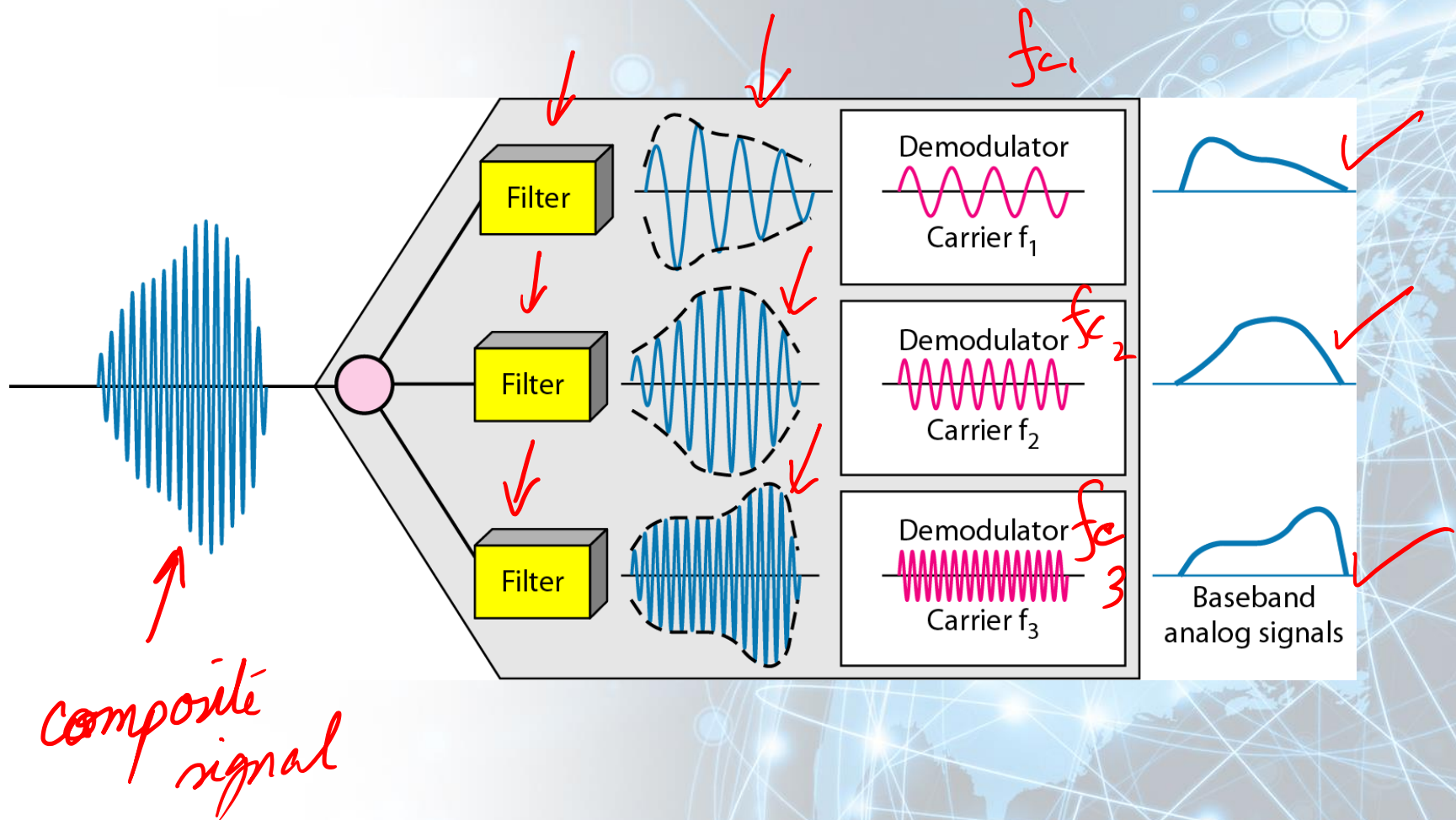
Frequency-Division Multiplexing

- **An analog technique that can be applied when the bandwidth of a link (in hertz) is greater than the combined bandwidths of the signals to be transmitted**

FDM Multiplexing

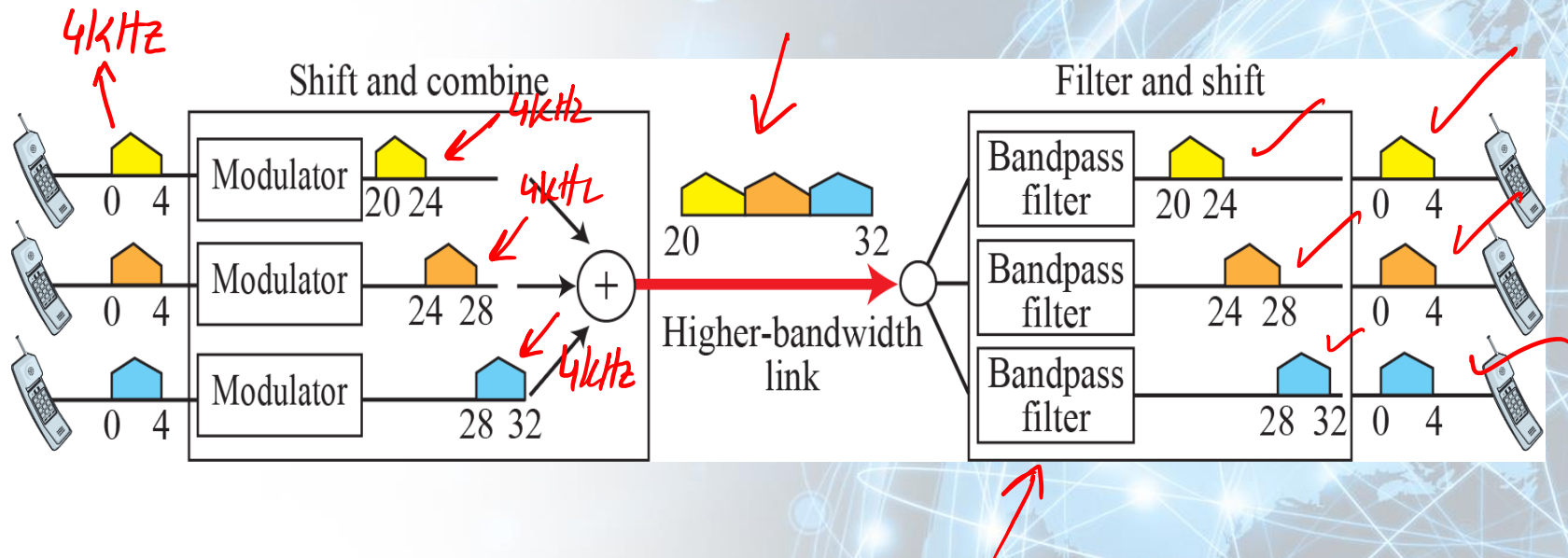


FDM De-Multiplexing



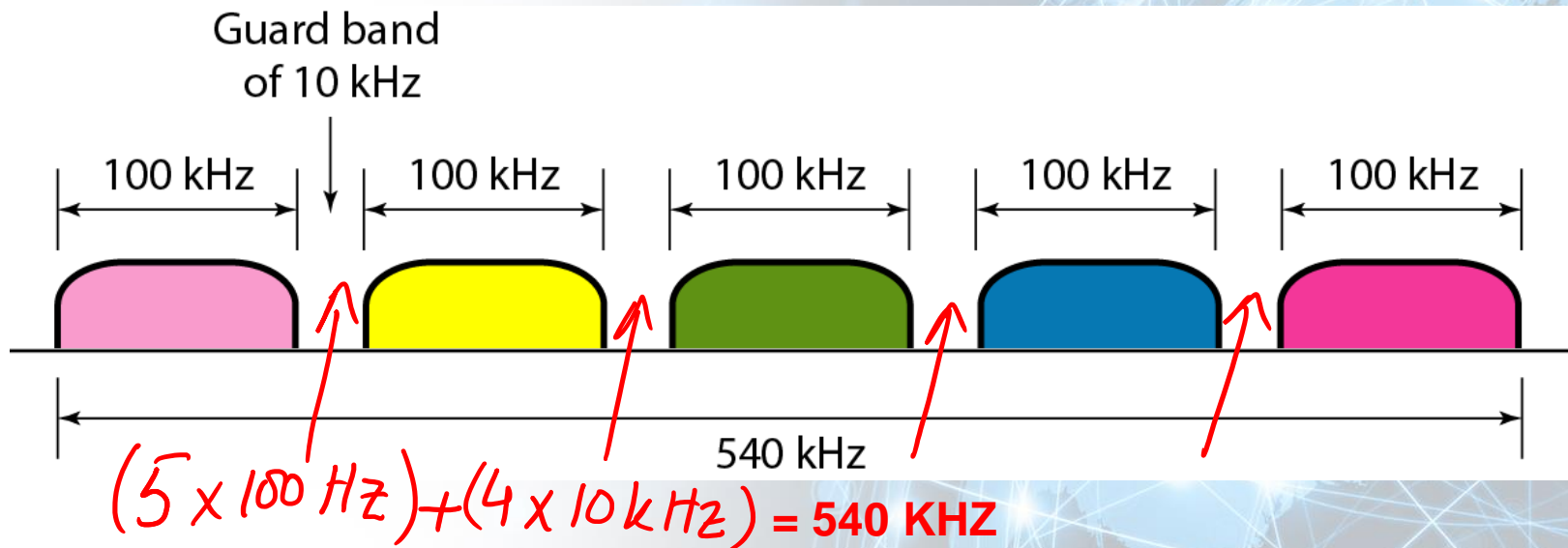
Example

Assume that a voice channel occupies a bandwidth of 4 kHz. We need to combine three voice channels into a link with a bandwidth of 12 kHz, from 20 to 32 kHz. Show the configuration, using the frequency domain. Assume there are no guard bands.



Example

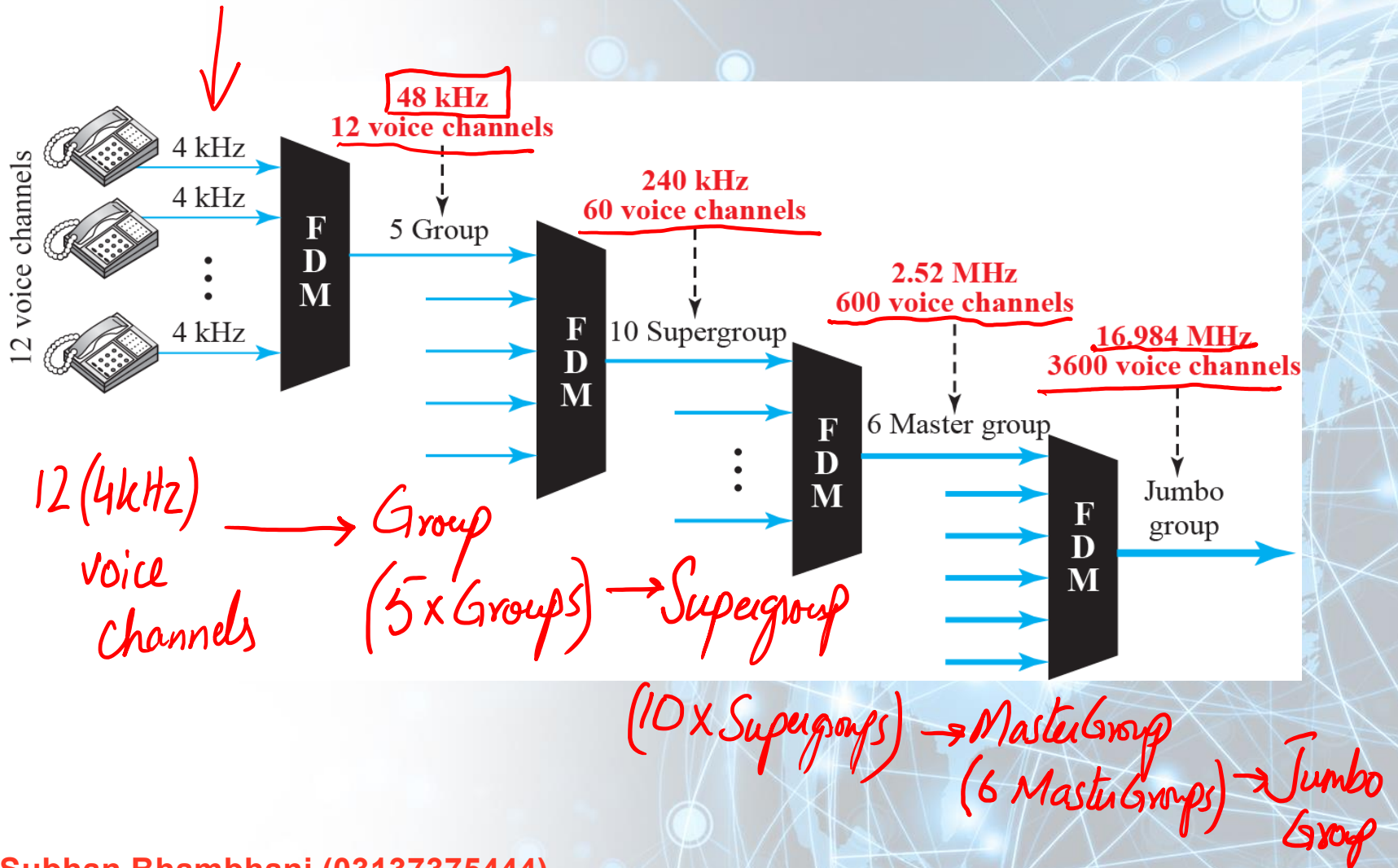
Five channels, each with a 100-kHz bandwidth, are to be multiplexed together. What is the minimum bandwidth of the link if there is a need for a guard band of 10 kHz between the channels to prevent interference?



The Analog Carrier System

- Telephone companies multiplex signals from lower-bandwidth lines on to higher-bandwidth lines
- For Analog, FDM is used

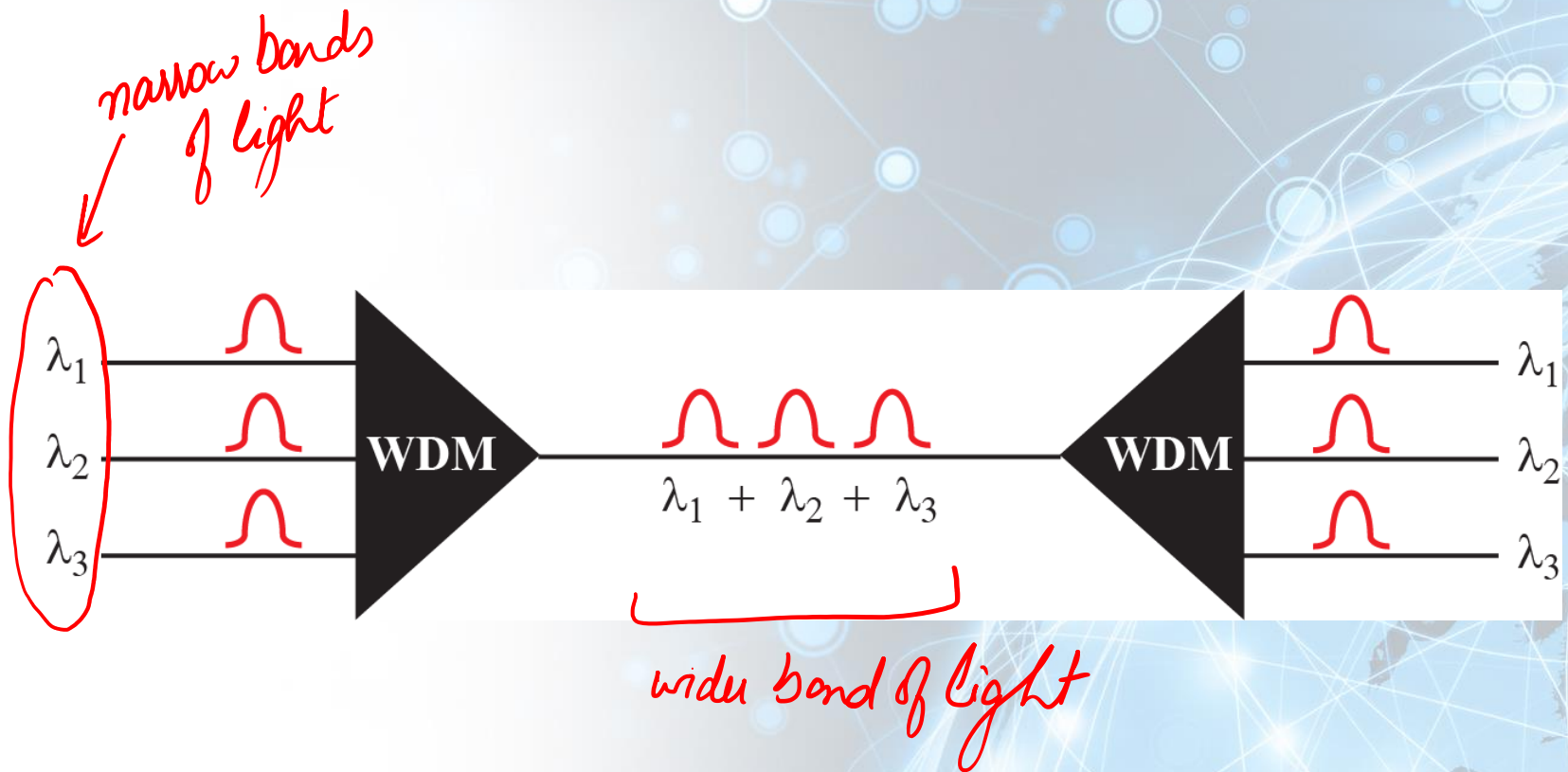
Analog Hierarchy



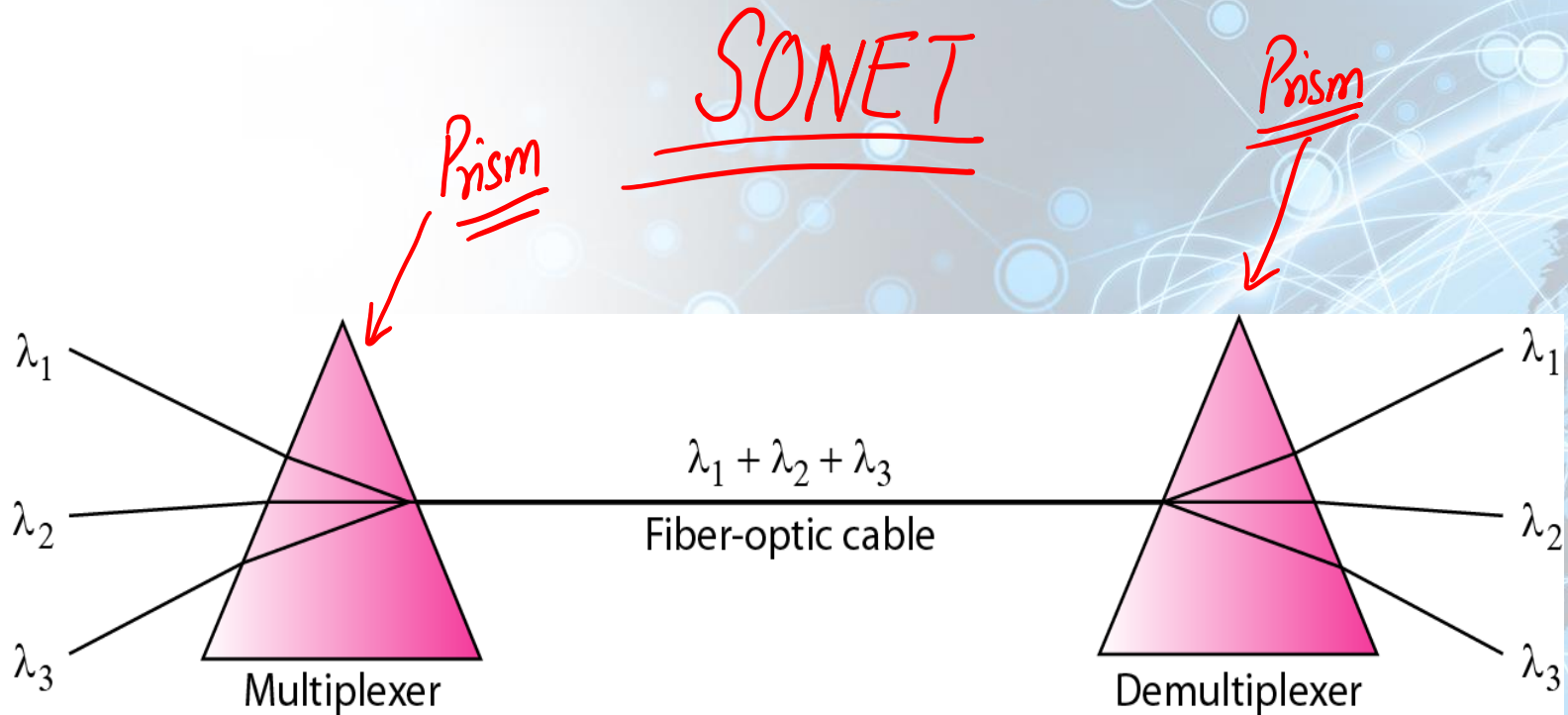
Wavelength-Division Multiplexing

- **Designed to use the high-data-rate capability of fiber-optic cable**
- **Fiber data rate is higher than the data rate of metallic transmission cable**
- **Using a fiber-optic cable for a single line wastes the available bandwidth**
- **Multiplexing allows us to combine several lines into one**

Wavelength-Division Multiplexing (WDM)



Prisms in Wave-Length Division Multiplexing

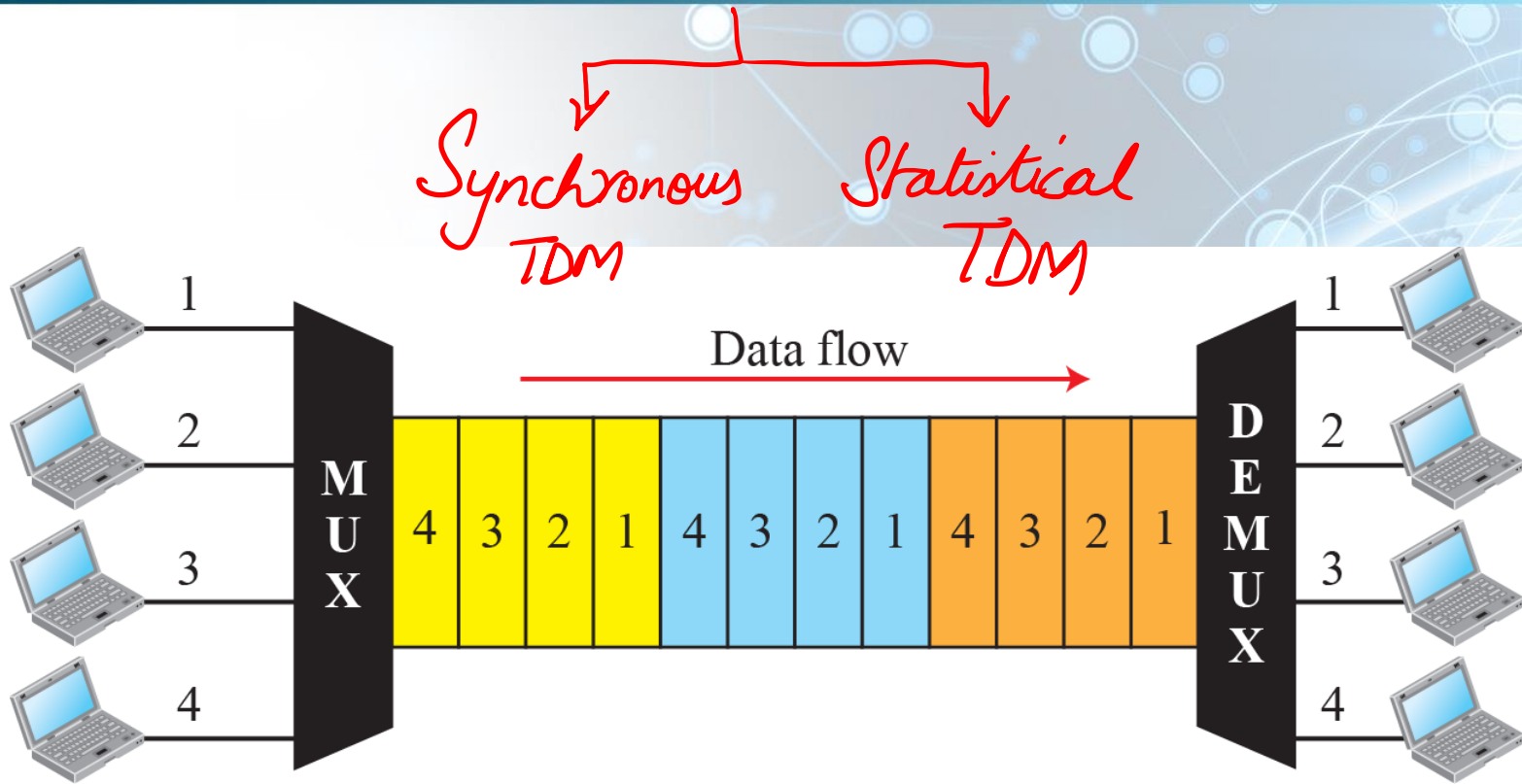


DWDM → Efficient than WDM
↓
Dense

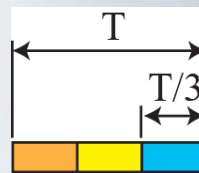
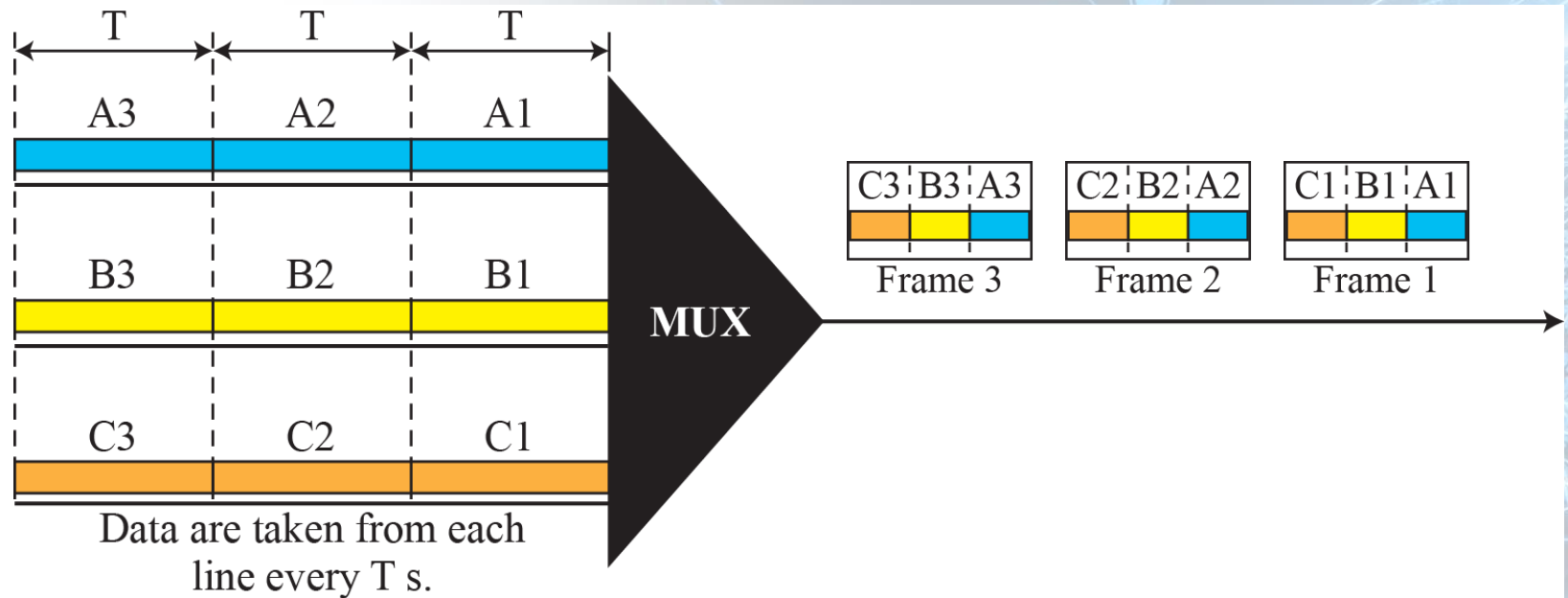
Time-Division Multiplexing

- **Digital process that allows several connections to share the high bandwidth of a link**
- **Time is shared i.e. each connection occupies a portion of time in the link**

TDM



Synchronous Time-Division Multiplexing



Each frame is 3 time slots.
Each time slot duration is $T/3$ s.

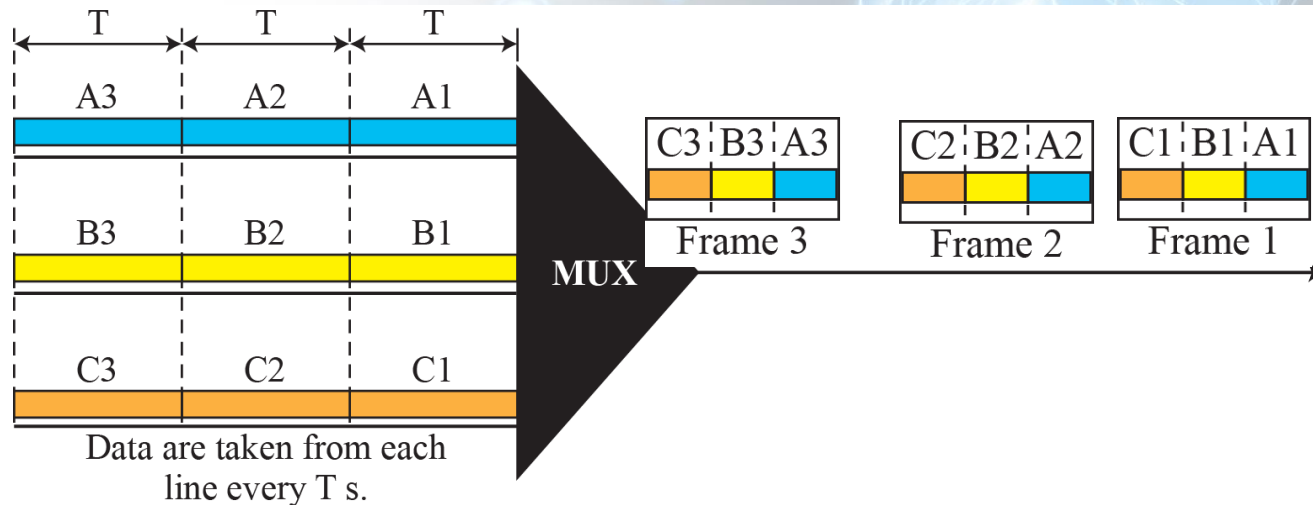
Time-Division Multiplexing

- **Digital process that allows several connections to share the high bandwidth of a link**
- **Time is shared i.e. each connection occupies a portion of time in the link**

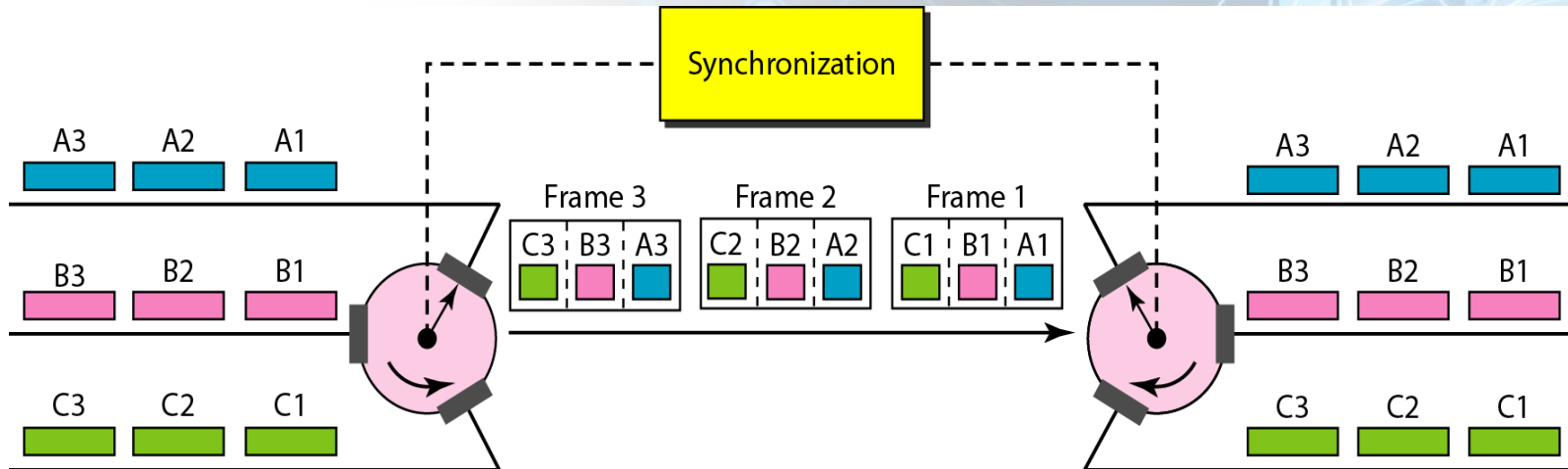
Example

In Figure the data rate for each input connection is 1 kbps. If 1 bit at a time is multiplexed (a unit is 1 bit), what is the duration of

- each input slot,
- each output slot, and
- each frame?



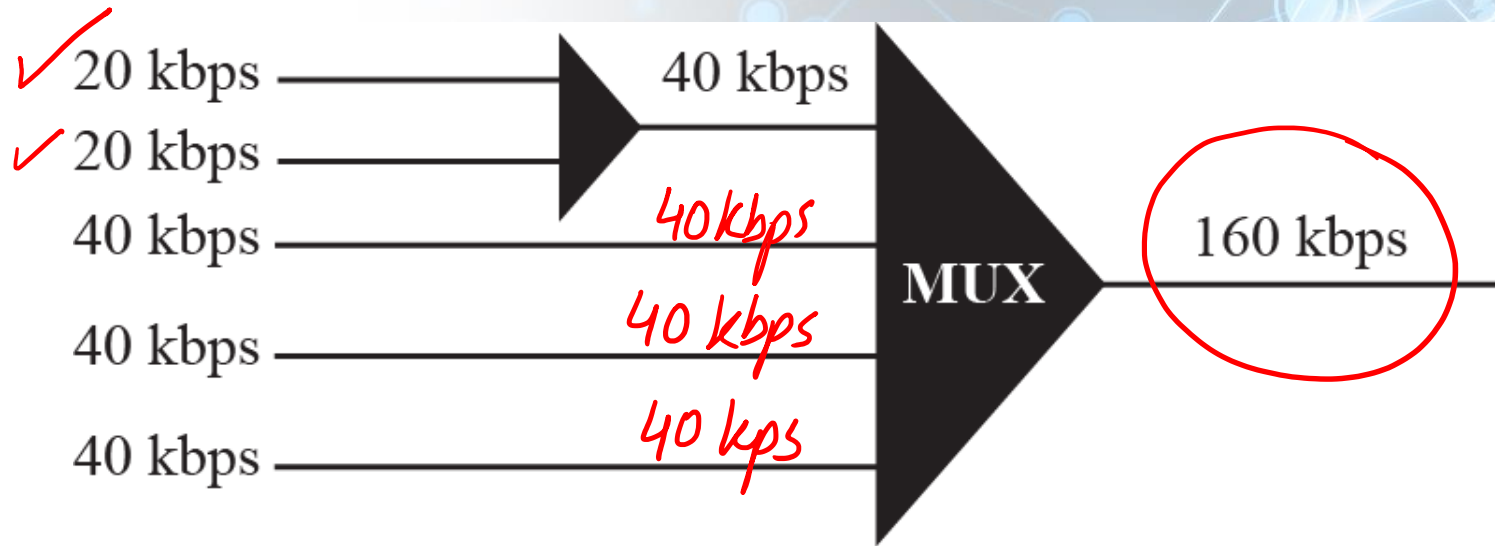
Interleaving



Time-Division Multiplexing

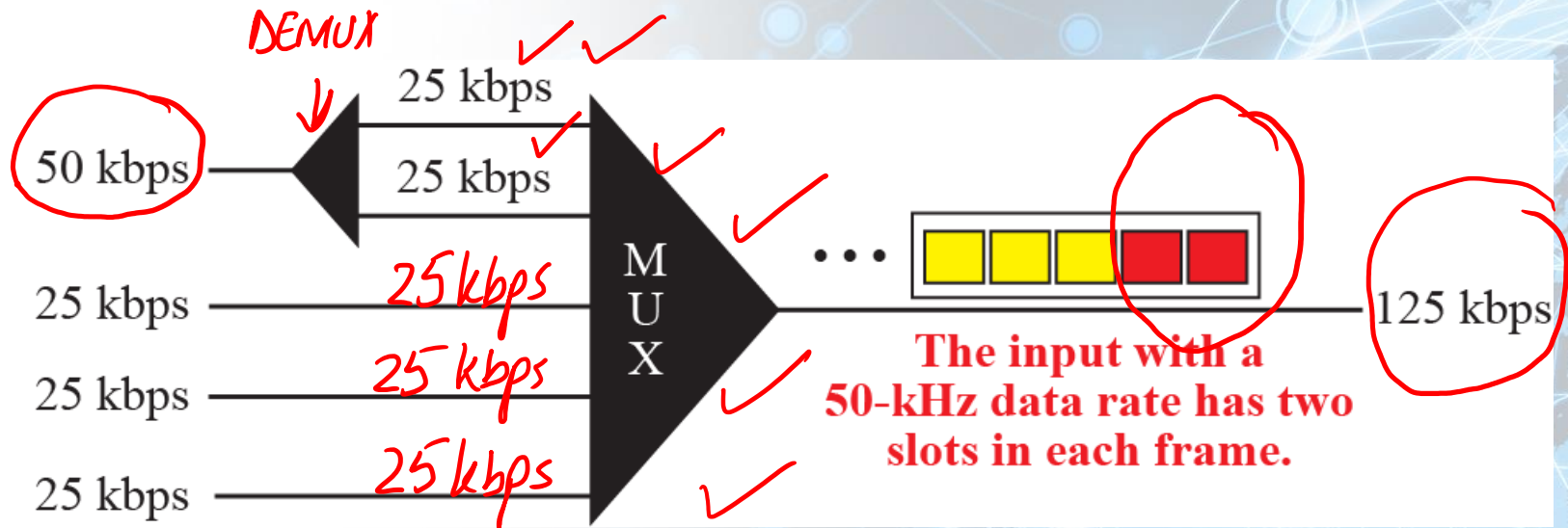
- **Digital process that allows several connections to share the high bandwidth of a link**
- **Time is shared i.e. each connection occupies a portion of time in the link**

Multilevel Multiplexing

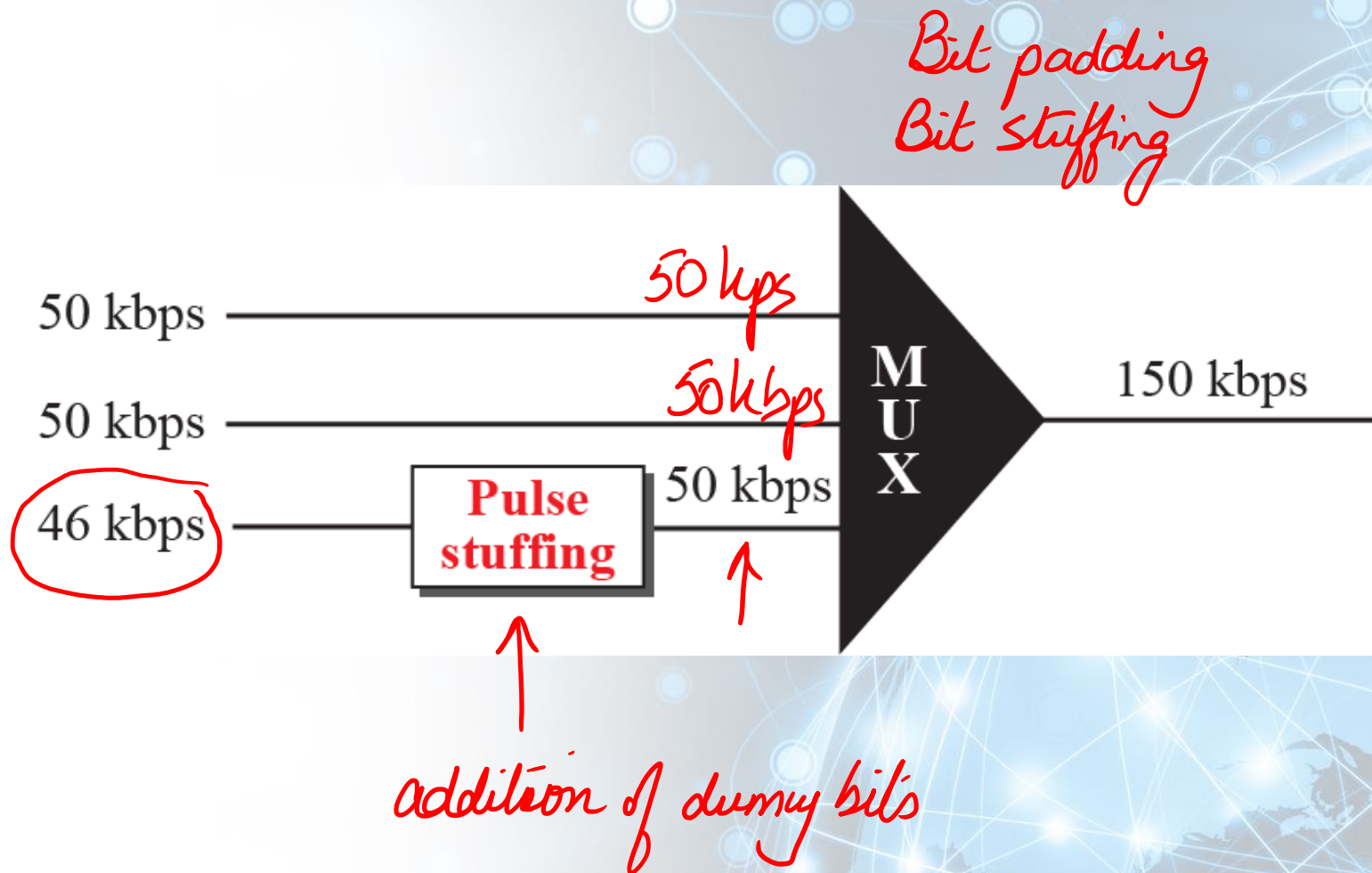


20 is a multiple of 40

Multiple-Slot Multiplexing



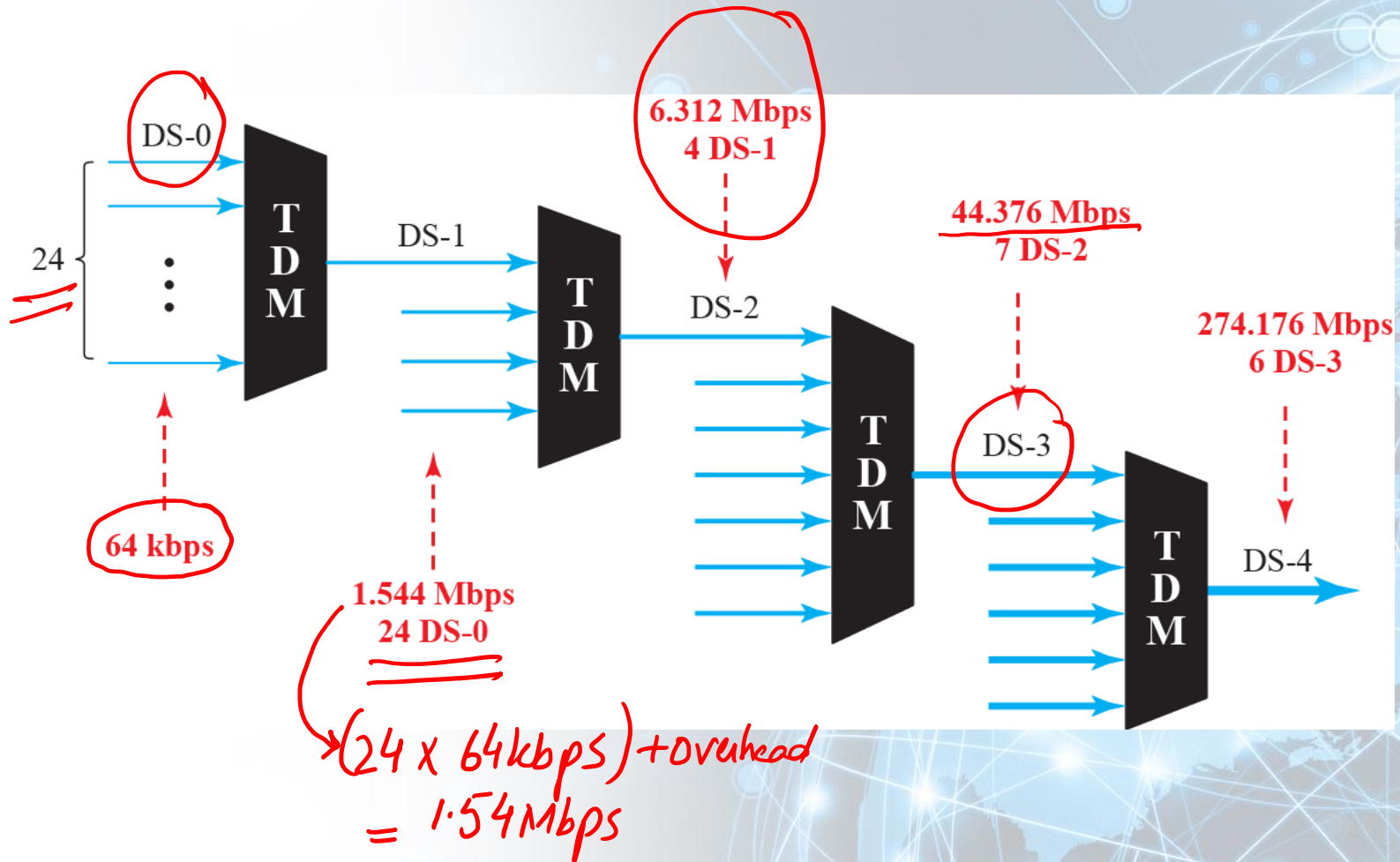
Pulse Stuffing



Time-Division Multiplexing

- **Digital process that allows several connections to share the high bandwidth of a link**
- **Time is shared i.e. each connection occupies a portion of time in the link**

Digital Hierarchy

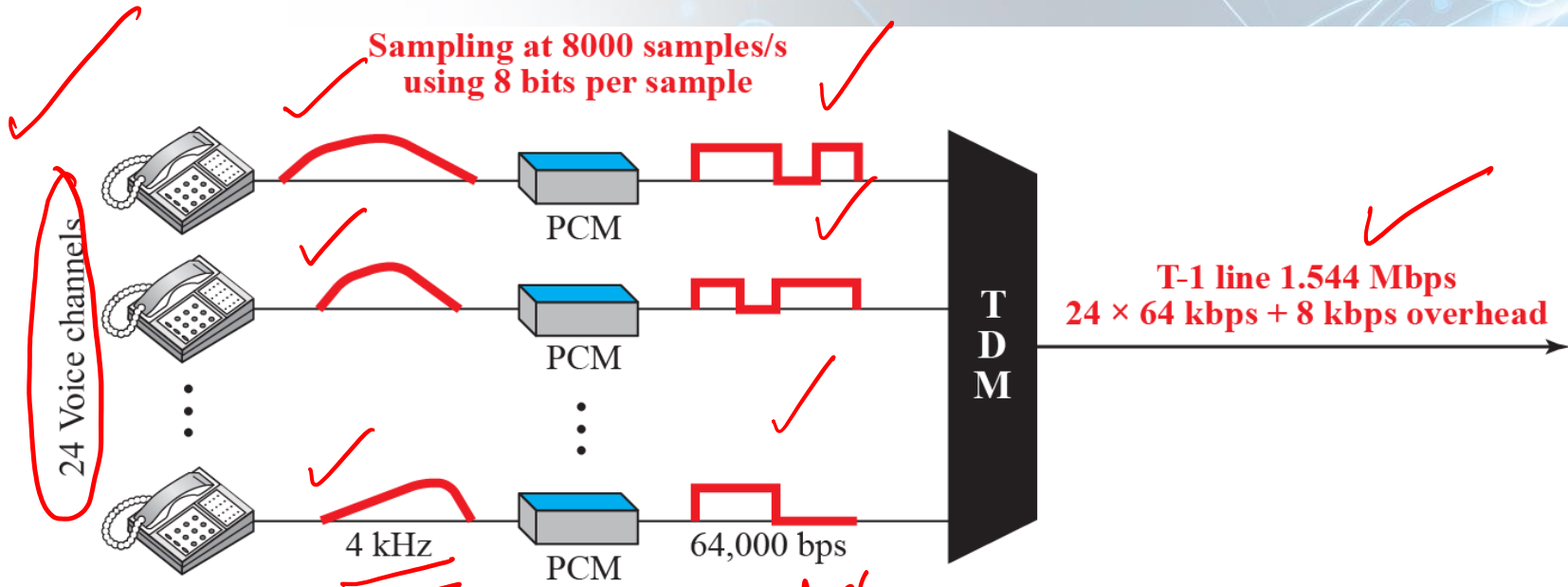


DS and T Line Rates

DSO

<i>Service</i>	<i>Line</i>	<i>Rate (Mbps)</i>	<i>Voice Channels</i>
DS-1	T-1 ✓	1.544 ✓	24 ✓
DS-2	T-2 ✓	6.312 ✓	96 ✓
DS-3	T-3 ✓	44.736 ✓	672 ✓
DS-4	T-4 ✓	274.176 ✓	4032 ✓

T-1 Line



4 kHz $\xrightarrow{8 \text{ bits/sample}}$ 64 kbps

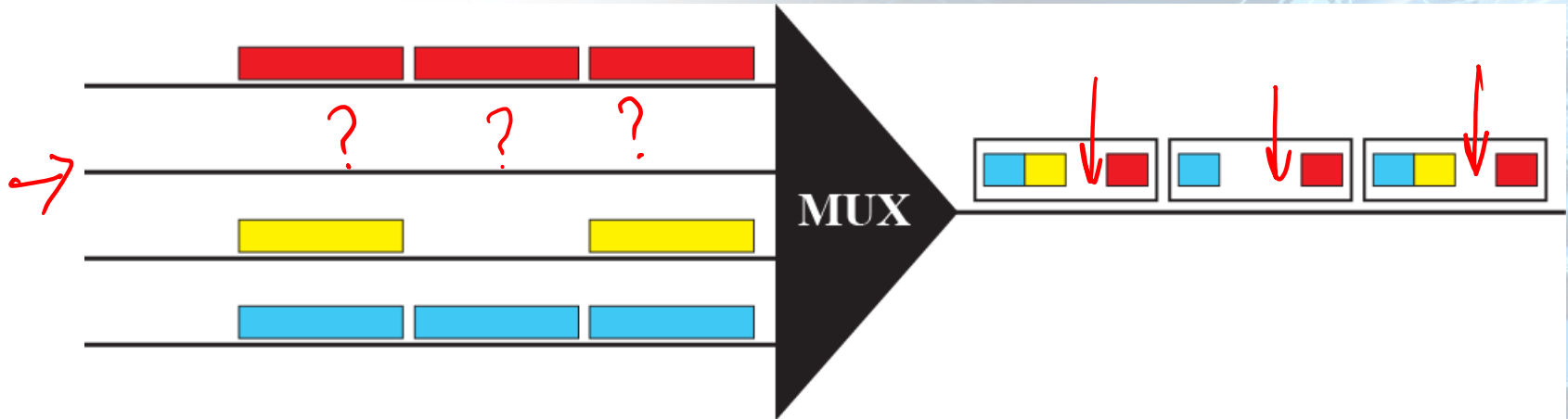
E Line Rates

<i>Line</i>	<i>Rate (Mbps)</i>	<i>Voice Channels</i>
E-1	2.048	30
E-2	8.448	120
E-3	34.368	480
E-4	139.264	1920

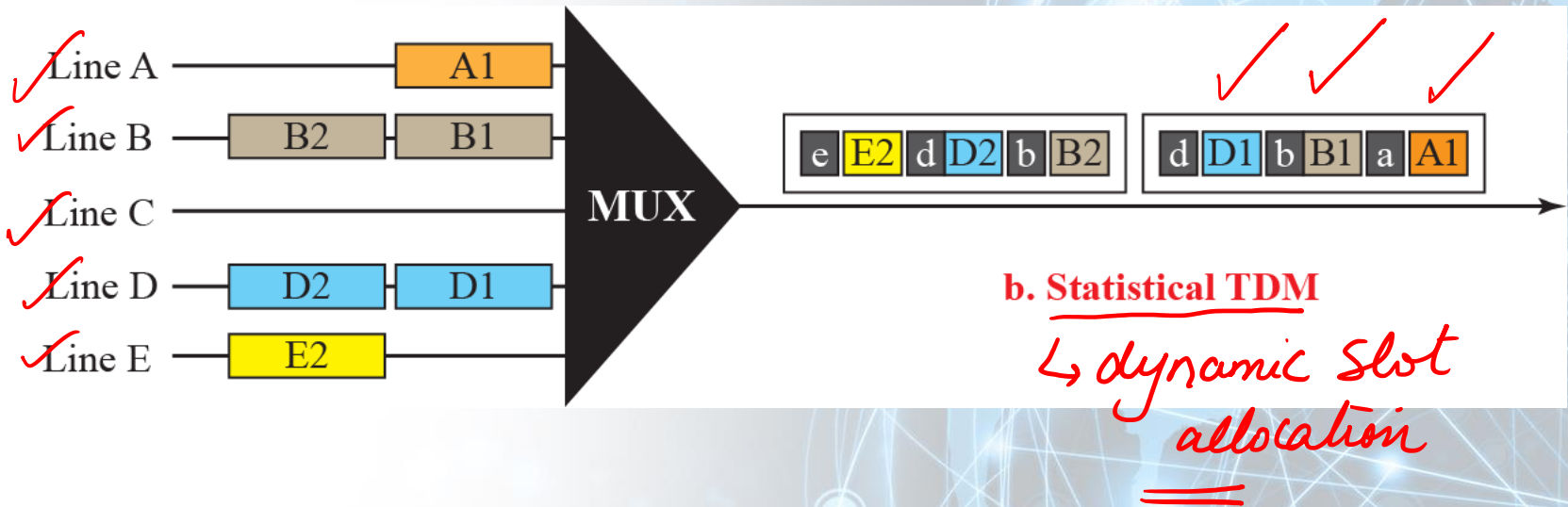
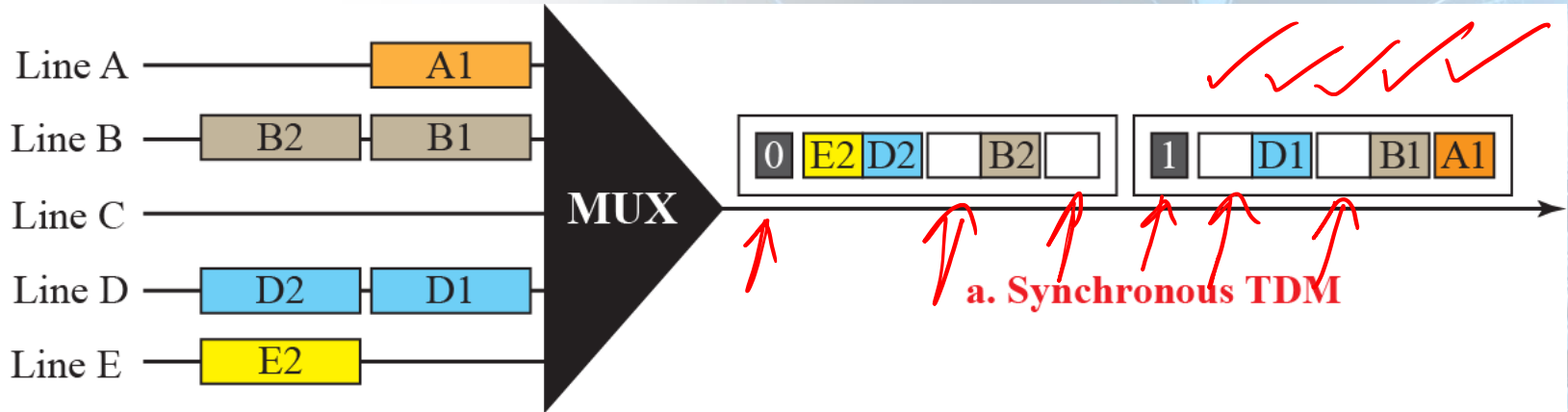
Time-Division Multiplexing

- Synchronous TDM
- Statistical TDM

Empty slots



Statistical TDM



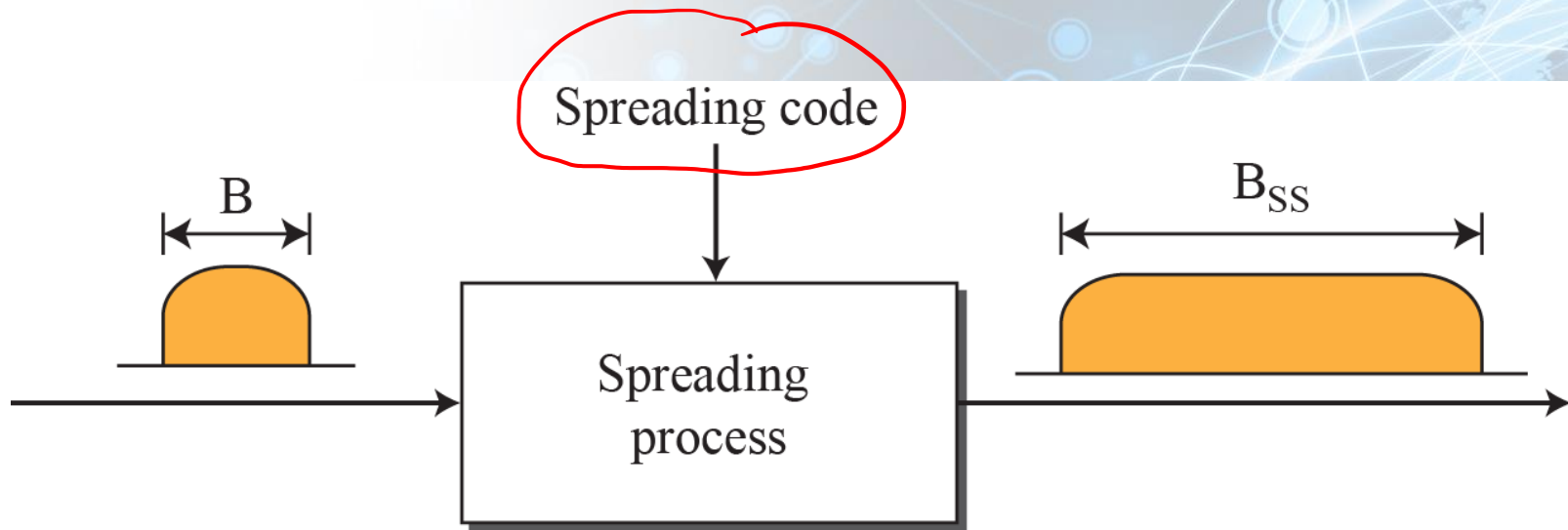
SPREAD SPECTRUM

- In wireless applications, stations must be able to share the medium without interception by an eavesdropper and without being subject to jamming from a malicious intruder
- To achieve these goals, spread spectrum adds redundancy and spread original spectrum needed for each station

SPREAD SPECTRUM - Principles

- **Bandwidth allocated to each station needs to be larger than what is needed to allow Redundancy**
- **Spreading process should be independent of the original signal**

Spread Spectrum



$$B_{SS} > B$$

SPREAD SPECTRUM TECHNIQUES

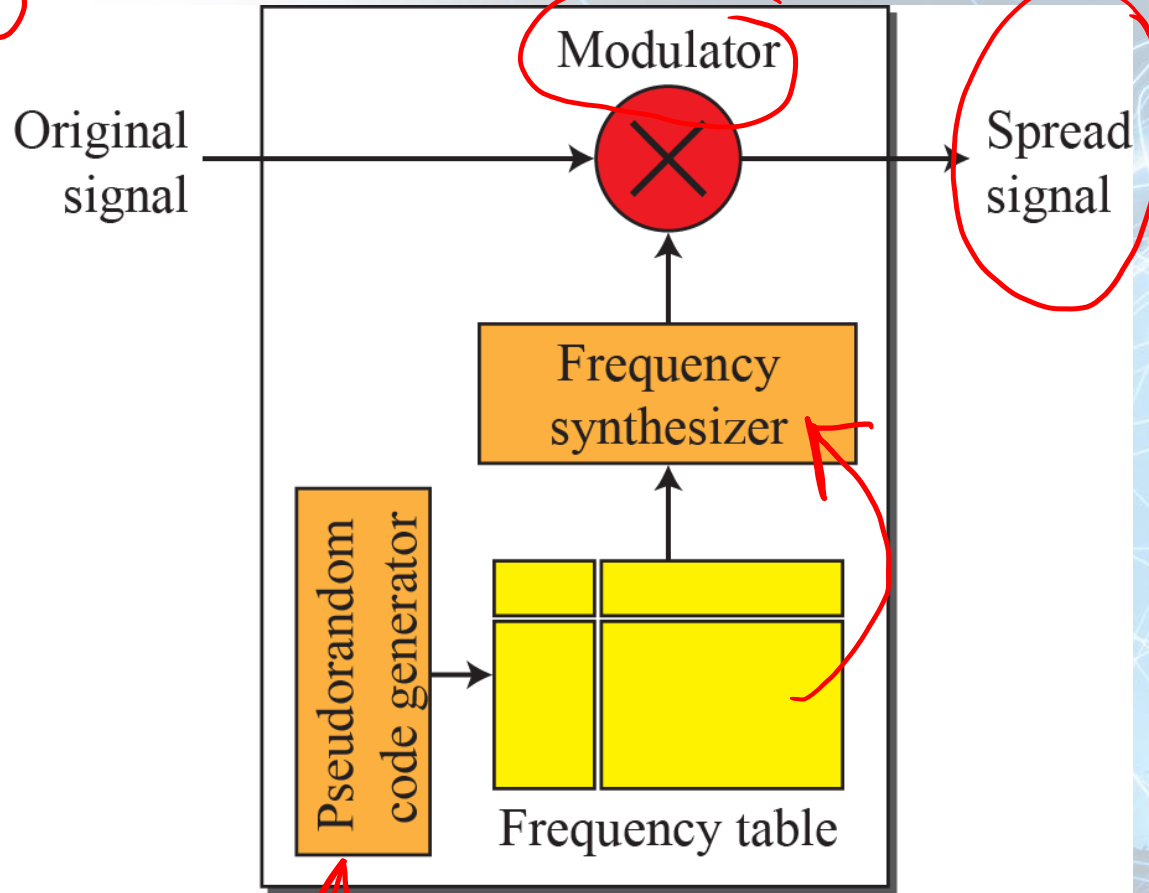
- **Frequency Hopping Spread Spectrum (FHSS)**
- **Direct Sequence Spread Spectrum (DSSS)**

Frequency Hopping Spread Spectrum (FHSS)

- **'M' different carrier frequencies that are modulated by the source signal**
- **At one moment, signal modulates one carrier frequency and at next moment, it modulates another**

Frequency Hopping Spread Spectrum (FHSS)

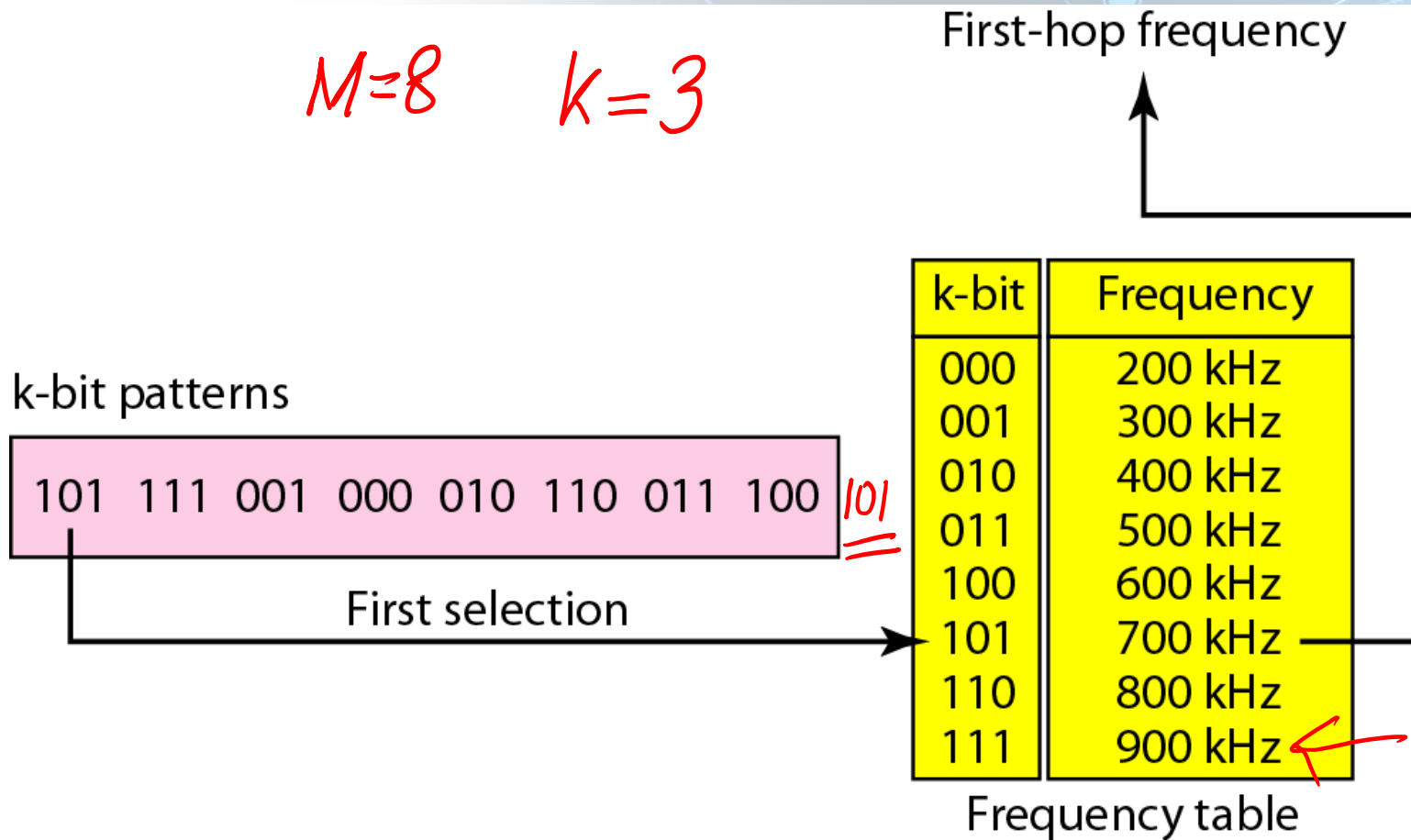
$$B_{FHSS} \gg B$$



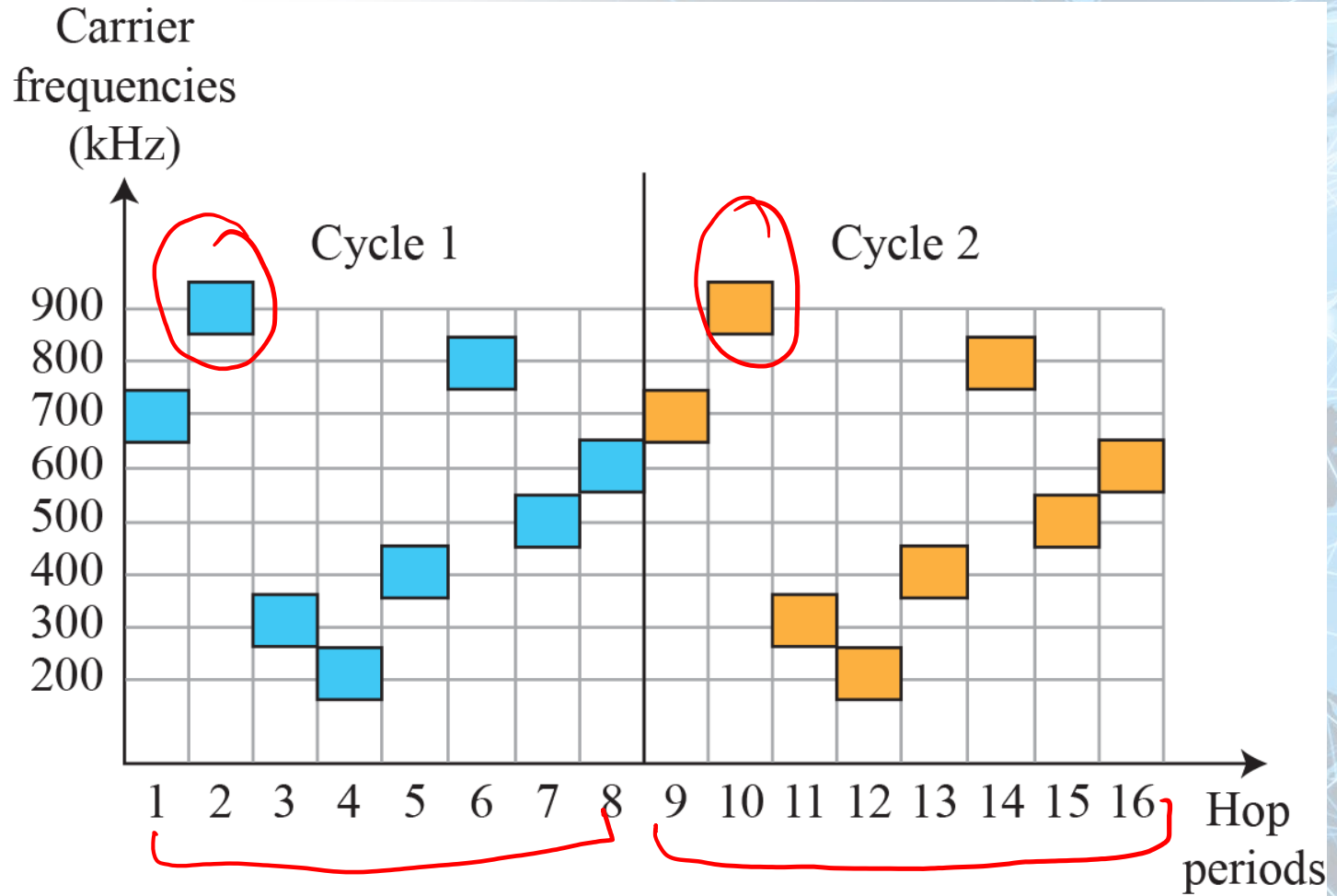
k-bit pattern (T_h)

Frequency Selection in FHSS

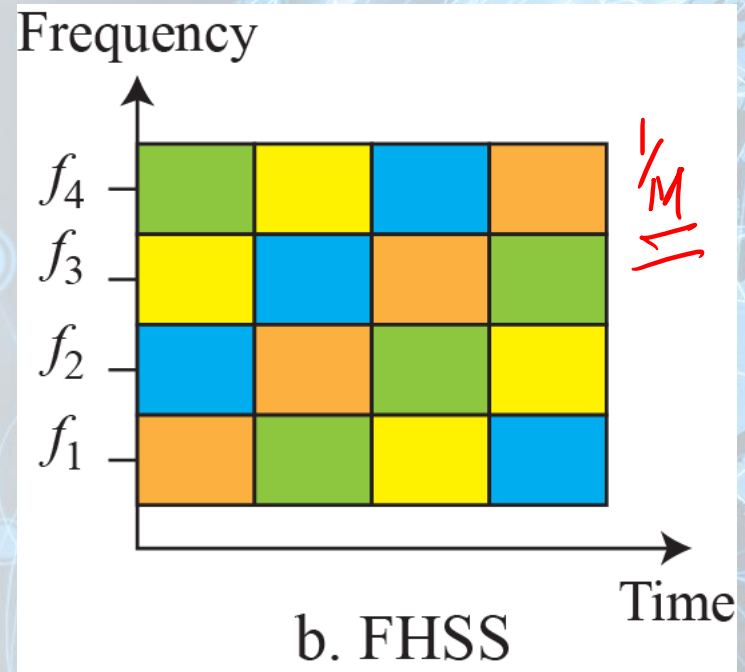
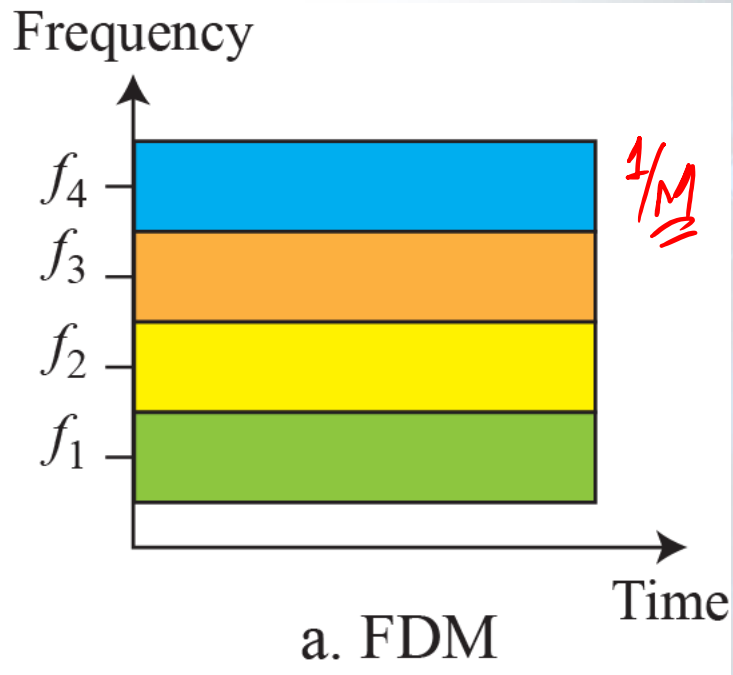
$M=8$ $k=3$



FHSS Cycles



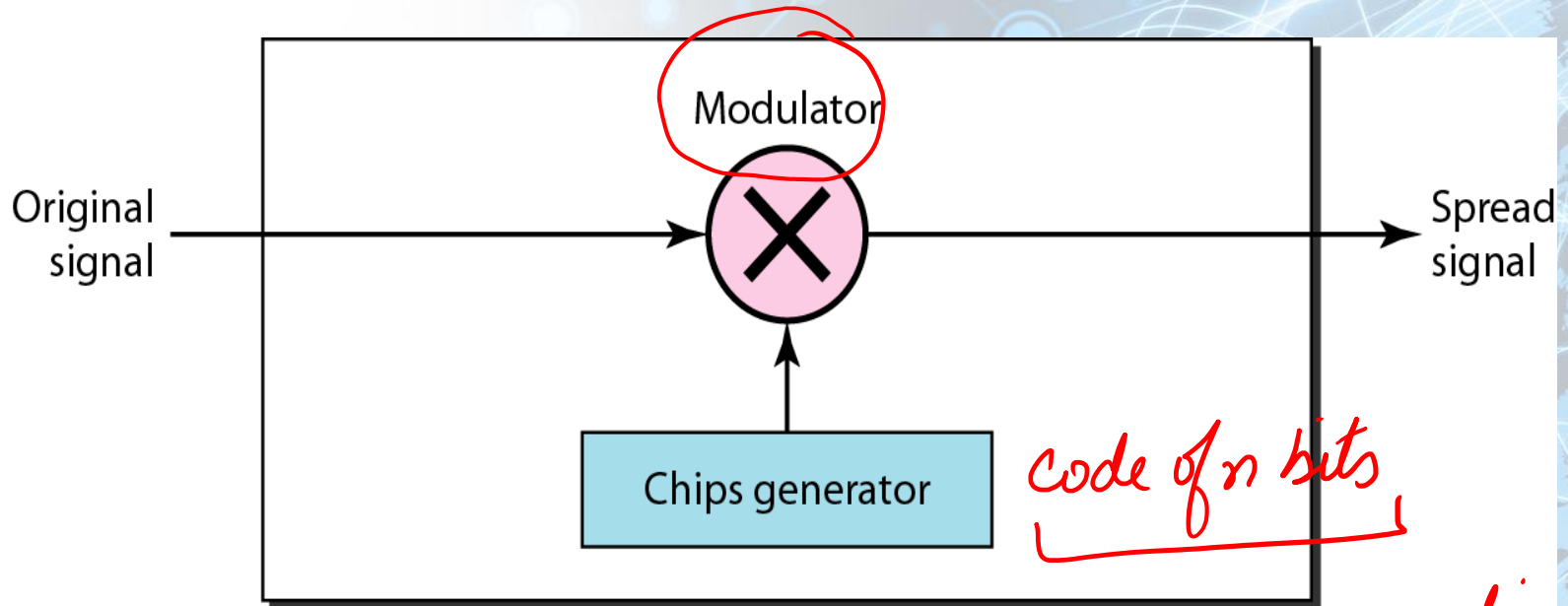
Bandwidth Sharing



DSSS

- DSSS also expands the bandwidth of the original signal, but the process is different
- We replace each data bit with 'n' bits using a spreading code
- Each bit is assigned a code of 'n' bits, called chips, where the chip rate is 'n' times that of the data bit

DSSS



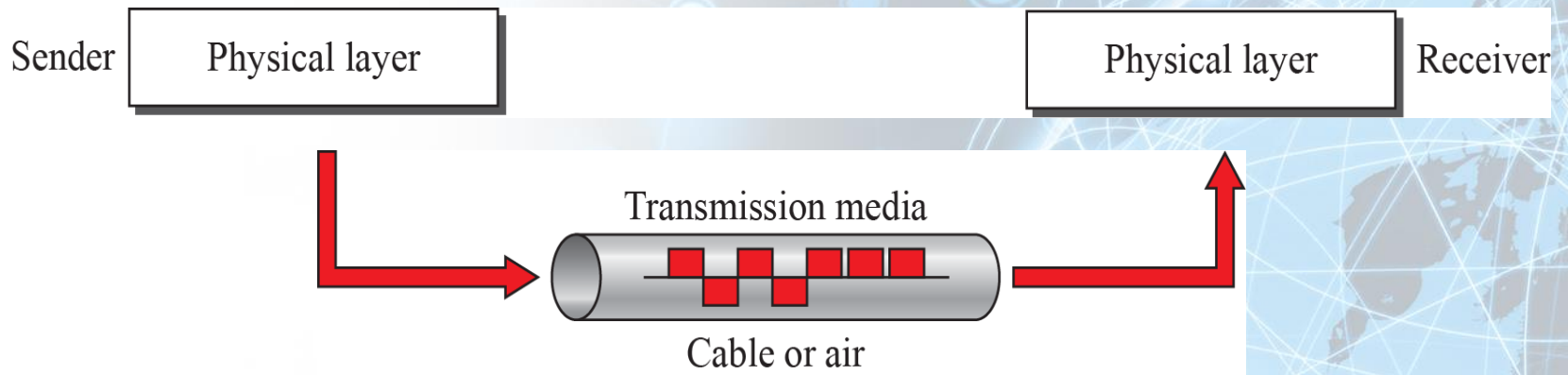
code of n bits

chips → Spreading code

Transmission Media

- Located below the physical layer and are directly controlled by the physical layer
- Belong to layer zero
- Metallic Media i.e. Twisted pair and Coaxial Cable
- Optical Fiber Cable
- Free Space i.e. Air, Vacuum

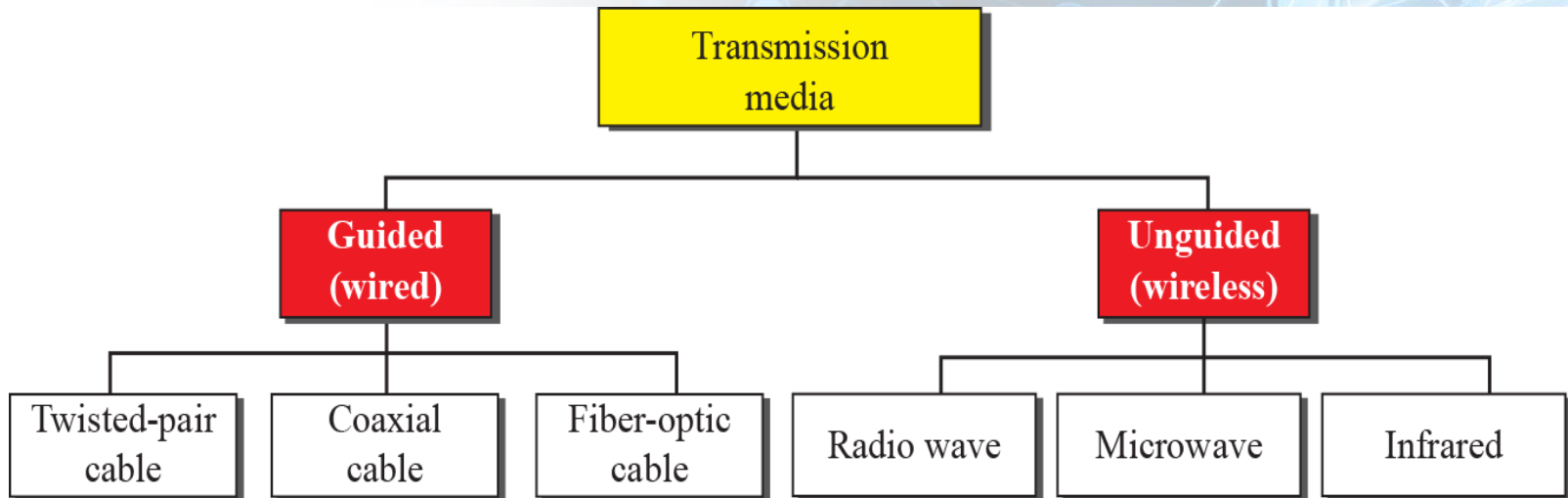
Transmission Media & Physical Payer



Transmission Media

- Located below the physical layer and are directly controlled by the physical layer
- Belong to layer zero
- Metallic Media i.e. Twisted pair and Coaxial Cable
- Optical Fiber Cable
- Free Space i.e. Air, Vacuum

Classes of Transmission Media



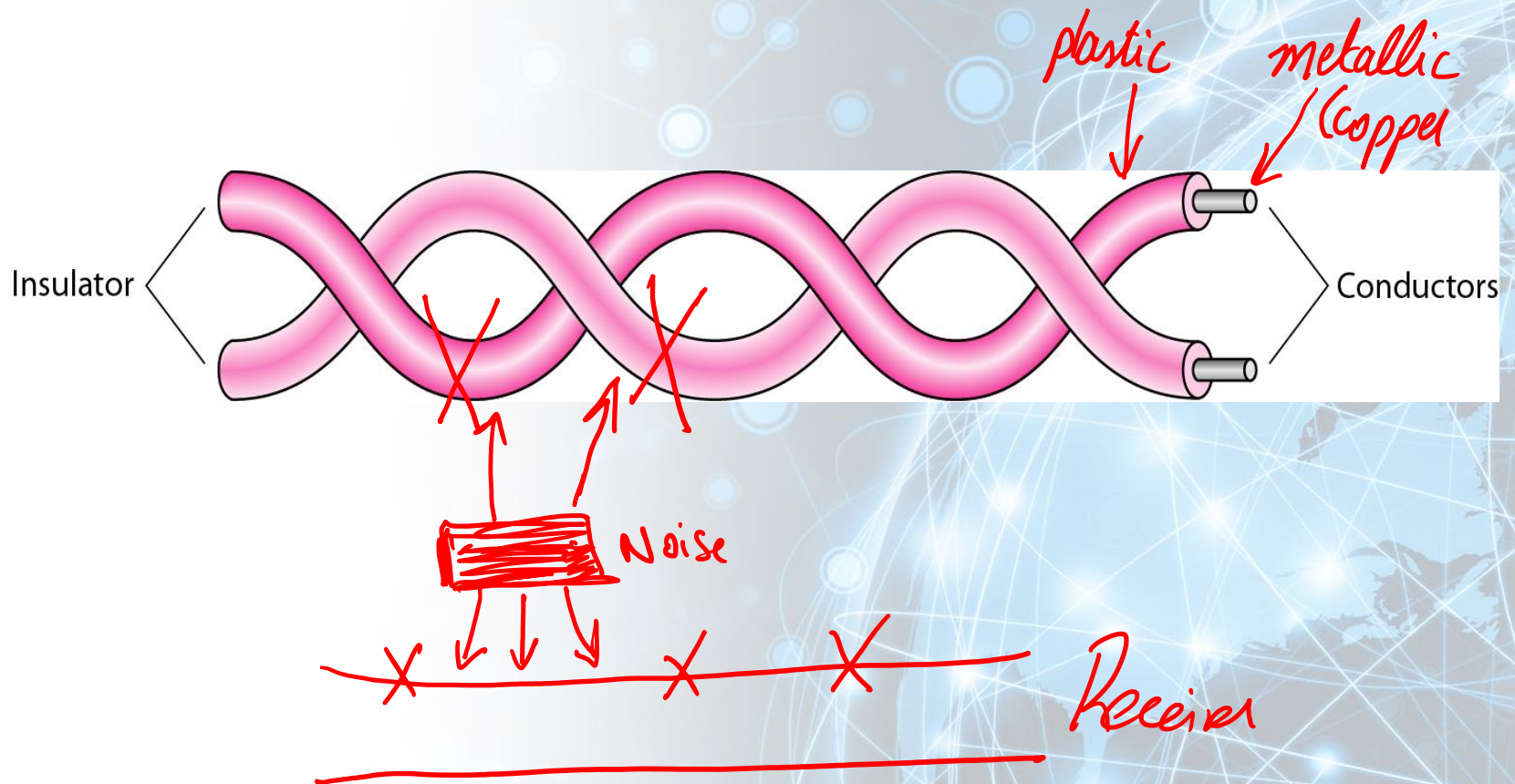
Guided Media

- **Media that provides a conduit from one device to another**
- **Twisted-pair cable, coaxial cable, and fiber-optic cable**
- **Signal traveling along any of these media is directed and contained by the physical limits of the medium**

Twisted-Pair Cable

- Consists of 2 copper conductors, each with its own plastic insulation, twisted together
- One wire carries signals and other is ground reference
- Receiver uses difference between the two
- Interference (Noise) & Crosstalk

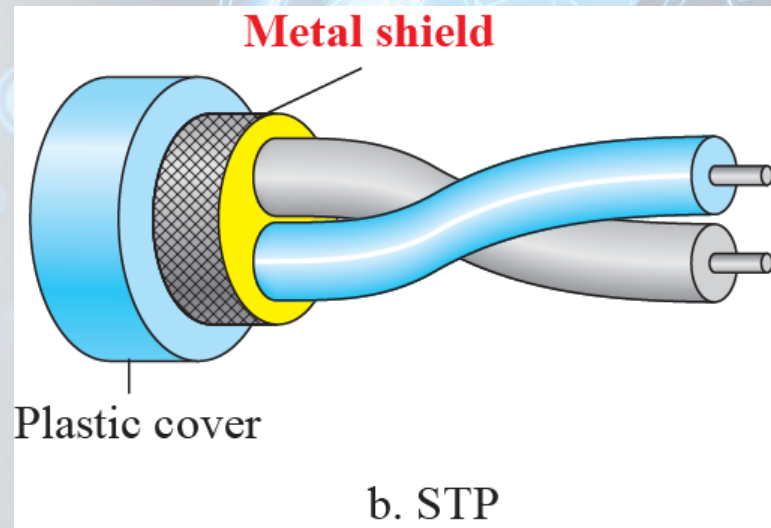
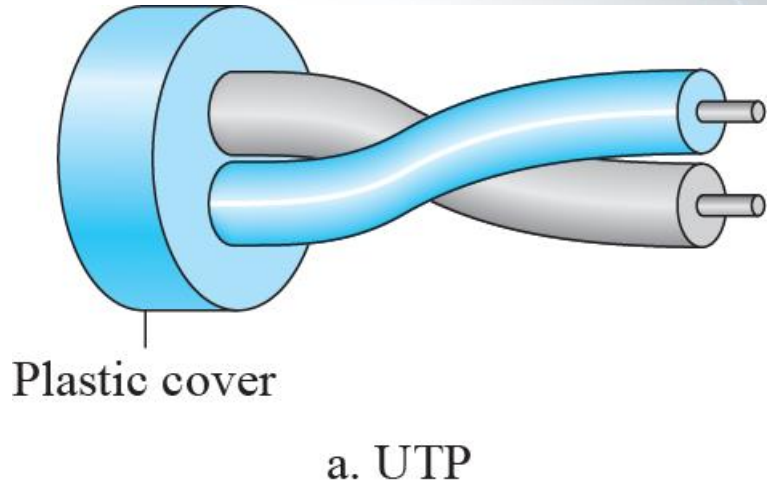
Twisted-Pair Cable



Twisted-Pair Cable

- UTP
- STP

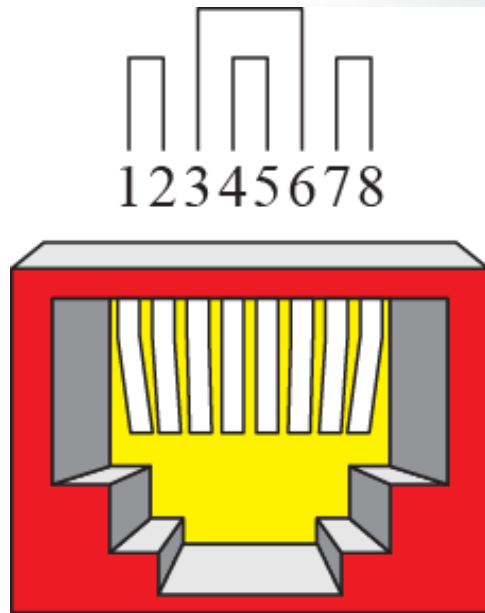
Unshielded vs. Shielded Twisted Pair Cable



Categories of Unshielded Twisted-Pair Cables

Category	Specification	Data Rate (Mbps)	Use
1	Unshielded twisted-pair used in telephone	< 0.1	Telephone
2	Unshielded twisted-pair originally used in T lines	2	T-1 lines
3	Improved CAT 2 used in LANs	10	LANs
4	Improved CAT 3 used in Token Ring networks	20	LANs
5	Cable wire is normally 24 AWG with a jacket and outside sheath	100	LANs
5E	An extension to category 5 that includes extra features to minimize the crosstalk and electromagnetic interference	125	LANs
6	A new category with matched components coming from the same manufacturer. The cable must be tested at a 200-Mbps data rate.	200	LANs
7	Sometimes called <i>SSTP (shielded screen twisted-pair)</i> . Each pair is individually wrapped in a helical metallic foil followed by a metallic foil shield in addition to the outside sheath. The shield decreases the effect of crosstalk and increases the data rate.	600	LANs

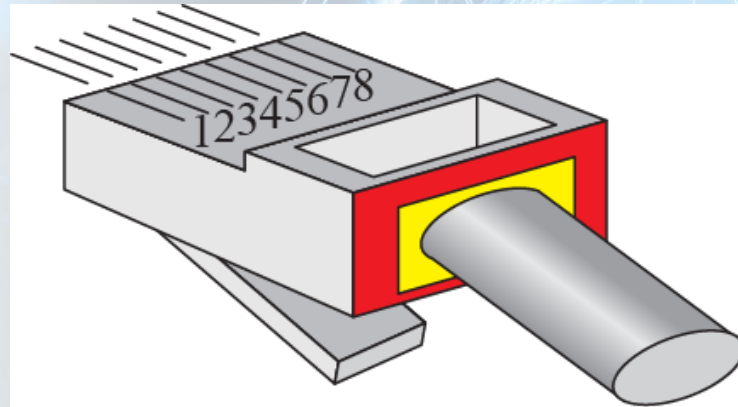
UTP Connectors



RJ-45 Female

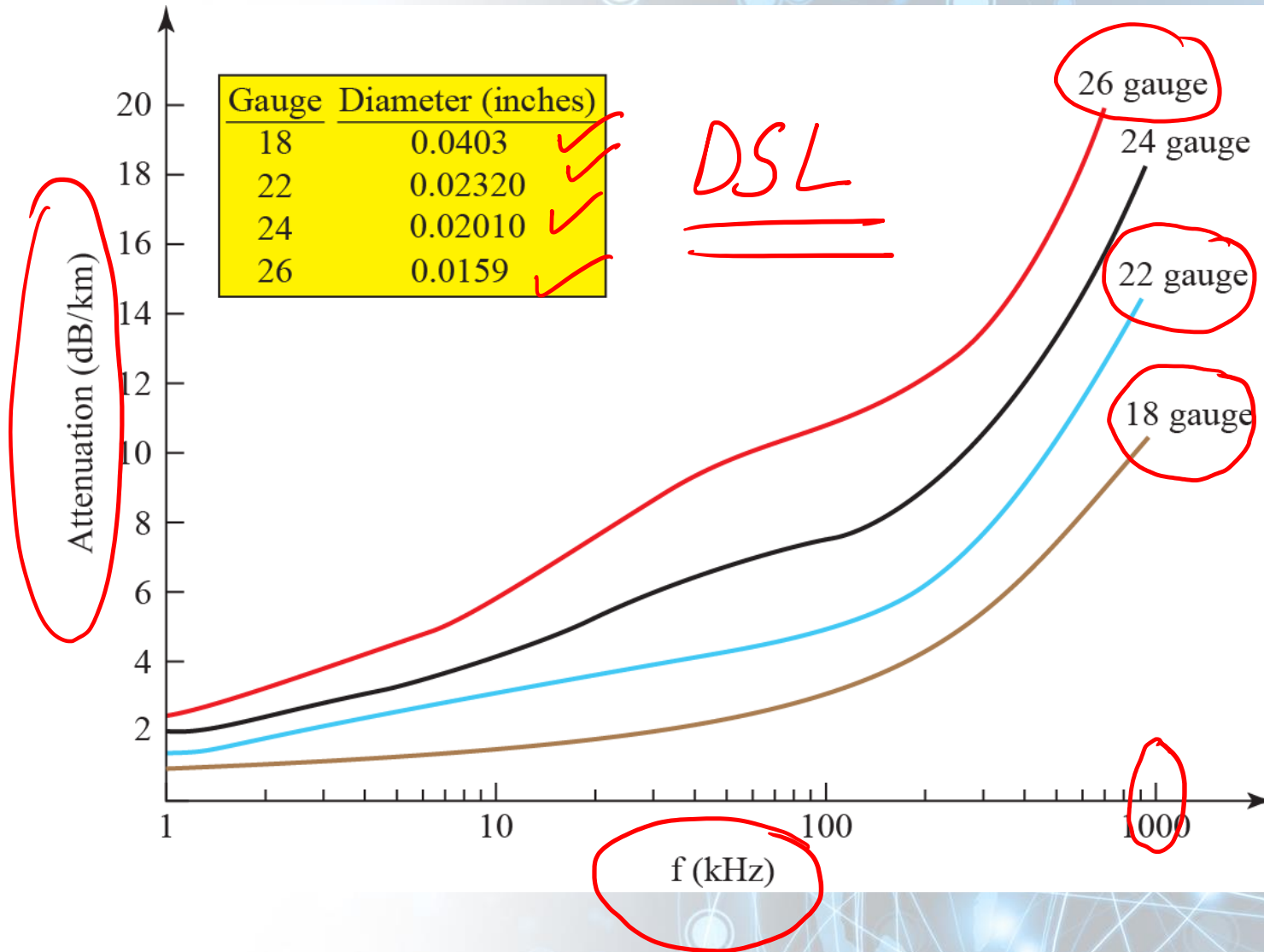
Registered Jack

Keyed



RJ-45 Male

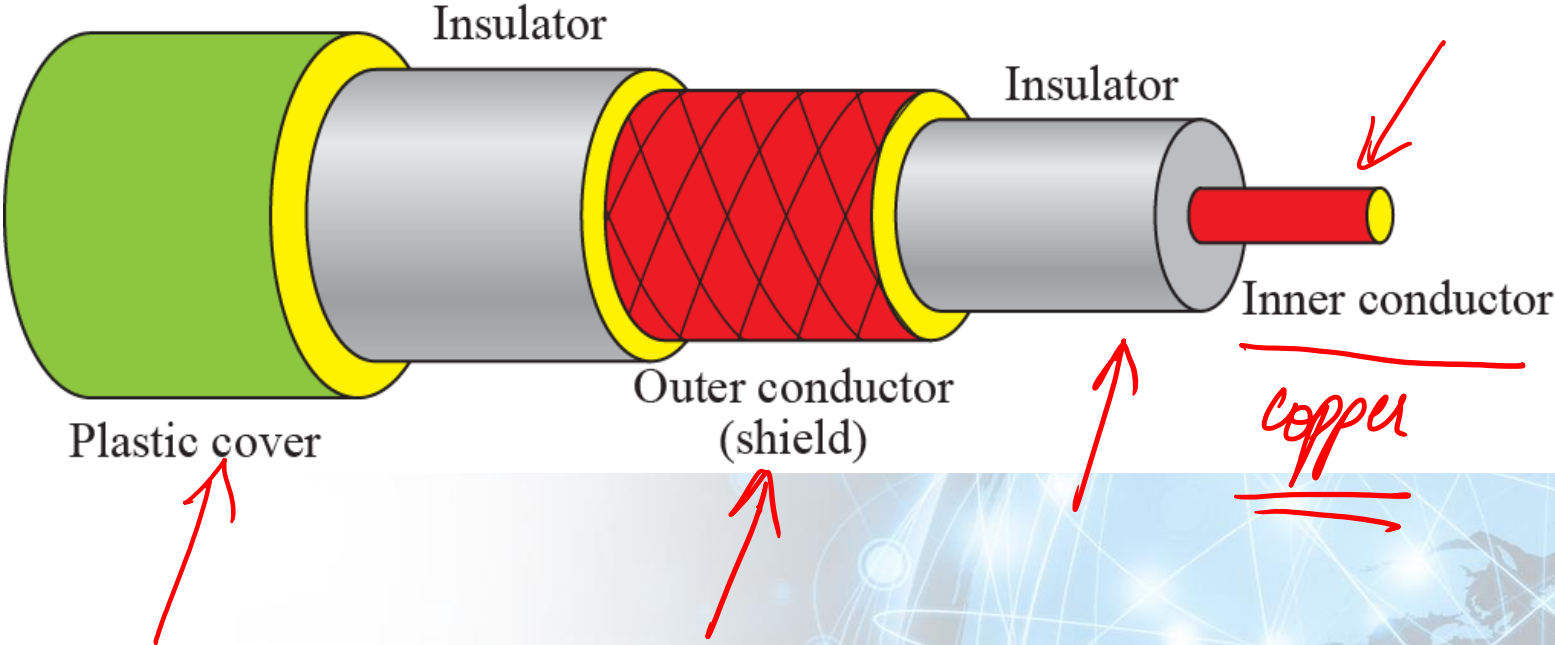
UTP Performance



Coaxial Cable

- **Carries signals of higher frequency ranges than those in twisted pair cable**

Coaxial Cable



Categories of Coaxial Cables

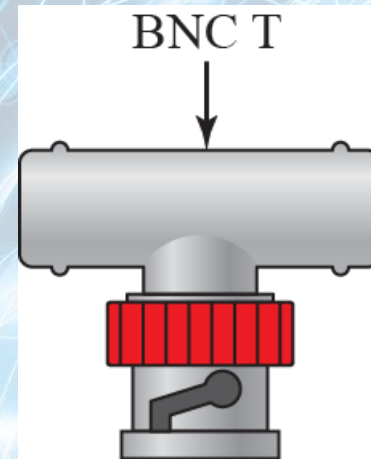
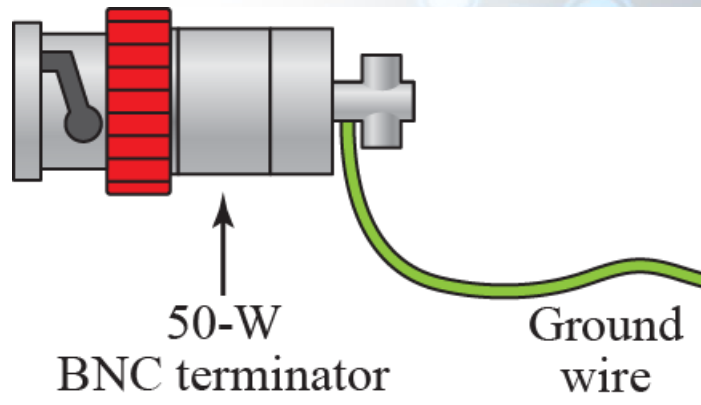
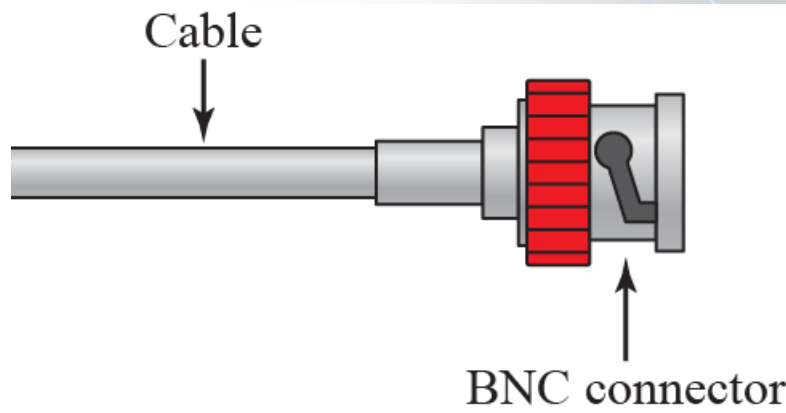
<i>Category</i>	<i>Impedance</i>	<i>Use</i>
RG-59	75 Ω	Cable TV
RG-58	50 Ω	Thin Ethernet
RG-11	50 Ω	Thick Ethernet

ohms

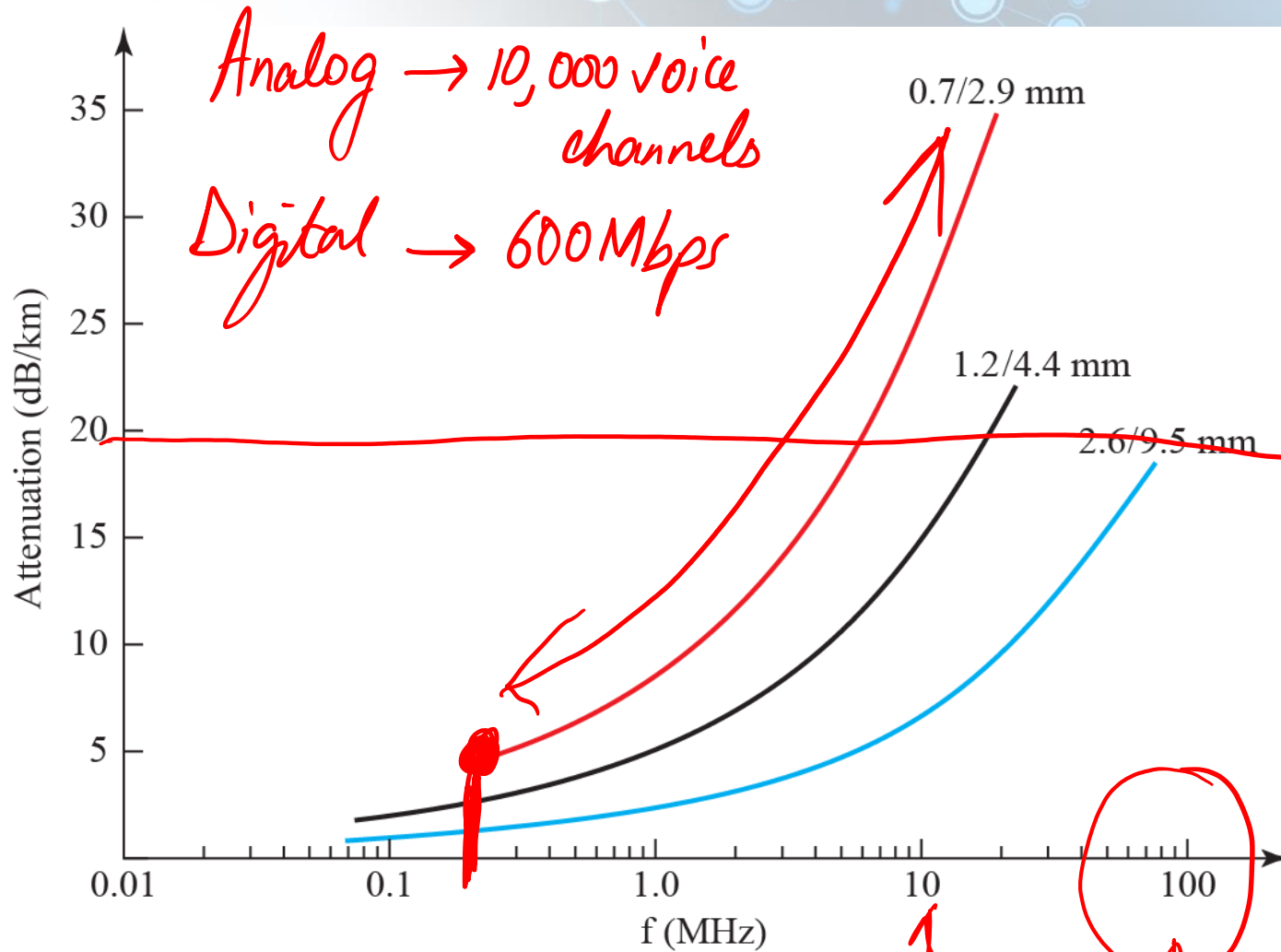
Coaxial Cable

- **Carries signals of higher frequency ranges than those in twisted pair cable**

BNC Connectors



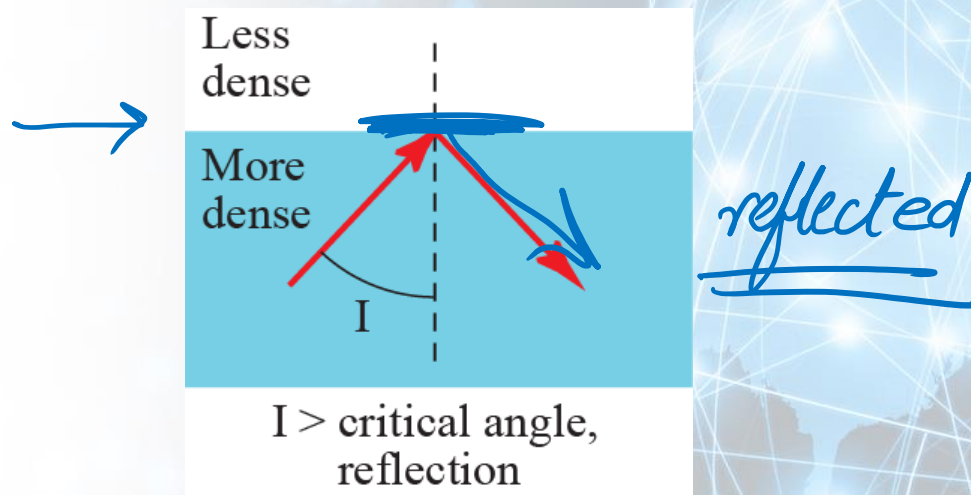
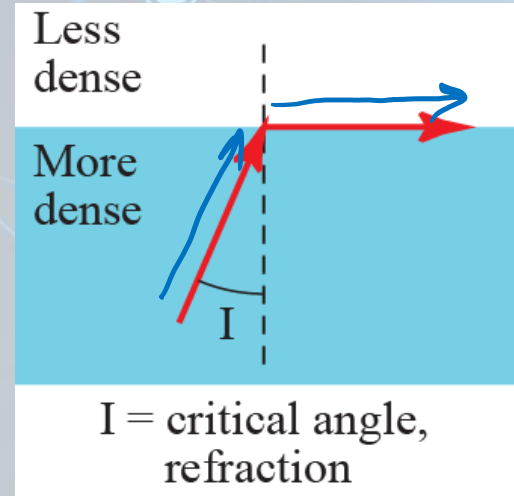
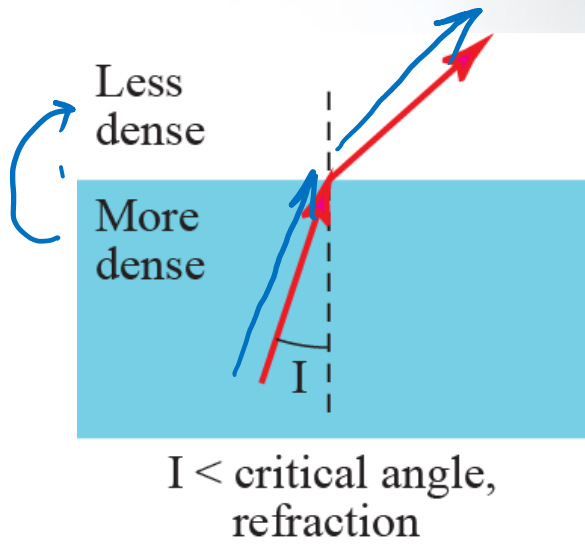
Coaxial Cable Performance



Fiber-Optic Cable

- Made of glass or plastic and transmits signals in the form of light
- Light travels in a straight line as long as it is moving through a single uniform substance
- If a ray of light traveling through one substance suddenly enters another substance (of a different density), the ray changes direction

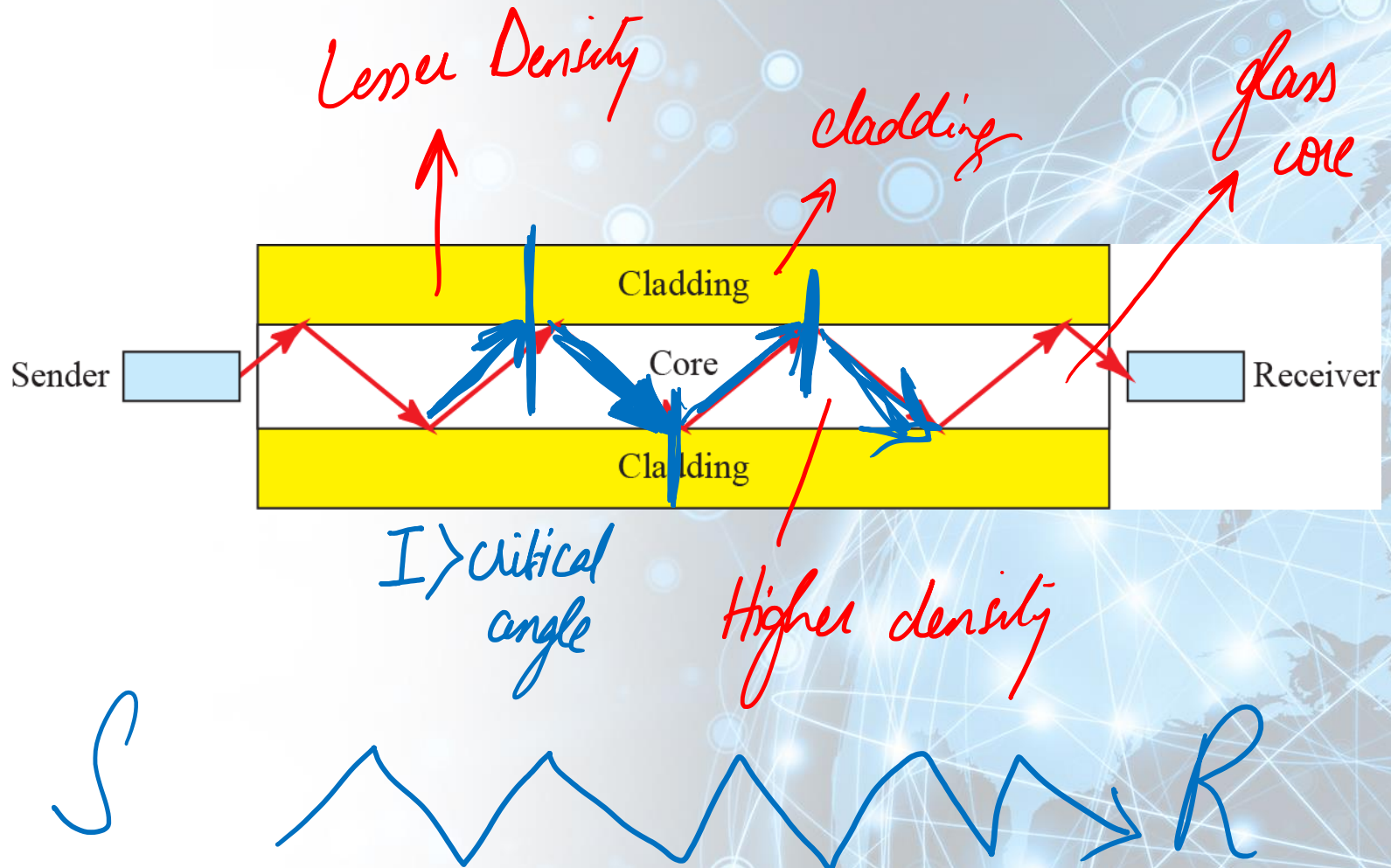
Bending of Light Ray



Fiber-Optic Cable

- Made of glass or plastic and transmits signals in the form of light

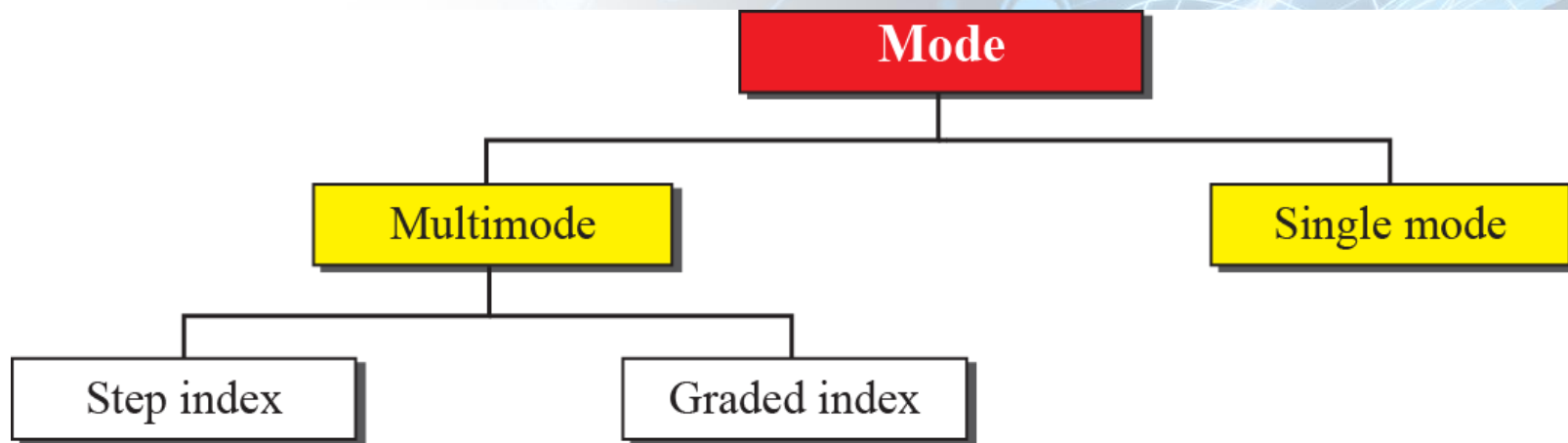
Optical Fiber



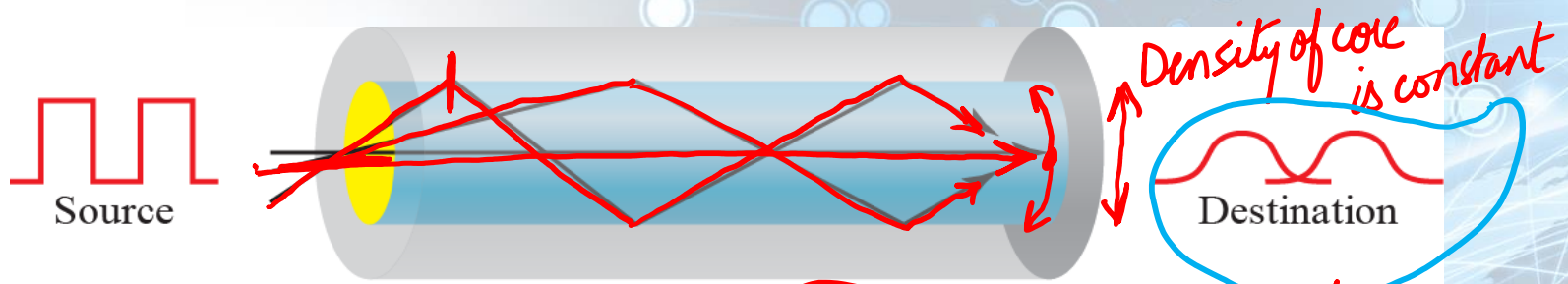
Fiber-Optic Cable

- Made of glass or plastic and transmits signals in the form of light

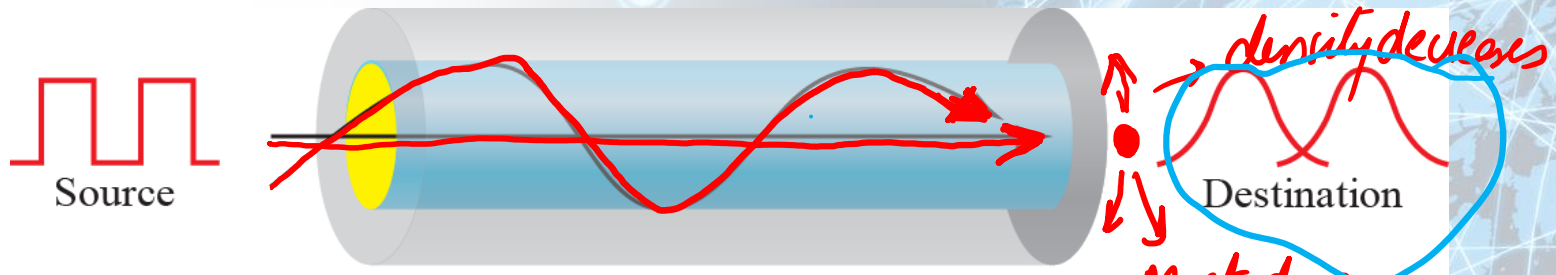
Propagation Modes



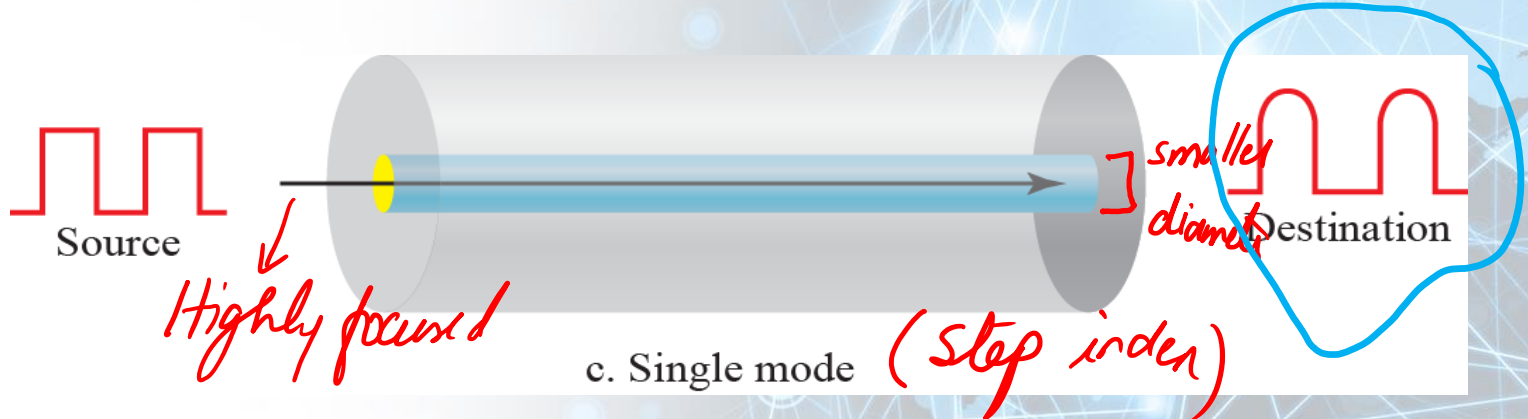
Modes



a. Multimode, step index sudden → distortion



b. Multimode, graded index



c. Single mode (step index)

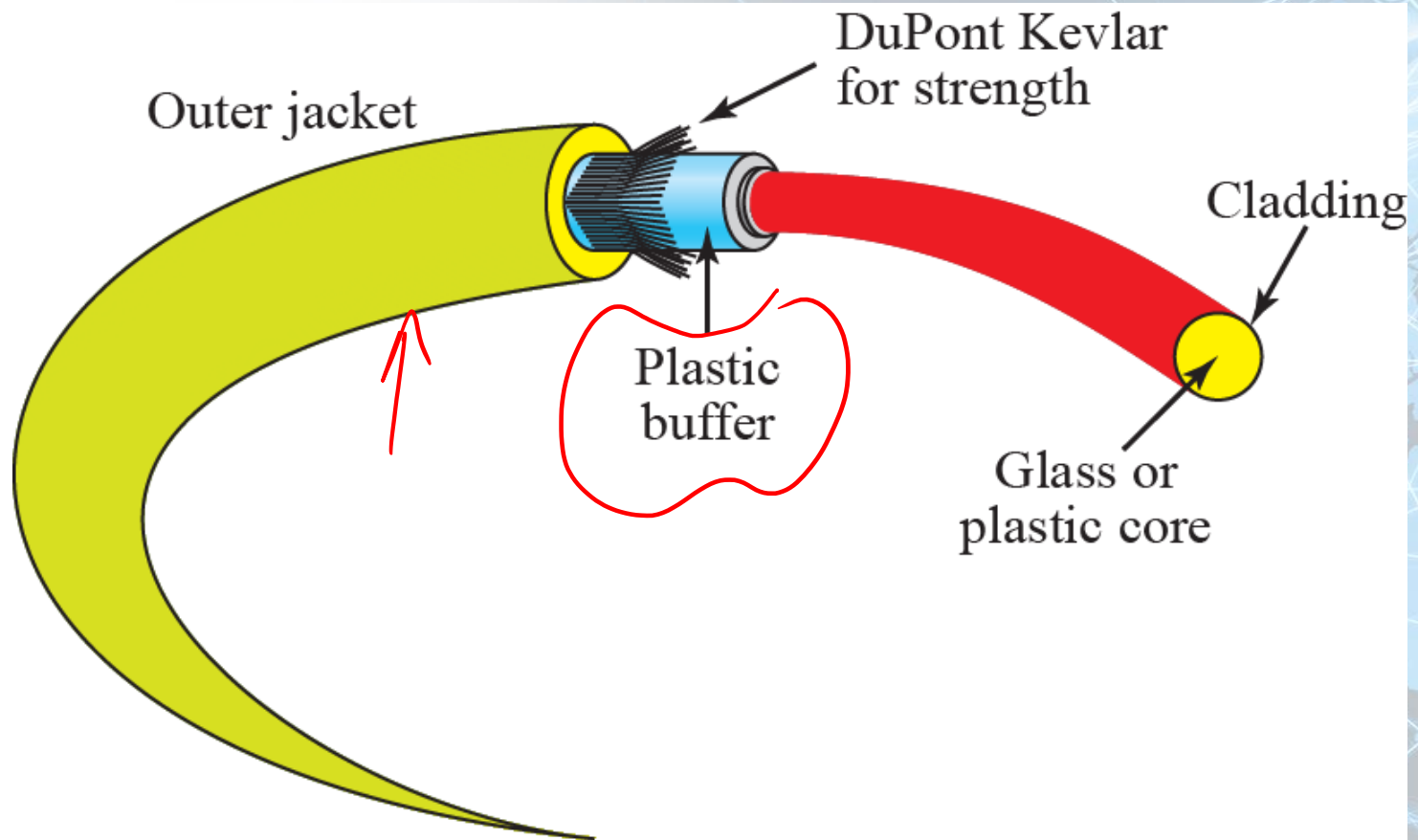
Fiber-Optic Cable

- Made of glass or plastic and transmits signals in the form of light

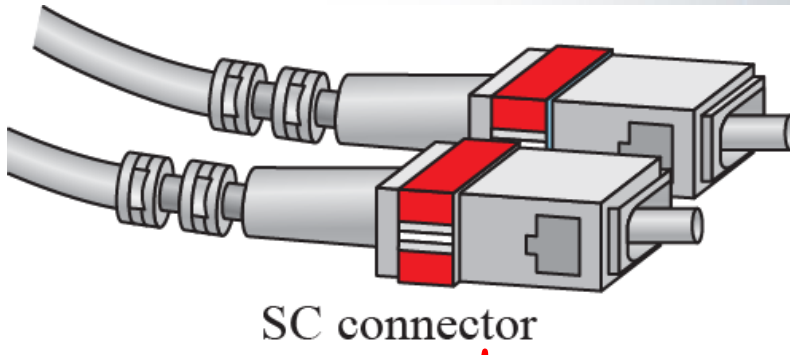
Fiber Types

<i>Type</i>	<i>Core (μm)</i>	<i>Cladding (μm)</i>	<i>Mode</i>
50/125	50.0	125	Multimode, graded index
62.5/125	62.5	125	Multimode, graded index
100/125	100.0	125	Multimode, graded index
7/125	7.0	125	Single mode

Fiber Composition

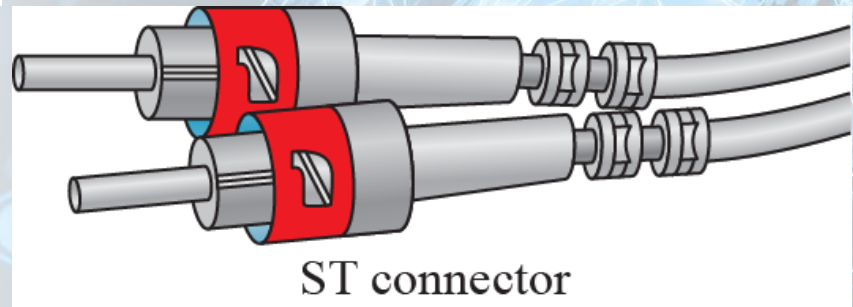


Fiber-Optic Cable Connector



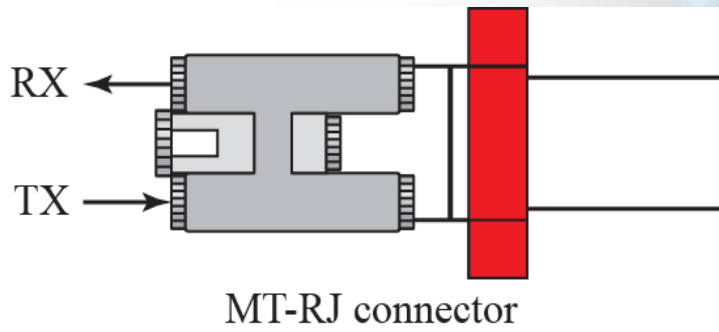
SC connector

Cable TV



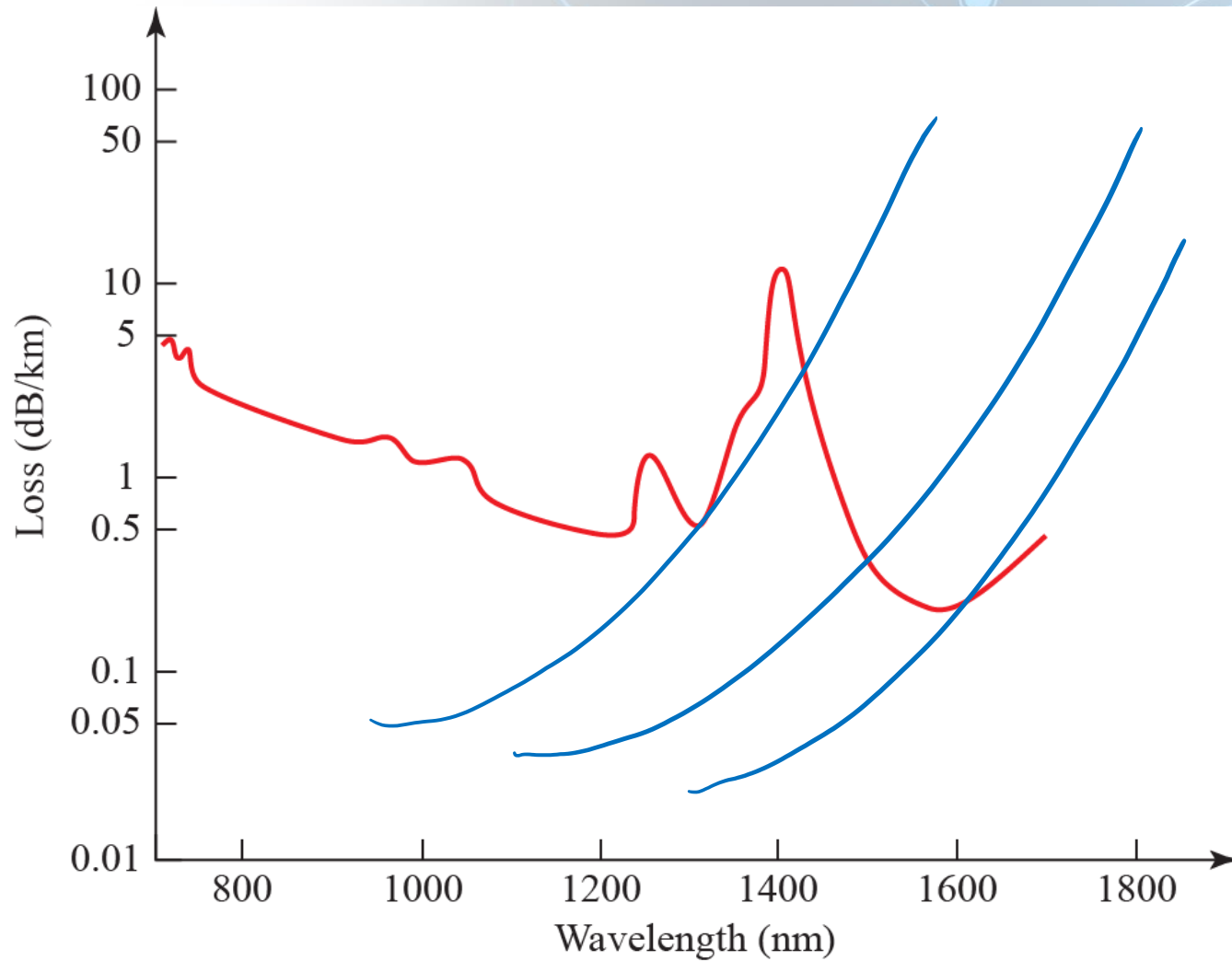
ST connector

*Networking
Routers*



MT-RJ connector

Optical Fiber Performance



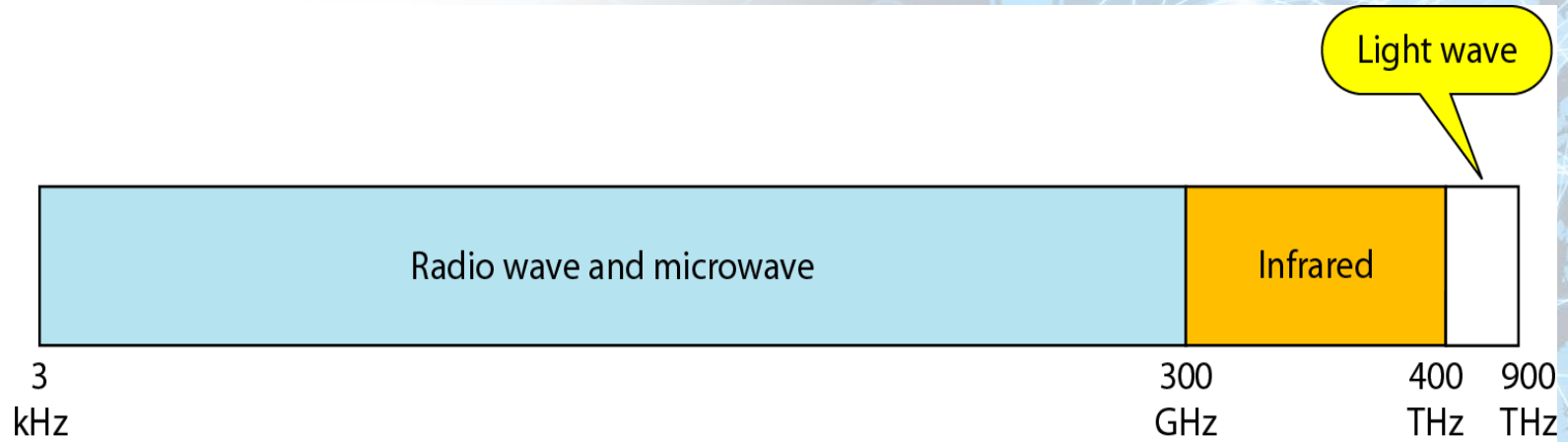
Advantages & Disadvantages

- Higher Bandwidth
- Less Attenuation
- Less EM Interference
- Light Weight
- Less corrosive than copper
- Installation/Maintenance
- Unidirectional
- Cost

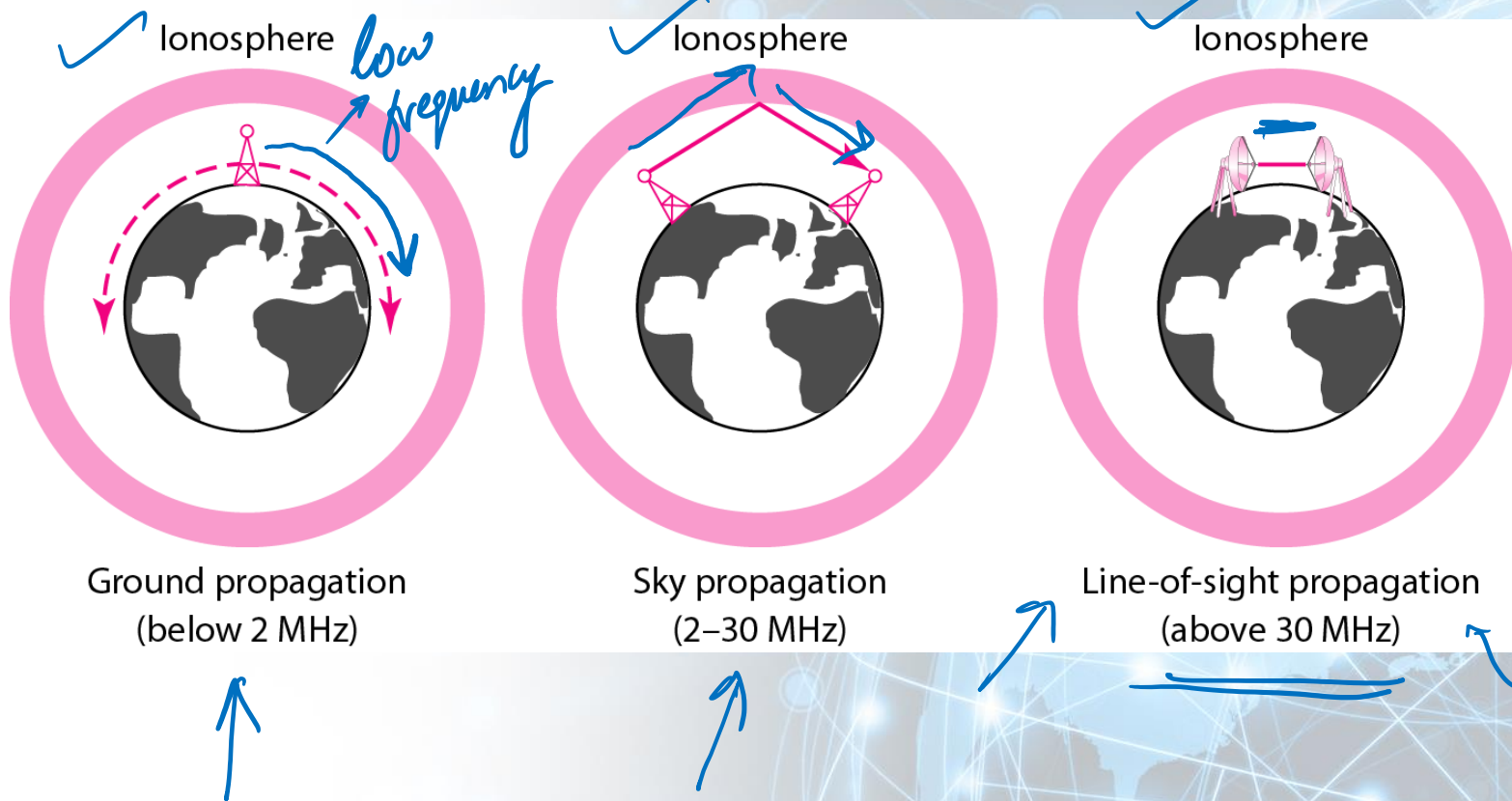
Unguided Media

- **Unguided medium transport waves without using a physical conductor**
- **Often referred to wireless communication**
- **Signals are normally broadcast through free space and thus are available to anyone who has a device capable of receiving them**

Electromagnetic Spectrum



Propagation Methods



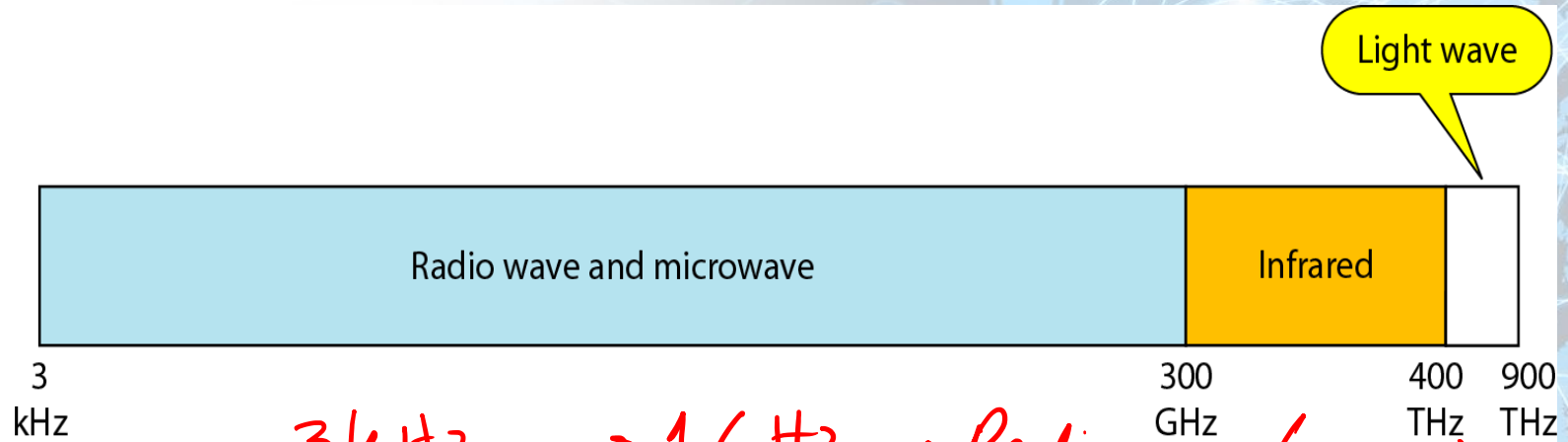
Bands

<i>Band</i>	<i>Range</i>	<i>Propagation</i>	<i>Application</i>
very low frequency (VLF)	3–30 kHz	Ground ✓	Long-range radio navigation ✓
low frequency (LF)	30–300 kHz	Ground ✓	Radio beacons and navigational locators ✓
middle frequency (MF)	300 kHz–3 MHz	Sky	AM radio ✓
high frequency (HF)	3–30 MHz	Sky	Citizens band (CB), ship/aircraft ✓
very high frequency (VHF)	30–300 MHz	Sky and line-of-sight	VHF TV, FM radio ✓
ultrahigh frequency (UHF)	300 MHz–3 GHz	Line-of-sight	UHF TV, cellular phones, paging, satellite ✓
superhigh frequency (SHF)	3–30 GHz	Line-of-sight	Satellite ✓
extremely high frequency (EHF)	30–300 GHz	Line-of-sight	Radar, satellite ✓

Radio Waves

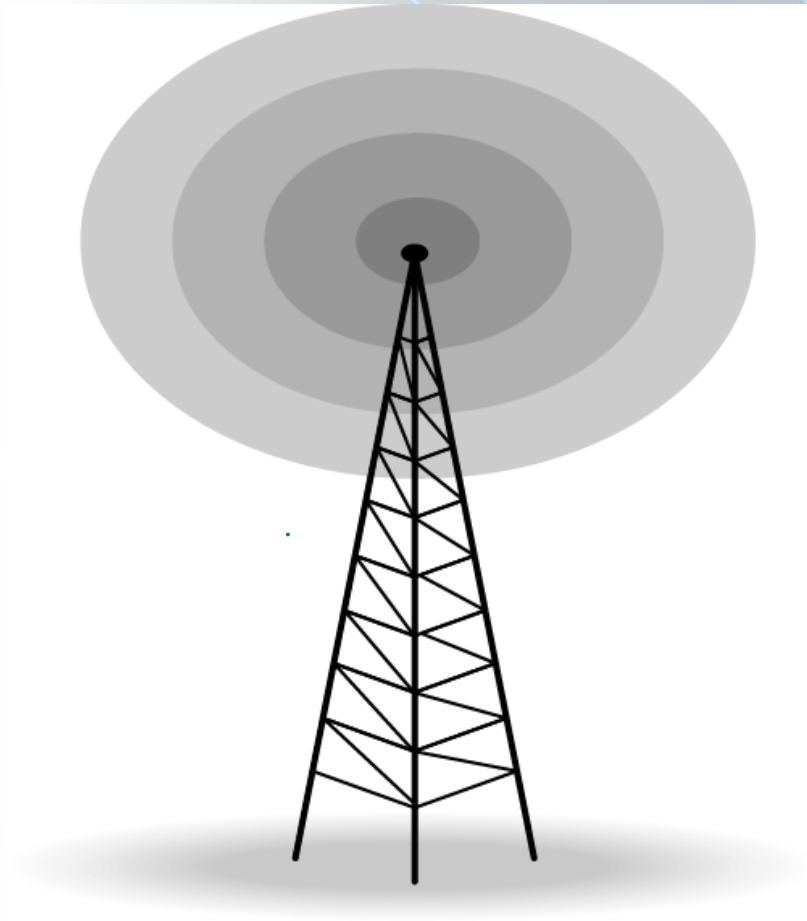
- **Electromagnetic waves ranging in frequencies between 3 kHz and 1 GHz are normally called radio waves**
- **Electromagnetic waves ranging in frequencies between 1 and 300 GHz are called microwaves**

Electromagnetic Spectrum



Sub-bands 3 kHz → 1 GHz → Radio waves (narrow)
1 GHz → 300 GHz → Microwaves

Omnidirectional Antenna



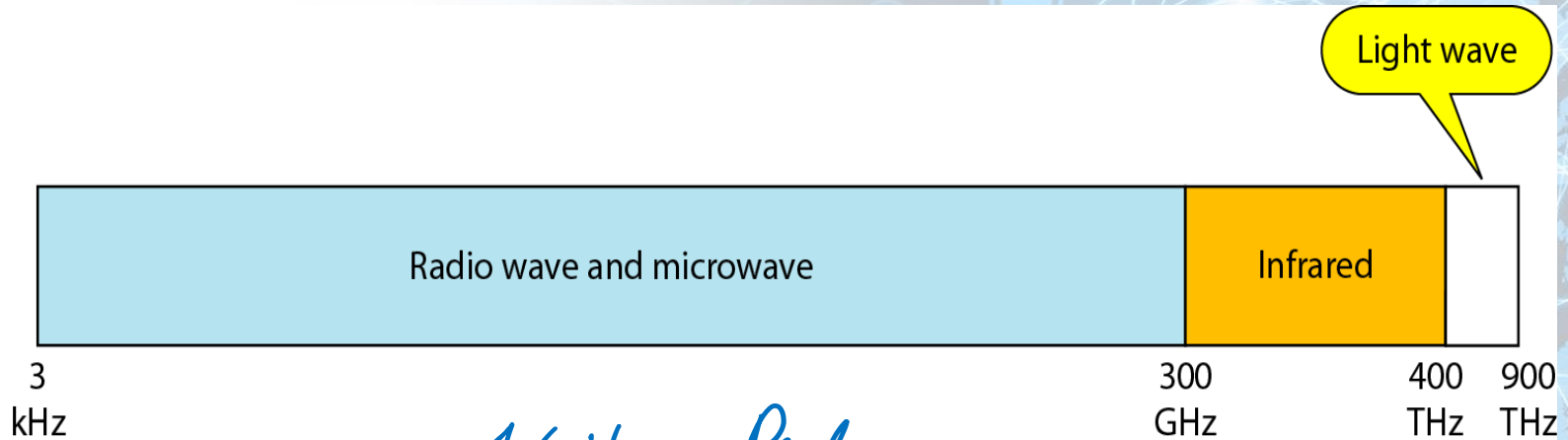
AM
FM } Radio

TV
cordless phones
pagers

Microwaves

- **Electromagnetic waves having frequencies between 1 and 300 GHz are called microwaves**
- **Microwaves are unidirectional**
- **When an antenna transmits microwaves, they can be narrowly focused**

Electromagnetic Spectrum

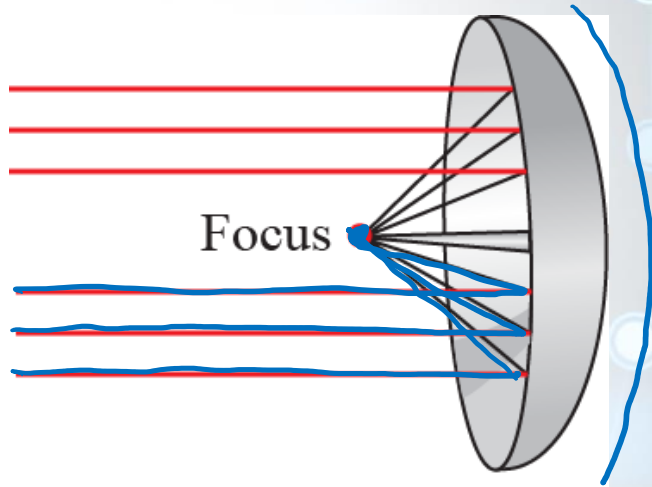


3kHz — 1GHz Radio waves

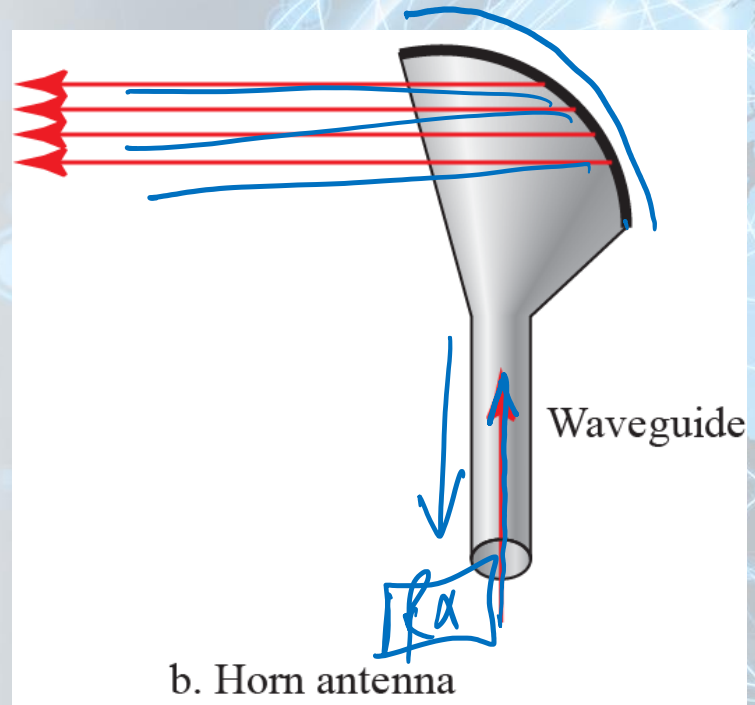
1GHz — 300GHz Microwaves (unidirectional)
(line of sight)

↓
299GHz → High data rates

Unidirectional Antennas



a. Parabolic dish antenna



b. Horn antenna

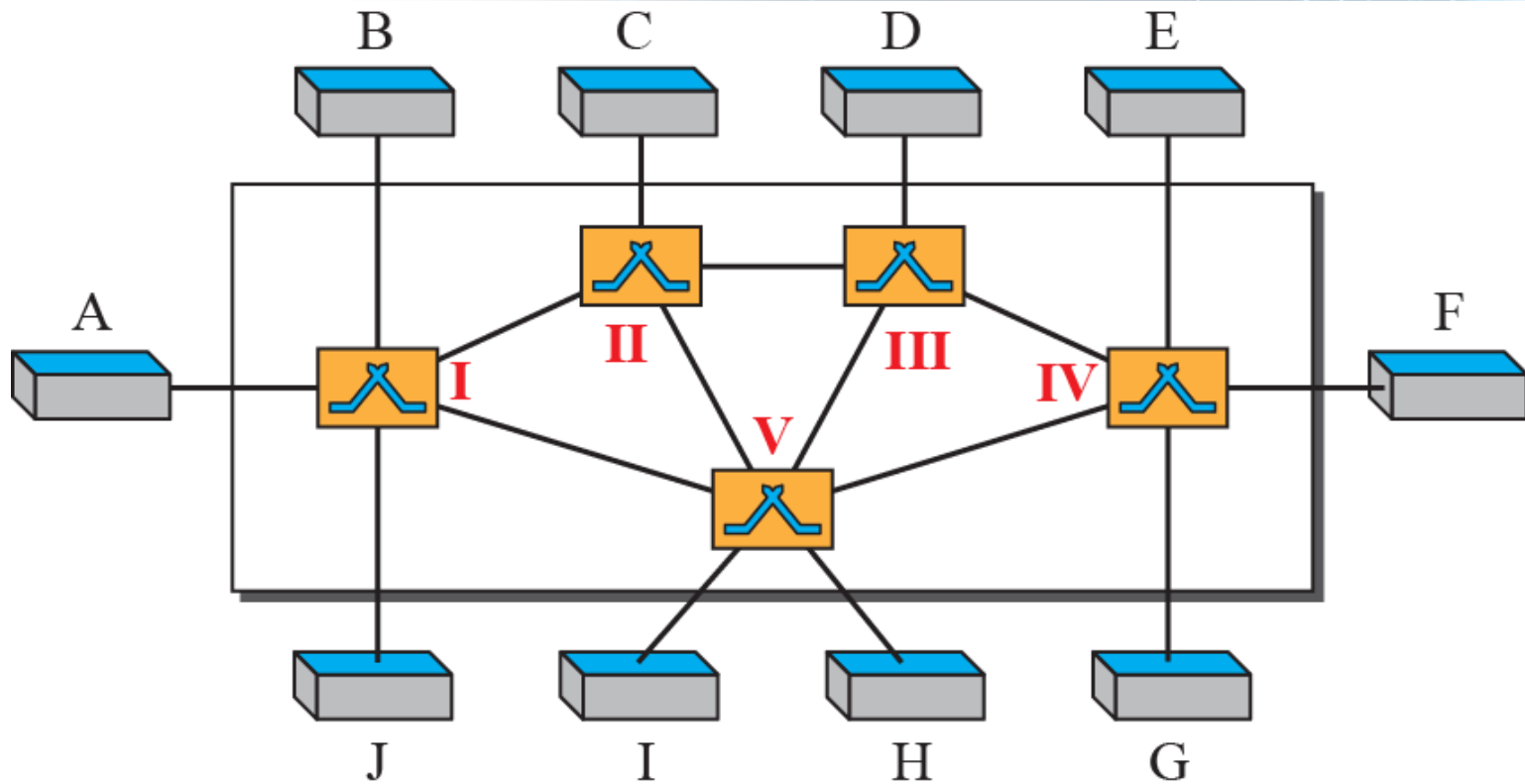
Infrared

- Infrared waves, with frequencies from 300 GHz to 400 THz (wavelengths from 1 mm to 770 nm), can be used for short-range communication
- Infrared waves, having high frequencies, cannot penetrate walls
- Prevents interference between one system and another

Switching

- A network is a set of connected devices
- Problem of how to connect multiple devices to make one-to-one communication possible
- The solution is Switching
- Switched network consists of a series of switches

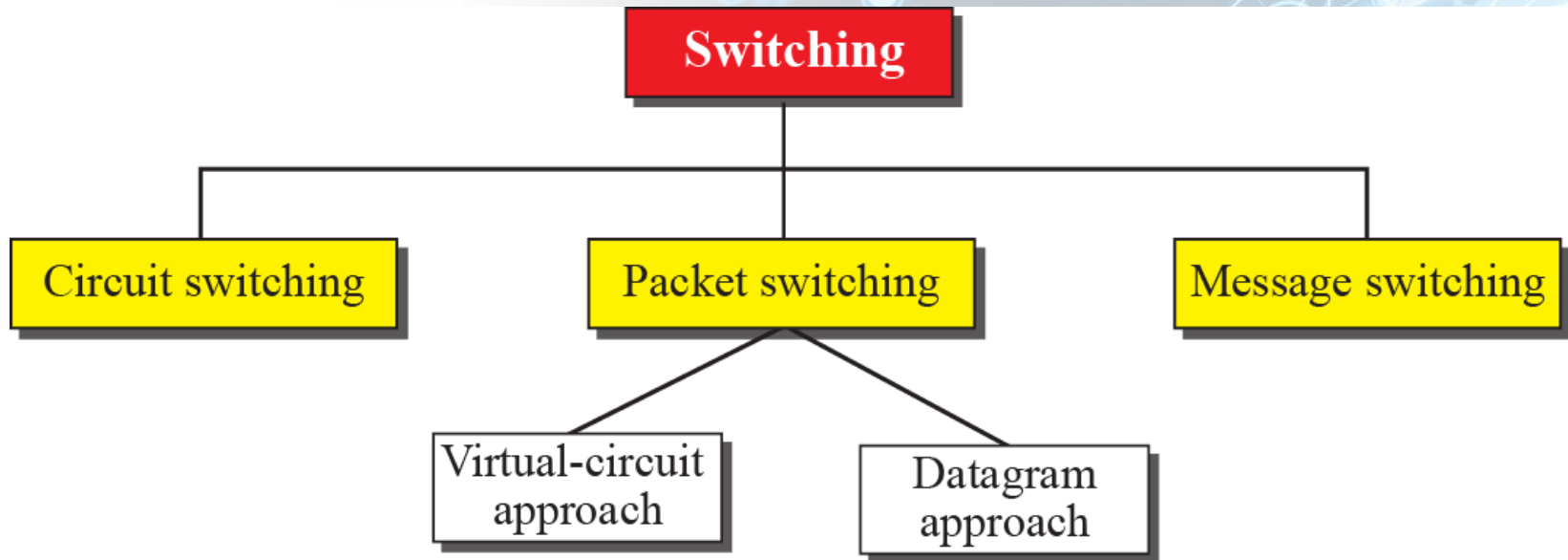
Switched Network



Three Methods of Switching

- **Three Methods:**
 - ✓ **Circuit Switching**
 - ✓ **Packet Switching**
 - ✓ **Message switching**
- **The first two are commonly used today**
- **The third has been phased out in general communications**

Taxonomy of Switched Networks



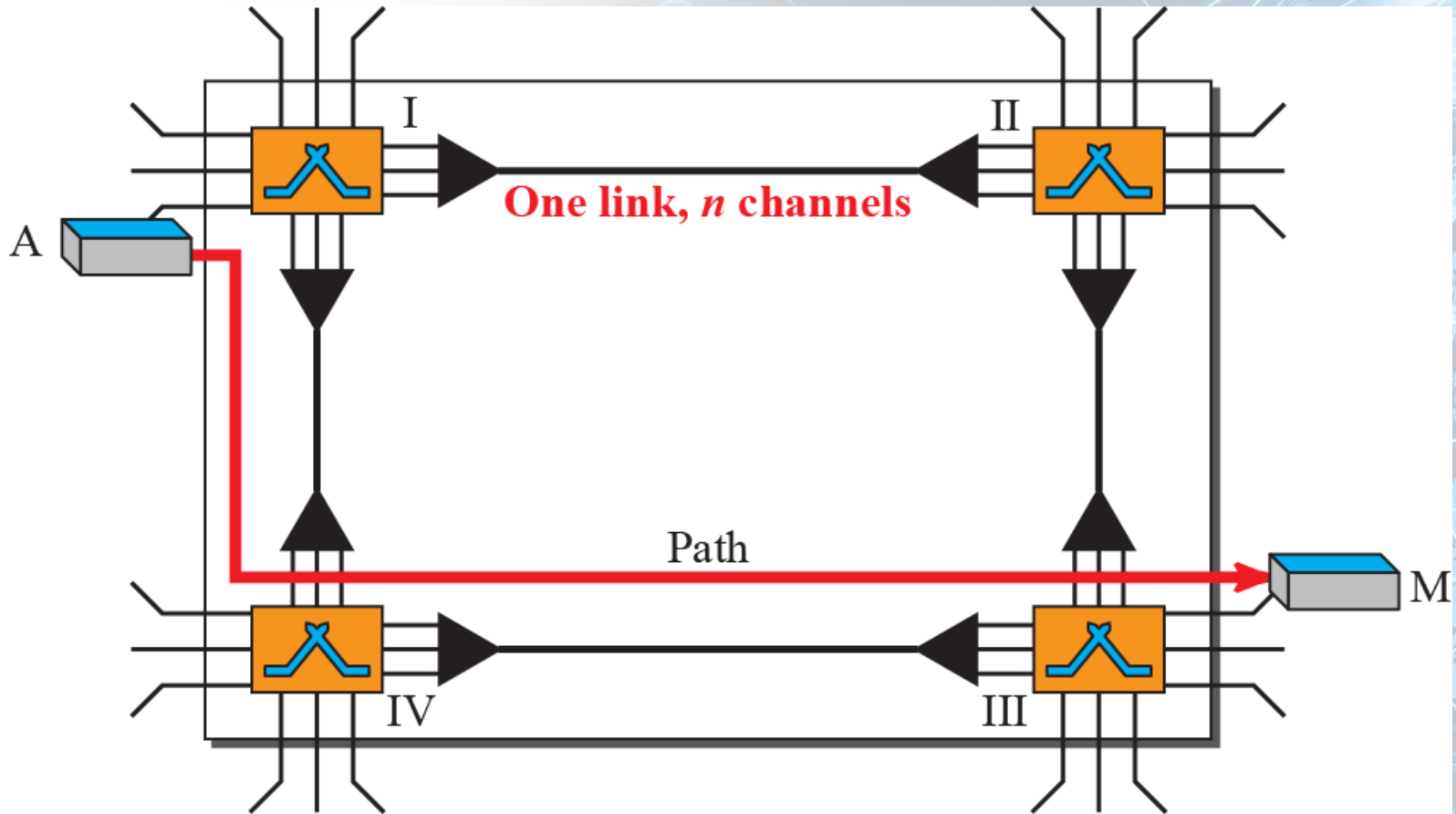
Circuit-switched Networks

- A set of switches connected by physical links
- A connection between two stations is a dedicated path made of one or more links
- Each connection uses only one dedicated channel on each link
- Each link is normally divided into n channels by using FDM or TDM

Circuit-switched Networks

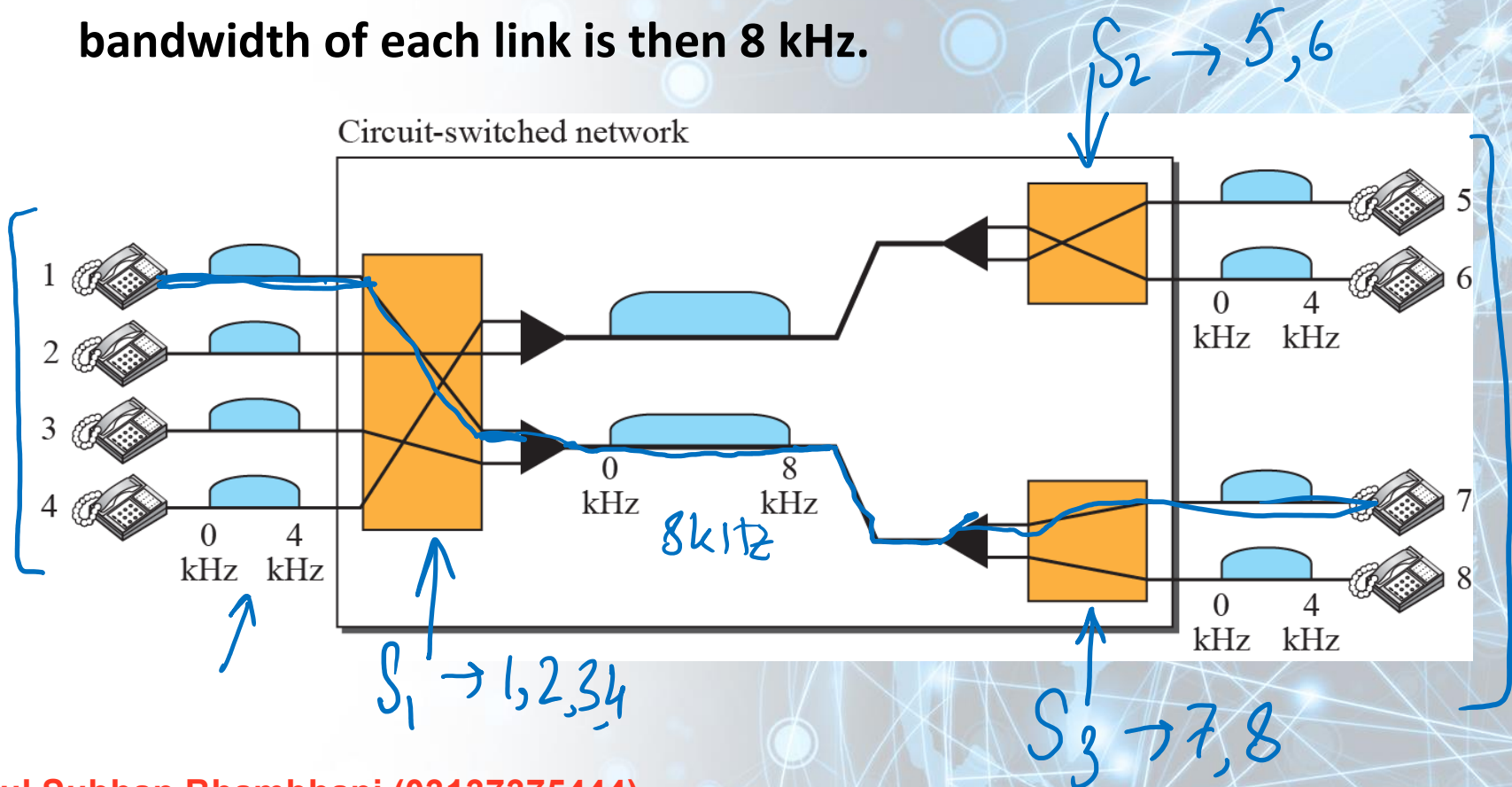
- A set of switches connected by physical links

A Circuit-Switched Network



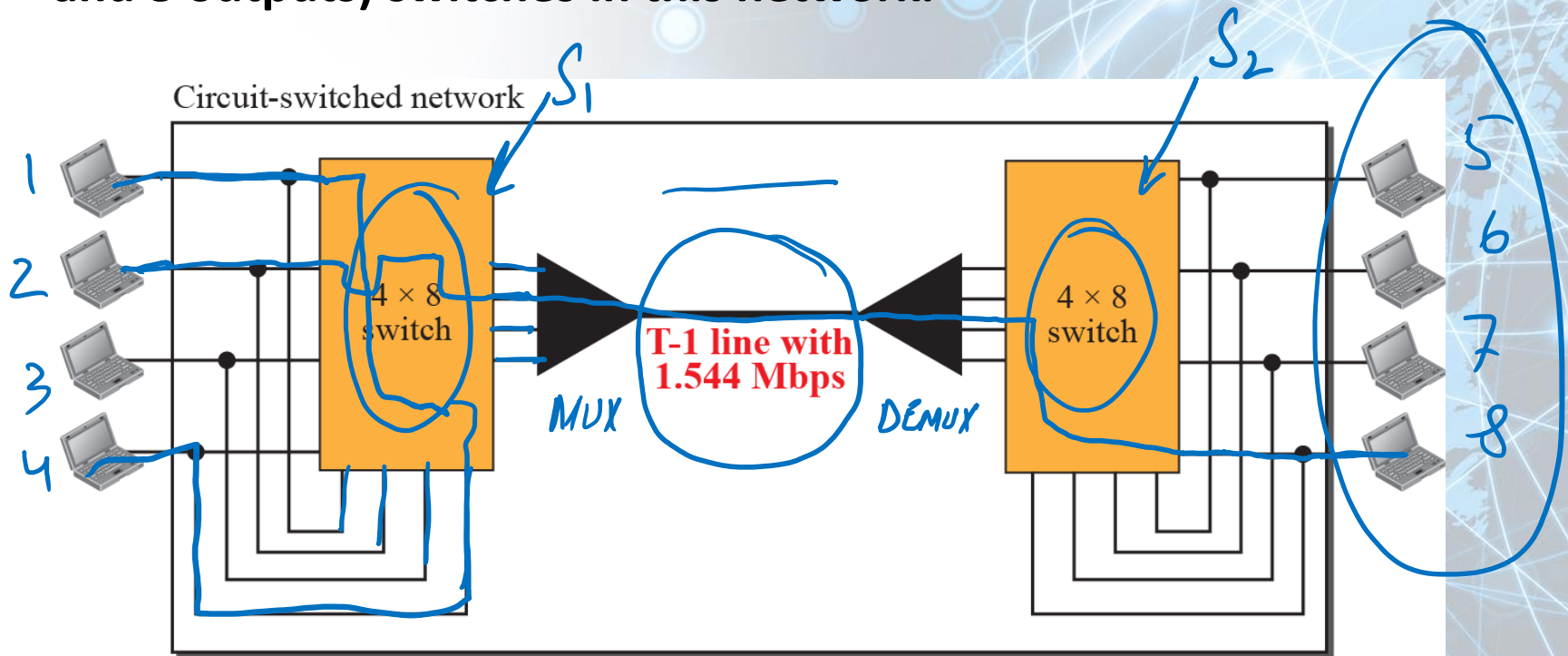
Example

As a trivial example, let us use a circuit-switched network to connect eight telephones in a small area. Communication is through 4-kHz voice channels. We assume that each link uses FDM to connect a maximum of two voice channels. The bandwidth of each link is then 8 kHz.



Example

As another example, consider a circuit-switched network that connects computers in two remote offices of a private company. The offices are connected using a T-1 line leased from a communication service provider. There are two 4×8 (4 inputs and 8 outputs) switches in this network.

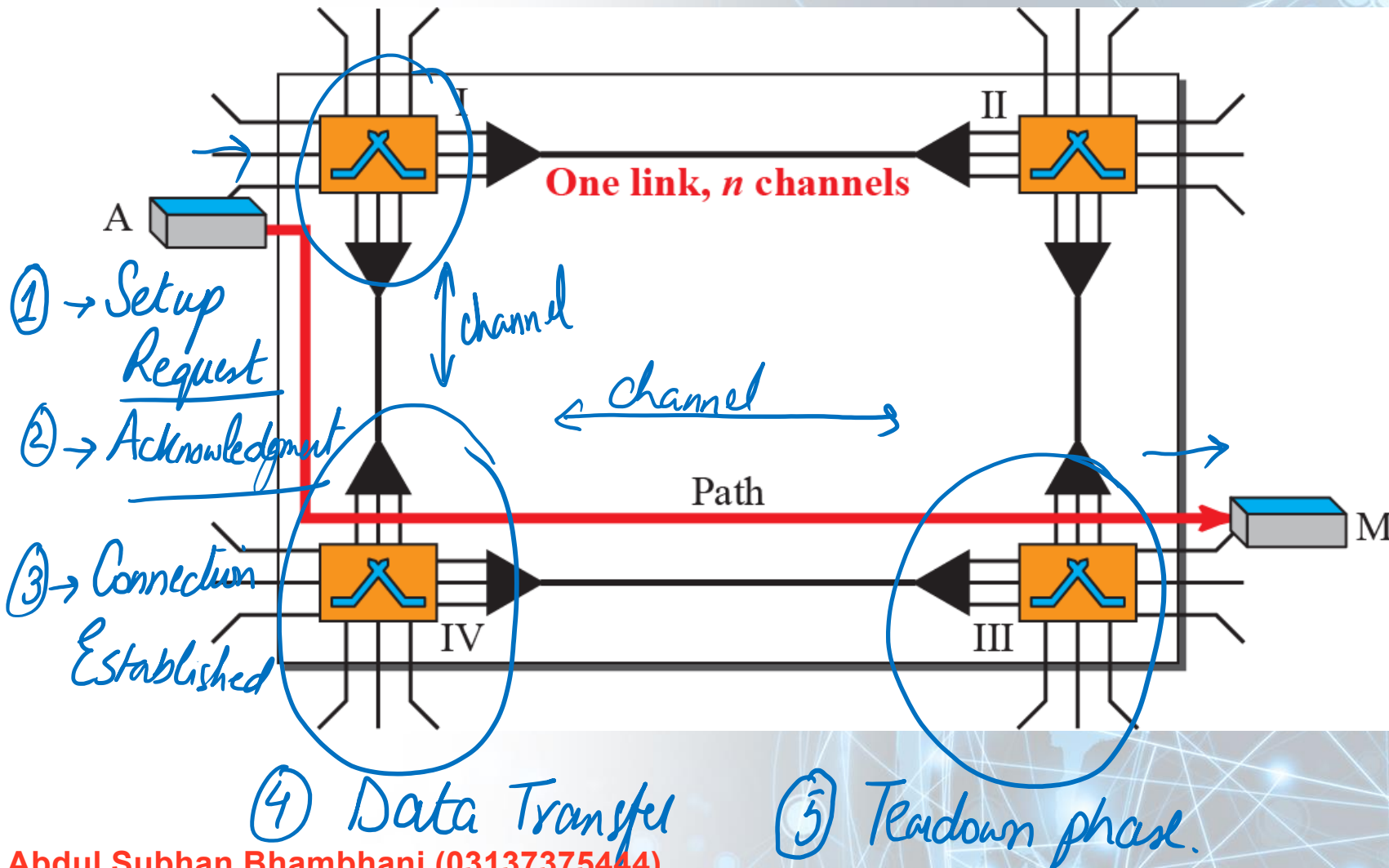


Three Phases in a Circuit Switched Network

- The actual communication in a circuit-switched network requires 3 phases:
 - ✓ Connection Setup
 - ✓ Data Transfer
 - ✓ Connection Teardown

Three Phases in a Circuit Switched Network

Dedicated Circuit → Link with channels



Efficiency of a Circuit-Switched Network

- **Not as efficient as packet switching because resources are allocated during the entire duration of the connection and these resources are unavailable to other connections**

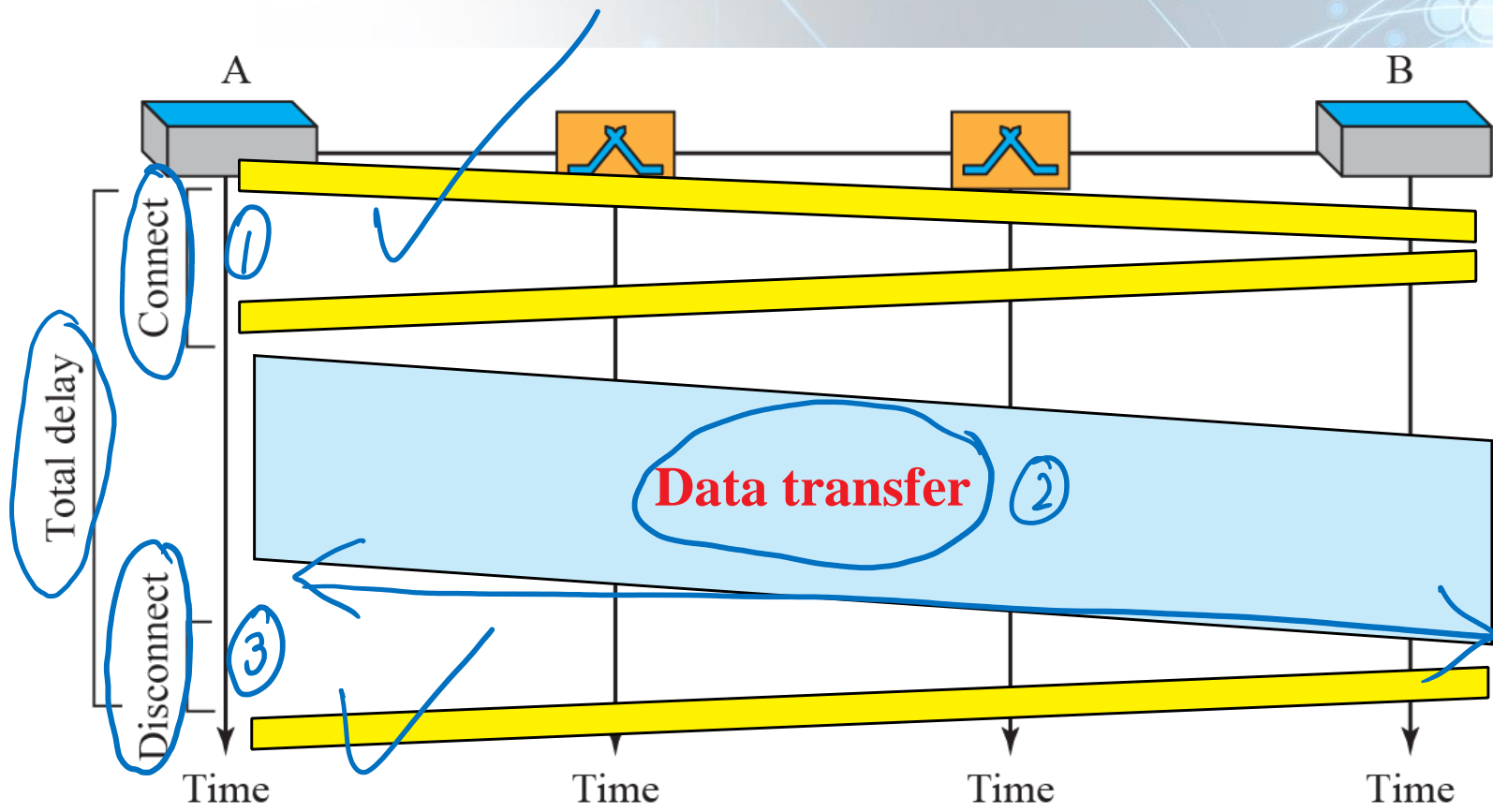
Efficiency of a Circuit-Switched Network

- In a telephone network, people normally terminate the communication when they have finished their conversation
- Data Network is an issue

Delay in a Circuit-Switched Network

- **Circuit switched networks have low efficiency but minimal delay**
- **Data is not delayed at each switch; the resources are allocated for the duration of the connection**

Delay in a Circuit-Switched Network



Packet Switching

- If the message is going to pass through a packet-switched network, it needs to be divided into packets of fixed or variable size
- The size of the packet is determined by the network and the governing protocol

Datagram Networks

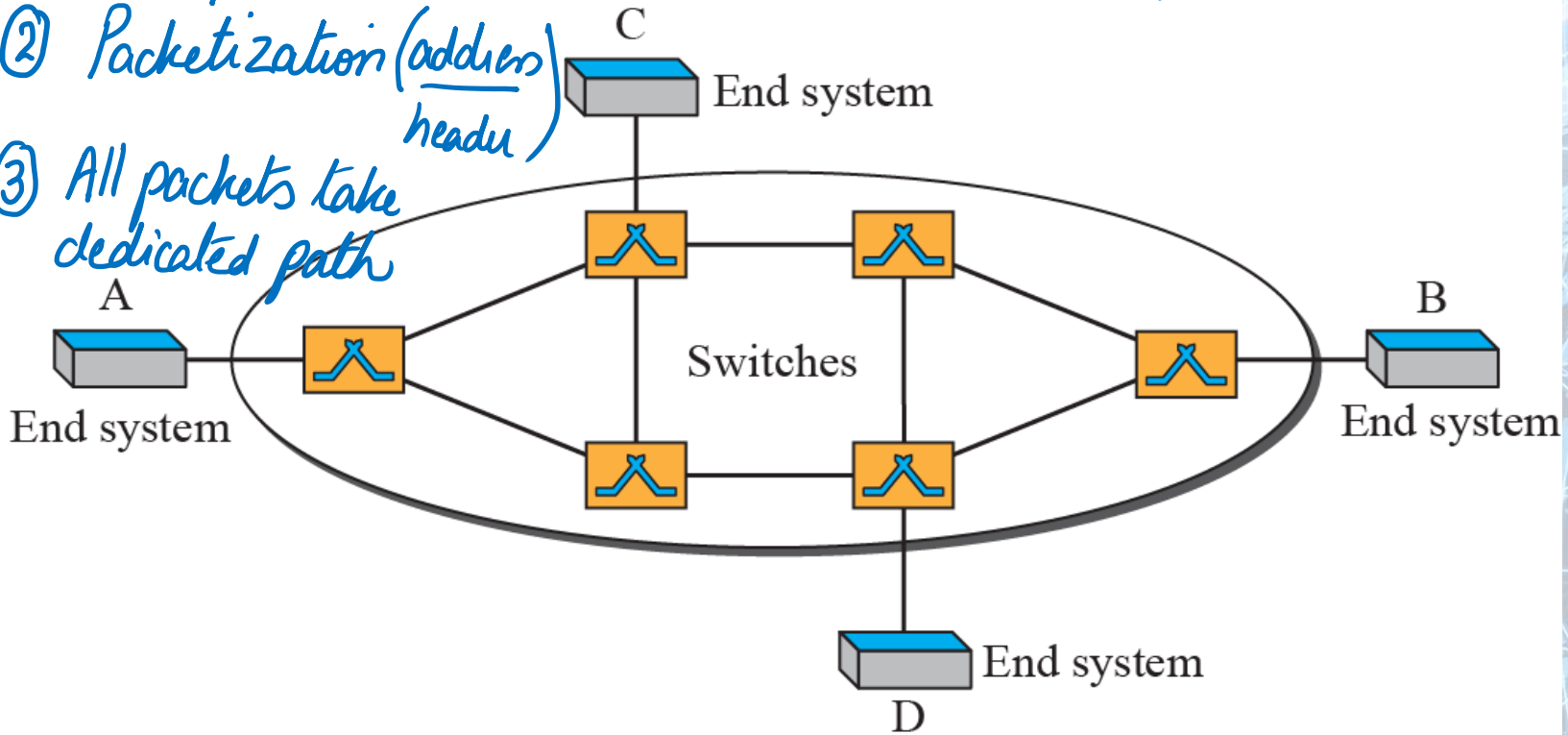
- Each packet is treated independently of all others.
- Even if a packet is part of a multi-packet transmission, the network treats it as though it existed alone
- Packets are referred to as datagrams

Virtual-Circuit Networks

- A virtual-circuit network is a cross between a circuit-switched network and a datagram network

Virtual-circuit network

- ① Setup & Teardown process (resources reservation)
- ② Packetization (address header)
- ③ All packets take dedicated path



Virtual-Circuit Networks

- A virtual-circuit network is a cross between a circuit-switched network and a datagram network

Virtual-Circuit Networks

Physical → Circuit Switching (Set up, Transfer & Tear down)

Data Link Layer → Virtual Circuit Approach
(Set up, Transfer & Tear down)
↳ Packets (Frames)

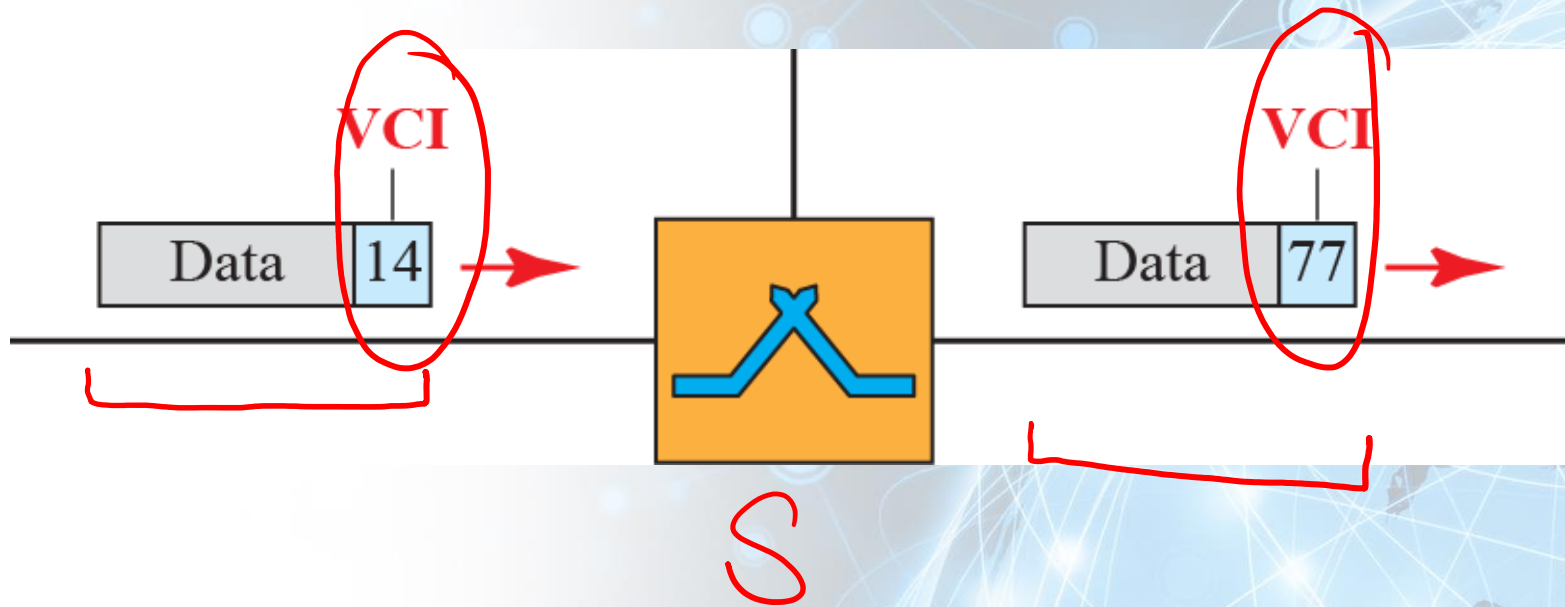
Network Layer → Datagram Switching
(Independent Datagrams or Packets)

Virtual-Circuit Networks

- A virtual-circuit network is a cross between a circuit-switched network and a datagram network

Virtual-Circuit Identifier

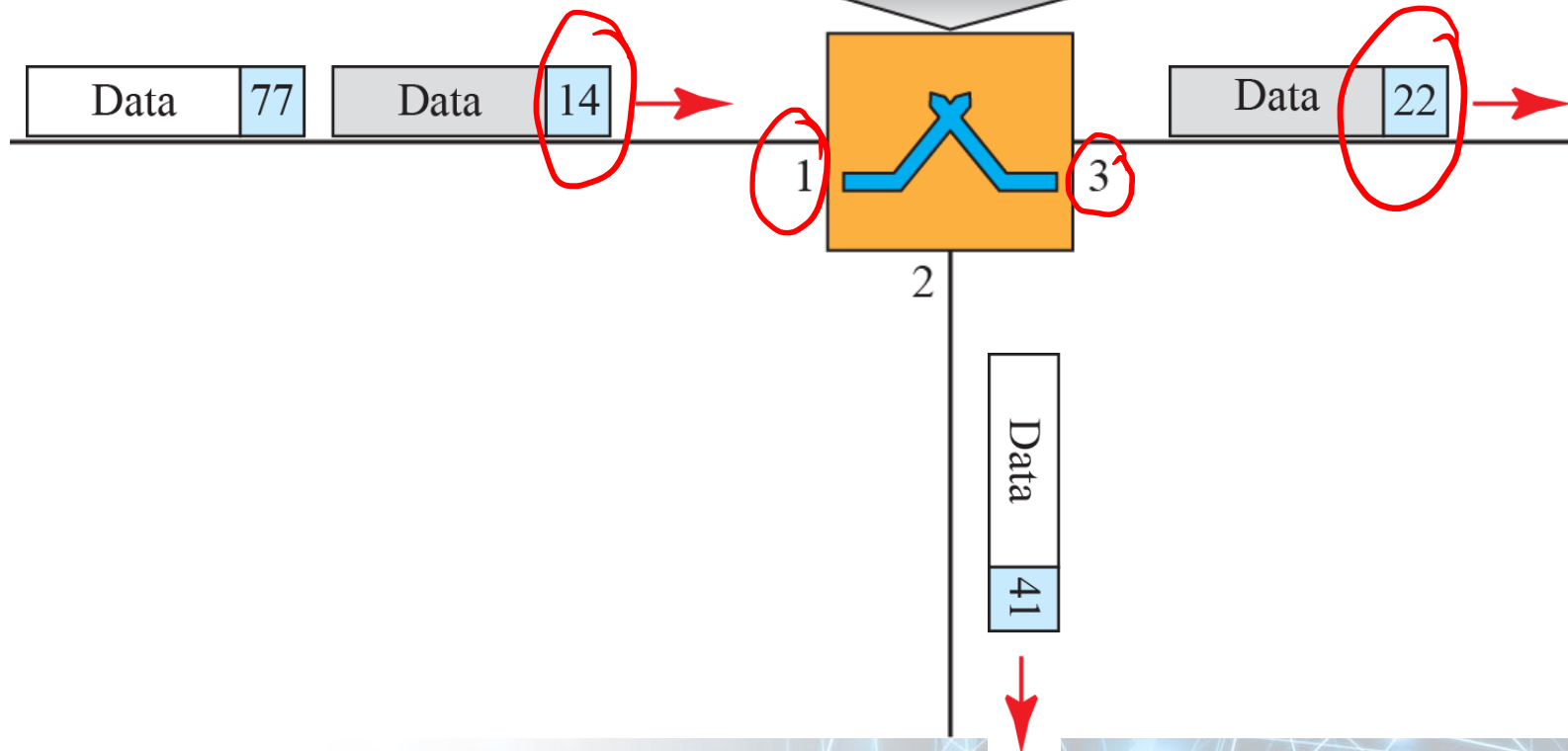
VCI (label) → local switch scope



Switch & table for a virtual-circuit network

Data Transfer Phase

Incoming		Outgoing	
Port	VCI	Port	VCI
1	14	3	22
1	77	2	41

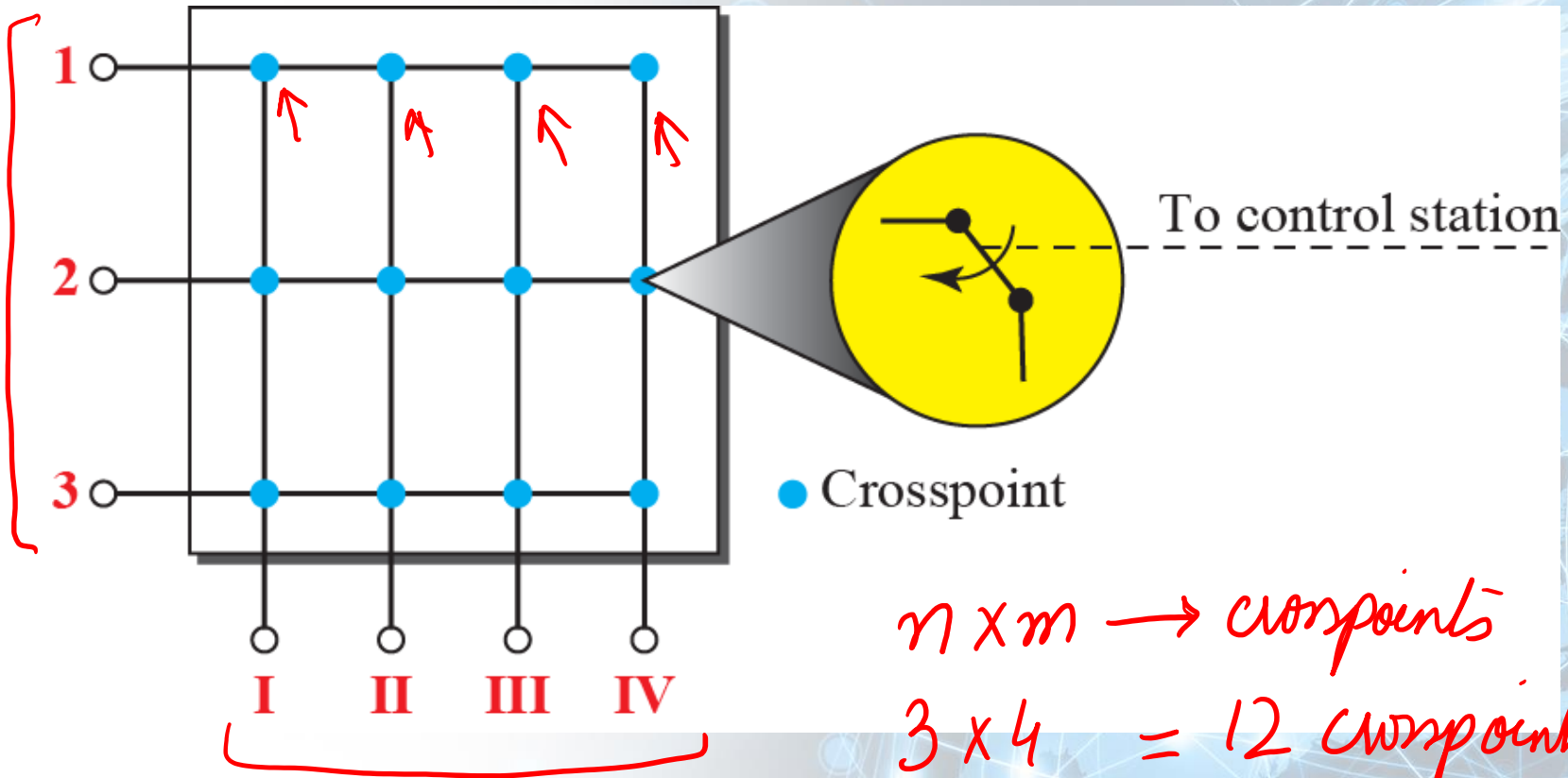


Structure Of A Circuit Switch

- **Circuit switching today can use either of two technologies:**
 - ✓ **The Space-Division switch**
 - ✓ **The Time-Division switch**

Crossbar switch with 3 inputs & 4 outputs

n inputs m outputs ($n=3; m=4$)



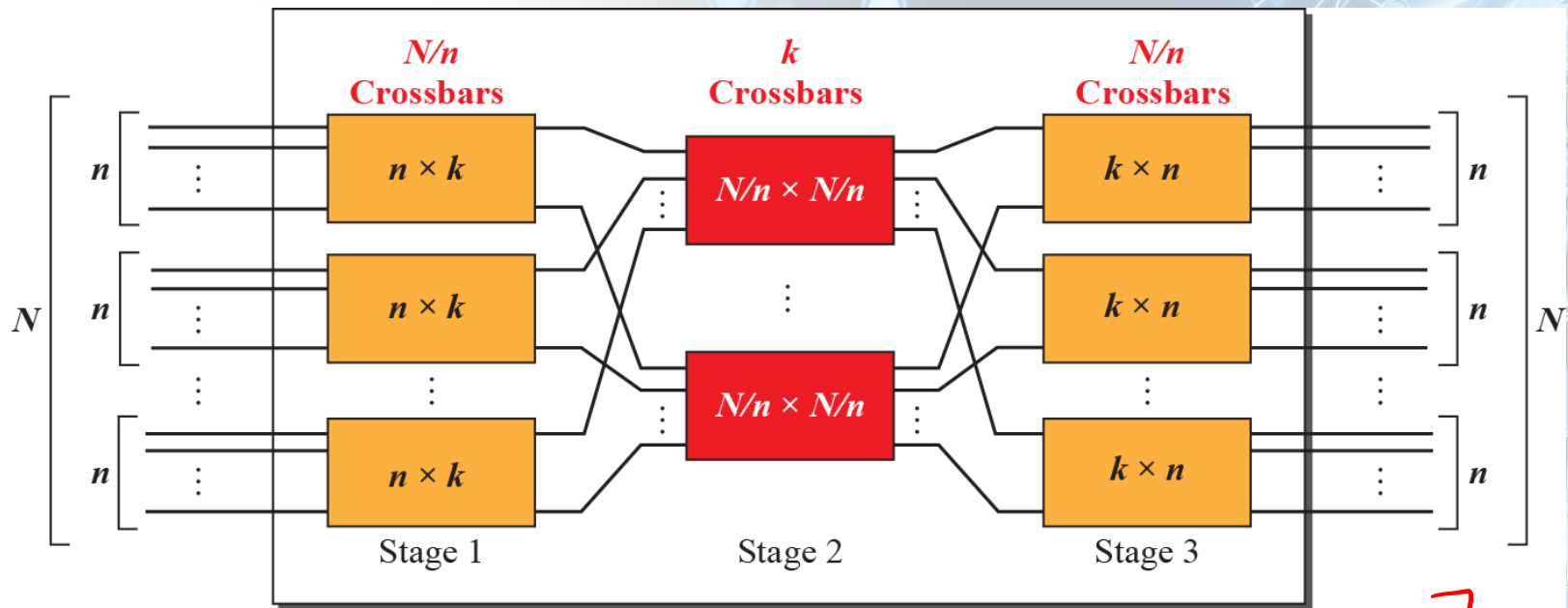
$n \times m \rightarrow$ crosspoints

$3 \times 4 = 12$ crosspoints

25% of crosspoints

Multistage Switch

$N \times N$ crosspoints



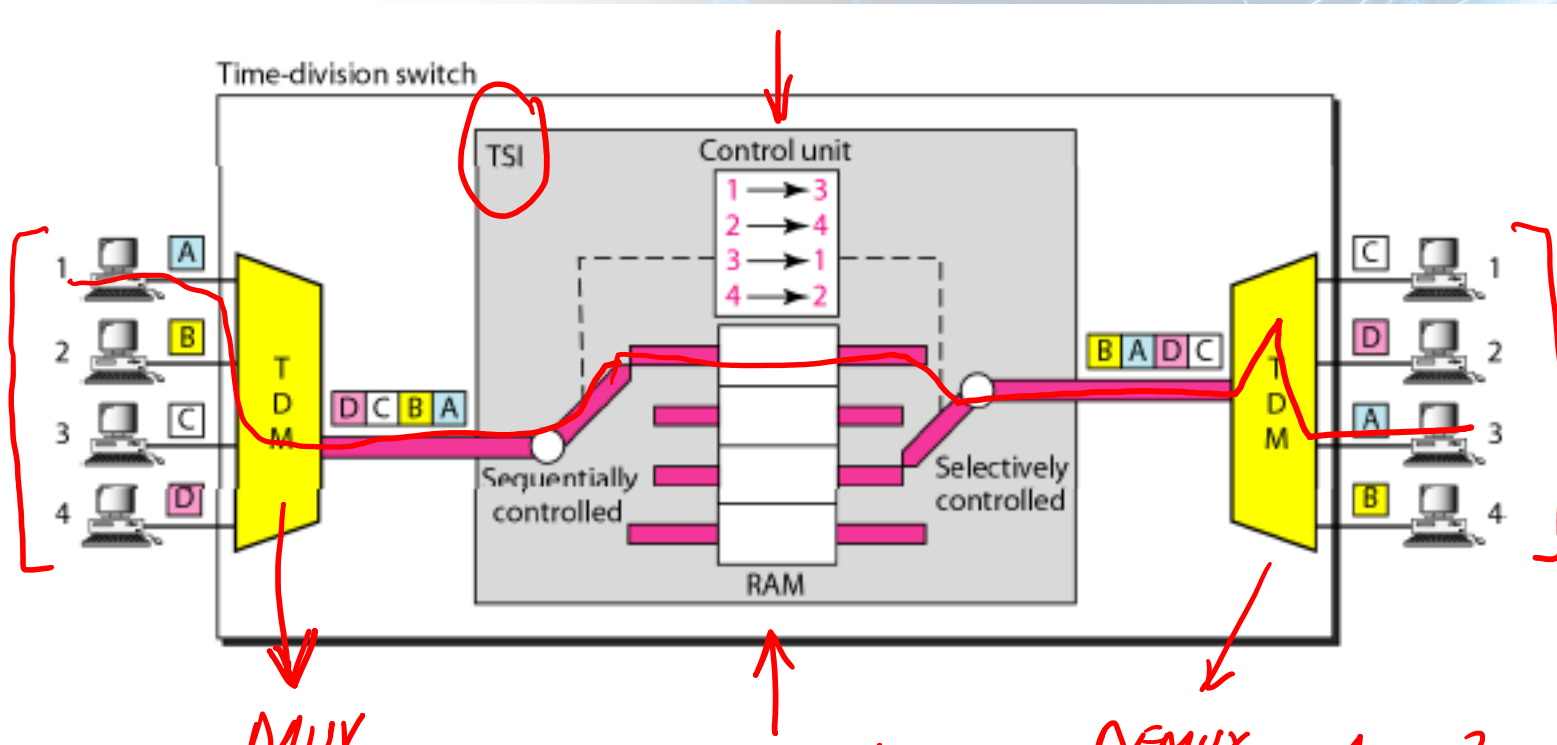
No. of crosspoints $\Rightarrow 2kN + k\left(\frac{N}{n}\right)^2$

// // // $\Rightarrow N^2$ \leftarrow lesser

Time-Division Switch

- **Uses TDM inside a switch**
- **Most popular technology is Time-Slot Interchange (TSI)**

Time-Division Switch



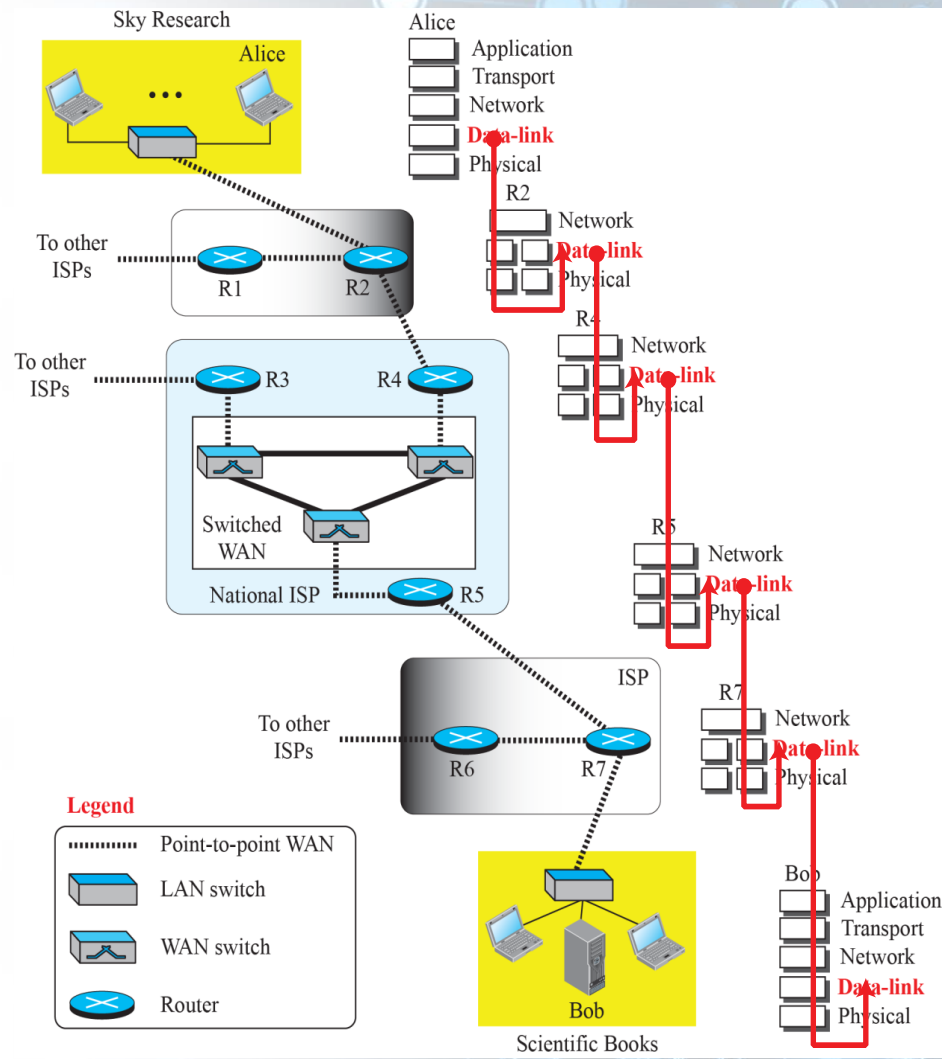
memory locations
 ↑↓
 time slots

DEMUX
 1 → 3
 2 → 4
 3 → 1
 4 → 2

Data-Link Layer

- The Internet is a combination of networks glued together by connecting devices (routers or switches)
- If a packet is to travel from a host to another host, it needs to pass through these networks
- Data Link layer controls node-to-node communication

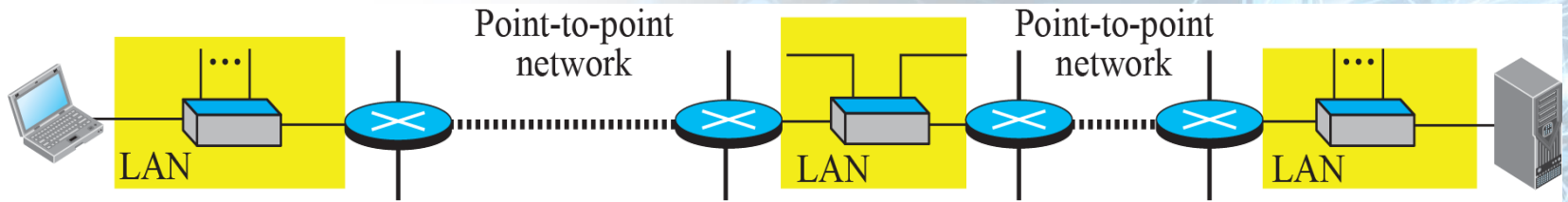
Communication at the Data-Link Layer



Nodes and Links

- **Communication at the data-link layer is node-to-node**
- **A data unit from one point in the Internet needs to pass through many networks (LANs and WANs) to reach another point**
- **We refer to the two end hosts and the routers as nodes and the networks in between as links**

Nodes and Links



a. A small part of the Internet

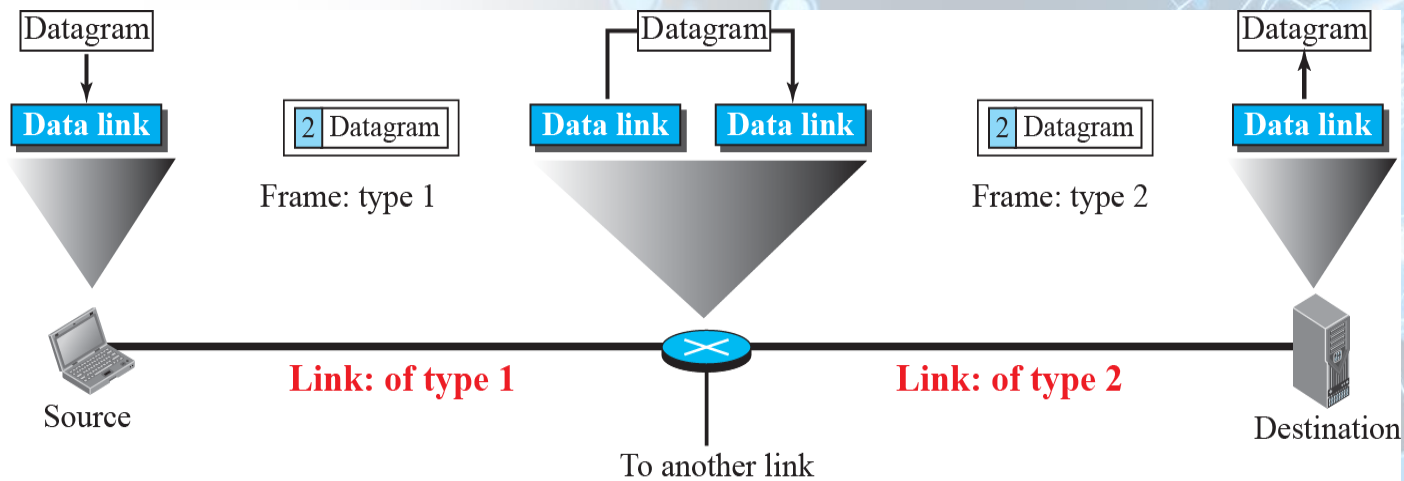


b. Nodes and links

Services provided by Data-Link Layer

- Located between the physical and the network layers
- Provides services to Network Layer and receives services from Physical layer
- Framing
- Flow Control
- Error Control
- Congestion Control

A Communication with only Three Nodes



Services provided by Data-Link Layer

- **Data-Link layer provides services to Network Layer and receives services from Physical layer**
 - ✓ **Framing**
 - ✓ **Flow Control**
 - ✓ **Error Control**
 - ✓ **Congestion Control**

Two Categories of Links

- Two nodes are physically connected by a transmission medium such as cable or air
- Data-link layer controls how the medium is used
 - ✓ Data-link layer can use whole capacity
 - ✓ Data-link layer can use only part of the capacity

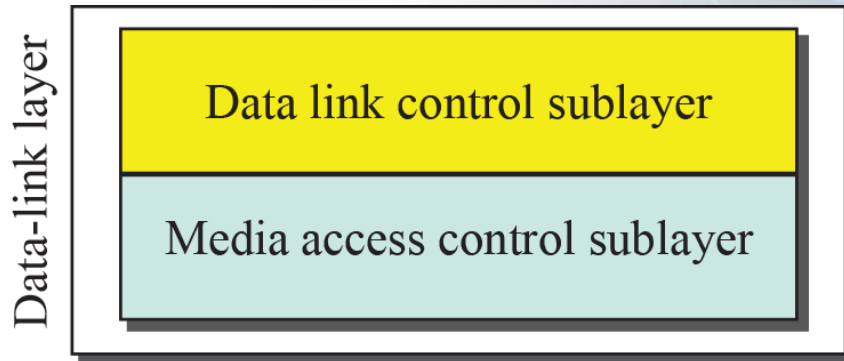
Two Categories of Links

- We can have the following two types of links:
 - ✓ Point-to-point link or a
 - ✓ Broadcast link

Two Sublayers of Data-Link Layer

- We can divide the data-link layer into two sublayers:
 - Data Link Control (DLC)
 - Media Access Control (MAC)

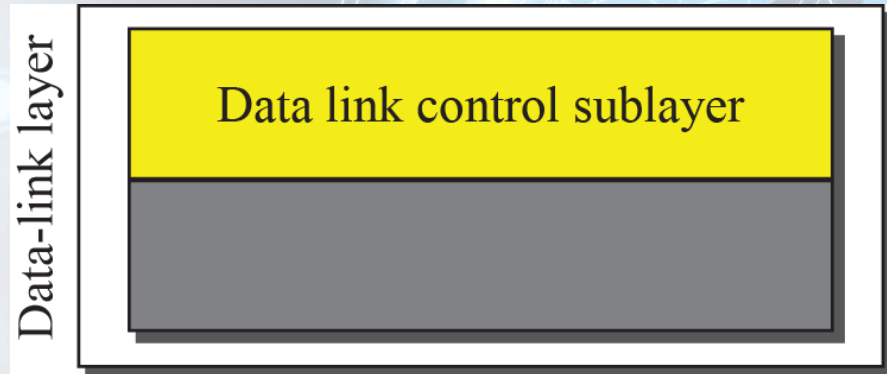
Dividing the data-link layer into two sublayers



a. Data-link layer of a broadcast link

*DLC → - Broadcast Links
- Point-to-point Links

*MAC → - Broadcast Link only

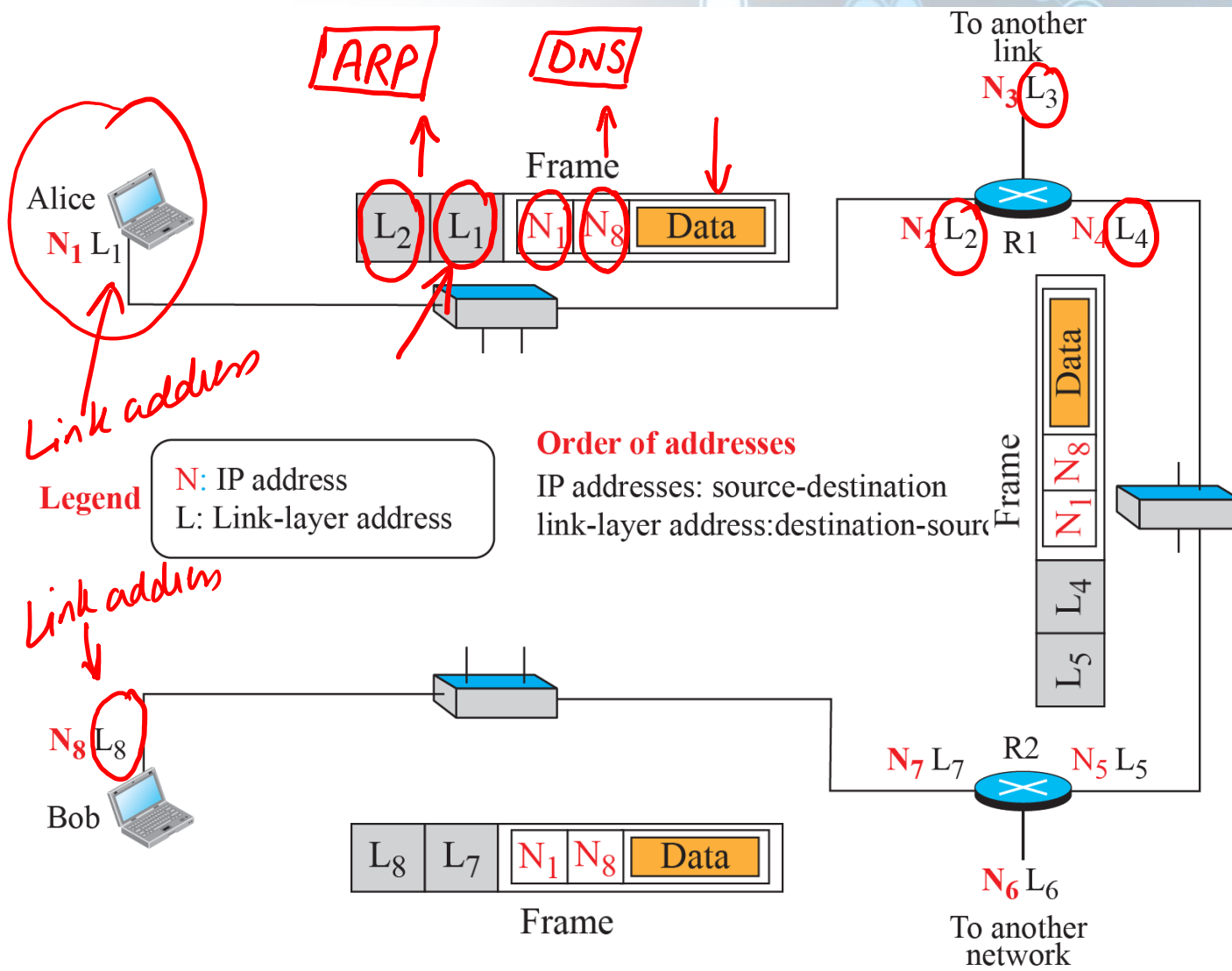


b. Data-link layer of a point-to-point link

Why LINK-LAYER ADDRESSING?

- IP addresses are the identifiers at the network layer
- In Internet we cannot make a packet reach its destination using only IP addresses
- Source and destination IP addresses define the two ends but cannot define which links the packet will take

IP addresses & Link-Layer Addresses



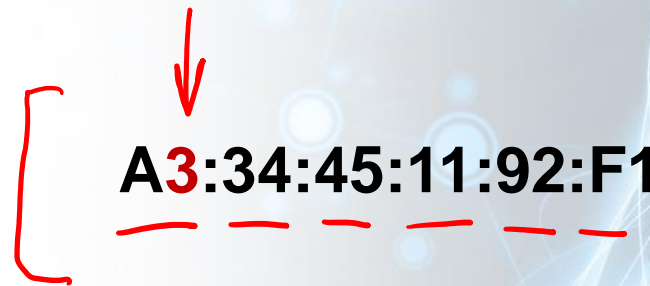
*Router → n interfaces
 ↳ n link addresses.*

Three Types of addresses

- **Some link-layer protocols define three types of addresses:**
- **Unicast**
- **Multicast**
- **Broadcast**

Example

The unicast link-layer addresses in the most common LAN, Ethernet, are 48 bits (six bytes) that are presented as 12 hexadecimal digits separated by colons; for example, the following is a link-layer address of a computer. The second digit needs to be an odd number.


A3:34:45:11:92:F1

48 bits

↳ 6 Bytes

12 Hex digits
separated by
colons

Example

The multicast link-layer addresses in the most common LAN, Ethernet, are 48 bits (six bytes) that are presented as 12 hexadecimal digits separated by colons. The second digit, however, needs to be an even number in hexadecimal. The following shows a multicast address:

even → multicast address

A2:34:45:11:92:F1

Example

The broadcast link-layer addresses in the most common LAN, Ethernet, are 48 bits, all 1s, that are presented as 12 hexadecimal digits separated by colons. The following shows a broadcast address:

FF:FF:FF:FF:FF:FF

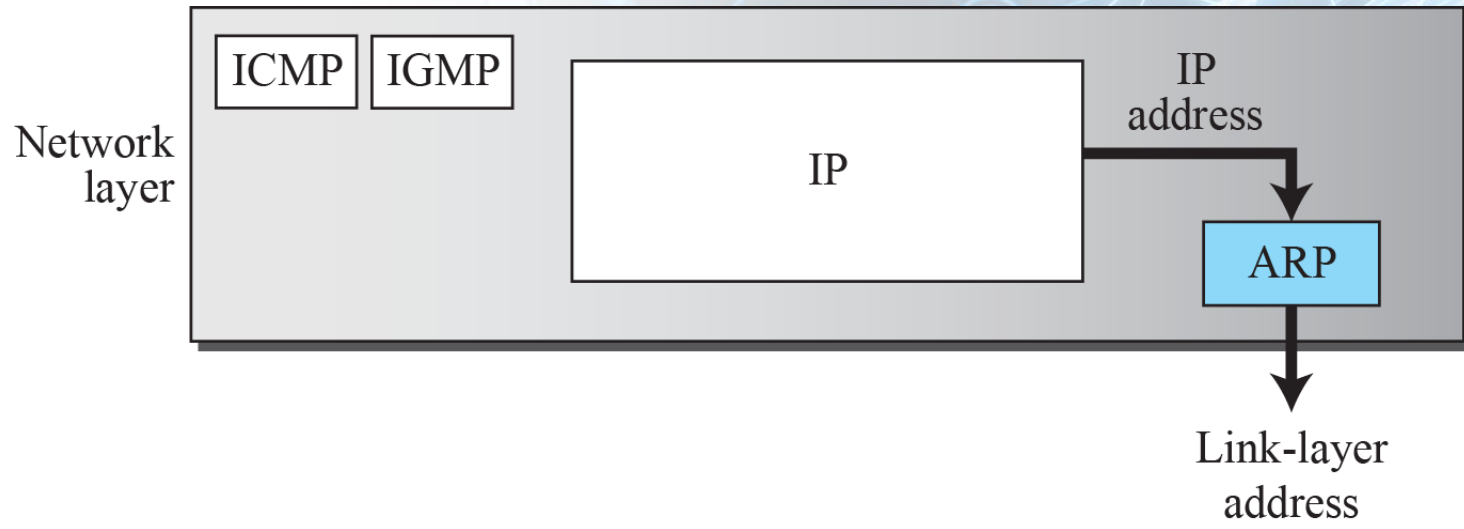
Address Resolution Protocol (ARP)

- Anytime a node has an IP packet to send to another node in a link, it has the IP address of the receiving node
- IP address of the next node is not helpful in moving a frame through a link; we need the link-layer address of the next node

Address Resolution Protocol (ARP)

- **We need Address Resolution Protocol (ARP)**

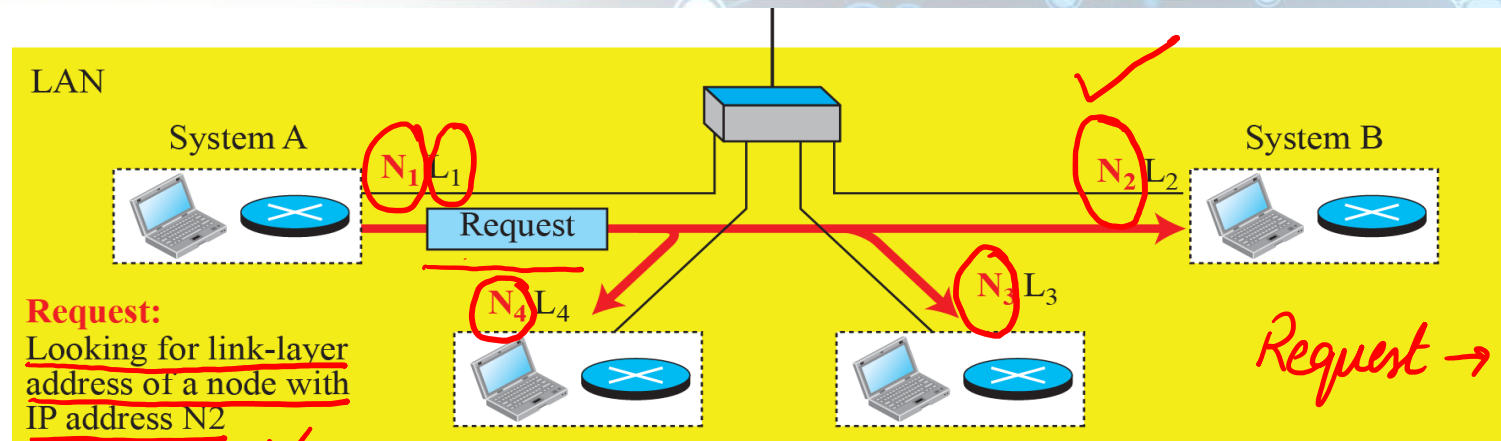
Position of ARP in TCP/IP protocol suite



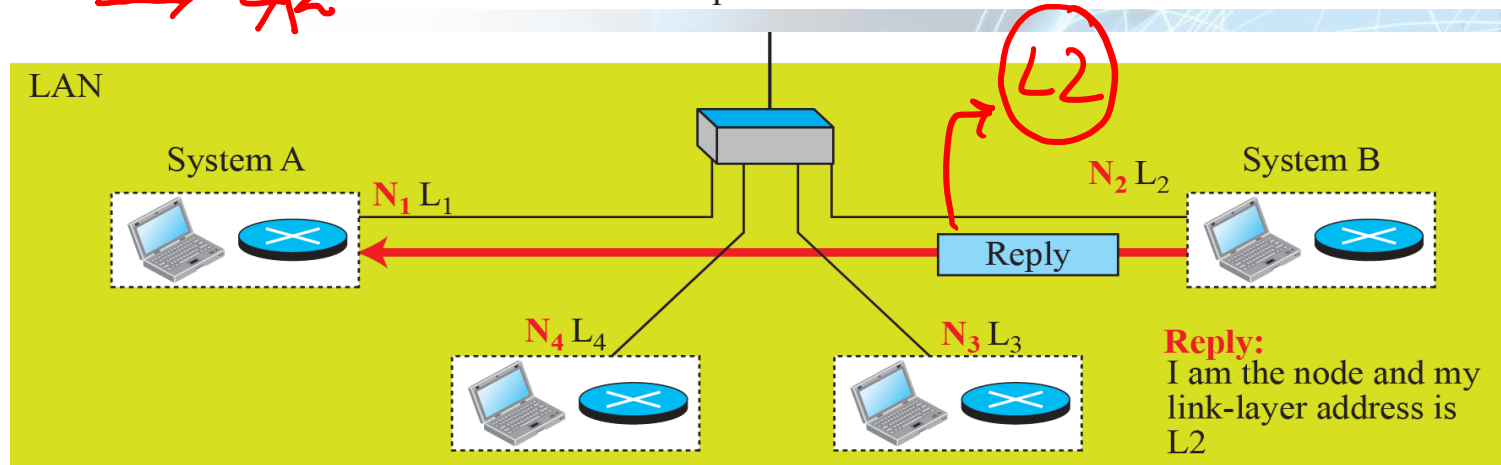
Address Resolution Protocol (ARP)

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- IP address of the next node is not helpful in moving a frame through a link; we need the link-layer address of the next node

ARP Operation



a. ARP request is broadcast



b. ARP reply is unicast

Address Resolution Protocol (ARP)

- Anytime a node has an IP packet to send to another node in a link, it has the IP address of the receiving node
- IP address of the next node is not helpful in moving a frame through a link; we need the link-layer address of the next node

ARP Packet

Hardware: LAN or WAN protocol

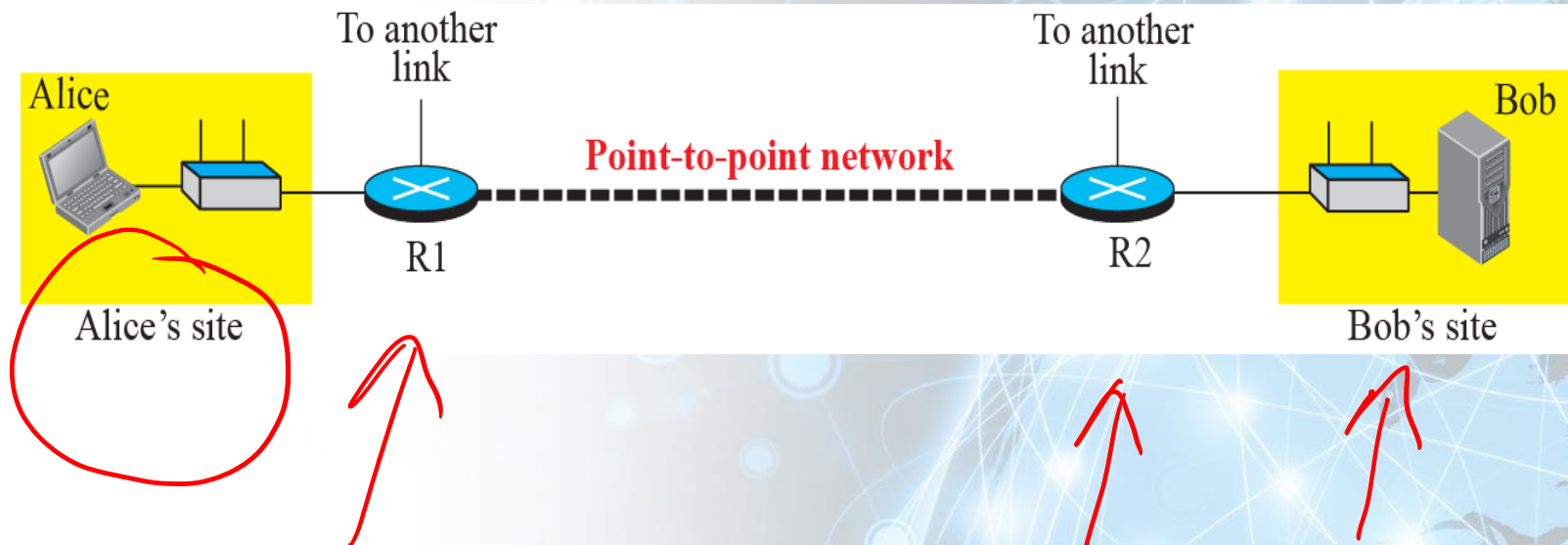
Protocol: Network-layer protocol

0		8	16	31
Hardware Type		Protocol Type		
Hardware length	Protocol length	Operation Request:1, Reply:2		
Source hardware address				
Source protocol address				
Destination hardware address (Empty in request)				
Destination protocol address				

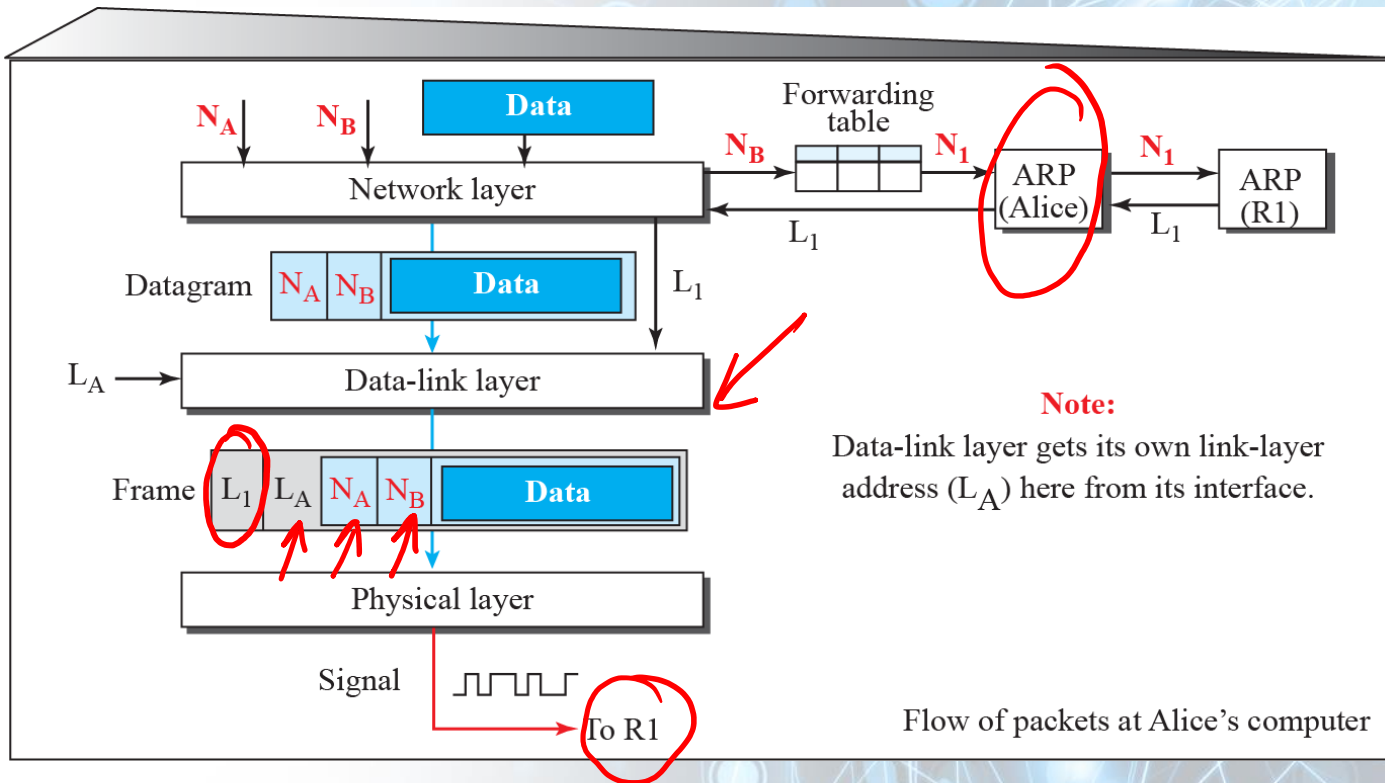
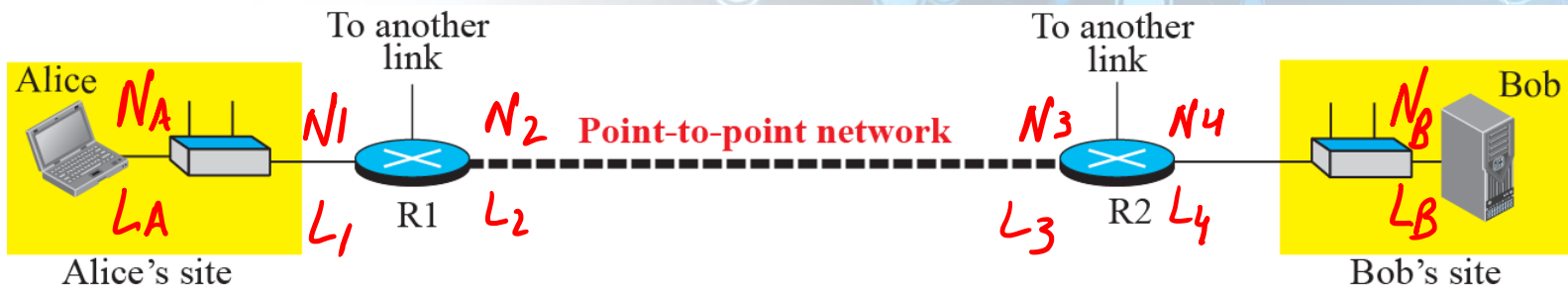
(0800)₁₆

empty ←

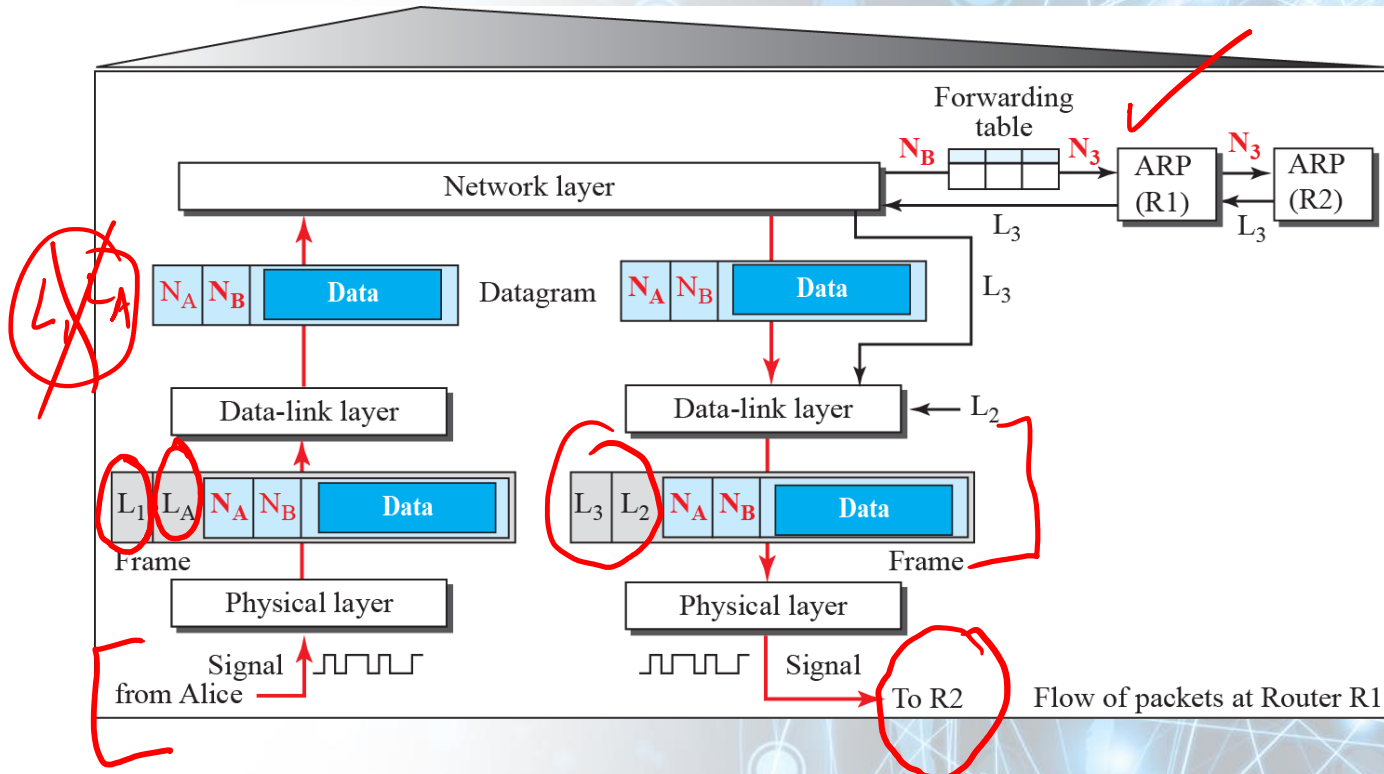
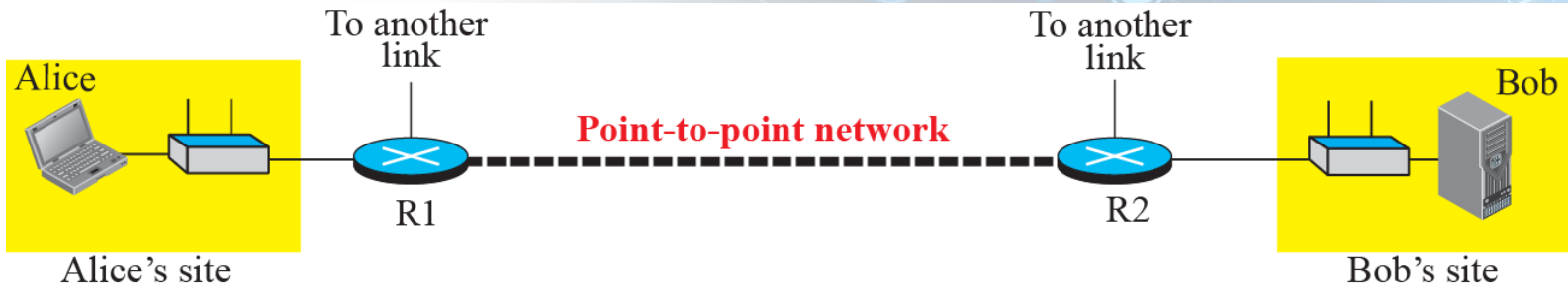
The internet for our example



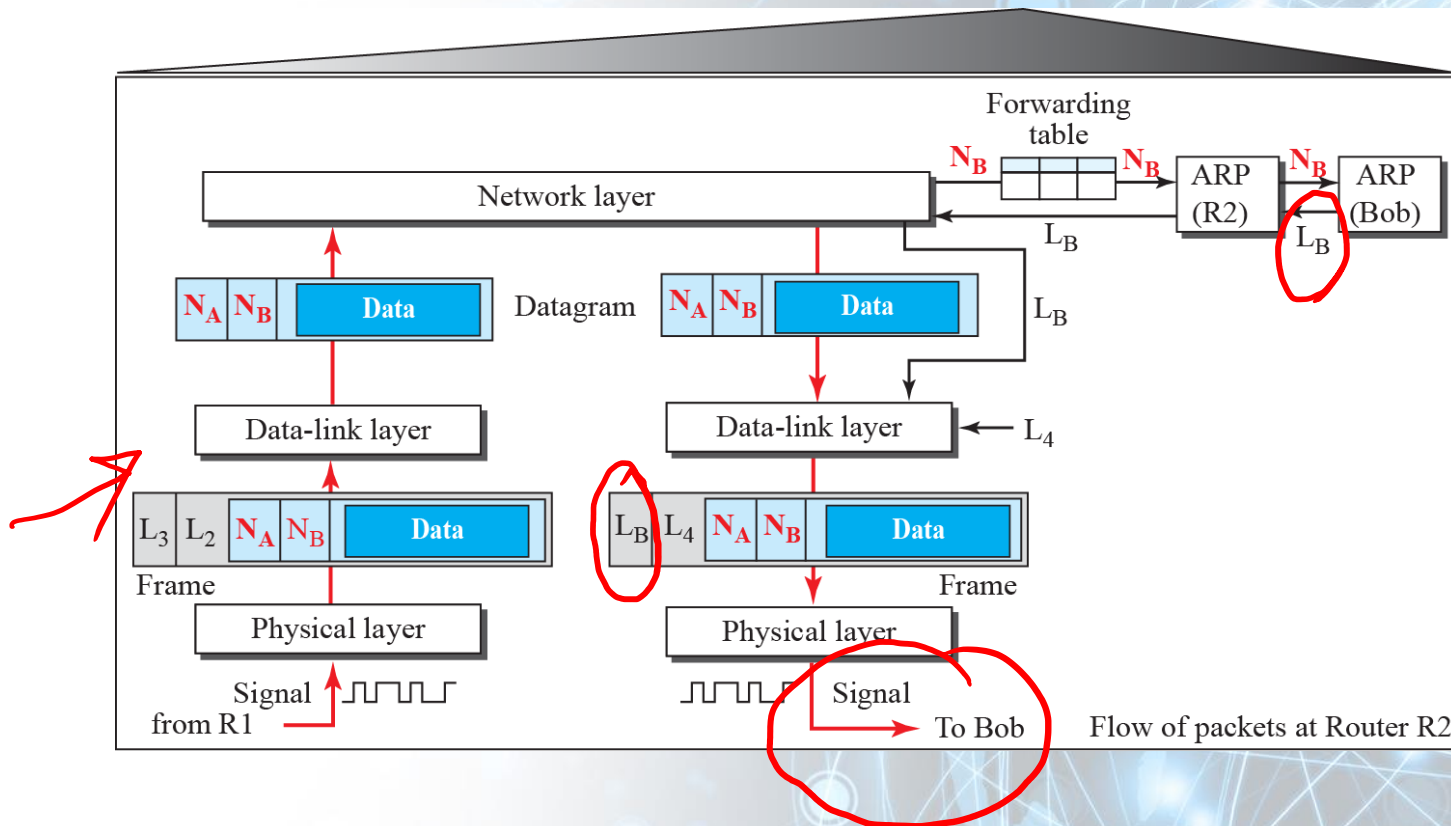
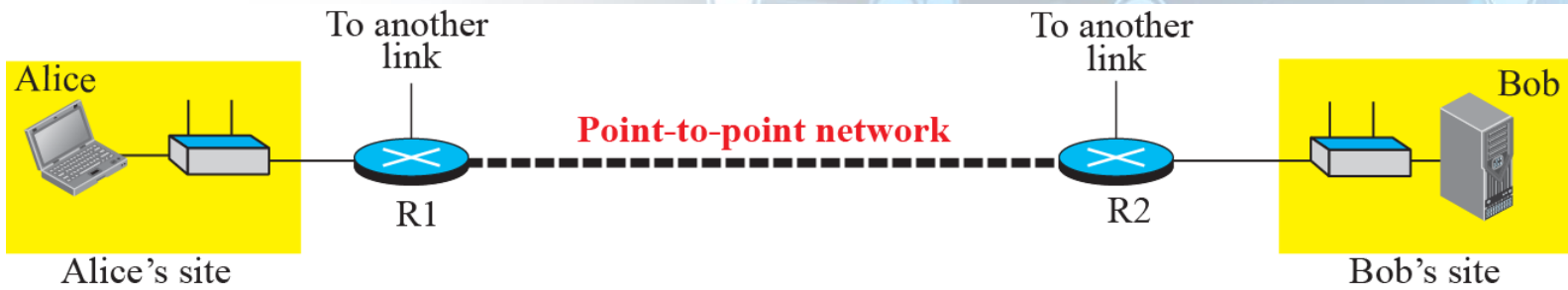
Flow of packets at Alice site



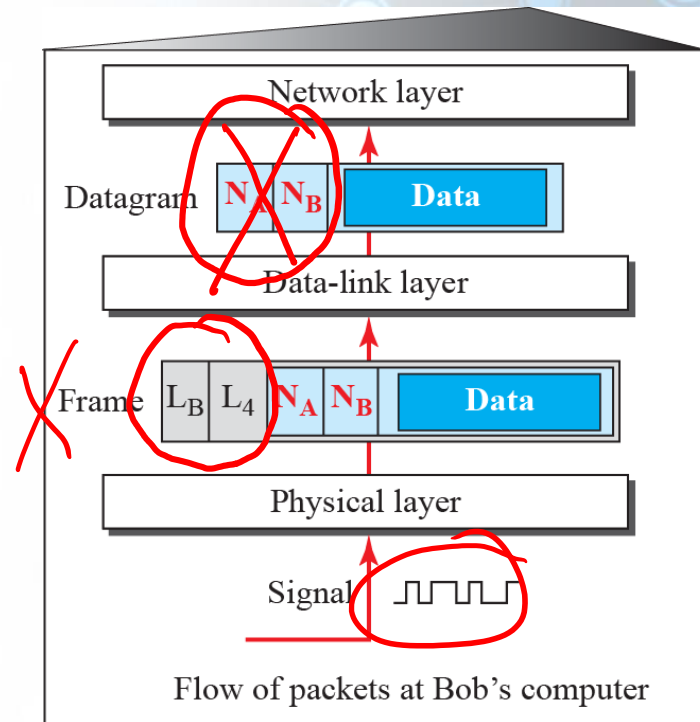
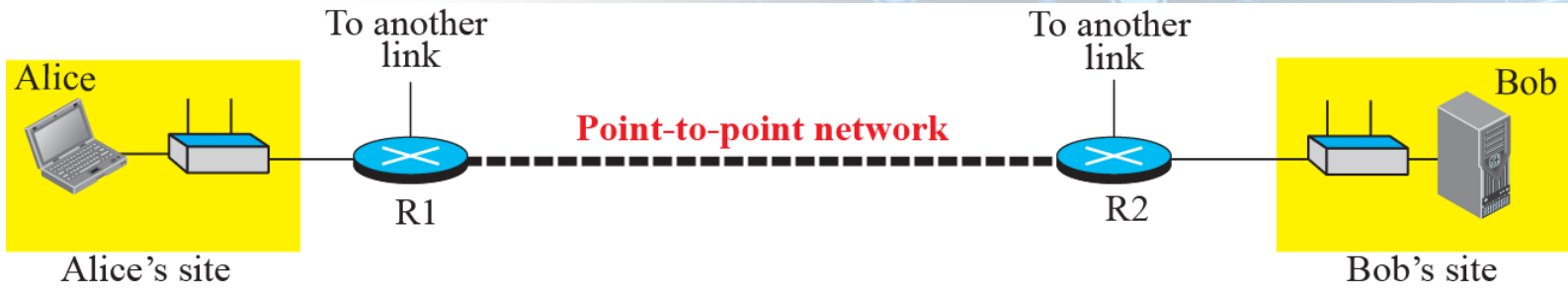
Flow of activities at router R1



Flow of activities at router R2



Activities at Bob's site



Types of Errors

- Data transmission suffers unpredictable changes because of interference
- The interference can change the shape of the signal
 - ✓ Single-bit error means that only 1 bit of a given data unit (such as a byte, character, or packet) is changed from 1 to 0 or from 0 to 1

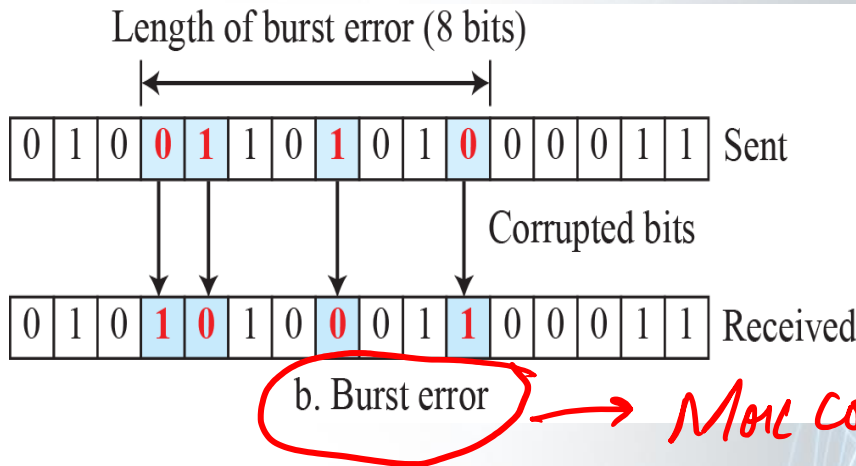
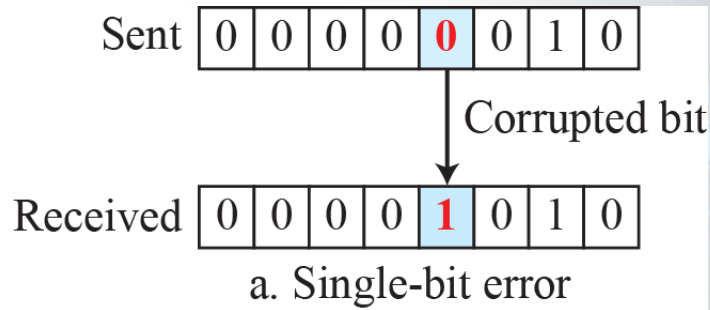
Types of Errors

- ✓ **Burst Error** means that 2 or more bits in the data unit have changed from 1 to 0 or from 0 to 1

Types of Errors

- ✓ **Single-bit error** means that only 1 bit of a given data unit (such as a byte, character, or packet) is changed from 1 to 0 or from 0 to 1
- ✓ **Burst Error** means that 2 or more bits in the data unit have changed from 1 to 0 or from 0 to 1

Single-Bit and Burst Error



No. of impacted bits

↓

Data Rate Duration of Noise

Duration of Noise } Duration of bit

1 kbps $\frac{1 \text{ sec}}{1000}$

↳ 10 bits

1 Mbps $\frac{1 \text{ sec}}{1000000}$

↳ 10,000 bits

→ More common

Redundancy

- **Central concept in detecting or correcting errors is Redundancy**
- **To be able to detect or correct errors, we send some extra bits with our data**
- **The presence of these redundant bits allows the receiver to detect or correct corrupted bits**

Detection versus Correction

- **Correction is more difficult than the detection**
- **In error detection, we are only looking to see if any error has occurred (Yes or No)**
- **We are not interested in the number of corrupted bits in Detection**
- **Single-bit error is same as a Burst error**

Detection versus Correction

- In Error Correction, we need to know:
 - ✓ The exact number of bits that are corrupted and,
 - ✓ Their location in the message

Coding

- Redundancy is achieved through various coding schemes
- Sender adds redundant bits through a process that creates a relationship between redundant bits and the actual data bits
- The receiver checks the relationships between the two sets of bits to detect errors

Coding

- **The ratio of redundant bits to data bits and the robustness of the process are important factors in any coding scheme**

Types of Coding Schemes

- Coding schemes can be divided into 2 broad categories:
 - ✓ Block Coding
 - ✓ Convolution Coding

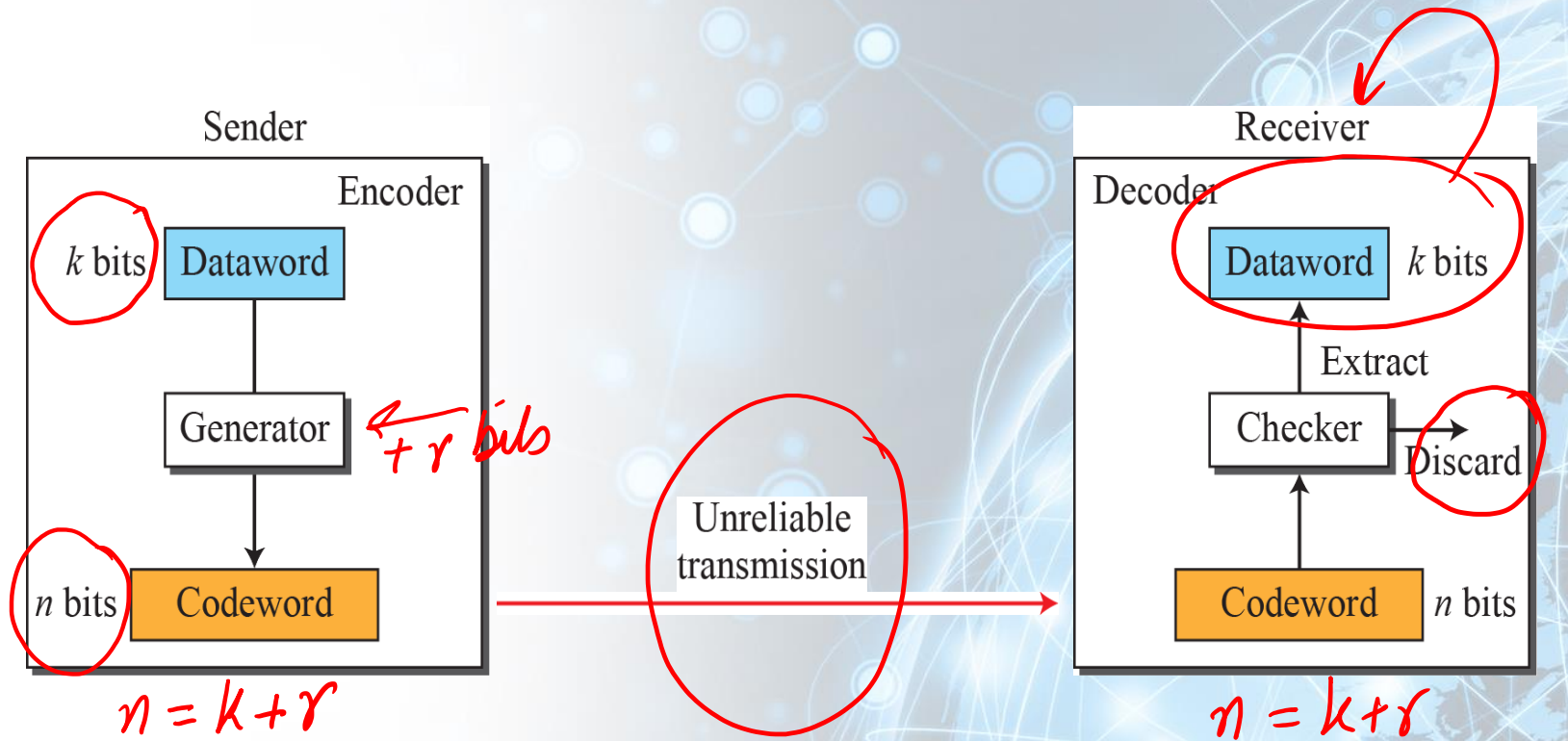
Block Coding

- We divide our message into blocks, each of 'k' bits, called datawords
- We add 'r' redundant bits to each block to make the length ' $n = k + r$ '
- The resulting 'n-bit' blocks are called codewords

BLOCK CODING in Error Detection

- If the following two conditions are met, the receiver can detect a change in the original codeword:
 - ✓ The receiver has (or can find) a list of valid codewords
 - ✓ The original codeword has changed to an invalid one

Process of Error Detection in Block Coding



Checker → received word is matching a valid Code word

Block Coding

- We divide our message into blocks, each of 'k' bits, called datawords
- We add 'r' redundant bits to each block to make the length ' $n = k + r$ '
- The resulting 'n-bit' blocks are called codewords

Example

Let us assume that $k = 2$ and $n = 3$. Table below shows the list of datawords and codewords. Later, we will see how to derive a cod word from a dataword.

$$2^n = 2^3 = 8$$
$$2^2 = 4$$

$$n = k + r$$

Codeword dataword red bits

Datawords	Codewords	Datawords	Codewords
1). 00	000	3). 10	101
2). 01	011	4). 11	110

① 011 → valid codeword 01 → extracted

② 111 → Corrupted codeword 111 → discarded

①
→ 011

③ 000 → Right (2 bits) are corrupted → Receiver accept as valid → 00

Hamming Distance

- Hamming Distance between two words of the same size is the number of differences between the corresponding bits
- Hamming Distance between two words x and y is $d(x,y)$
- Hamming distance between received codeword and sent codeword is number of bits corrupted

Example

Let us find the Hamming distance between two pairs of words.

1. $d(000, 011)$ $\xrightarrow{\quad}$ $d(x, y) = d(000, 011) = 2$

2. $d(10101, 11110)$

$\hookrightarrow d(10101, 11110) = 3$

$d(x, y) \neq 0 \rightarrow$ corrupted (error)

XOR \oplus $000 \oplus 011 \rightarrow$ Count no. of 1's in result
 $\hookrightarrow 2$

Minimum Hamming Distance

- Minimum Hamming Distance is smallest hamming distance between all possible pairs of codewords
- $d_{\min} = s + 1$
where,
 $s \rightarrow$ no. of detectable errors
 $d_{\min} \rightarrow$ minimum hamming distance

Example

A code scheme has a Hamming distance $d_{\min} = 4$. This code guarantees the detection of up to how many errors?

$$d_{\min} = 4$$

$$d_{\min} = S + 1$$

$$S = d_{\min} - 1$$

$$= 4 - 1$$

$$\boxed{S = 3} \rightarrow$$

Block code guarantees
error detection for up to
3 bits in a codeword

Linear Block Codes

- **Subset of Block Codes in which the exclusive OR of two valid codewords creates another valid codeword**

Example

The code below is a linear block code because the result of XORing any codeword with any other codeword is a valid codeword. For example, the XORing of the second and third codewords creates the fourth one.

Datawords	Codewords	Datawords	Codewords
00	000	10	101
01	011	11	110

$011 \oplus 101 = 110 \rightarrow$ Linear block code

The numbers of 1s in the nonzero codewords are 2, 2, and 2. So the minimum Hamming distance is $d_{\min} = 2$.

$d_{\min} = 2$

Parity-Check Code

- **Most common error-detecting code**
- **Linear block code ($n=k+1$)**
- **The extra parity bit is selected to make total number of 1s in codeword even**

Simple parity-check code C(5, 4)

$$2^4 = 16$$

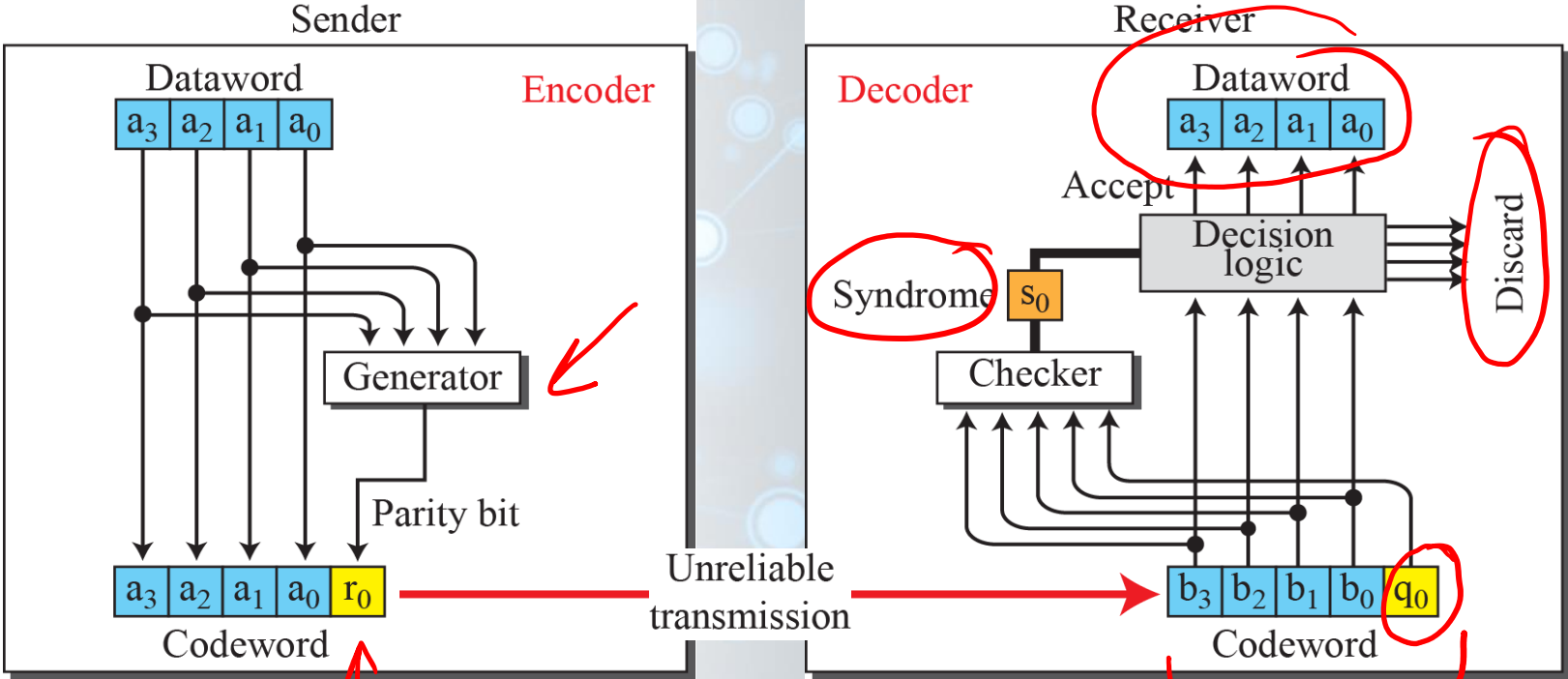
$$2^5 = 32$$

$$k = 4, n = 5$$

Datawords	Codewords	Datawords	Codewords
0000	00000	1000	10001
0001	00011	1001	10010
0010	00101	1010	10100
0011	00110	1011	10111
0100	01001	1100	11000
0101	01010	1101	11011
0110	01100	1110	11101
0111	01111	1111	11110

$n > k \rightarrow$ no. of codewords $>$ no. of datawords
 $2^n - 2^k \rightarrow$ (codewords) \rightarrow invalid

Encoder & decoder for simple parity-check code



$r_0 \rightarrow$ Total 1's is even

Syndrome $\rightarrow s_0$
 $\rightarrow 0$ (no. of 1s is even)
 $s_0 = 1$ (no. of 1s is odd.)

CYCLIC CODES

- **Special linear block codes with one extra property**
- **If a codeword is cyclically shifted (rotated), the result is another codeword**
- **If 1011000 is a codeword and we cyclically left-shift, then 0110001 is also a codeword**

Cyclic Redundancy Check (CRC)

- **Subset of Cyclic Codes**
- **Cyclic redundancy check (CRC) is used in networks such as LANs and WANs**

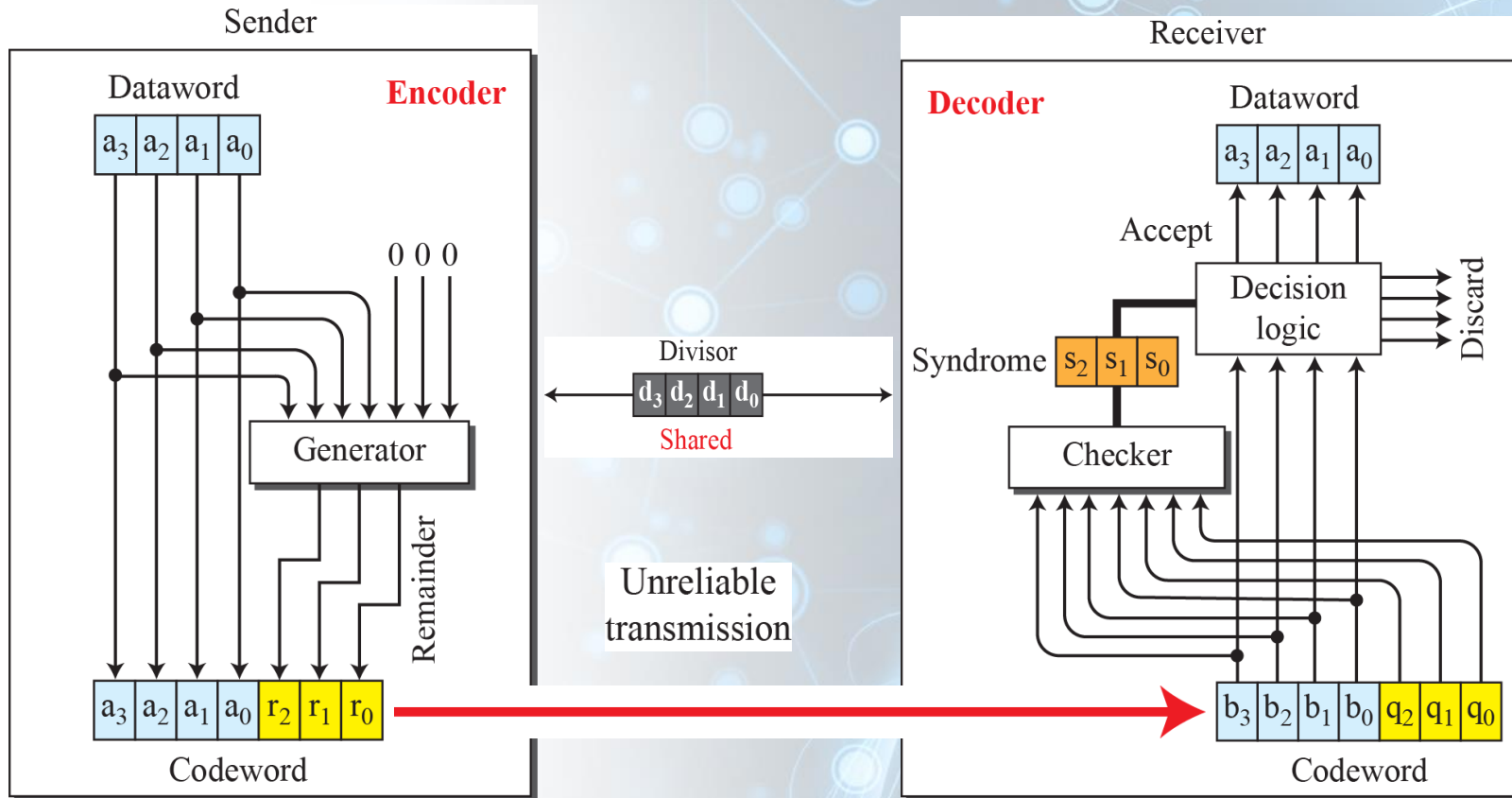
A CRC code with C(7, 4)

<i>Dataword</i>	<i>Codeword</i>	<i>Dataword</i>	<i>Codeword</i>
0000	0000000	1000	1000101
0001	0001011	1001	1001110
0010	0010110	1010	1010011
0011	0011101	1011	1011000
0100	0100111	1100	1100010
0101	0101100	1101	1101001
0110	0110001	1110	1110100
0111	0111010	1111	1111111

Cyclic Redundancy Check (CRC)

- **Subset of Cyclic Codes**
- **Cyclic redundancy check (CRC) is used in networks such as LANs and WANs**

CRC Encoder and Decoder



Cyclic Code Analysis using Polynomials

Dataword = $d(x)$, Codeword = $c(x)$, Generator = $g(x)$, Syndrome = $S(x)$, Error = $e(x)$

$S(x) \neq 0 \rightarrow$ Data is corrupted \rightarrow Discard

$S(x) = 0 \rightarrow$ No bit is corrupted

\hookrightarrow Corruption \rightarrow decoder has not detected it

Received Codeword = $\underline{\underline{c(x)}} + \underline{\underline{e(x)}}$

$$S(x) \frac{R. \text{ Codeword}}{g(x)} = \frac{c(x)}{g(x)} + \frac{e(x)}{g(x)}$$

$$S(x) = \textcircled{0} + \frac{e(x)}{g(x)}$$

Not
Caught

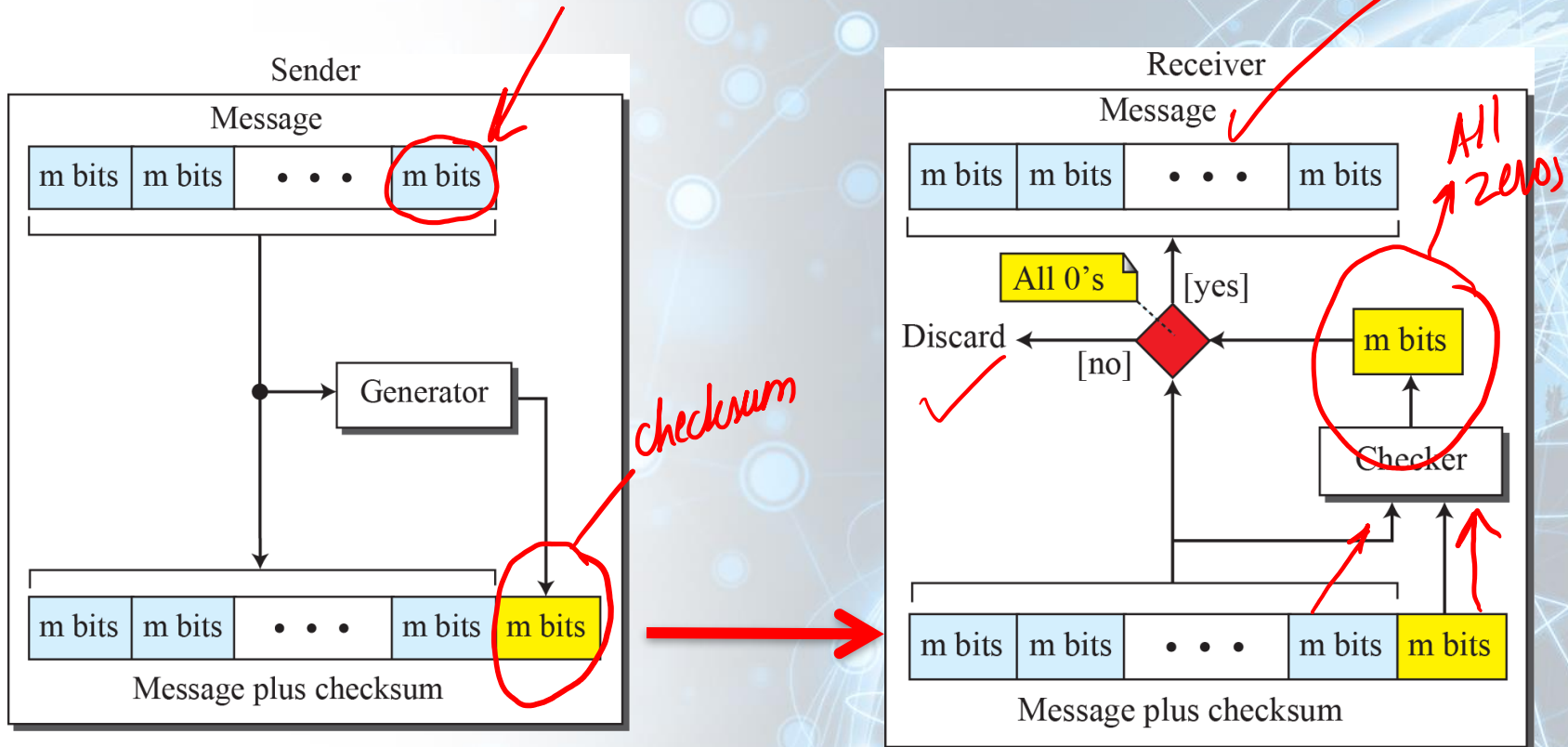
Advantages of Cyclic Codes

- **Good performance in detection:**
 - **Single-bit errors**
 - **Double errors**
 - **Odd number of errors**
 - **Burst errors**
- **Easy Implementation**
- **Fast Implementation**

CHECKSUM

- **Error-detection technique that can be applied to a message of any length**
- **Checksum mostly used at the network and transport layer rather than the data-link layer**

Checksum



Concept behind Checksum

- The idea of the traditional checksum is simple. We show this using a simple example

Example

Suppose the message is a list of five 4-bit numbers that we want to send to a destination. In addition to sending these numbers, we send the sum of the numbers.

Set of numbers is (7, 11, 12, 0, 6)

$$7 + 11 + 12 + 0 + 6 = \underline{\underline{36}}$$

(7, 11, 12, 0, 6, 36)
=====

4-bit word (each < 15)

(36)

Example

In the previous example, the decimal number 36 in binary is (100100)₂. To change it to a 4-bit number we add the extra leftmost bit to the right four bits as shown below

$$\begin{array}{l} \overline{(10)}_2 + \overline{(0100)}_2 = \overline{(0110)}_2 \\ \longrightarrow \quad \textcircled{(6)}_{10} \end{array}$$

*one's complement
arithmetic*

$$\begin{array}{l} (7, 11, 12, 0, 6, 36) \\ \downarrow \\ \underline{\underline{(7, 11, 12, 0, 6, 6)}} \end{array}$$

Forward Error Correction

- Retransmission of corrupted and lost packets is not useful for real-time multimedia transmission
- We need to correct the error or reproduce the packet immediately
- Several techniques developed and are commonly called Forward Error Correction techniques

Using Hamming Distance

- For error detection, we definitely need more distance
- It can be shown that to correct 't' errors, we need to have:
$$d_{\min} = 2t + 1$$
- If we want to correct 10 bits in a packet, we need to make the minimum hamming distance 21 bits
- A lot of redundant bits need to be sent with the data

Using Hamming Distance

If we want to correct 10 bits in a packet, we need to make the minimum hamming distance 21 bits

$$d_{\min} = 2t + 1$$

$$d_{\min} = 2(10) + 1$$

$$d_{\min} = \underline{\underline{21}} \rightsquigarrow \text{no. of bits (red)}$$

that you will
send with dataword

BCH

$$99 \text{ bits} \rightarrow \underline{\underline{255 \text{ bits}}}$$

$$\hookrightarrow \underline{\underline{156}}$$

$$\textcircled{\underline{\underline{(23)}}}$$

Using XOR

Another recommendation is to use the property of the exclusive OR operation as shown below.

$$R = P_1 \oplus P_2 \oplus \dots \oplus P_i \oplus \dots \oplus P_N$$

This means:

$$P_i = P_1 \oplus P_2 \oplus \dots \oplus R \oplus \dots \oplus P_N$$

Using XOR

Another recommendation is to use the property of the exclusive OR operation as shown below.

$$\underline{\underline{R}} = P_1 \oplus P_2 \oplus \dots \oplus P_i \oplus \dots \oplus P_N$$

$$\underline{\underline{N=4}}$$

→ 25% extra data

send.
XOR (one out of 4 chunks)

Data → P_1 → P_N

$$P_i = P_1 \oplus P_2 \oplus \dots \oplus R \oplus \dots \oplus P_N$$

⏟

N chunks

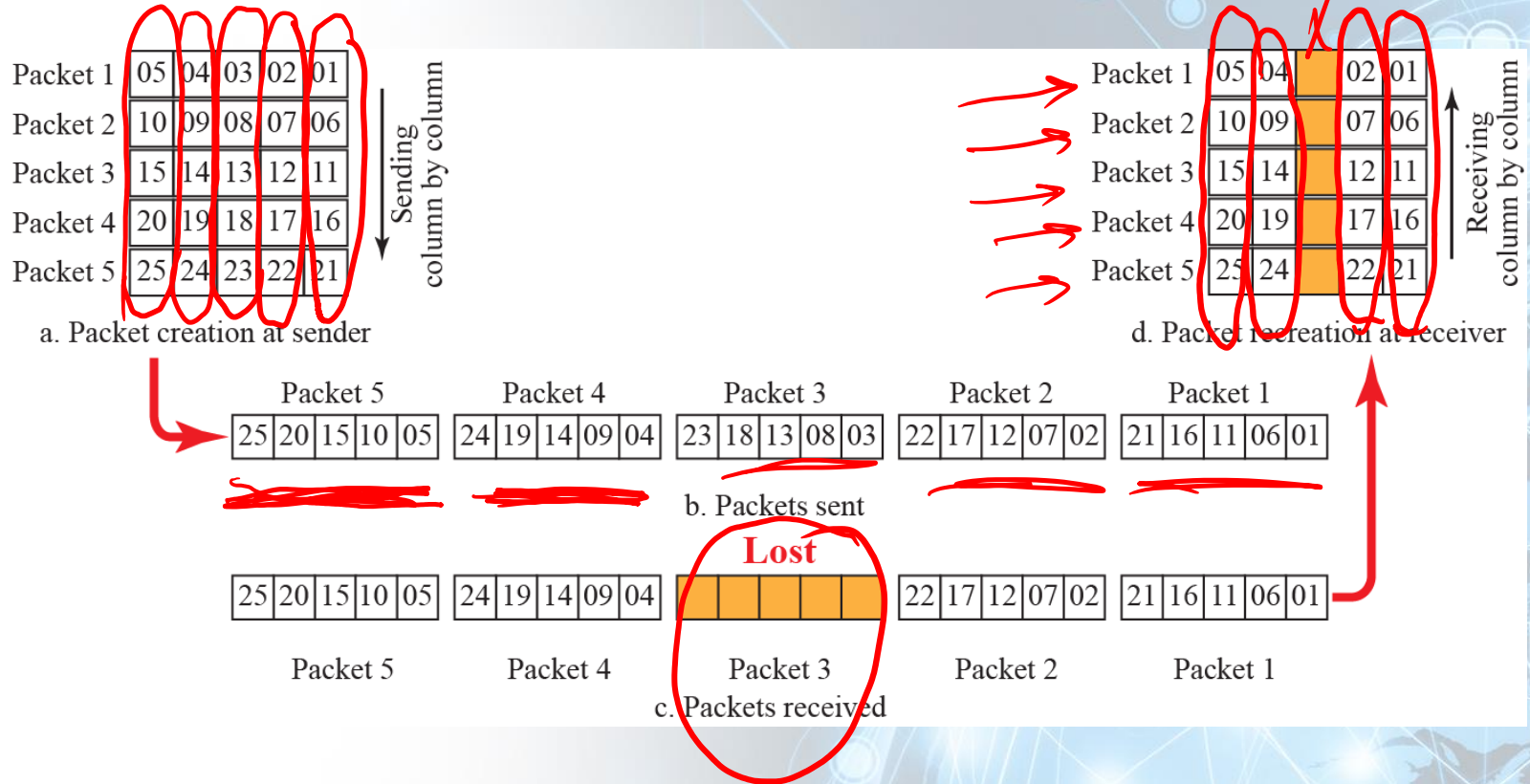
↳ N+1 chunks are

send.

Chunk Interleaving

- Another way to achieve FEC in multimedia is to allow some small chunks to be missing at the receiver
- We cannot afford to let all the chunks belonging to the same packet be missing; however, we can afford to let one chunk be missing in each packet

Interleaving



Combining Hamming Distance & Interleaving

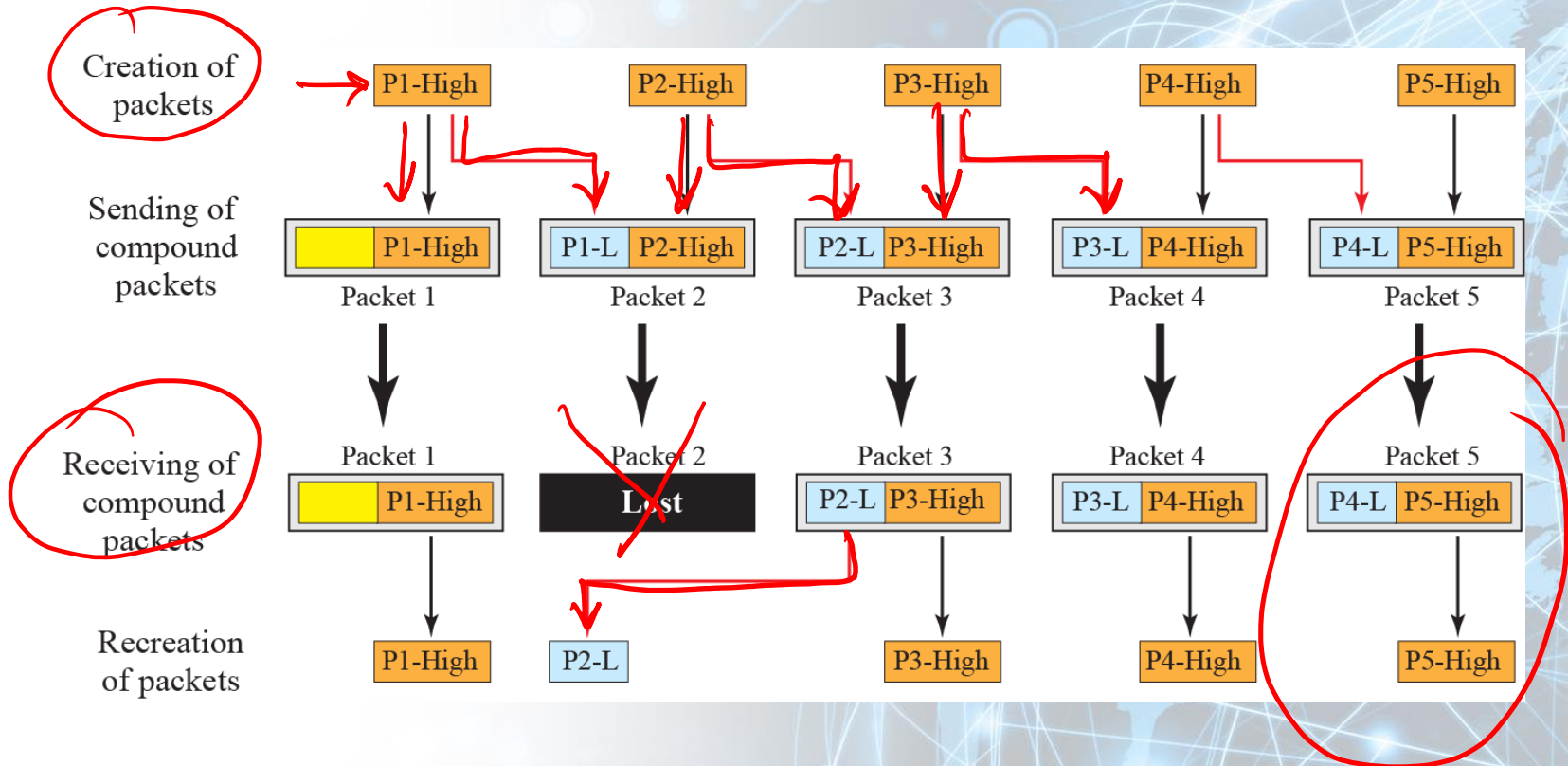
- Hamming distance and interleaving can be combined
- We can first create n -bit packets that can correct t -bit errors
- Then we interleave m rows and send the bits column by column
- Possible to correct burst errors up to $m \times t$ bits of errors

Compounding High & Low Resolution Packets

- **Creation of a duplicate of each packet with a low-resolution redundancy and combine the redundant version with the next packet**
- **For example, we can create four low-resolution packets out of five high-resolution packets and send them**

Compounding High-and-Low resolution Packets

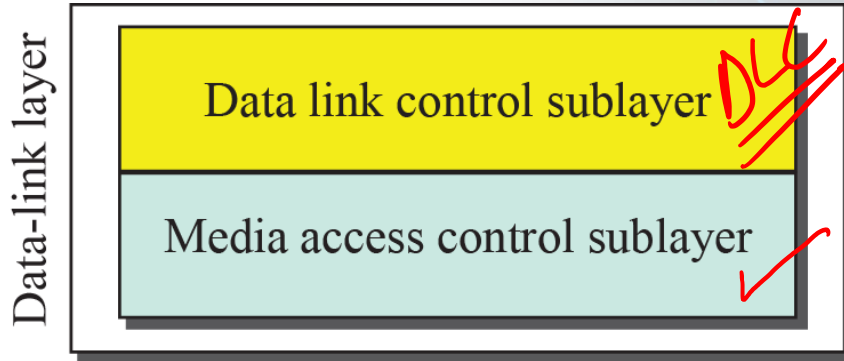
Legend



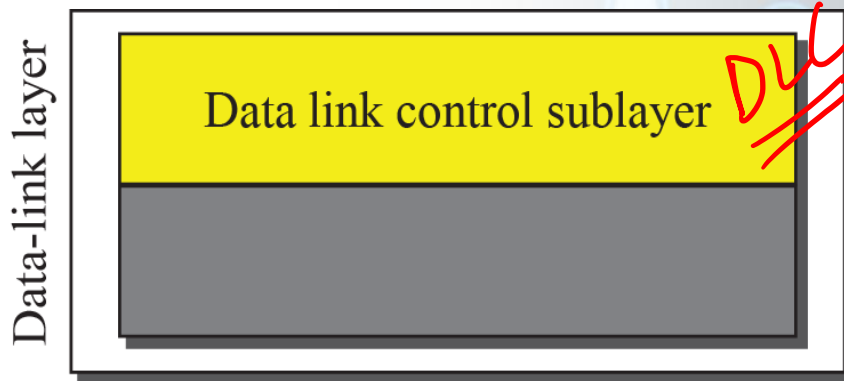
Data Link Control (DLC) Services

- The data link control (DLC) deals with procedures for communication between two adjacent nodes no matter whether the link is dedicated or broadcast
- Data link control functions include framing, flow control and error control

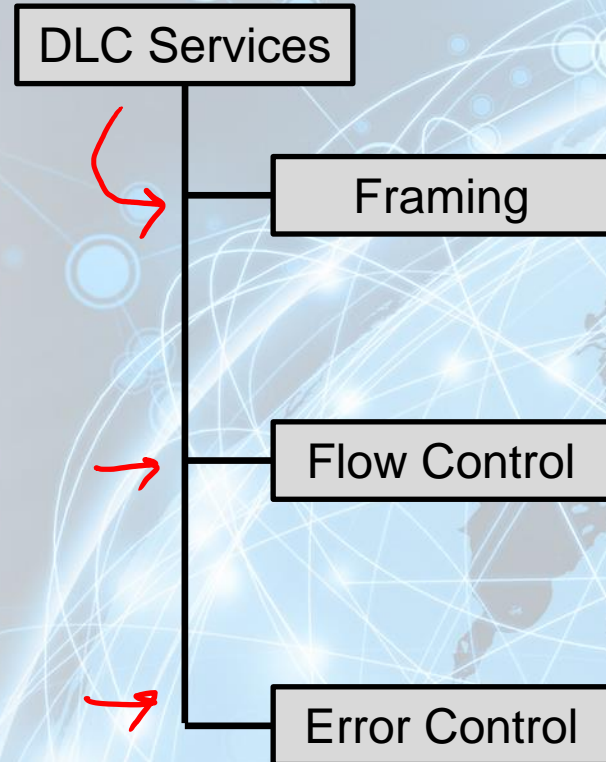
DLC Services



a. Data-link layer of a broadcast link



b. Data-link layer of a point-to-point link



Framing

- **Data-Link layer needs to pack bits into frames, so that each frame is distinguishable from another**
- **Our postal system practices a type of framing**
- **Framing separates a message by adding a sender address and a destination address**

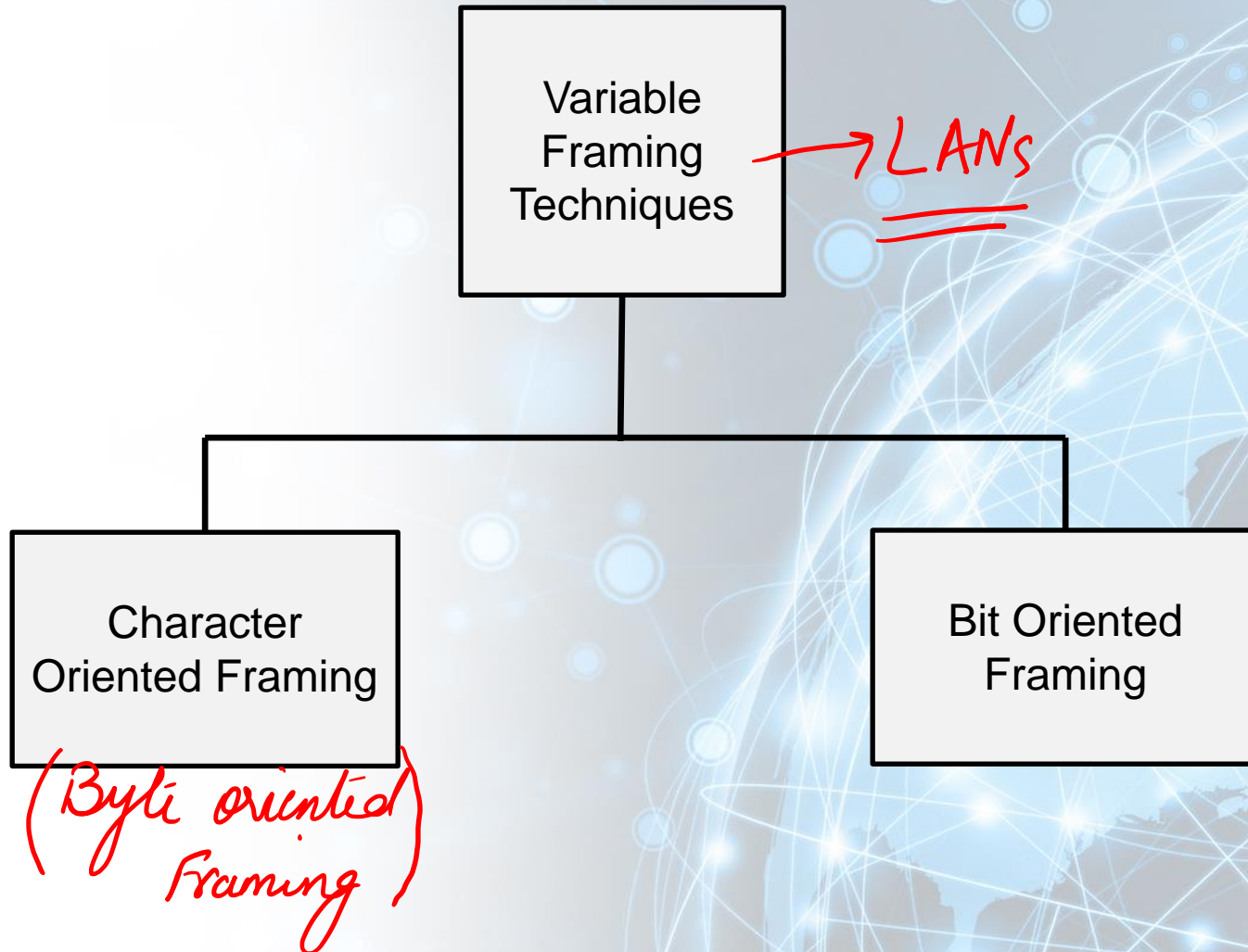
Framing

- **The destination address defines where the packet is to go; the sender address helps the recipient acknowledge the receipt**

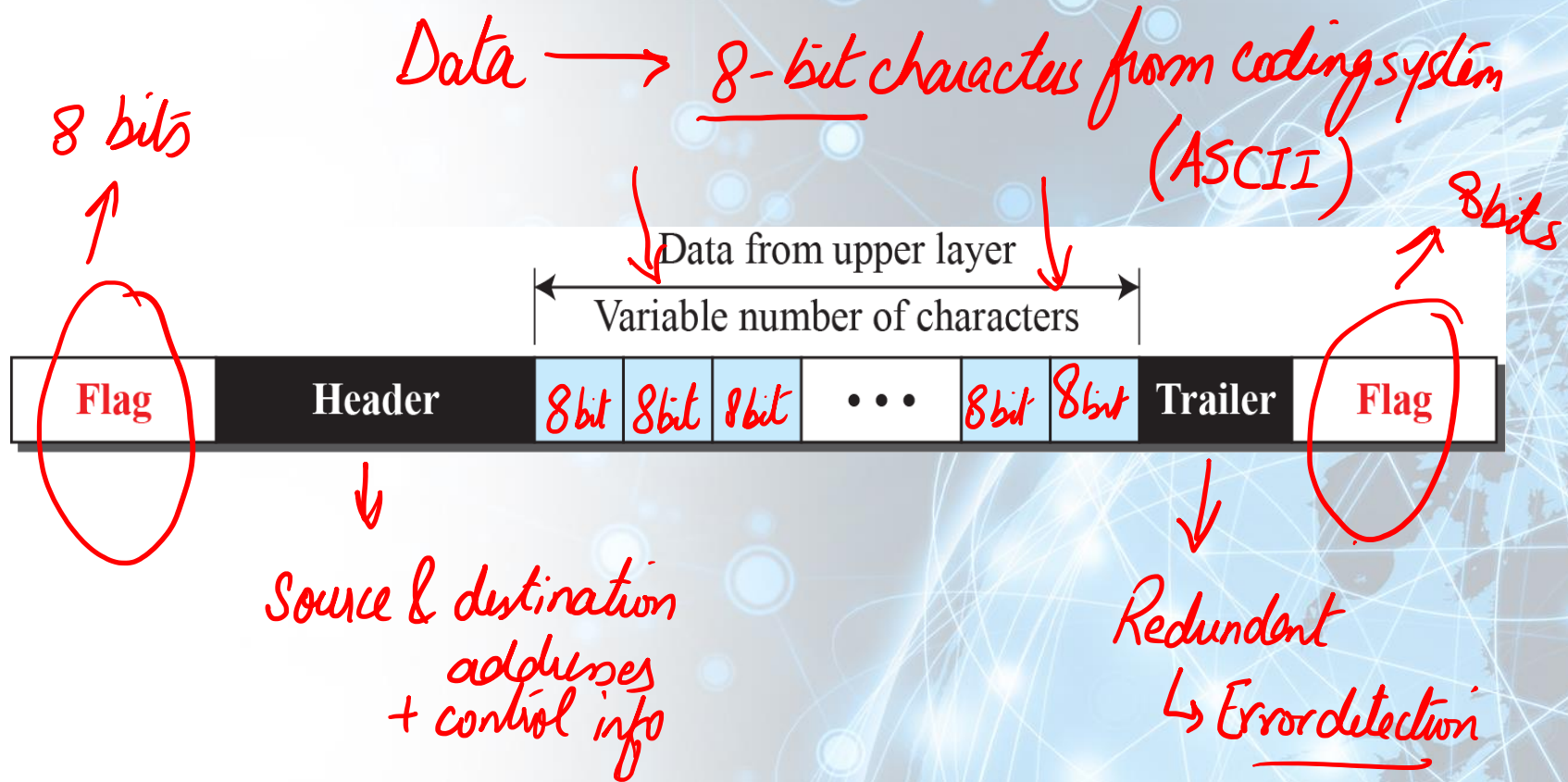
Frame Size

- **Why not one BIG Frame?**
- **Frames can be of:**
 - ✓ **Fixed Size**
 - **Size acts as a boundary/delimiter**
 - ✓ **Variable Size**
 - **How to define Beginning and End of a Frame?**

Variable Framing Techniques



A Frame in a Character-Oriented Protocol



Connection Oriented Framing

- Data to be carried are 8-bit characters

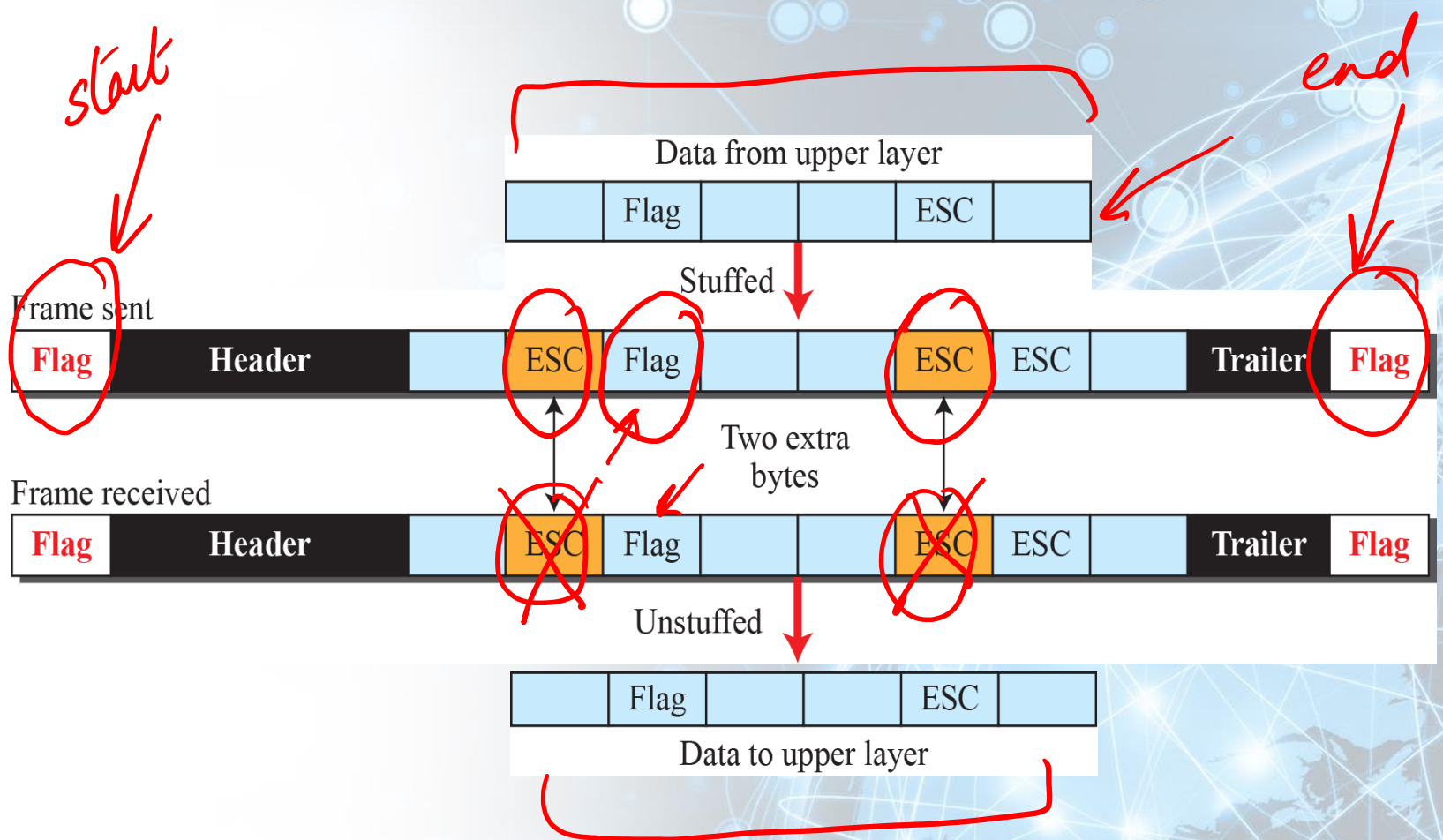
Byte Stuffing in Connection-Oriented Framing

- **Connection-oriented Framing used text characters as flags**
- **Nowadays any character used for flag can also be a part of the data**
- **In order to avoid confusing the receiver, we use Byte Stuffing**

Byte Stuffing in Connection-Oriented Framing

- **Several Issues:**
 - ✓ **One or more escape characters followed by a byte with same pattern as a flag?**
 - ✓ **Unicode (16/32 bit) vs. 8-bit characters**
- **Data is stuffed with a pre-defined Escape Character (byte) when there is a character with same pattern as a flag**

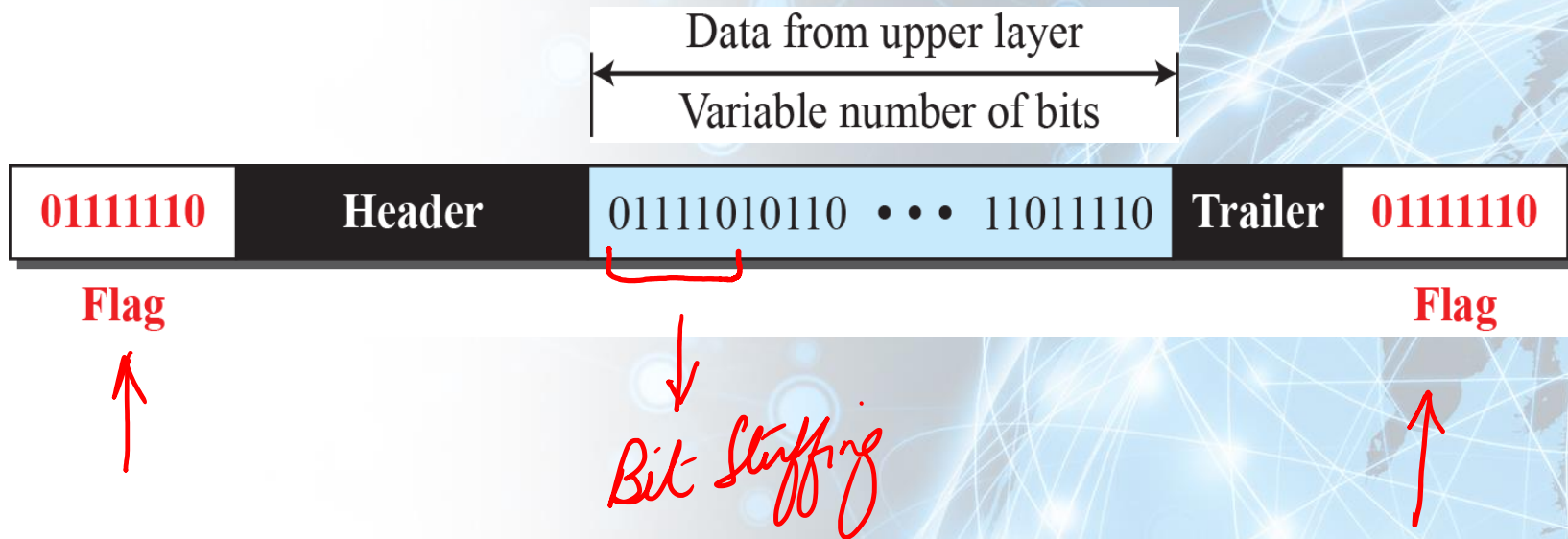
Byte Stuffing and Unstuffing



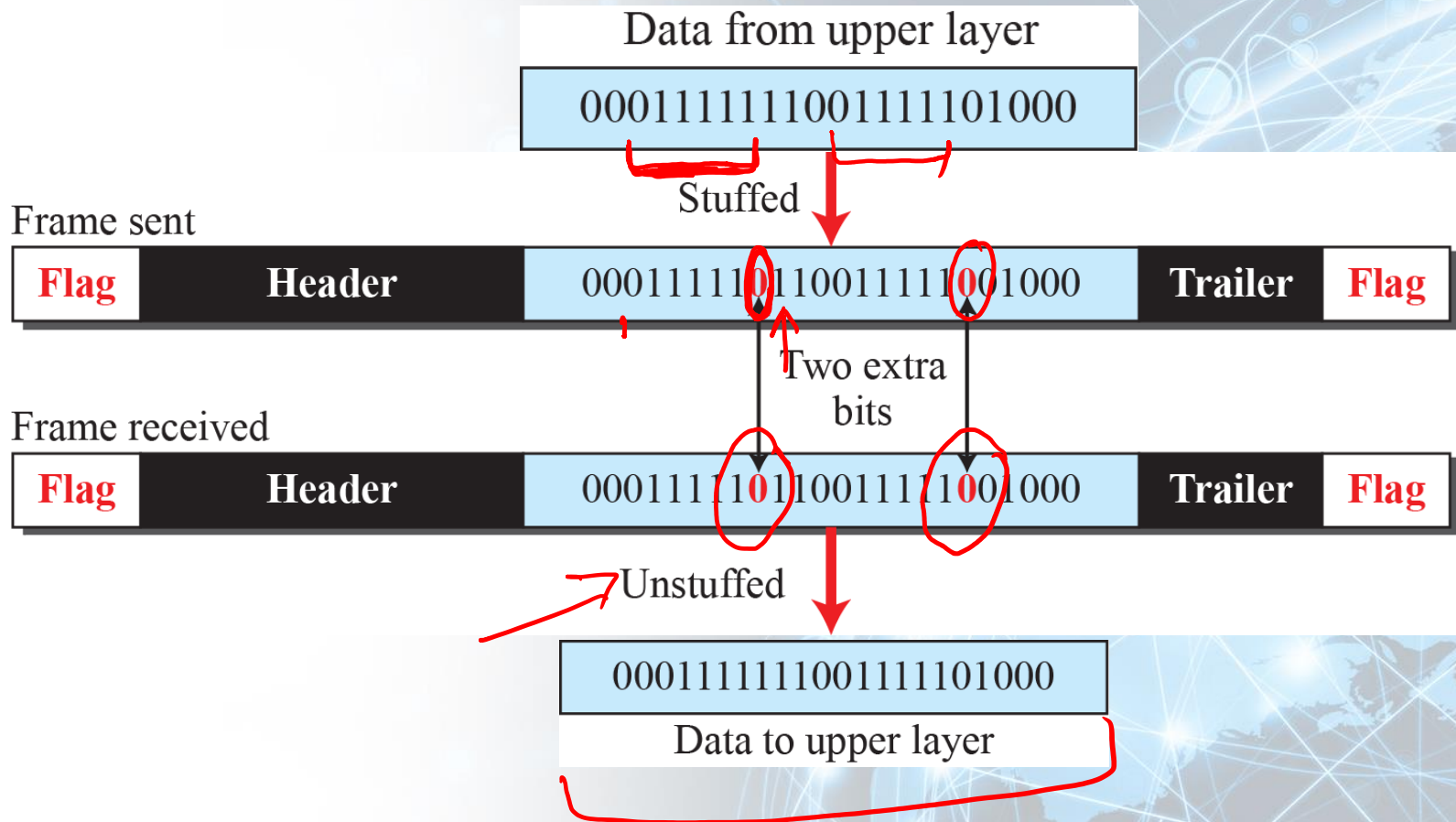
Bit-Oriented Framing

- Data section of frame is a sequence of bits
- We need a delimiter to separate one frame from the other
- A special 8-bit pattern (01111110) to define beginning and end of a frame
- Same issue as Connection-oriented Framing

A Frame in a Bit-Oriented Protocol



Bit Stuffing and Unstuffing



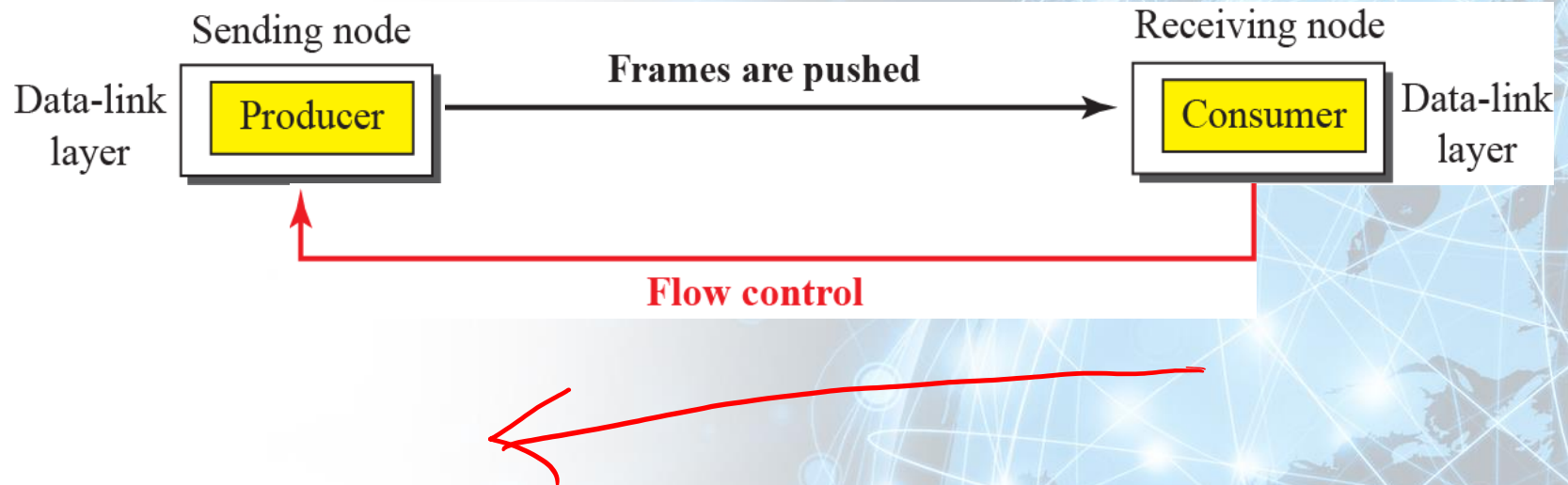
Flow and Error Control

- One of the responsibilities of the data-link control sublayer is flow and error control at the data-link layer

Flow Control

- **Balance between production and consumption rates**
- **If frames are produced faster than they are consumed at the receiving data link layer, the frames will be discarded**
- **Use of buffers; one at sending end and other at receiving end**

Flow Control at the Data Link Layer



Example

- **Consumers need to communicate with the producers on two occasions:**
 - ✓ **When the buffer is full; &**
 - ✓ **When there are vacancies**
- ✓ **If the two parties use a buffer with only one slot, the communication can be easier**

Error Control

- **Error Control at Data Link layer uses CRC in one of the two ways:**
 - ✓ **If a frame is corrupted, it is silently discarded and if it is good, it is delivered to network layer**
 - ✓ **If frame is corrupted, it is silently discarded and if it is good, an acknowledgement is sent to sender**

Connectionless and Connection-Oriented

- A DLC protocol can be either connectionless or connection-oriented
- **Connectionless:** No relationship between the frames
- **Connection-Oriented:** Frames are numbered and sent in order

DATA-LINK LAYER PROTOCOLS

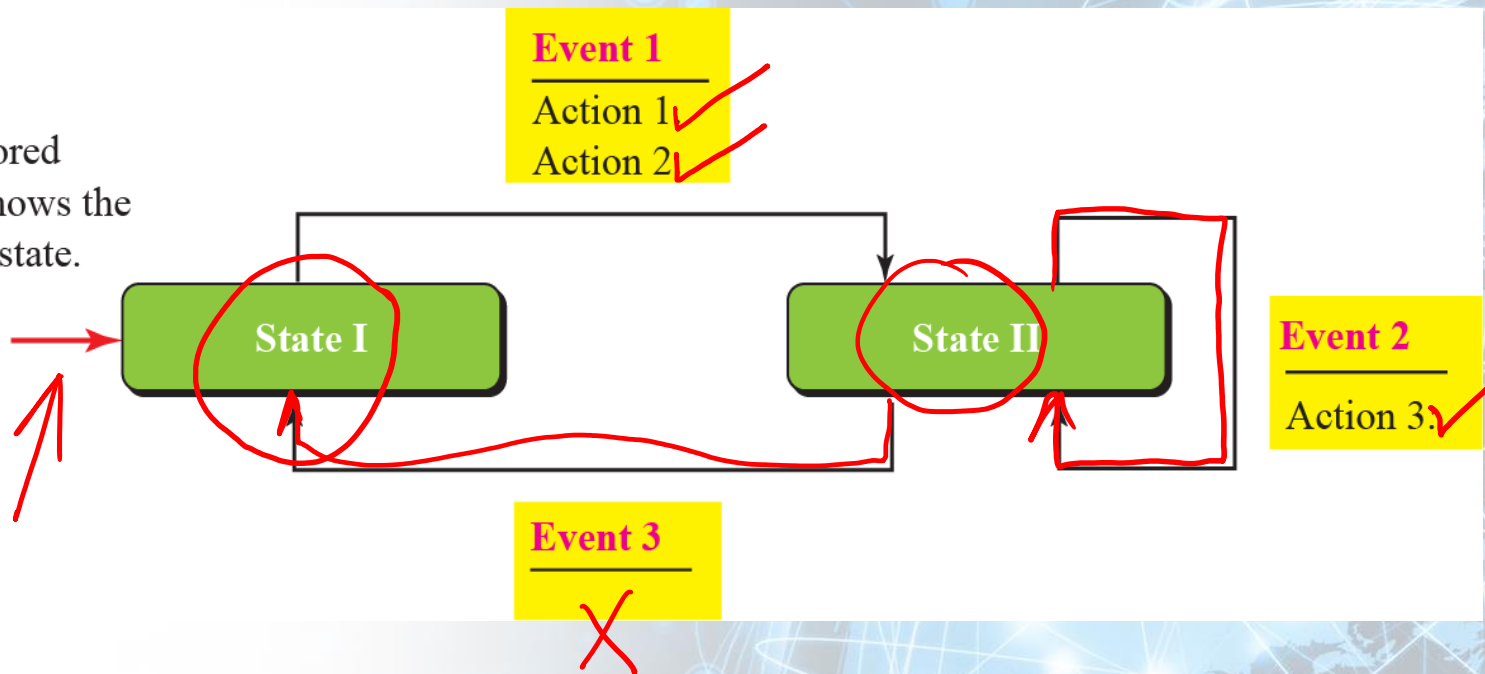
- Traditionally four protocols have been defined for the data-link layer to deal with flow and error control:
 - ✓ Simple Protocol
 - ✓ Stop-and-Wait Protocol
 - ✓ Go-Back-N Protocol
 - ✓ Selective-Repeat Protocol
- Last two protocols have almost disappeared completely

Finite State Machine (FSM)

- A machine with a finite number of states
- Machines stays in one of the states until an event occurs
- Each event is associated with 2 reactions:
 - ✓ List of actions to be performed
 - ✓ Determining the next state

Finite State Machine (FSM)

Note:
The colored
arrow shows the
starting state.



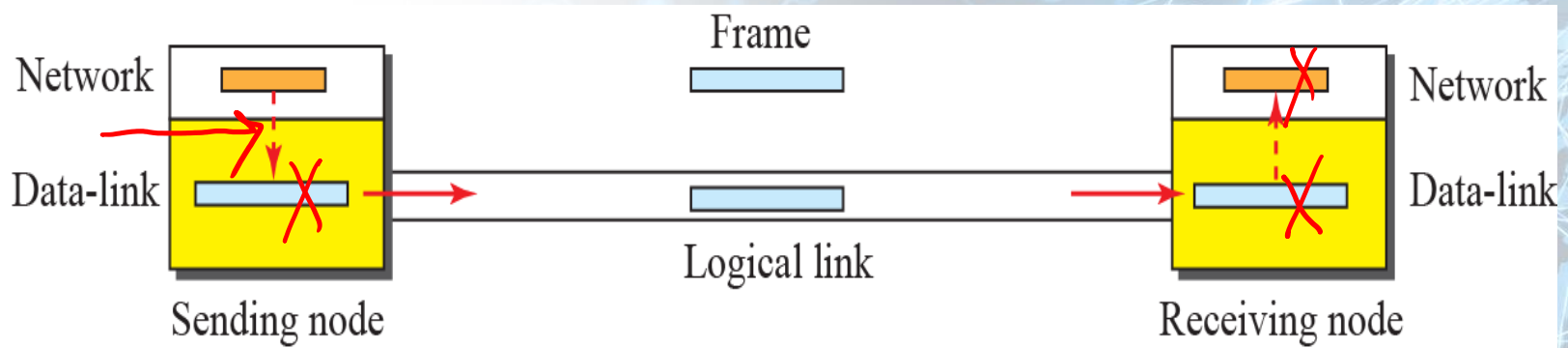
DATA-LINK LAYER PROTOCOLS

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 - ✓ Simple Protocol
 - ✓ Stop-and-Wait Protocol
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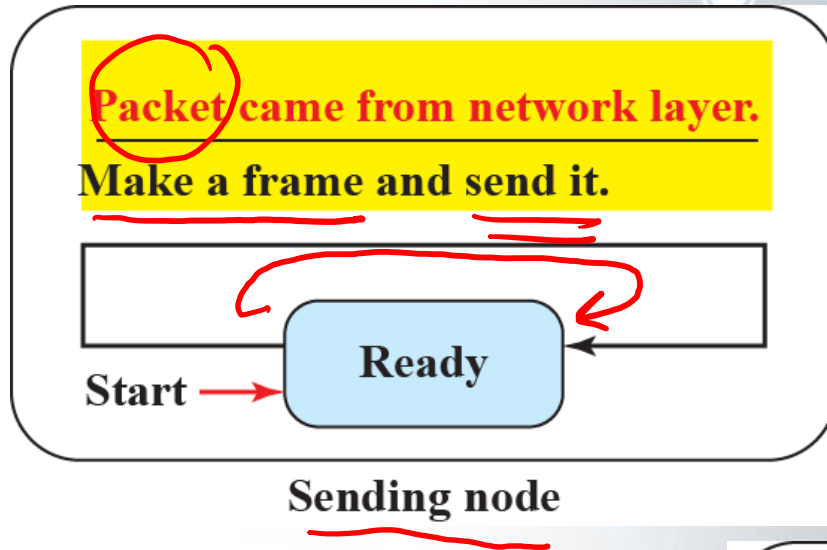
Simple Protocol

- **Simple protocol has neither flow nor error control**
- **Assumption: The receiver can immediately handle any frame it receives**
- **The receiver can never be overwhelmed with incoming frames**

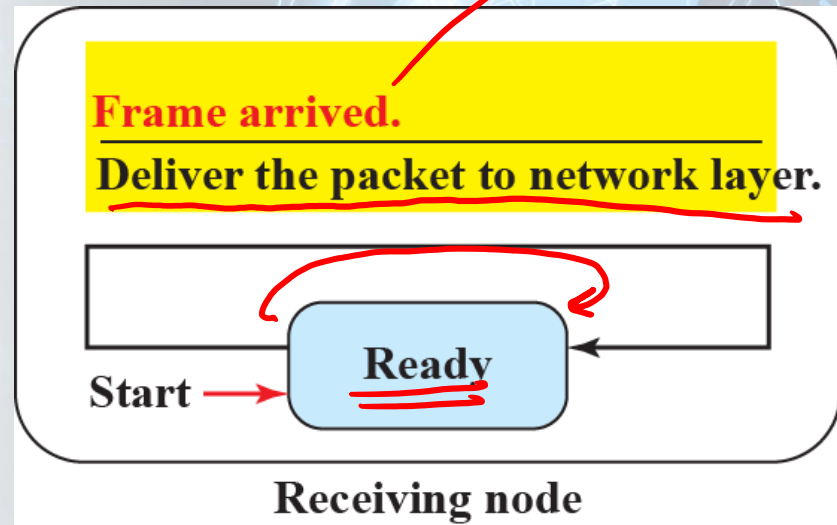
Simple Protocol



FSM for Simple Protocol



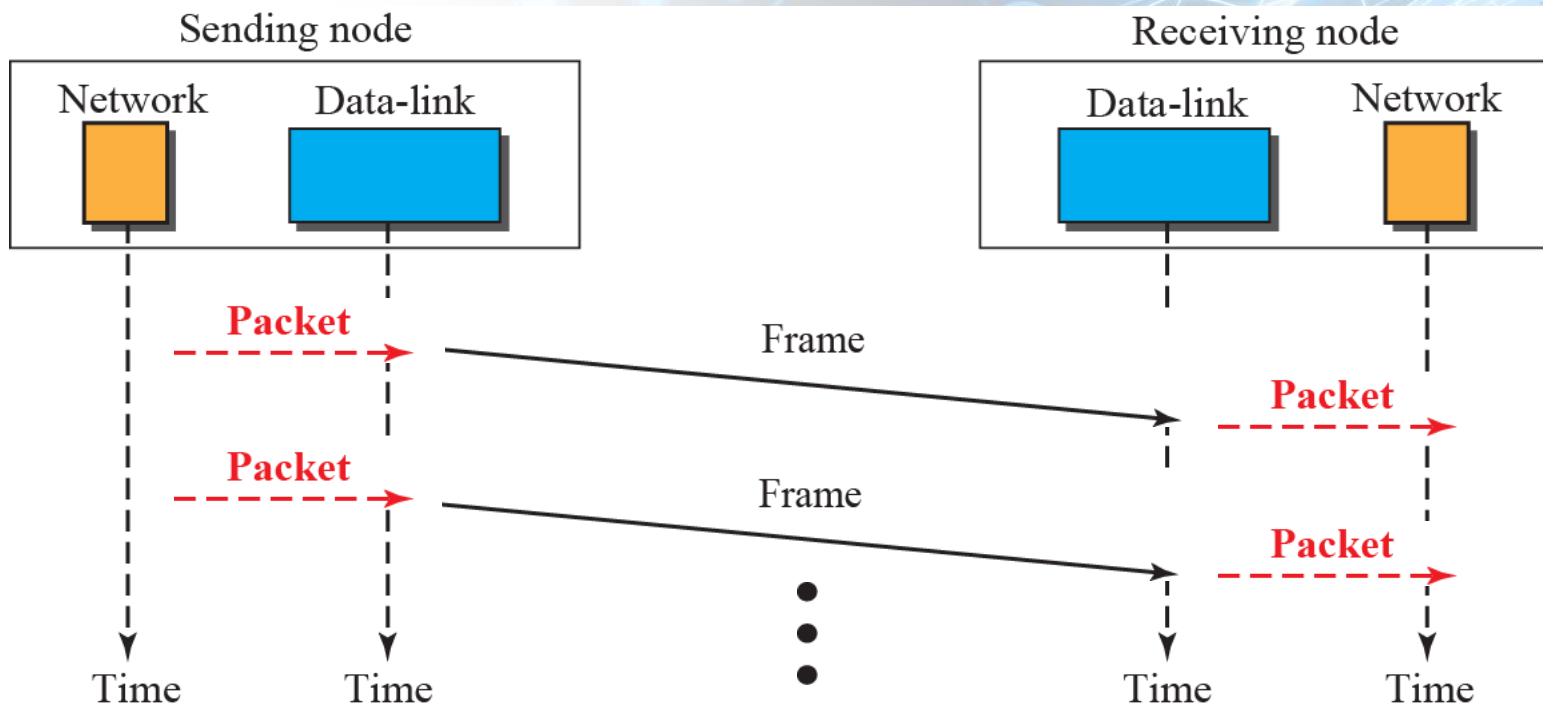
L3
↓ packet
DL } events



event

Example

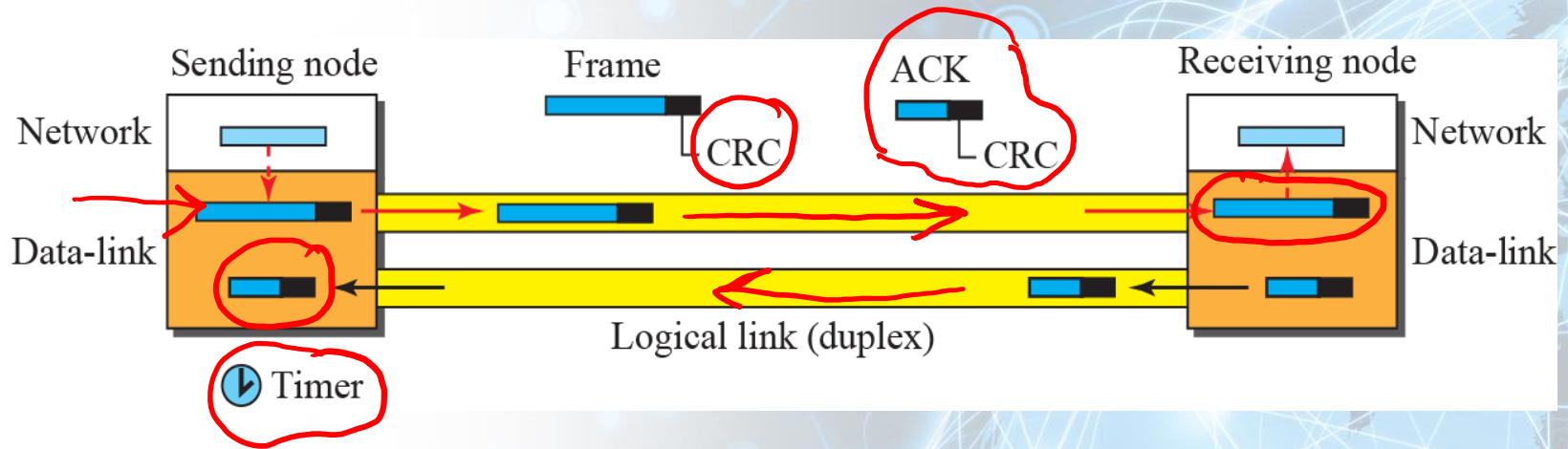
Here is an example of communication using this protocol. It is very simple. The sender sends frames one after another without even thinking about the receiver.



Stop-and-Wait Protocol

- **Stop-and-Wait protocol uses both flow and error control**
- **The sender sends one frame at a time and waits for an acknowledgment before sending the next one**
- **To detect corrupted frames, we add a CRC code**

Stop-and-Wait Protocol






Stop-and-Wait Protocol

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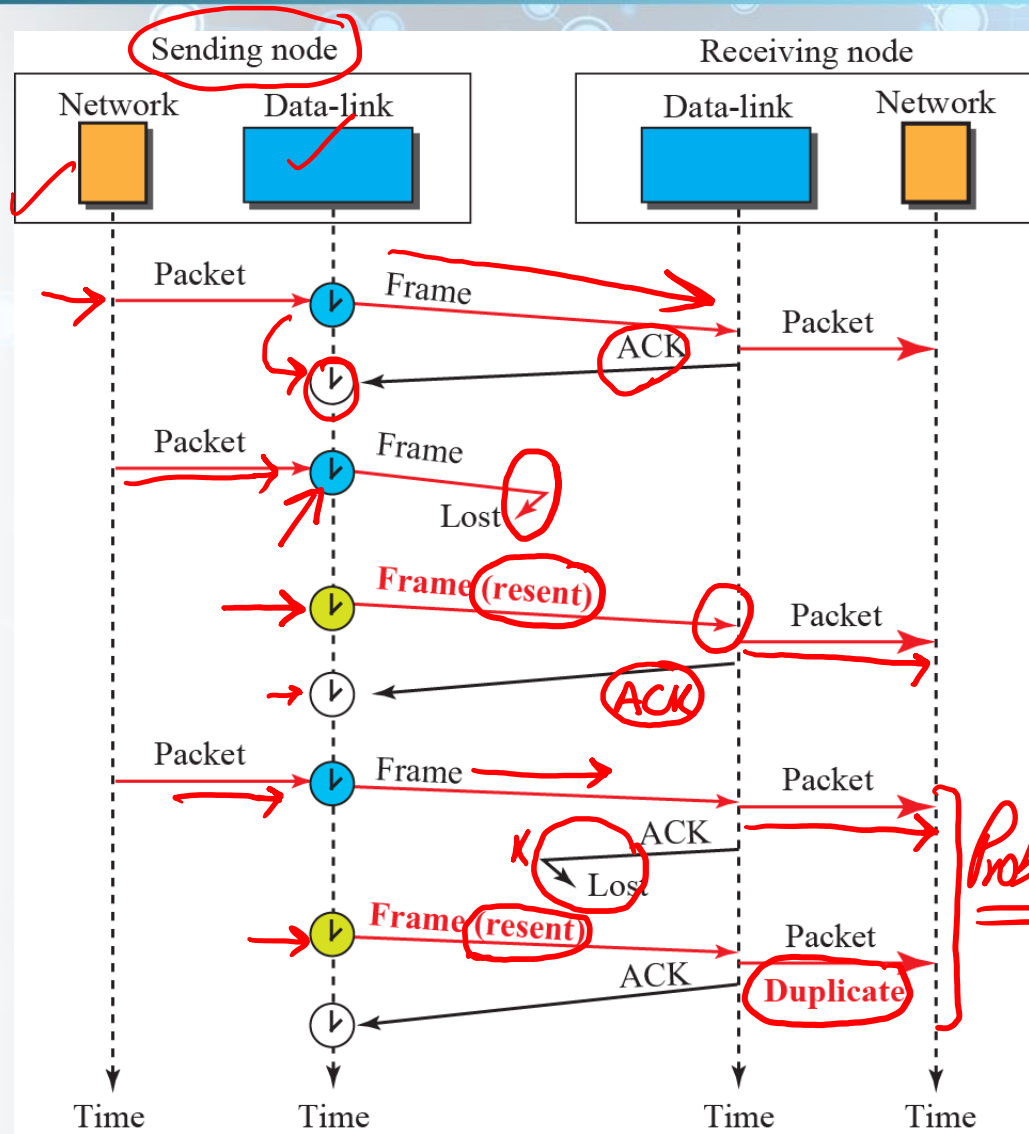
Example

Legend

-  Start the timer.
-  Stop the timer.
-  Restart a time-out timer.

Notes:

A lost frame means either lost or corrupted.
A lost ACK means either lost or corrupted.



Example

Legend

- Start the timer.
- Stop the timer.
- Restart a time-out timer.

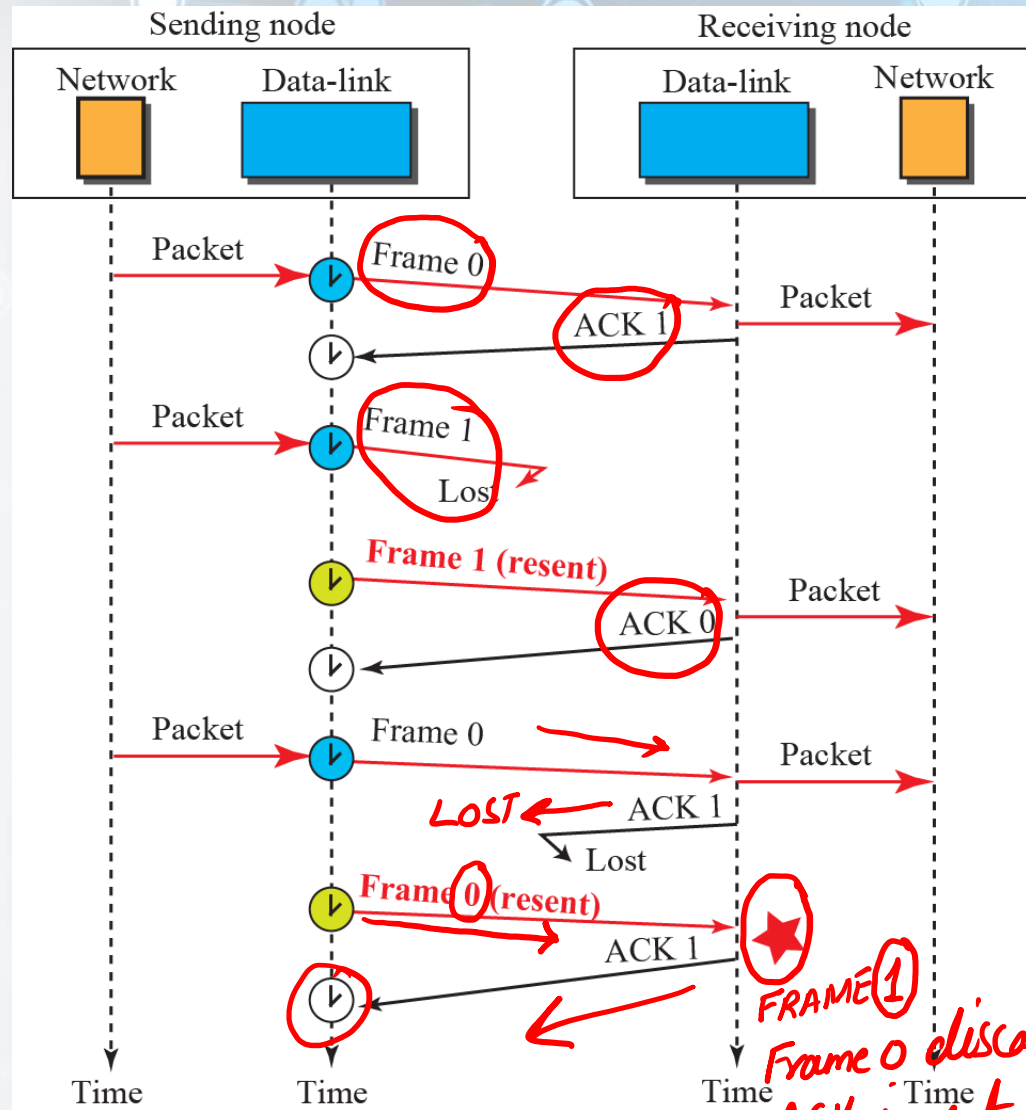
Notes:

A lost frame means either lost or corrupted.

A lost ACK means either lost or corrupted.



Frame 0 is discarded because the receiver expects frame 1.



Piggybacking

- **Both Simple and Stop-and-wait protocols are designed for unidirectional communication**
- **Data flows in one direction and ACK travels in the other**
- **To make the system efficient, the data in one direction is piggybacked with the acknowledgment in the other direction**

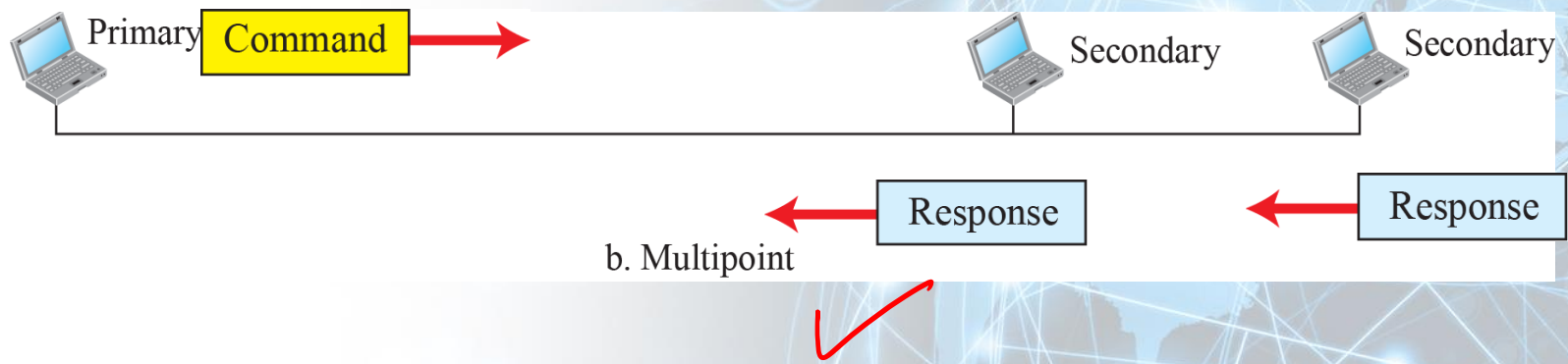
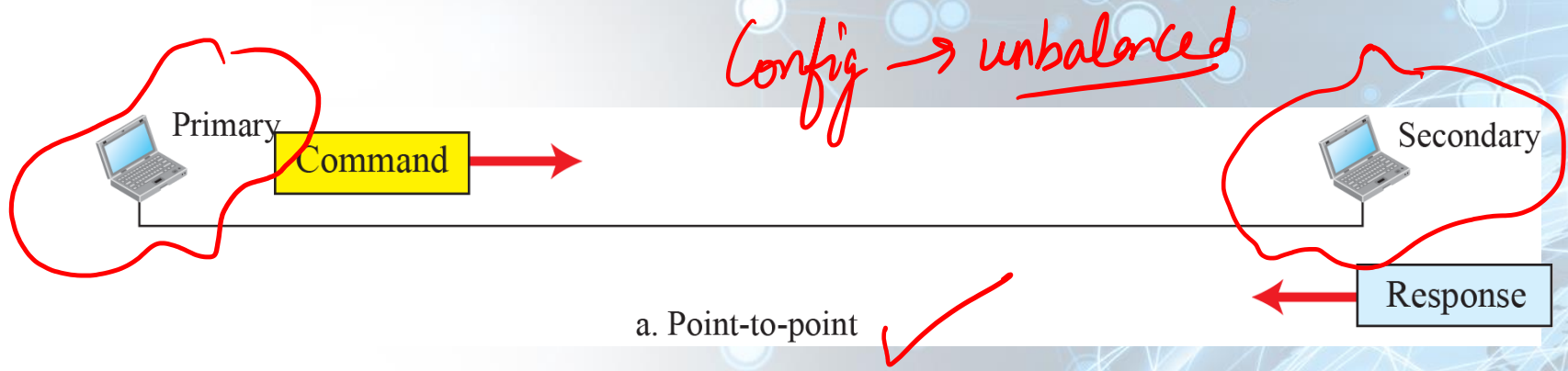
High-level Data Link Control (HDLC)

- **Bit -oriented protocol for communication over point-to-point and multipoint links**
- **It implements Stop-and-Wait protocol**
- **Most of the concepts defined in this protocol is the basis for other protocols such as PPP, Ethernet, or wireless LANs**

Configurations & Transfer Modes in HDLC

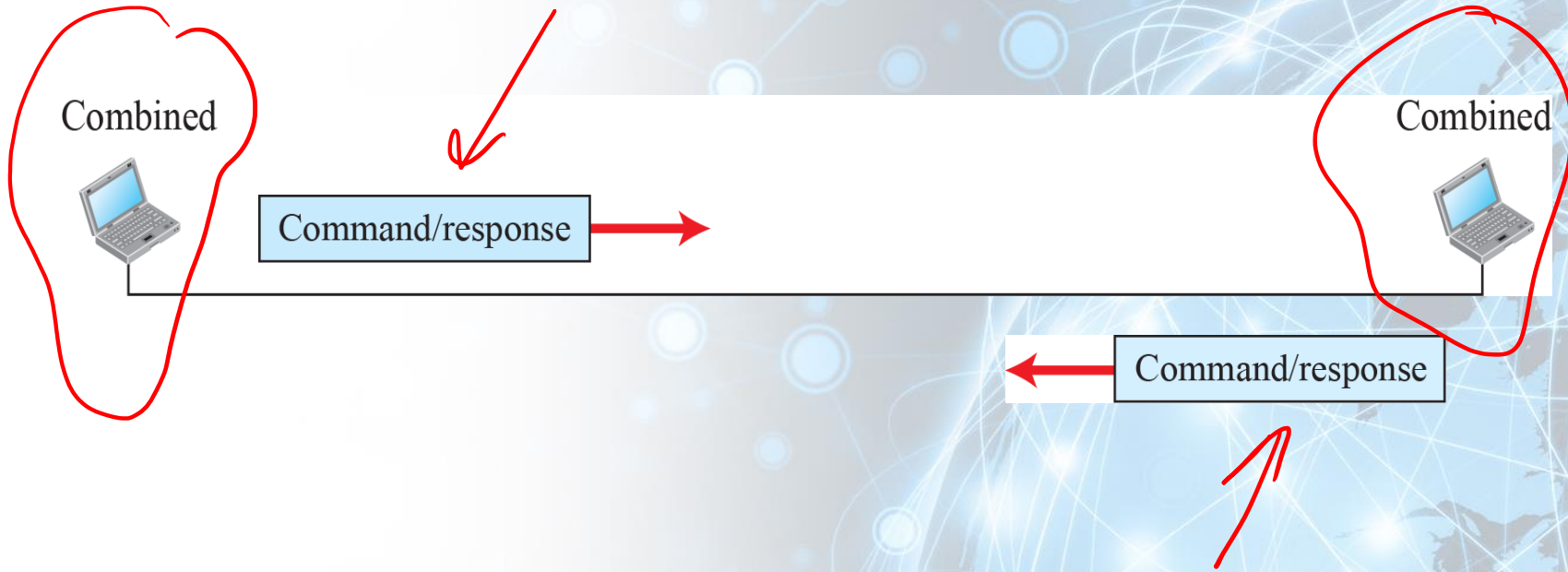
- HDLC provides two common transfer modes that can be used in different configurations:
 - ✓ Normal Response Mode (NRM) &
 - ✓ Asynchronous Balanced Mode (ABM)

Normal Response Mode



Asynchronous Balanced Mode

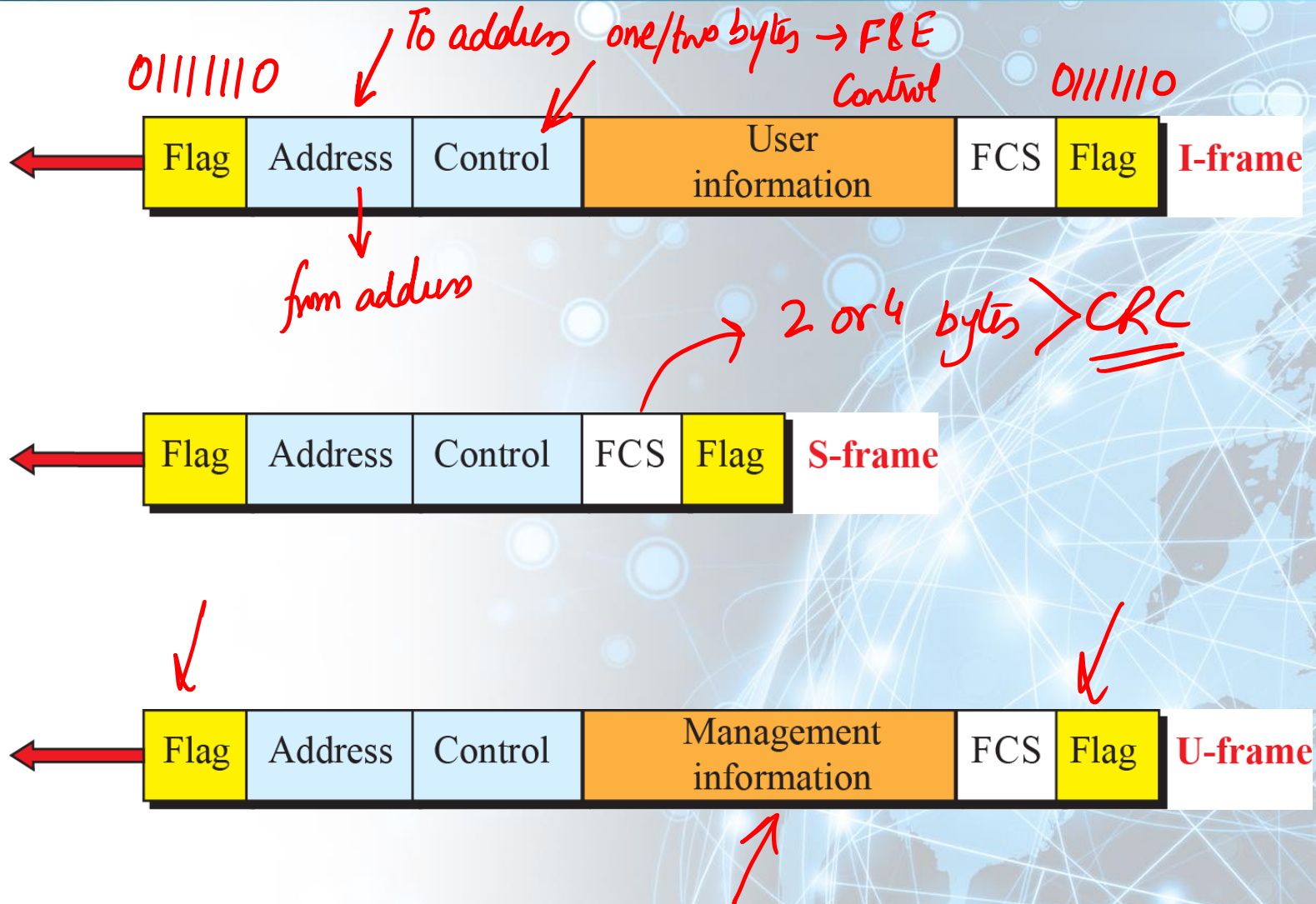
ABM



Framing

- HDLC defines three types of frames:
 - ✓ information frames (I-frames)
 - ✓ Supervisory frames (S-frames)
 - ✓ Unnumbered frames (U-frames)

HDLC Frames



Point-to-Point Protocol (PPP)

- **Most common protocol for point-to-point access**
- **Millions of Internet users who need to connect their home computers to the server of an Internet service provider use PPP**
- **To control and manage the transfer of data, there is a need for a PPP at the data-link layer**

Services provided by PPP

The designers of PPP have included several services to make it suitable for a point-to-point protocol, but have ignored some traditional services to make it simple

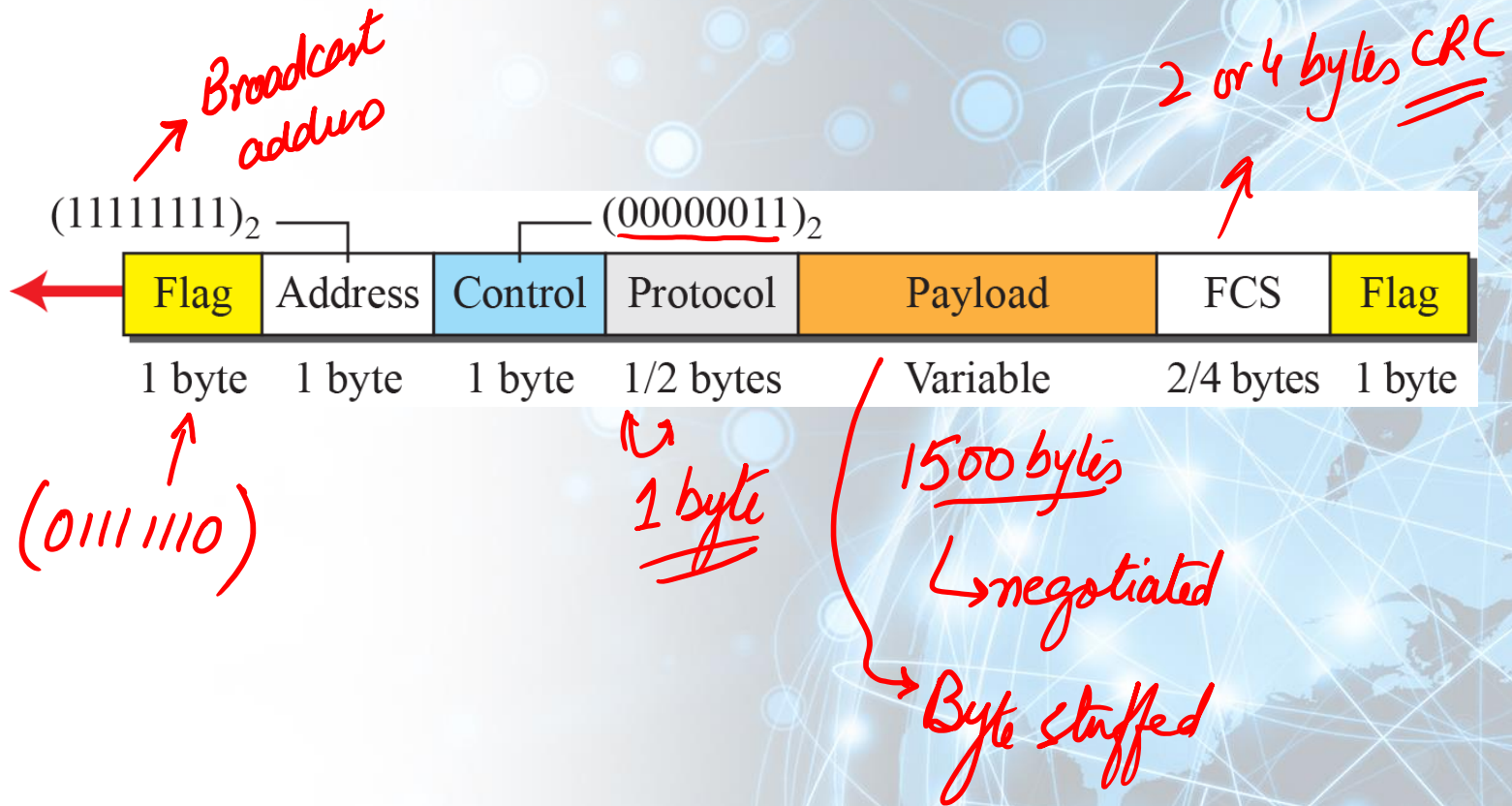
Services Included	Services Not Included
Framing	Flow Control
Link Establishment and Data Exchange	Error Correction (PPP has CRC detection only)
Authentication	No Sequence Numbering
Multilink PPP Address configuration	Absence of sophisticated Addressing Mechanism
Network Address configuration	

Point-to-Point Protocol (PPP)

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PPP Frame Format

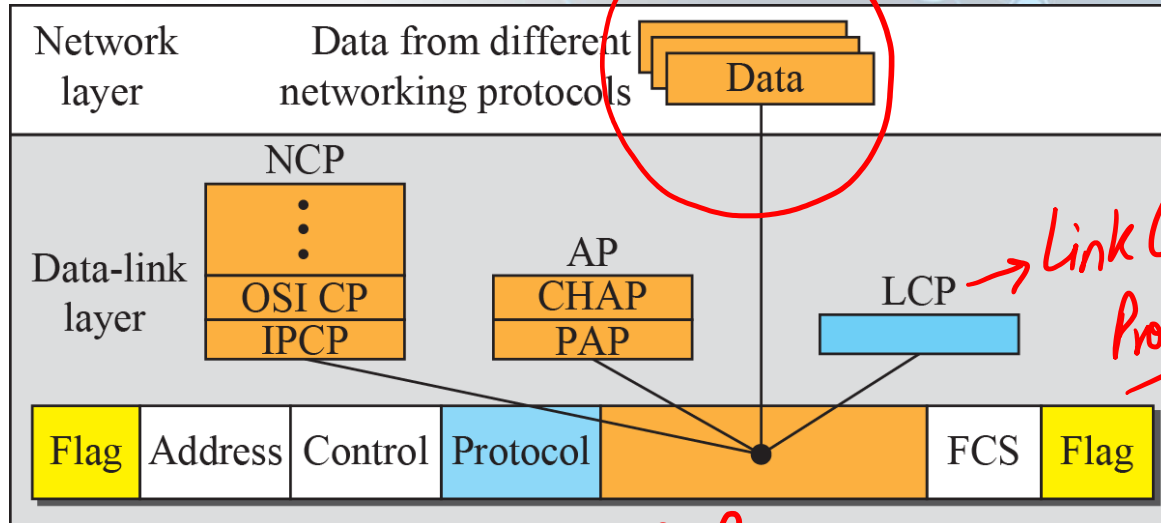
PPP uses a character-oriented (or byte-oriented) frame



Multiplexing in PPP

- Although PPP is a link-layer protocol, it uses another set of protocols to establish the link, authenticate and carry the network-layer data
- Three sets of protocols are:
 - Link Control Protocol (LCP)
 - Two Authentication Protocols (APs)
 - Several Network Control Protocols (NCPs)

Multiplexing in PPP



Legend

LCP : Link control protocol
 AP : Authentication protocol
 NCP: Network control protocol

Protocol values:

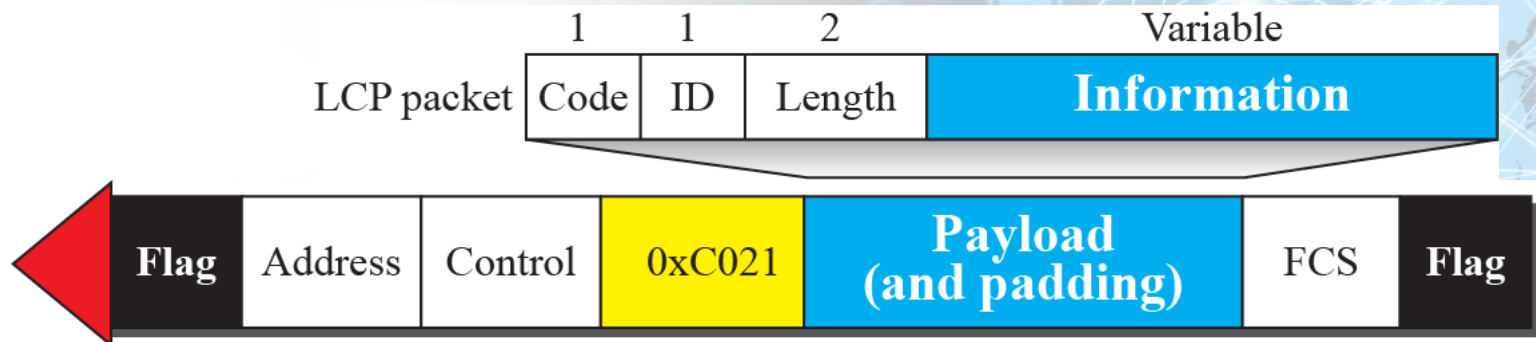
LCP : 0xC021
 AP : 0xC023 and 0xC223
 NCP: 0x8021 and
 Data: 0x0021 and

*AP → PAP
 → CHAP
 NCP → IPCP*

Link Control Protocol

*↓
 establishing
 maintaining
 configuring
 terminating
 links*

LCP Packet encapsulated in a Frame



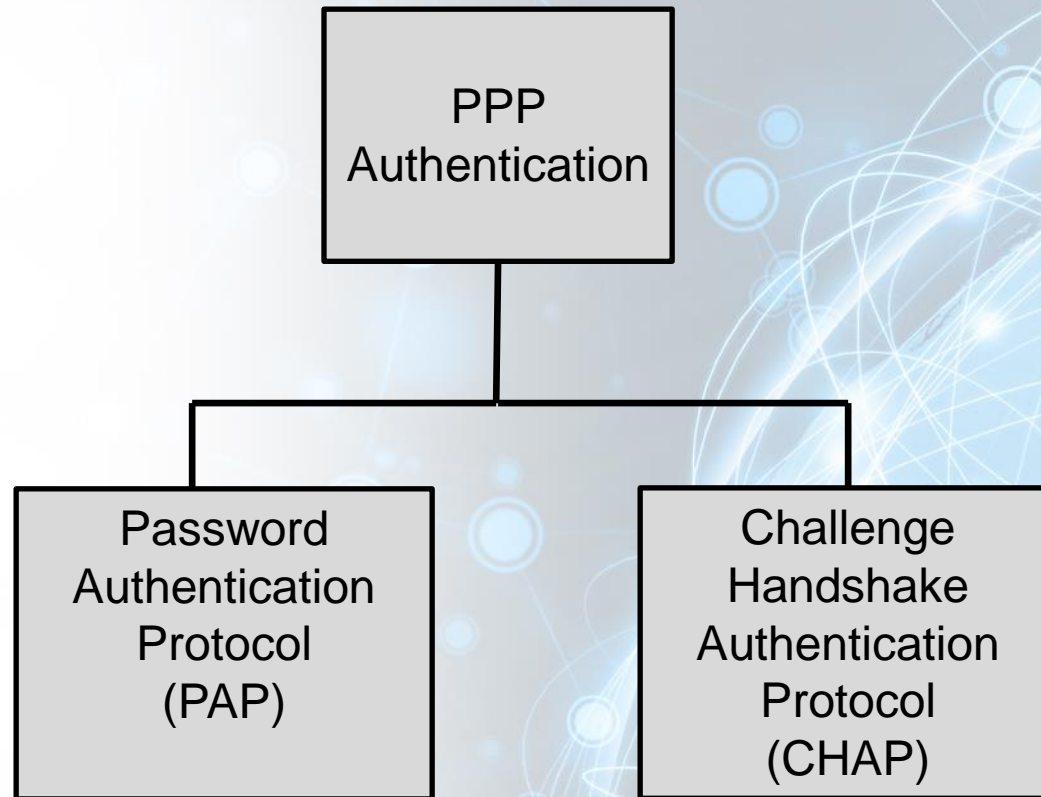
LCP Packets

Code	Packet Type	Description
0x01	Configure-request	Contains the list of proposed options and their values
0x02	Configure-ack	Accepts all options proposed
0x03	Configure-nak	Announces that some options are not acceptable
0x04	Configure-reject	Announces that some options are not recognized
0x05	Terminate-request	Request to shut down the line
0x06	Terminate-ack	Accept the shutdown request
0x07	Code-reject	Announces an unknown code
0x08	Protocol-reject	Announces an unknown protocol
0x09	Echo-request	A type of hello message to check if the other end is alive
0x0A	Echo-reply	The response to the echo-request message
0x0B	Discard-request	A request to discard the packet

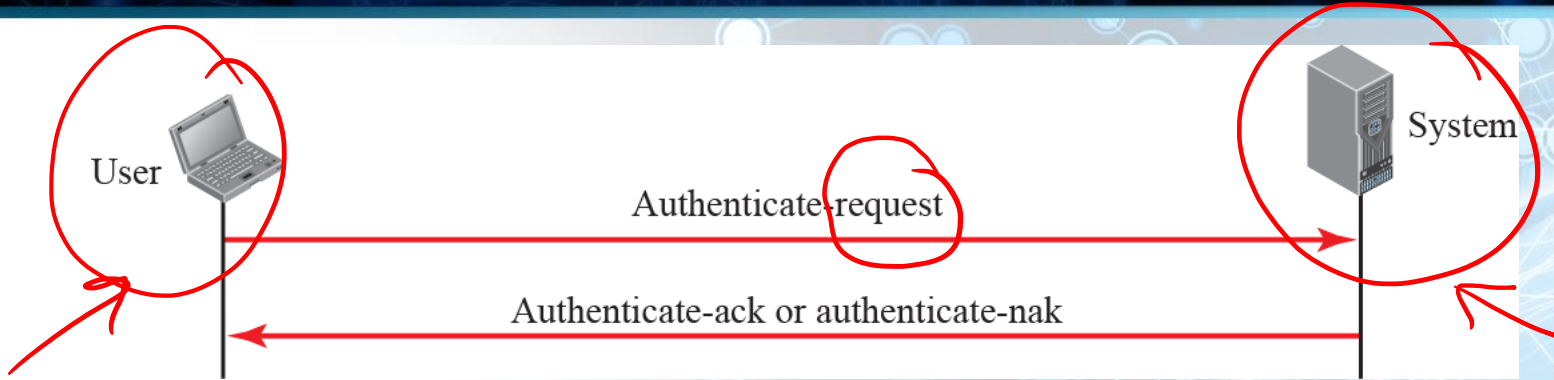
Multiplexing in PPP

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Authentication Protocols in PPP



PAP packets encapsulated in a PPP frame



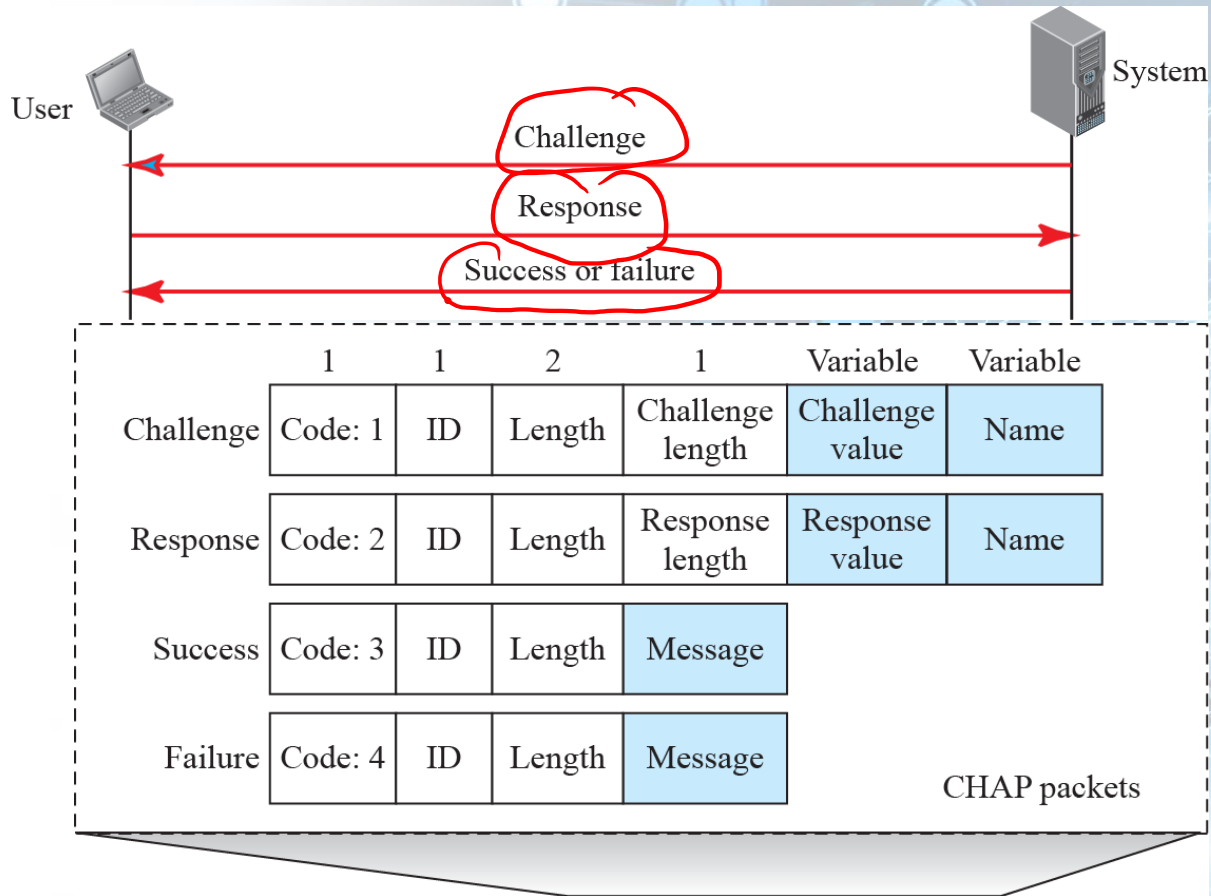
	1	1	2	1	Variable	1	Variable
Authenticate-request	Code: 1	ID	Length	User name length	User name	Password length	Password
Authenticate-ack	Code: 2	ID	Length	Message length	User name		
Authenticate-nak	Code: 3	ID	Length	Message length	User name		

PAP packets

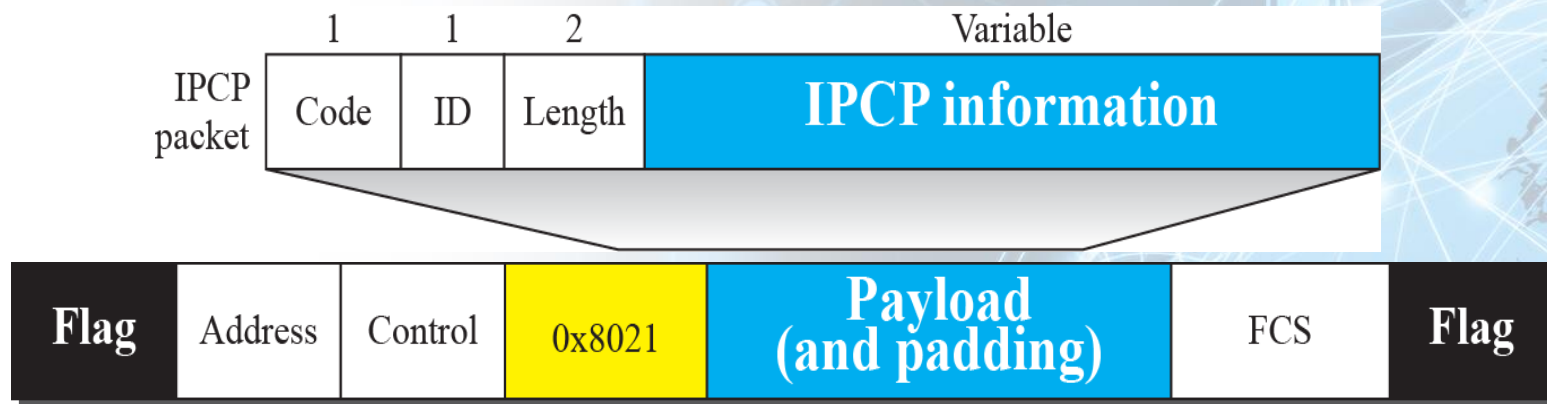
PPP frame



CHAP Packets encapsulated in a PPP frame



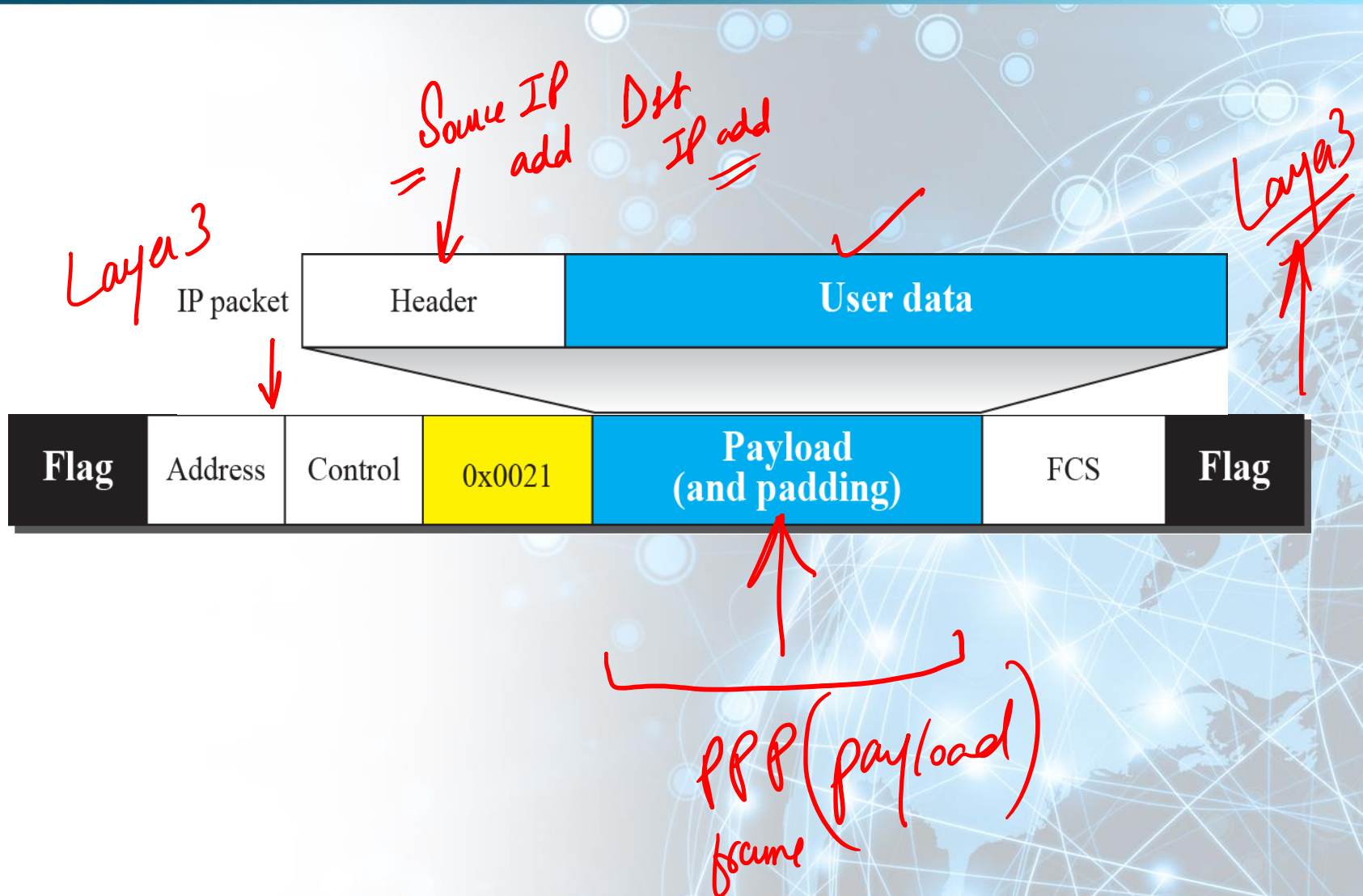
Internet Protocol Control Protocol (IPCP)



Code values for IPCP Packets

<i>Code</i>	<i>IPCP Packet</i>
0x01	Configure-request ✓
0x02	Configure-ack ✓
0x03	Configure-nak ✓
0x04	Configure-reject ✓
0x05	Terminate-request ✓
0x06	Terminate-ack ✓
0x07	Code-reject ✓

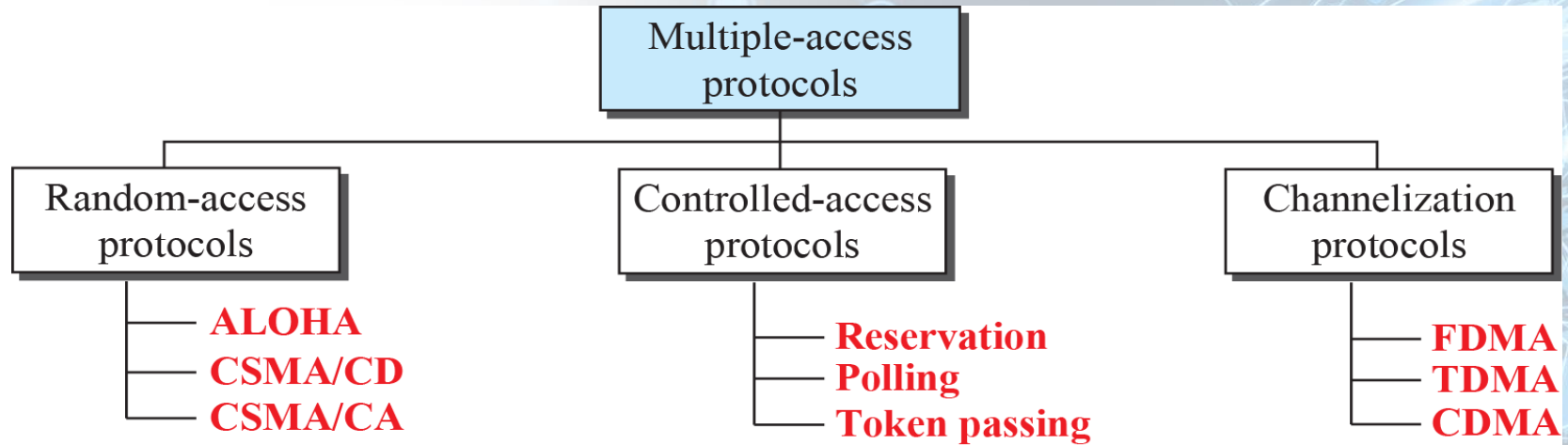
IP datagram encapsulated in a PPP frame



Media Access Control (MAC) Sub-Layer

- When nodes use a multipoint or broadcast link, we need a multiple-access protocol to coordinate access to the link
- Many protocols have been devised to handle access to a shared link
- All of these protocols belong to Media Access Control (MAC) sub-layer

Taxonomy of Multiple-Access Protocols



Random Access

- In random-access or contention no station is superior to the other and none is assigned control over the other
- Station that has data to send uses a procedure defined by the protocol to make a decision on whether or not to send
- This decision depends on the state of the medium (idle or busy)

ALOHA

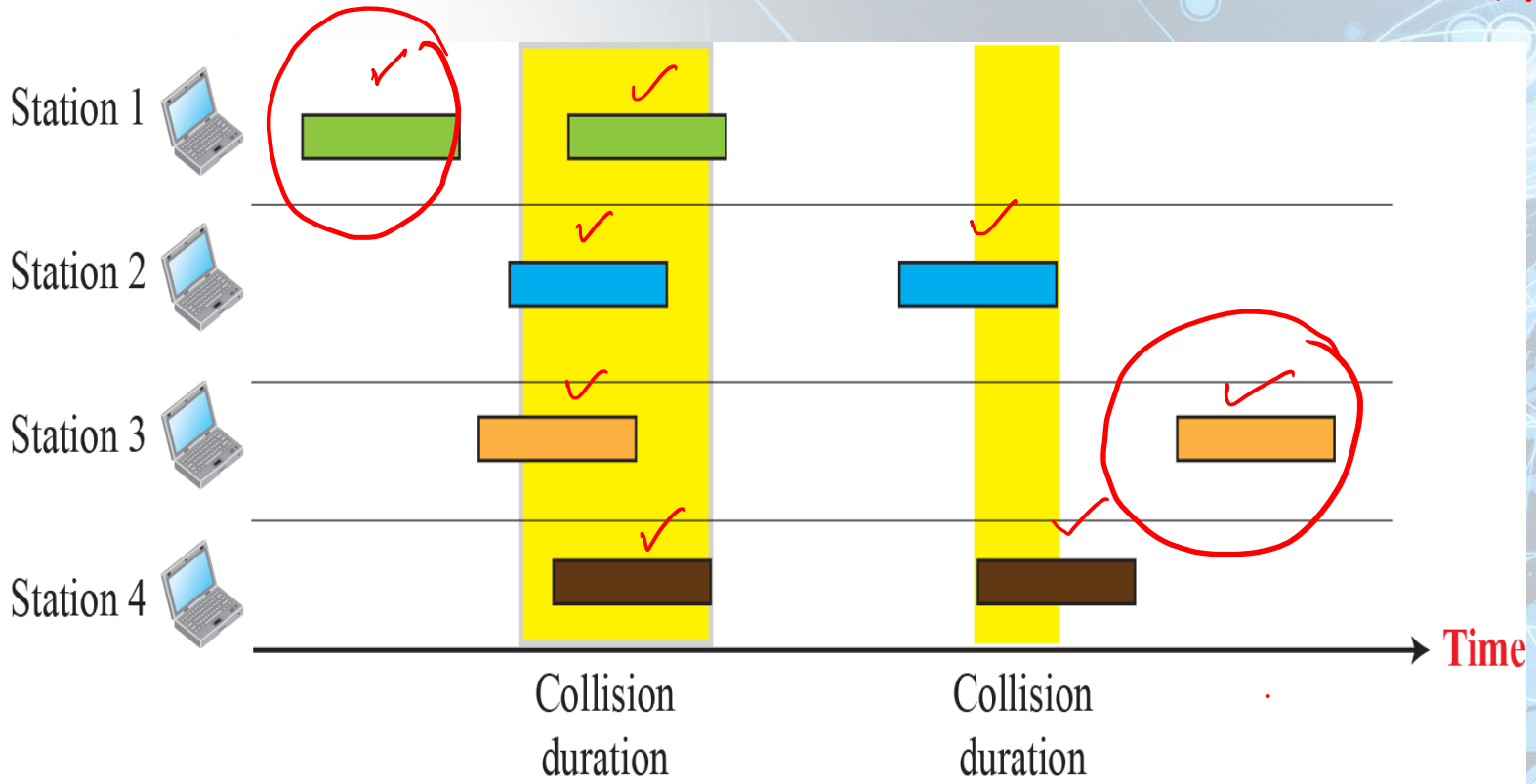
- **ALOHA, the earliest random access method, was developed in early 1970s**
- **Designed for a radio (wireless) LAN, but it can be used on any shared medium**
- **Potential collisions in this arrangement as the medium is shared between the stations**

ALOHA

- **When a station sends data, another station may attempt to do so at the same time**
- **The data from the two stations collide and become garbled**

Frames in a pure ALOHA network

Pure ALOHA → Slotted ALOHA



ACK → Sending waits from Rec station
 T_B → Back off Time → Random wait

ALOHA

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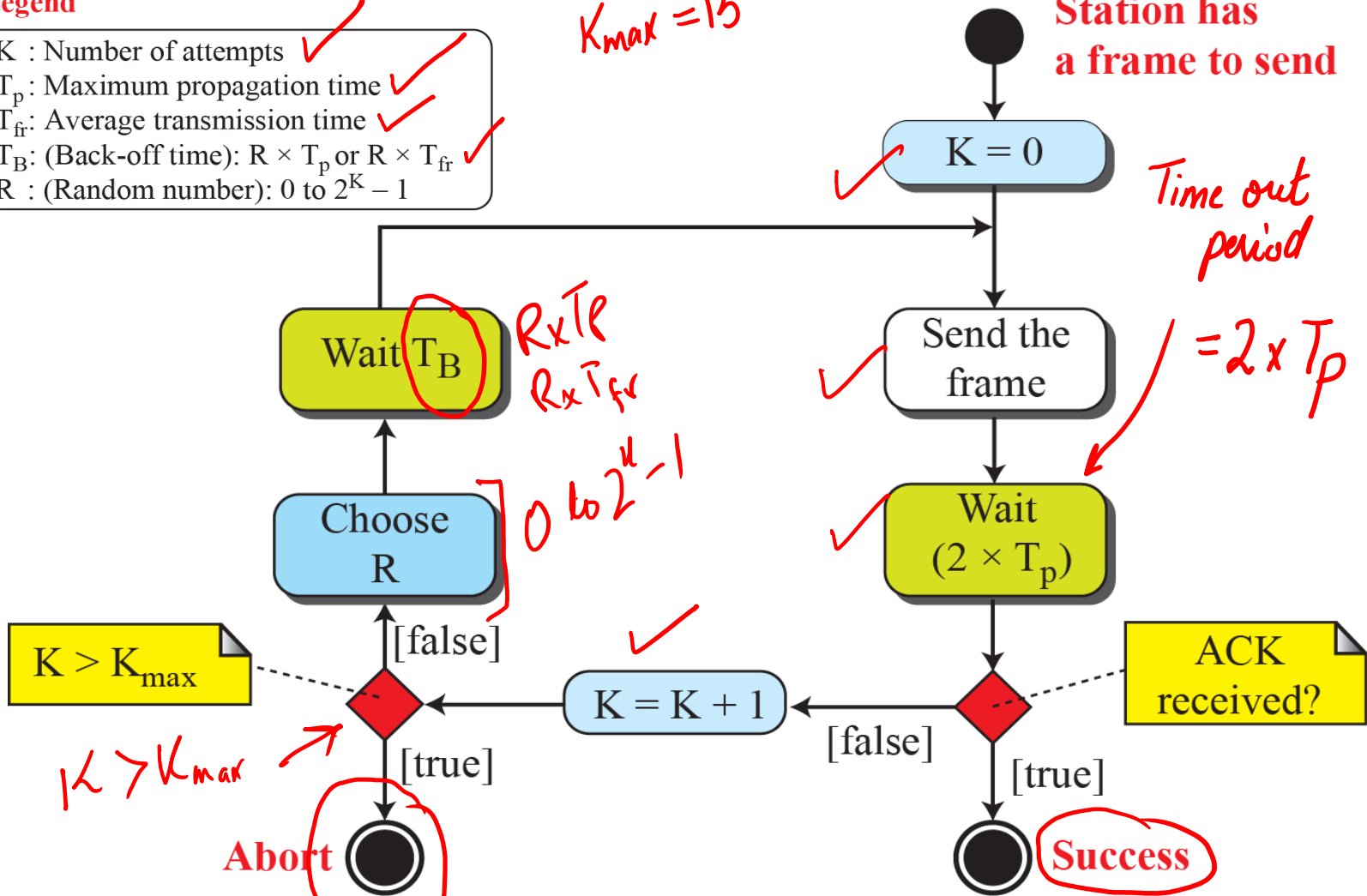
Procedure for pure ALOHA protocol

Legend

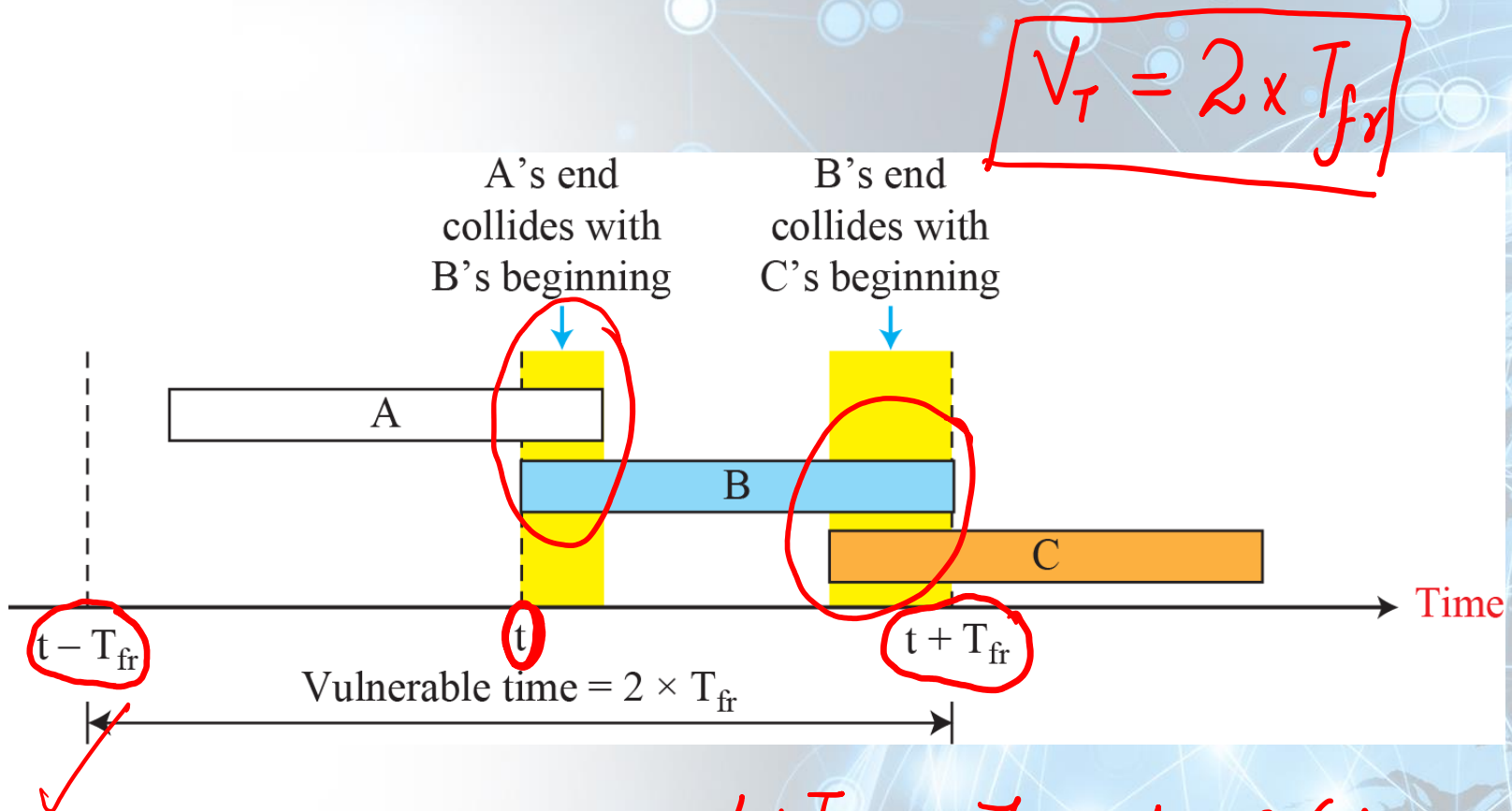
- K : Number of attempts ✓
- T_p : Maximum propagation time ✓
- T_{fr} : Average transmission time ✓
- T_B : (Back-off time): $R \times T_p$ or $R \times T_{fr}$ ✓
- R : (Random number): 0 to $2^K - 1$ ✓

$K_{max} = 15$

Station has a frame to send



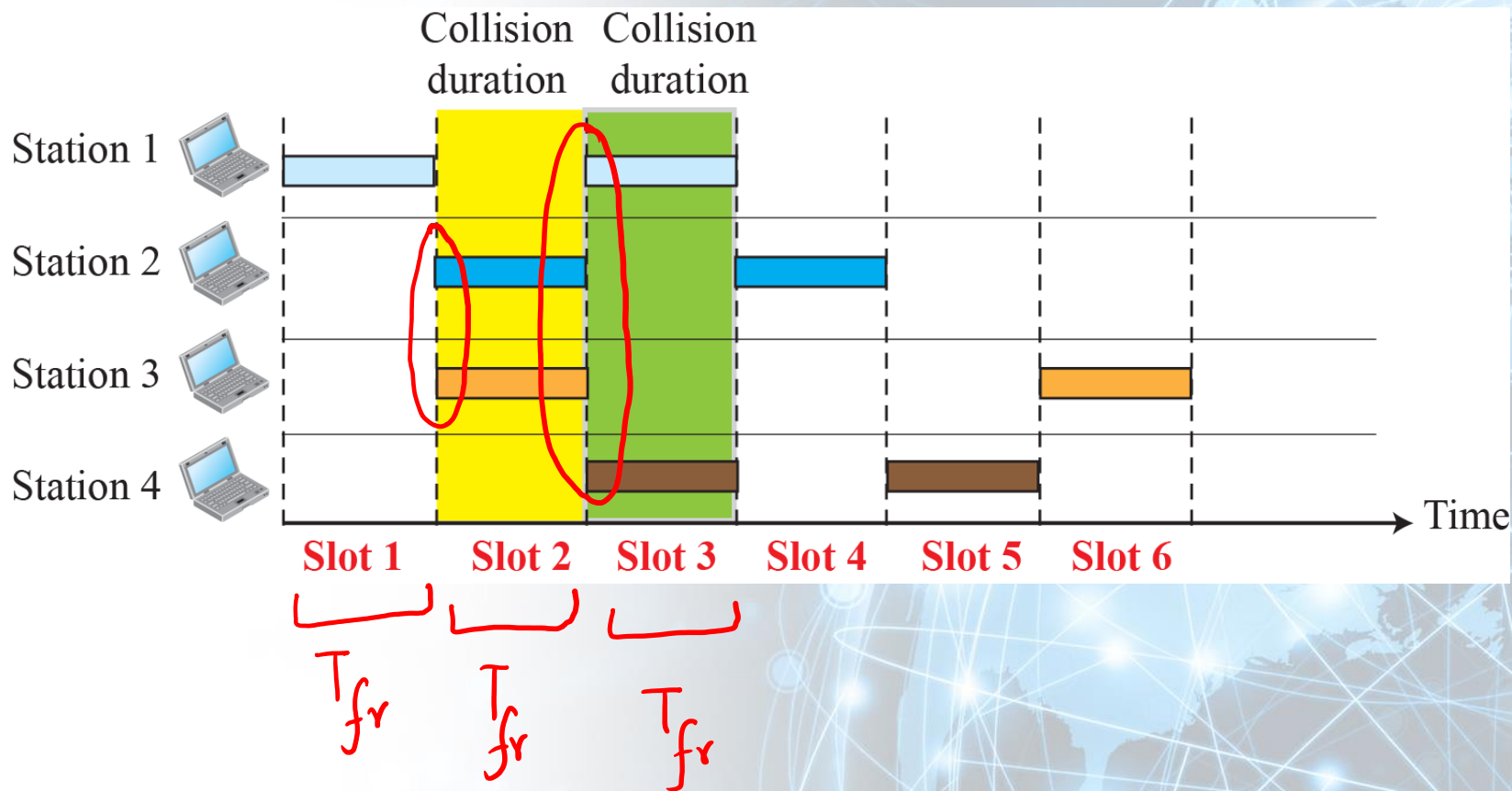
Vulnerable Time for pure ALOHA protocol



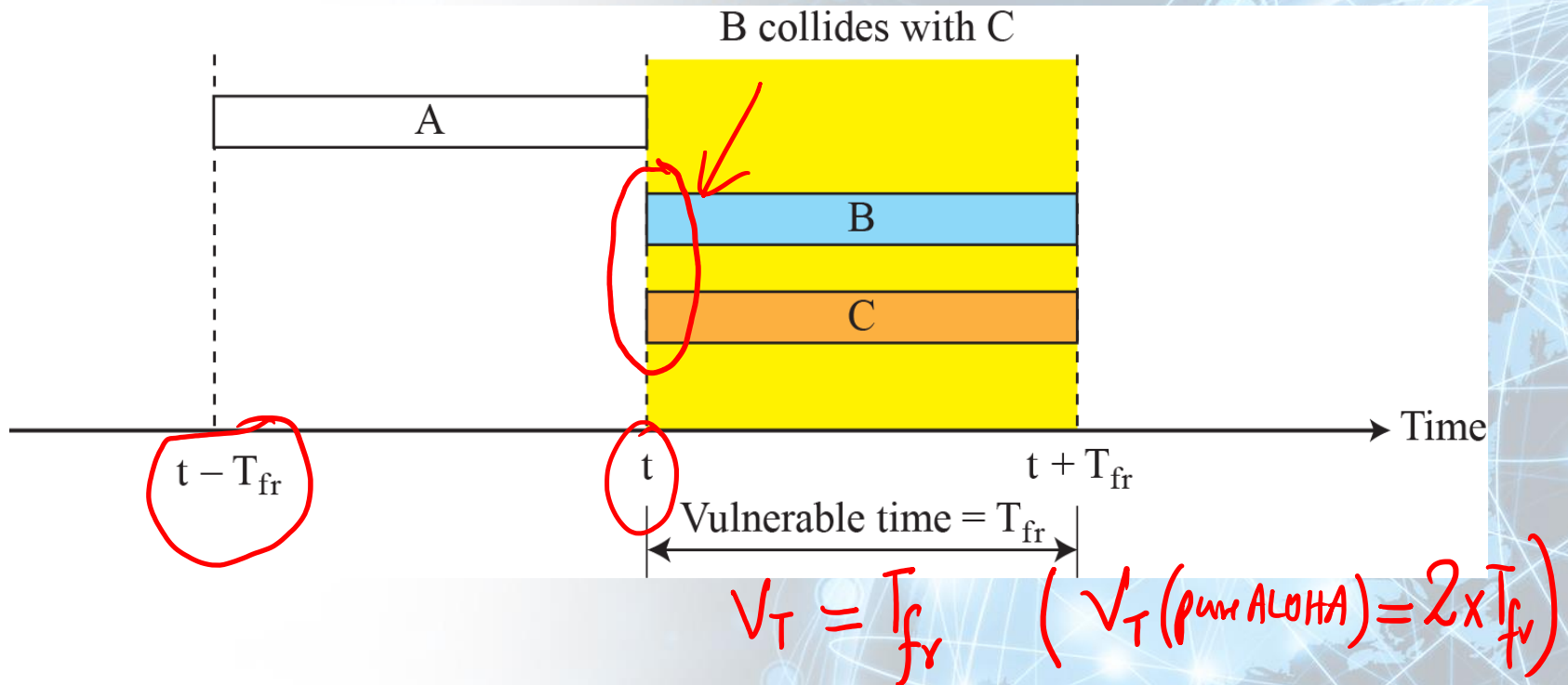
Slotted ALOHA

- We divide time into slots of T_{fr} sec and force the station to send only at the beginning of the slot
- Invented to improve the efficiency of pure ALOHA
- If a station misses the time slot, it must wait until beginning of next time slot reducing vulnerable time to T_{fr} (vs. $2 \times T_{fr}$ for pure ALOHA)

Frames in a Slotted ALOHA Network



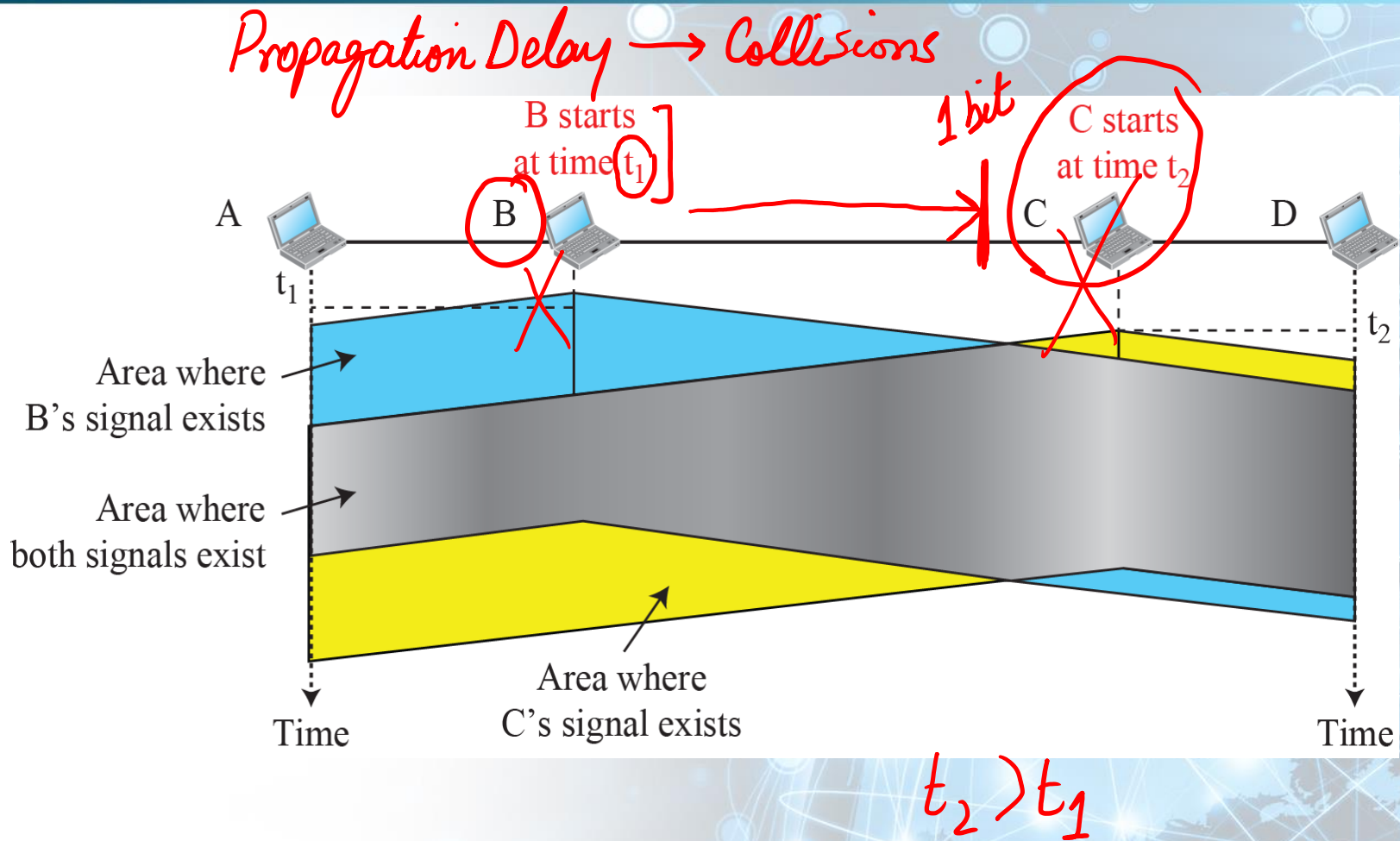
Vulnerable Time for Slotted ALOHA



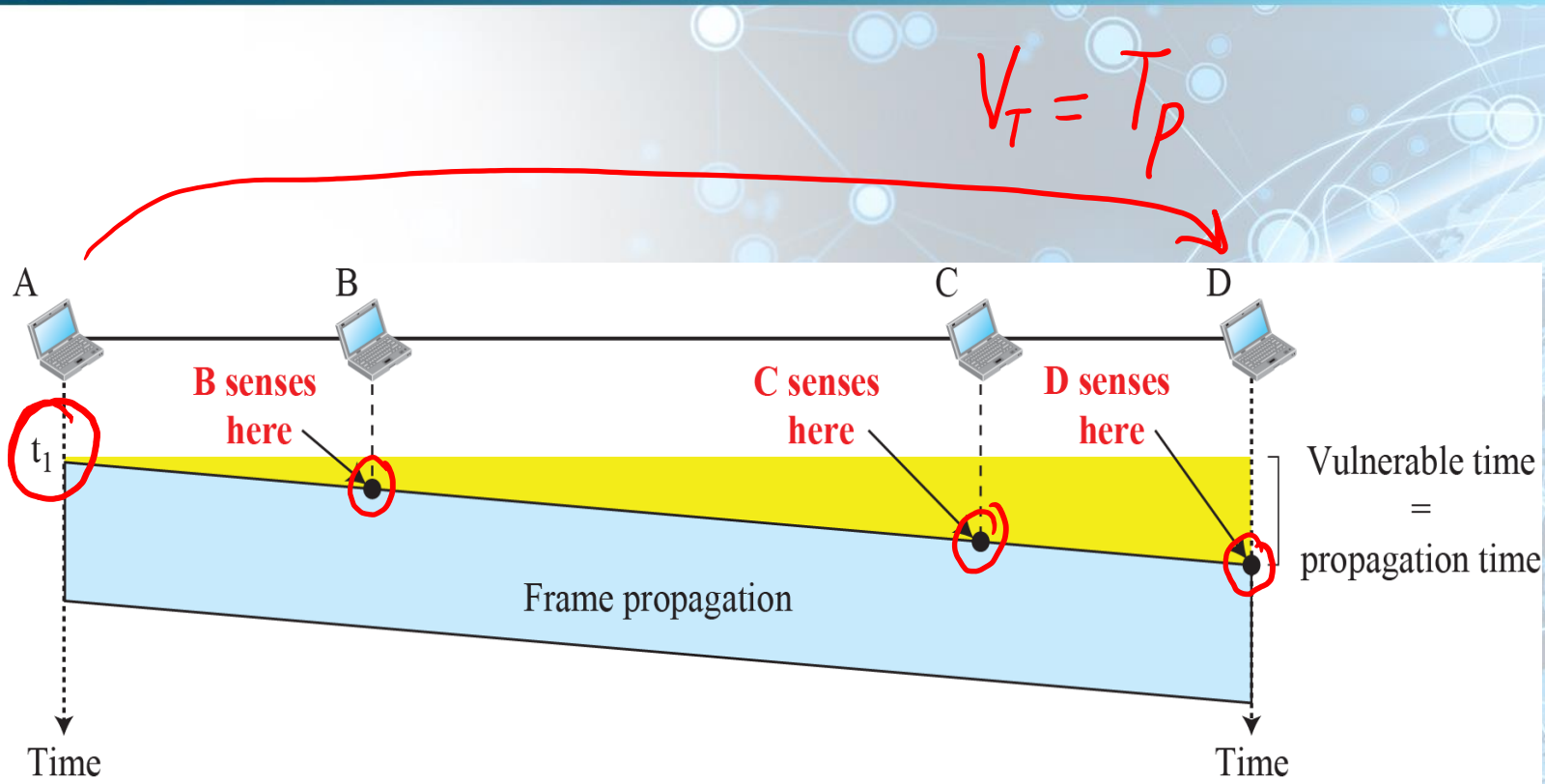
Carrier Sense Multiple Access (CSMA)

- To minimize the chance of collision and, therefore, increase the performance, CSMA was developed
- The chance of collision is reduced as the station is required to sense/listen to the medium before sending data
- 'sense before transmit' or 'listen before talk'

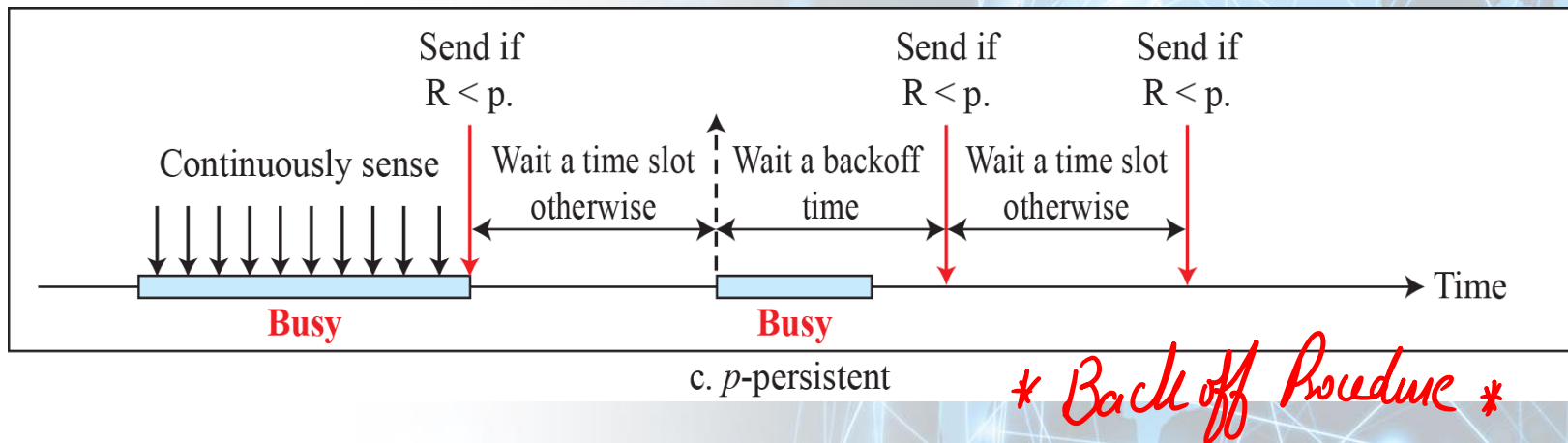
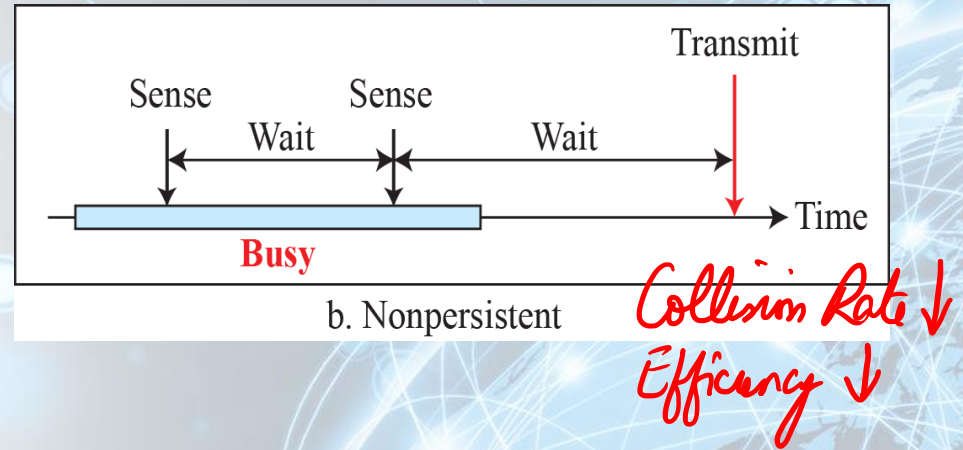
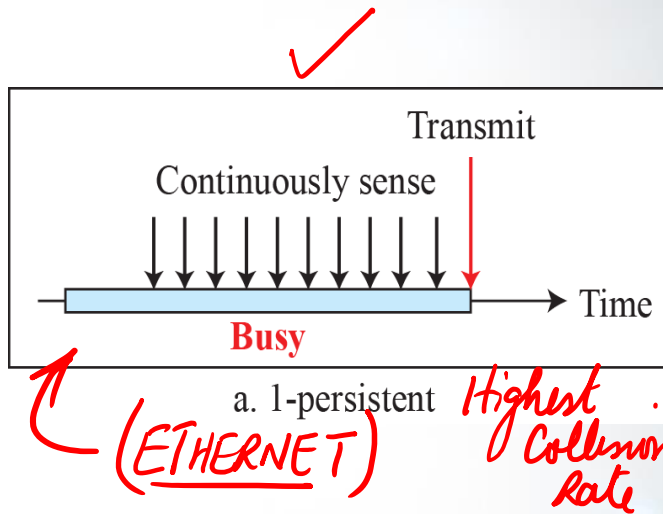
Space/Time Model of a Collision in CSMA



Vulnerable Time in CSMA



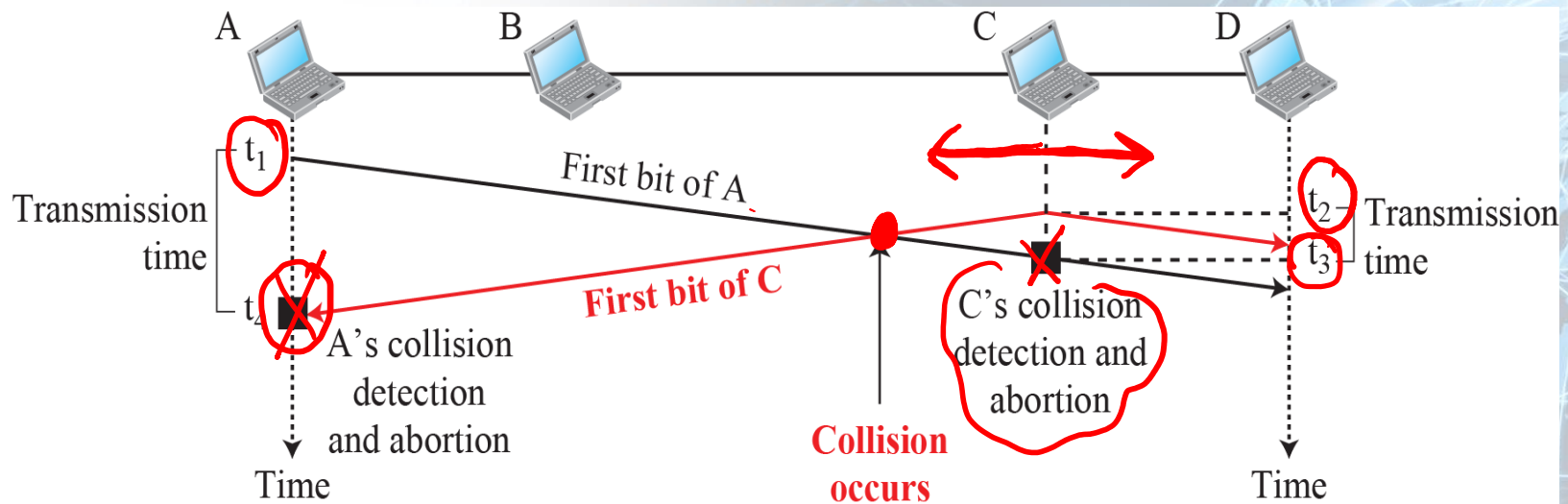
Behavior of Three Persistence Methods



Carrier Sense Multiple Access/Collision Detection

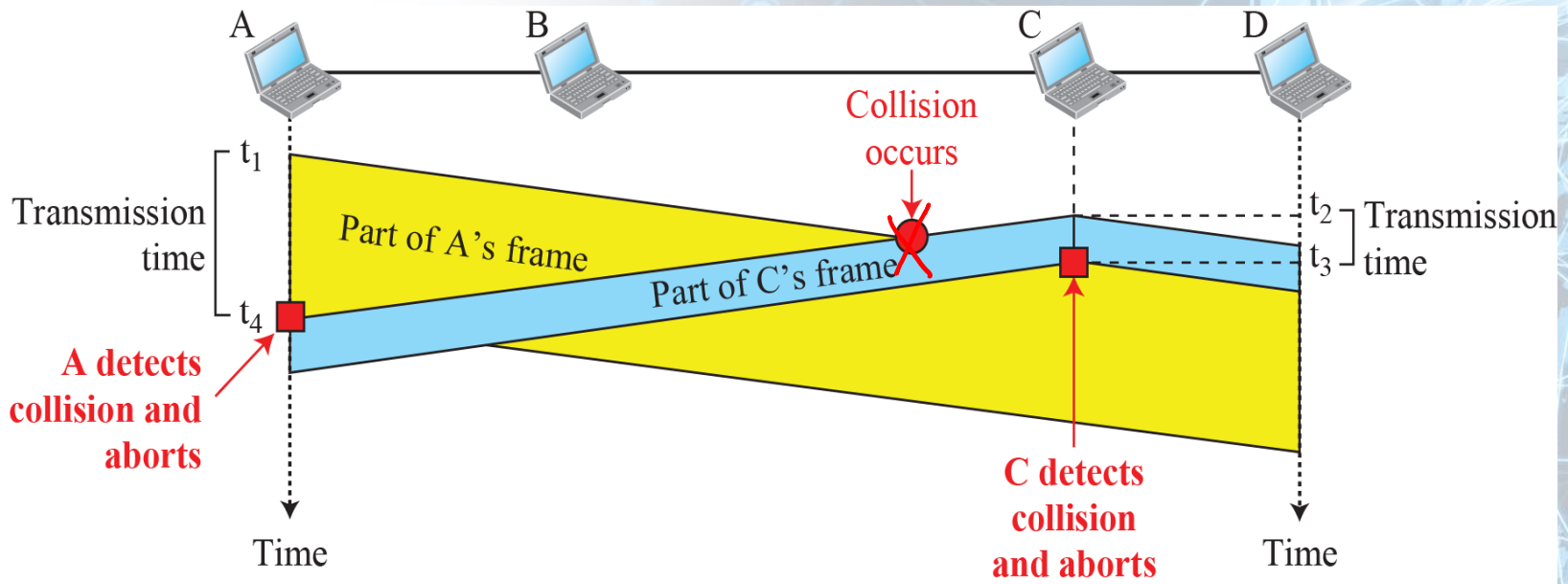
- CSMA method does not specify the procedure following a collision
- CSMA/CD augments the algorithm to handle the collision
- The station monitors the medium after it sends a frame to see if the transmission was successful. If there is a collision, the frame is sent again

Collision of the First Bits in CSMA/CD



$A \rightarrow t_4 - t_1$
 $C \rightarrow t_3 - t_2$ } → Duration of two transmissions

Collision and Abortion in CSMA/CD



Flow Diagram for the CSMA/CD

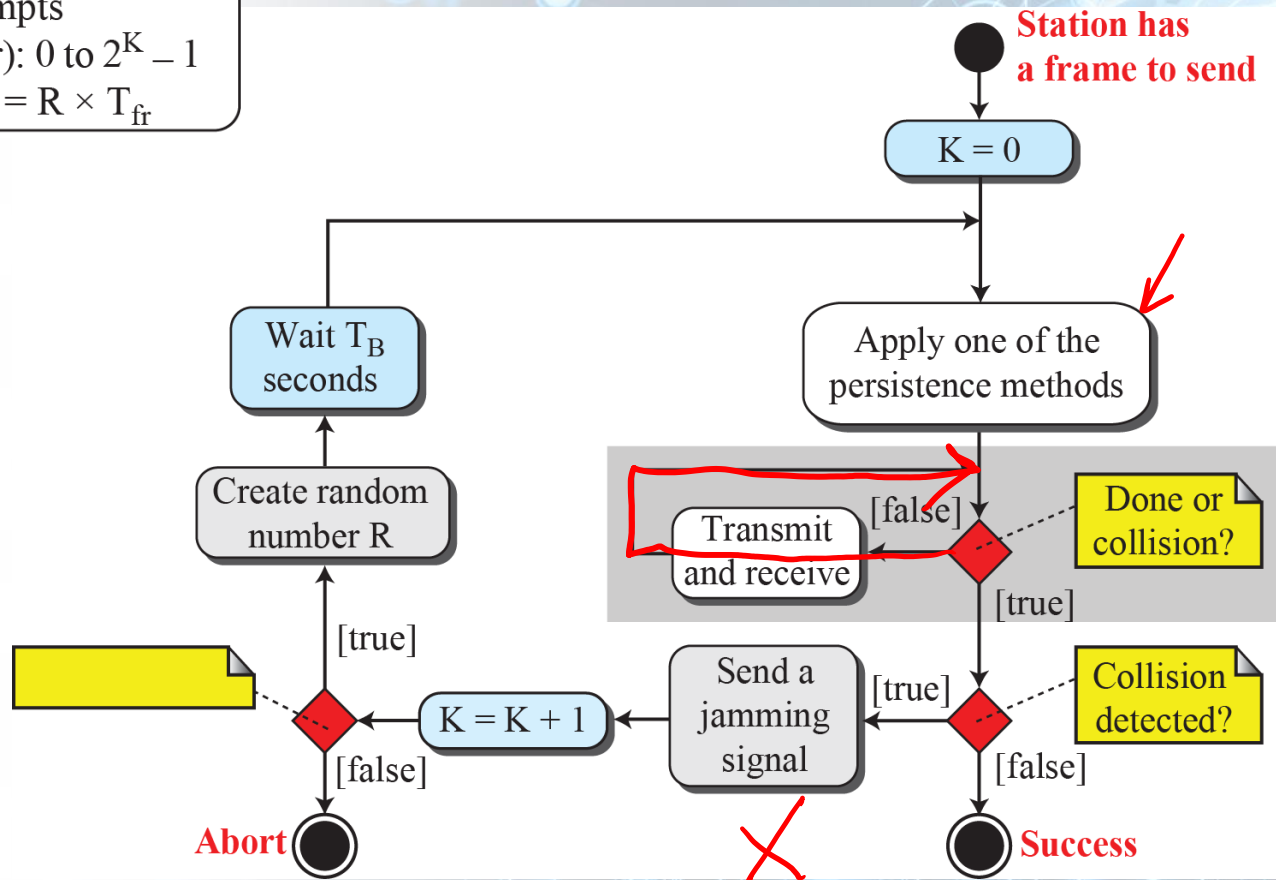
Legend

T_{fr} : Frame average transmission time

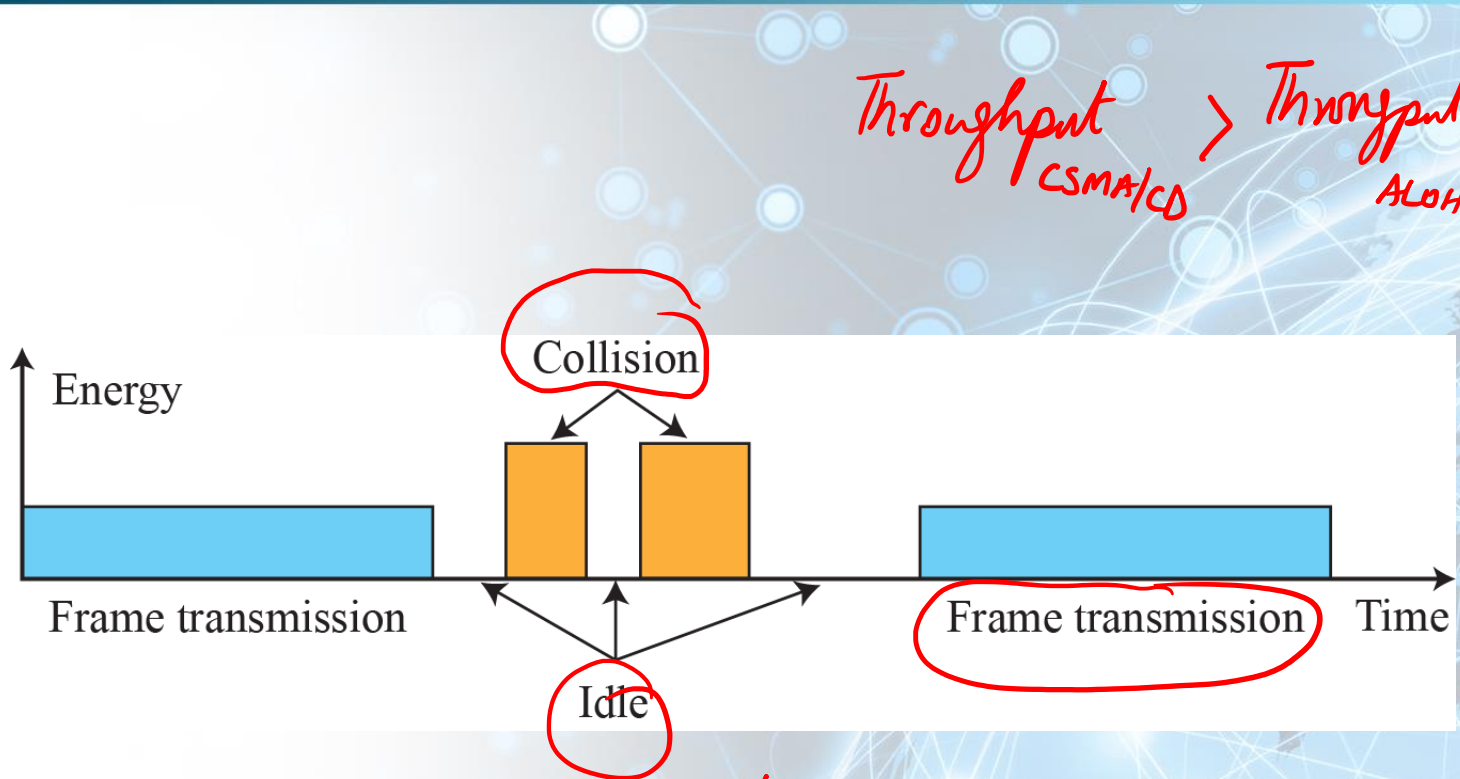
K : Number of attempts

R : (random number): 0 to $2^K - 1$

T_B : (Back-off time) = $R \times T_{fr}$



Energy Level During Transmission, Idleness and Collision



*Throughput*_{CSMA/CD} > *Throughput*_{ALOHA}

↳ 10Mbps Ethernet Standard

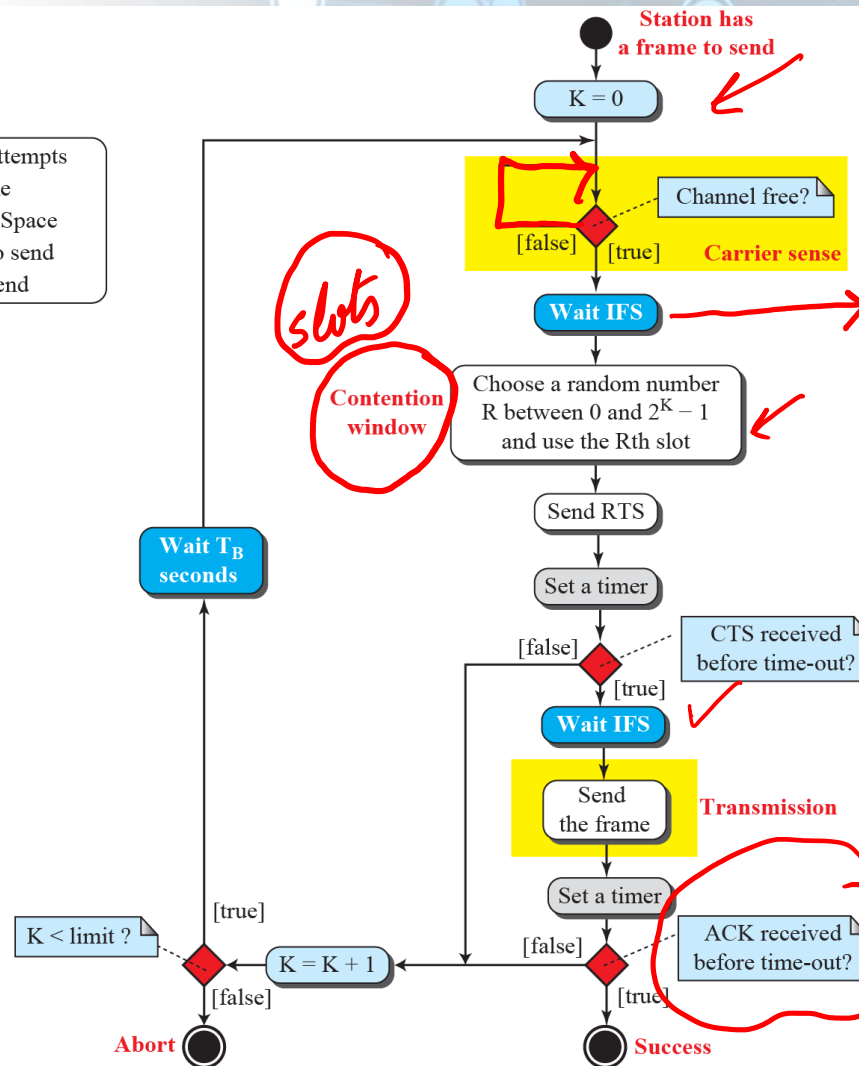
Carrier Sense Multiple Access/Collision Avoidance

- **CSMA/CA was invented for Wireless Networks**
- **Collisions are avoided through the use of three strategies:**
 - ✓ **The Interframe Space**
 - ✓ **The Contention Window**
 - ✓ **Acknowledgements**

Flow Diagram for CSMA/CA

Legend

K: Number of attempts
 T_B : Backoff time
 IFS: Interframe Space
 RTS: Request to send
 CTS: Clear to send
 CTS: Clear to send



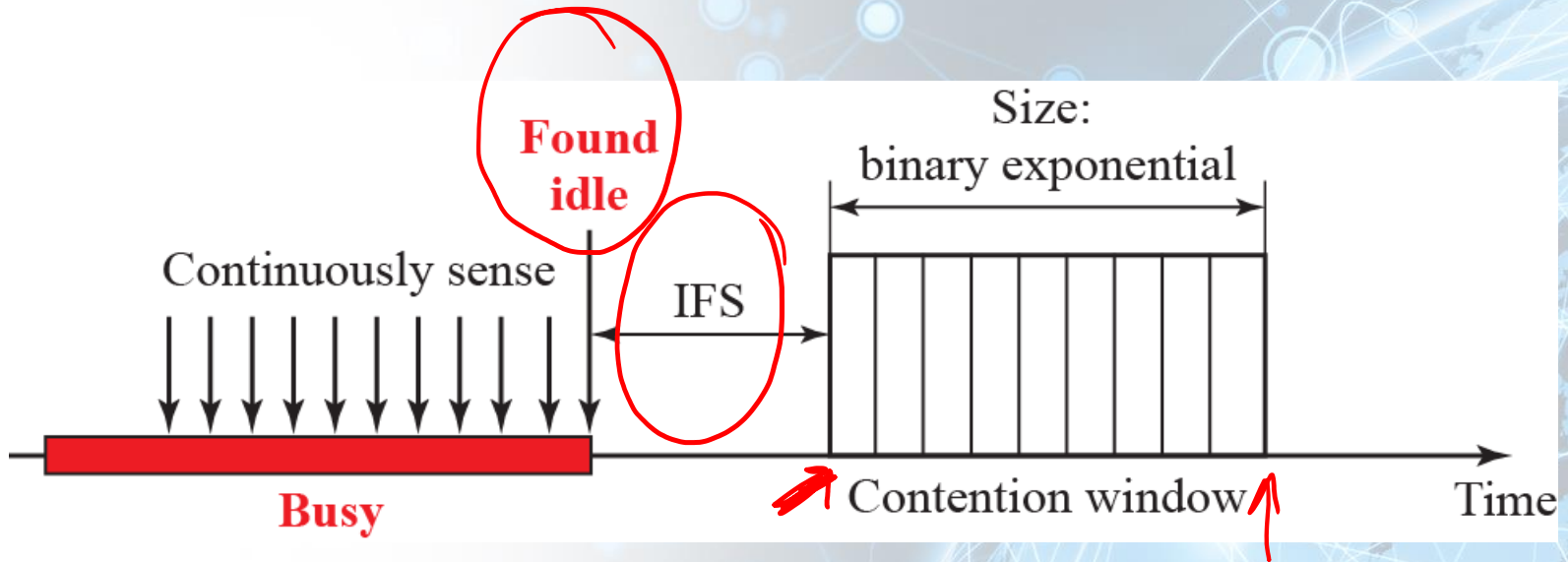
Carrier Sense Multiple Access/Collision Avoidance

- **CSMA/CA was invented for Wireless Networks**
- **Collisions are avoided through the use of three strategies:**
 - ✓ **The Interframe Space**
 - ✓ **The Contention Window**
 - ✓ **Acknowledgements**

CSMA/CA

- **Interframe Space (IFS):**
Collisions are avoided by deferring transmission even if the channel is idle
- **Contention Window:**
Amount of time divided into slots. Station chooses a random number of slots as its wait time (one slot first time and double each time system cannot detect an idle channel)

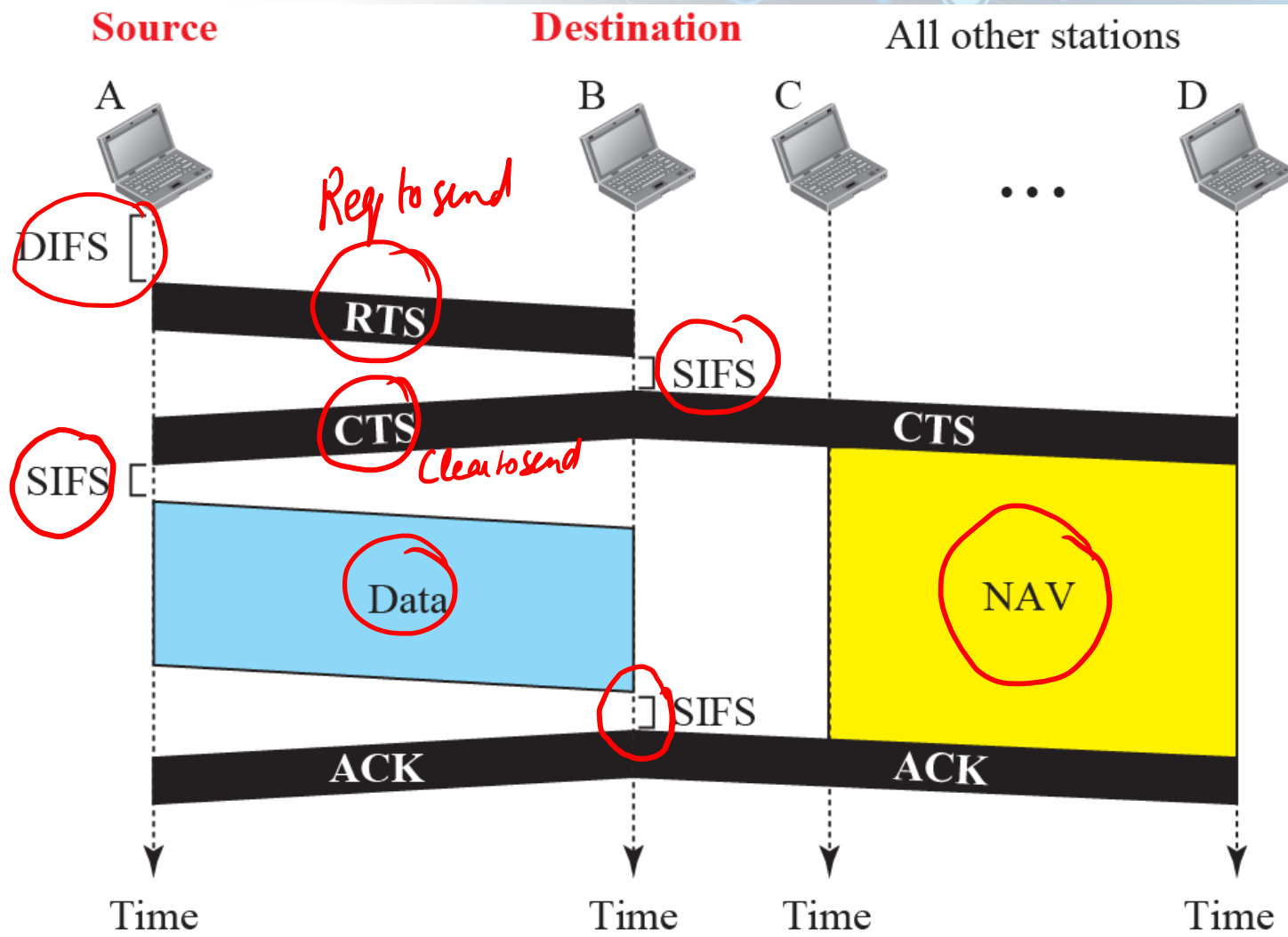
Contention Window



CSMA/CA

- **Acknowledgement:**
Positive acknowledgement and time-out timer can help guarantee that the receiver has received the frame

CSMA/CA and Network Allocation Vector (NAV)



CONTROLLED ACCESS

- The stations consult one another to find which station has the right to send
- A station cannot send unless authorized by other stations
- We discuss three controlled-access methods:
 - ✓ Reservation
 - ✓ Polling
 - ✓ Token Passing

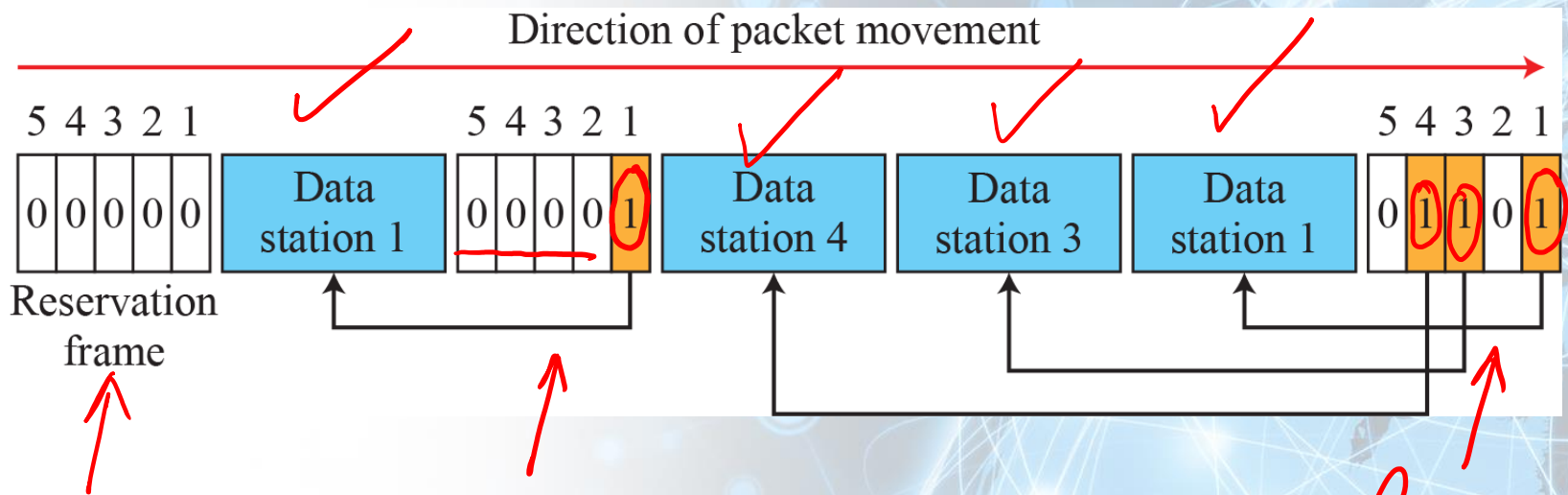
Reservation

- In the reservation method, a station needs to make a reservation before sending data
- Time is divided into intervals
- In each interval, a reservation frame precedes the data frames sent in that interval

Reservation Access Method

N Stations

N → minislots (reservation)



Polling

- Polling works with topologies in which one device is designated as a primary station and the other devices are secondary stations
- All data exchanges must be made through primary device even when the ultimate destination is a secondary device

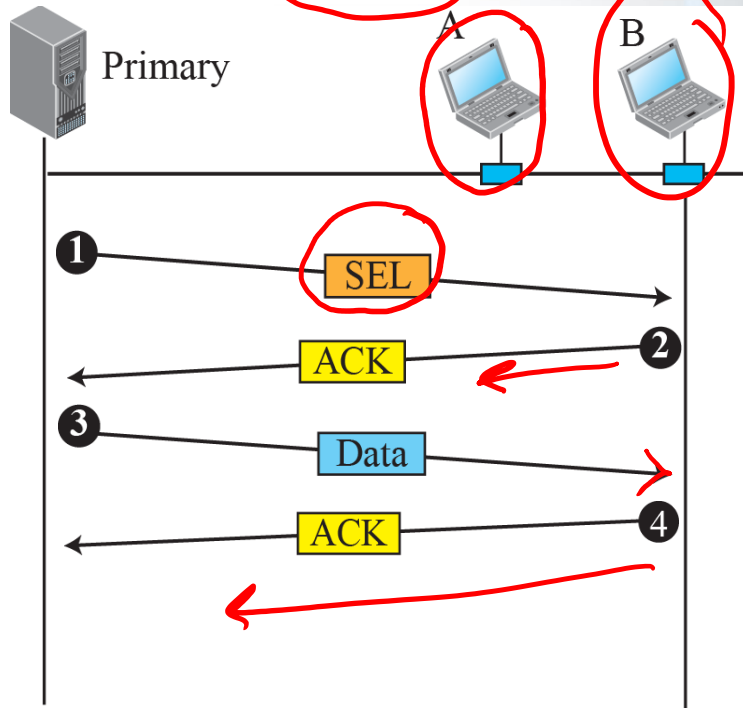
Polling

- **The primary device controls the link; the secondary devices follow its instructions**

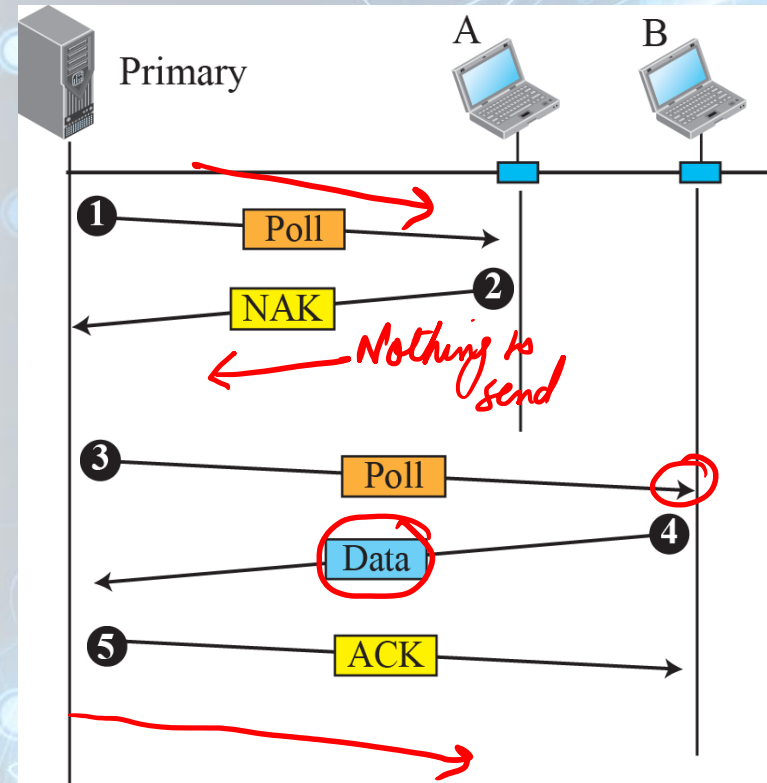
Select and Poll Functions in Polling-Access Method

Select & Poll

Select



Poll



o
o
o
o
o
o
o
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o

CONTROLLED ACCESS

- **Three controlled-access methods:**
 - ✓ **Reservation**
 - ✓ **Polling**
 - ✓ **Token Passing**

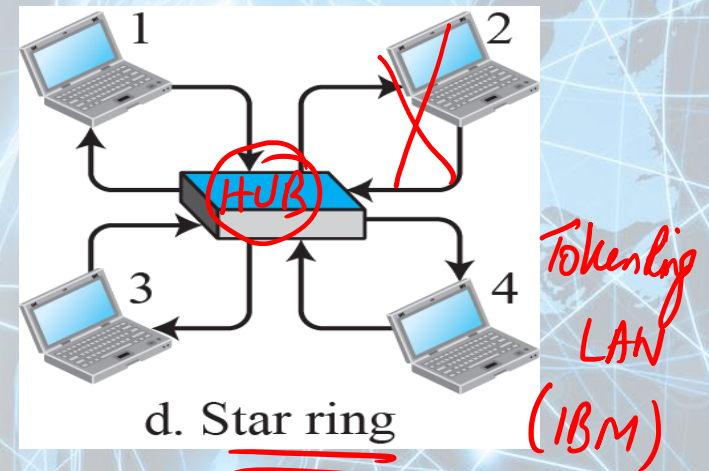
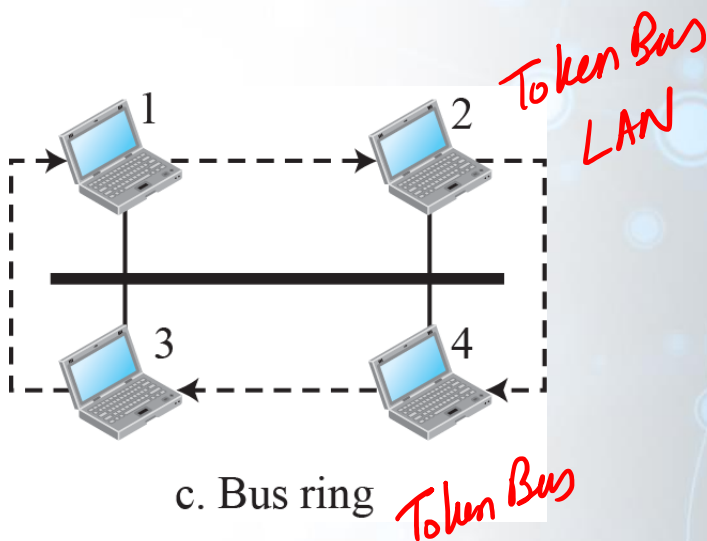
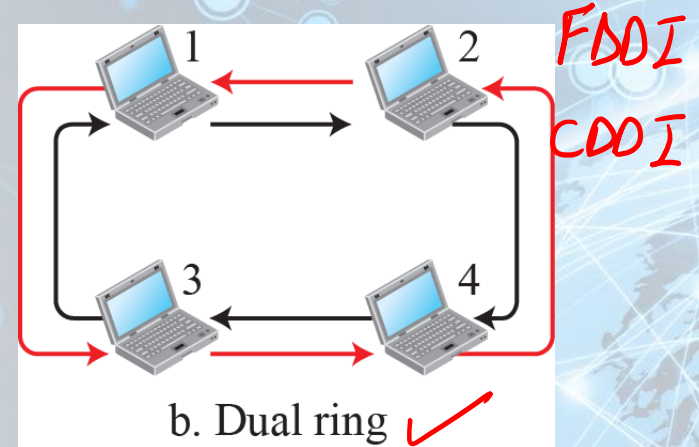
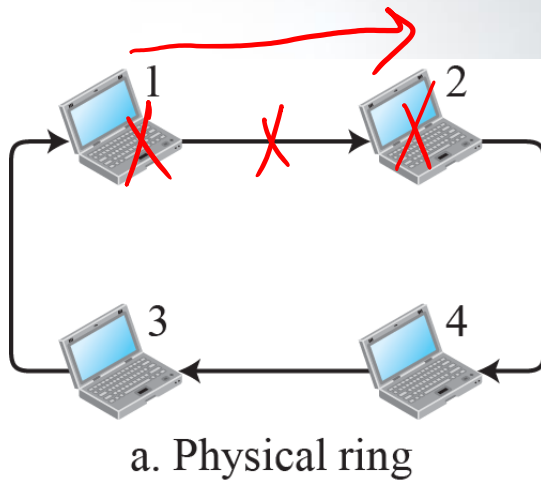
Token Passing

- In the token-passing method, the stations in a network are organized in a logical ring
- For each station, there is a predecessor and a successor
- The predecessor is the station which is logically before the station in the ring; the successor is the station which is after the station in the ring

Token Passing

- Special packet called **TOKEN** circulates through the ring
- Possession of **TOKEN** gives the station the right to send the data
- **TOKEN Management** is required to manage possession time, Token monitoring, priority assignment etc.

Logical Ring & Physical Topology in Token-Passing Method



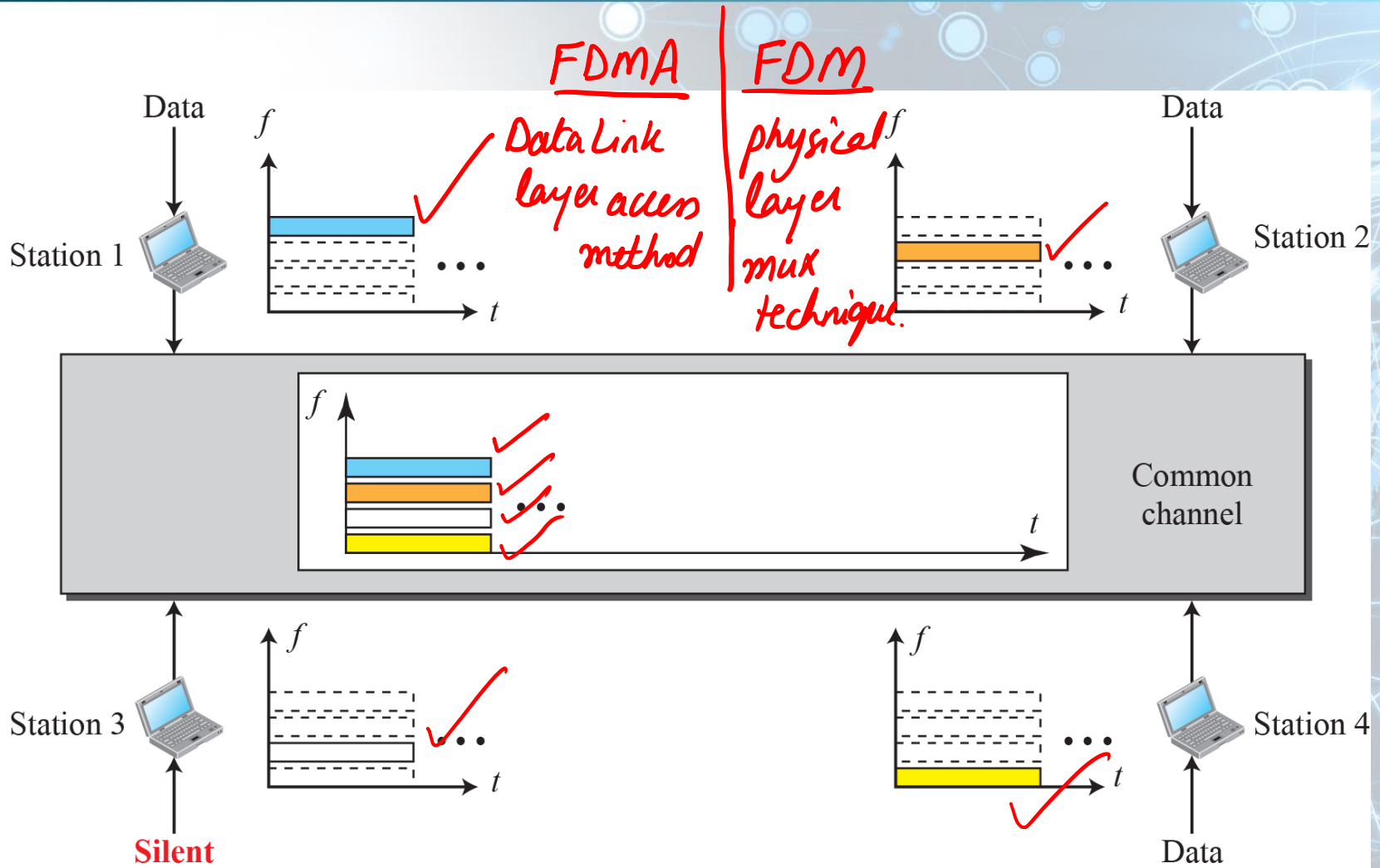
CHANNELIZATION (Channel Partition)

- The available bandwidth of a link is shared in time, frequency, or through code, among different stations
- We discuss three protocols:
 - ✓ Frequency Division Multiple Access (FDMA)
 - ✓ Time Division multiple Access (TDMA)
 - ✓ Code Division Multiple Access (CDMA)

Frequency-Division Multiple Access (FDMA)

- In FDMA, the available bandwidth is divided into frequency bands
- Each station is allocated a band to send its data i.e. each band is reserved for a specific station, and it belongs to the station all the time
- Each station also uses a bandpass filter to confine the transmitter frequencies

Frequency-Division Multiple Access (FDMA)



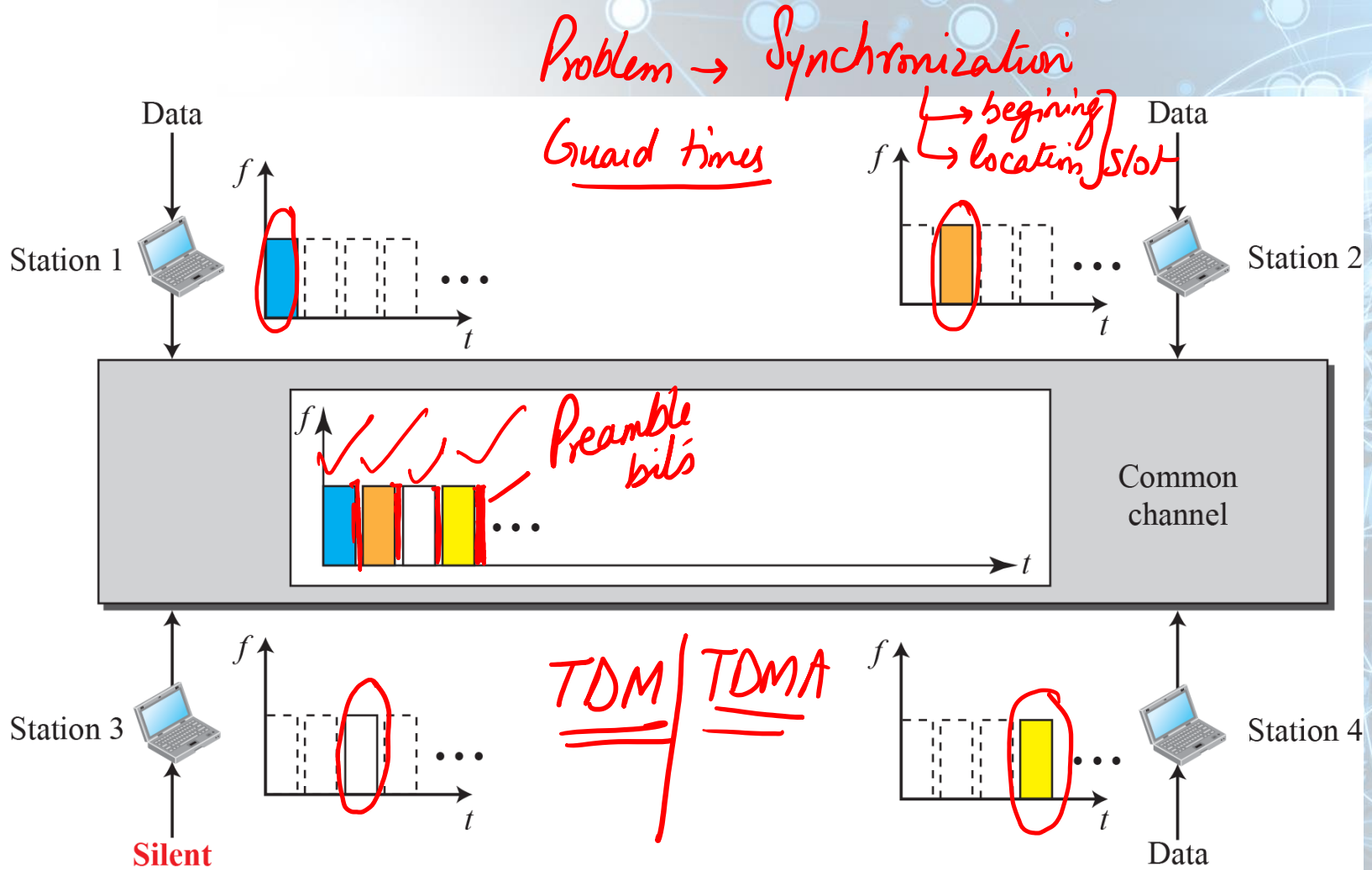
CHANNELIZATION (Channel Partition)

- **Three protocols:**
 - ✓ **Frequency Division Multiple Access (FDMA)**
 - ✓ **Time Division Multiple Access (TDMA)**
 - ✓ **Code Division Multiple Access (CDMA)**

TDMA

- Stations share the bandwidth of the channel in time
- Each station is allocated a time slot during which it can send data
- Each station transmits its data in its assigned time slot

Time-Division Multiple Access (TDMA)



CHANNELIZATION (Channel Partition)

- **Three protocols:**
 - ✓ **Frequency Division Multiple Access (FDMA)**
 - ✓ **Time Division Multiple Access (TDMA)**
 - ✓ **Code Division Multiple Access (CDMA)**

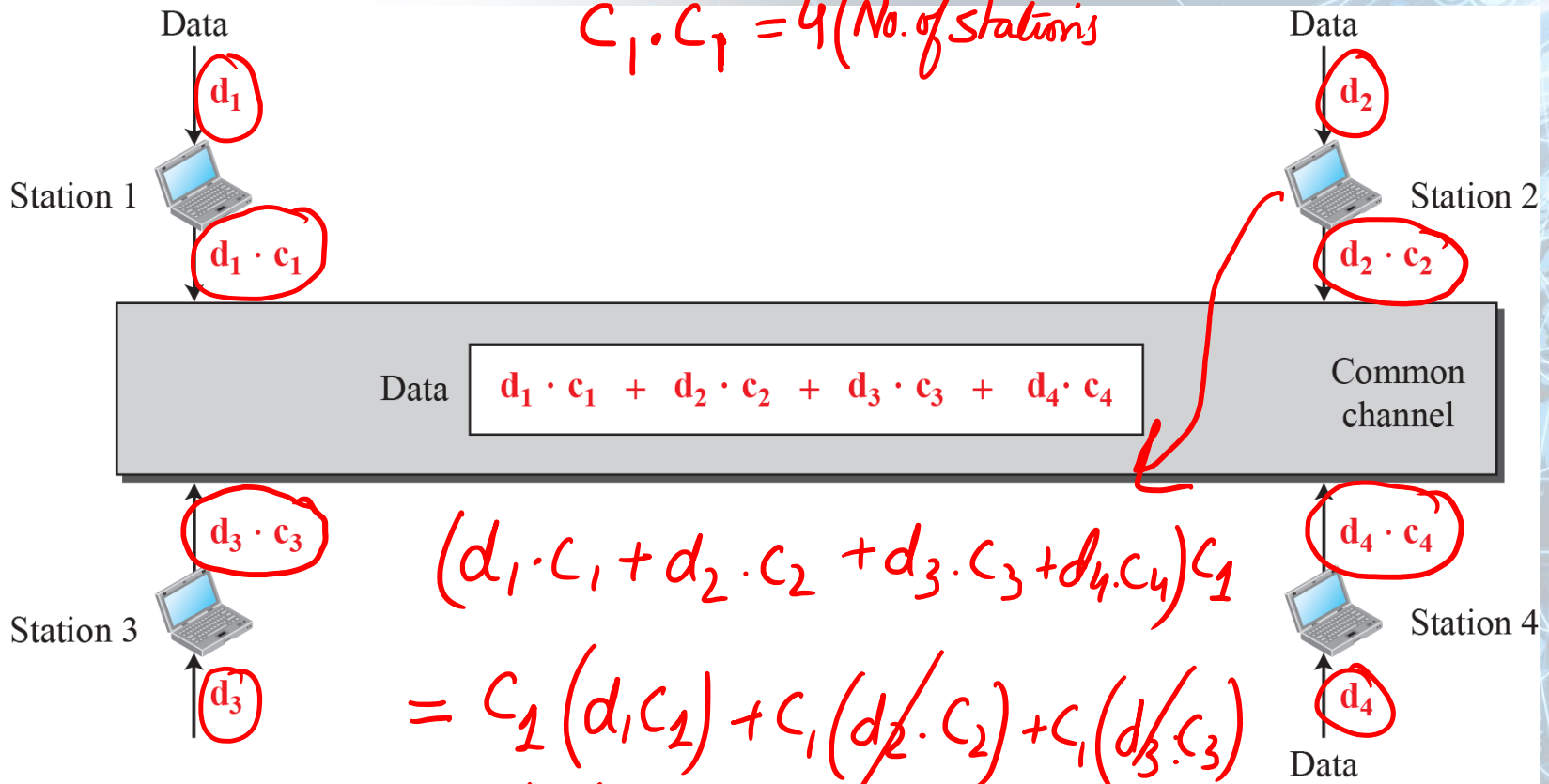
Code Division Multiple Access (CDMA)

- **CDMA differs from FDMA in that only one channel occupies the entire bandwidth of the link**
- **CDMA differs from TDMA in that all stations can send data simultaneously; there is no timesharing**

Simple idea of Communication with Code

$$c_1 \cdot c_2 = 0 \quad (c_2 \cdot c_3 | c_3 \cdot c_4)$$

$$c_1 \cdot c_1 = 4 \text{ (No. of stations)}$$



$$(d_1 \cdot c_1 + d_2 \cdot c_2 + d_3 \cdot c_3 + d_4 \cdot c_4) c_1$$

$$= c_1 (d_1 c_1) + c_1 (d_2 c_2) + c_1 (d_3 c_3) + c_1 (d_4 c_4)$$

$$= 4d_1 + c_1 (d_4/c_4)$$

$$B \rightarrow \text{divides by } 4 \rightarrow \frac{4d_1}{4} = d_1$$

Data Representation in CDMA

Data bit 0 \longrightarrow -1

Data bit 1 \longrightarrow +1

Silence \longrightarrow 0

Ethernet Protocol

- **Data-link layer and the physical layer are the territory of the local and wide area networks**
- **We can have wired or wireless networks**

IEEE Project 802

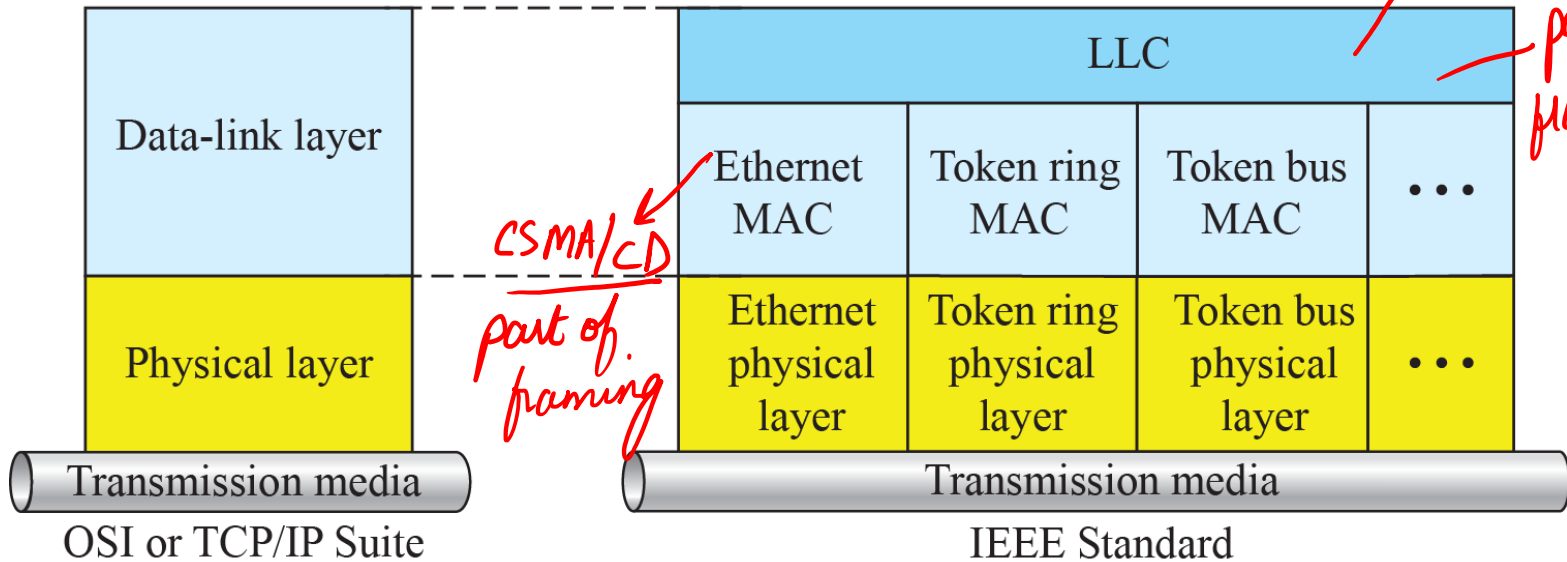
- In 1985, the Computer Society of the IEEE started a project, called Project 802, to set standards to enable inter-communication among equipment from a variety of manufacturers
- Project 802 did not seek to replace any part of the OSI model or TCP/IP protocol suite

IEEE Project 802

- **A way of specifying functions of the physical layer and the data-link layer of major LAN protocols**

IEEE Standard for LANs

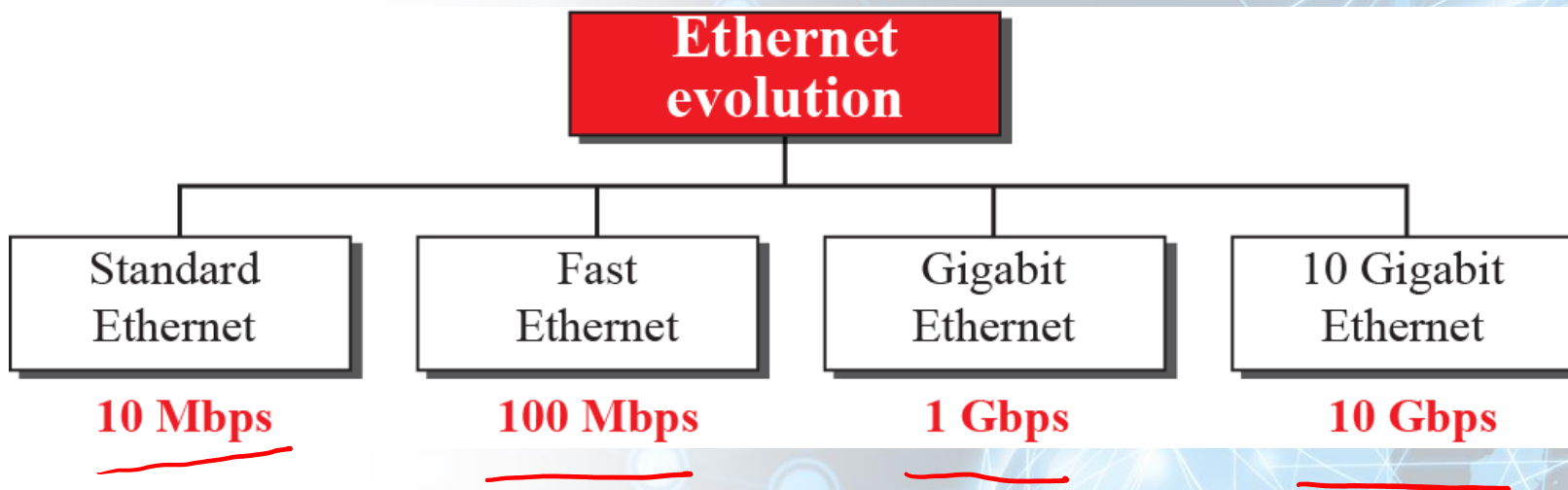
LLC: Logical link control **MAC:** Media access control



Ethernet Evolution

- The Ethernet LAN was developed in the 1970s
- Since then, it has gone through four generations:
 - ✓ Standard Ethernet (10 Mbps)
 - ✓ Fast Ethernet (100 Mbps)
 - ✓ Gigabit Ethernet (1 Gbps)
 - ✓ 10 Gigabit Ethernet (10 Gbps)

Ethernet Evolution



Standard Ethernet

- The original Ethernet technology with the data rate of 10 Mbps is called Standard Ethernet
- Most implementations have moved to later evolutions
- Still some features of the Standard Ethernet that have not changed during the evolution

Connectionless & Unreliable Service

- Each frame is independent of other
- No connection establishment or tear down process
- The sender may overwhelm receiver with frames and frames are dropped
- If frame drops, sender will not know about it unless we are using TCP (Transport)

Connectionless & Unreliable Service

- Ethernet is unreliable like IP and UDP
- If a frame is corrupted, receiver silently drops it
- Left to high level protocols to find out about it

Standard Ethernet

- **The original Ethernet technology with the data rate of 10 Mbps is called Standard Ethernet**

Ethernet Frame Format

max = 1518 bytes 18 bytes of header

max length = 1518 - 18 = 1500 bytes

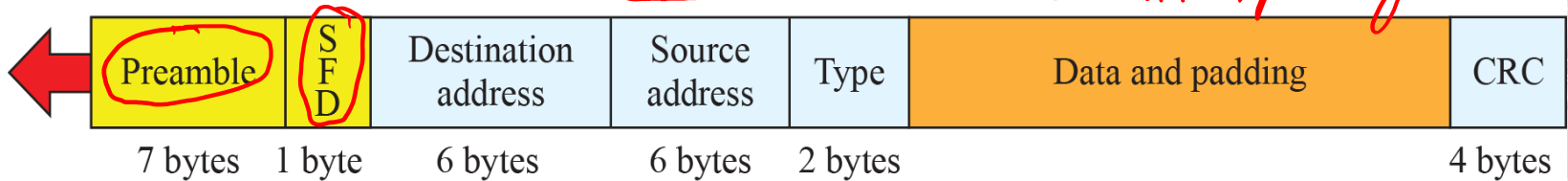
Preamble: 56 bits of alternating 1s and 0s

SFD: Start frame delimiter, flag **(10101011)**

Minimum payload length: **46 bytes**

Maximum payload length: **1500 bytes**

less than 46 → padding CRC 32



Physical-layer header

Minimum frame length: 512 bits or 64 bytes

Maximum frame length: 12,144 bits or 1518 bytes

min = 512 bits (64 bytes)

18 bytes of header

min length = 64 - 18 = 46 Bytes

Addressing in Standard Ethernet

- Each station on Ethernet has its own network interface card (NIC)
- The NIC fits inside the station and provides the station with a link-layer/physical address
- The Ethernet address is 6 bytes (48 bits), normally written in hexadecimal notation, with a colon between the bytes

Addressing

- For example, the following shows an Ethernet MAC address:

4A:30:10:21:10:1A

Transmission of Address Bits

How the address 47:20:1B:2E:08:EE is sent out online.

The address is sent left to right, byte by byte; for each byte, it is sent right to left, bit by bit, as shown below:

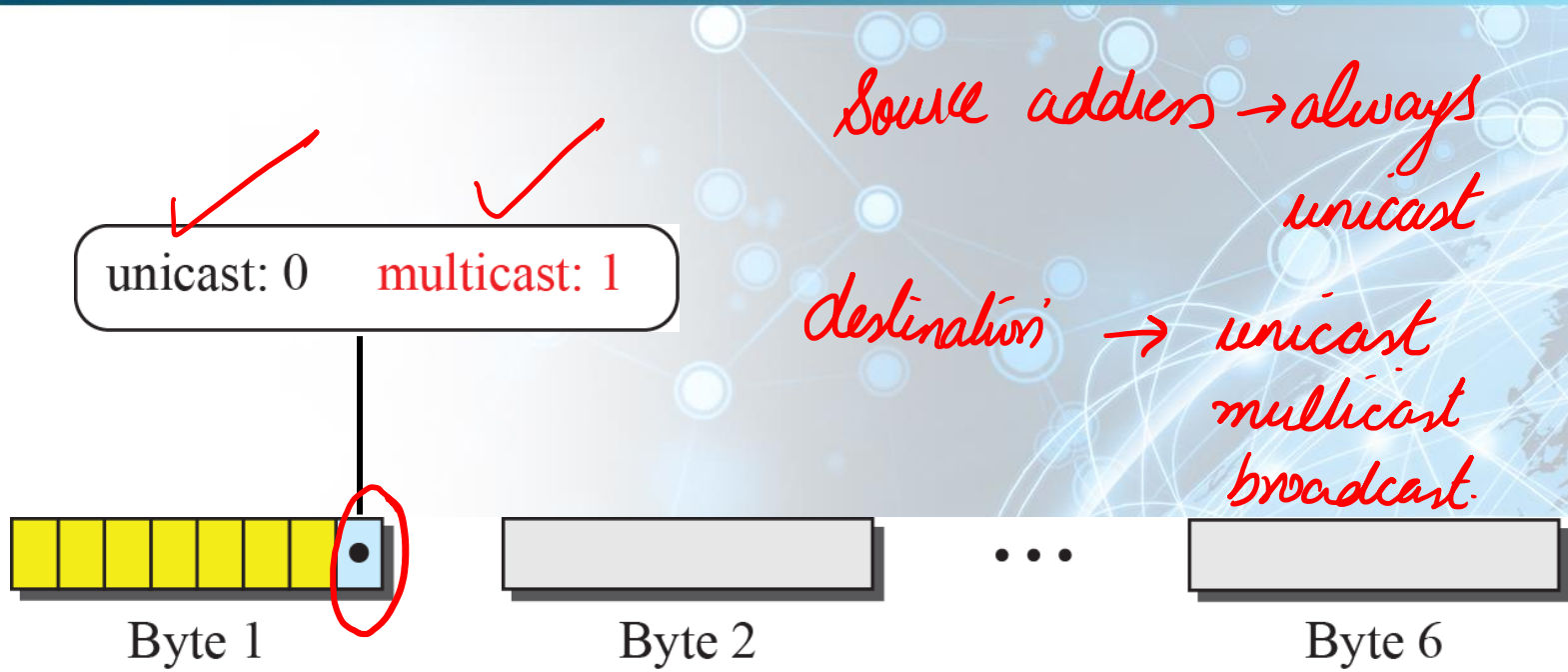
Hexadecimal	47	20	1B	2E	08	EE
Binarys	01000111	00100000	00011011	00101110	00001000	11101110
Transmitted ←	11100010	00000100	11011000	01110100	00010000	01110111

↑
LS

↑
MS

→ unicast
→ multicast
→ broadcast

Unicast and Multicast Addresses



Example 13.2

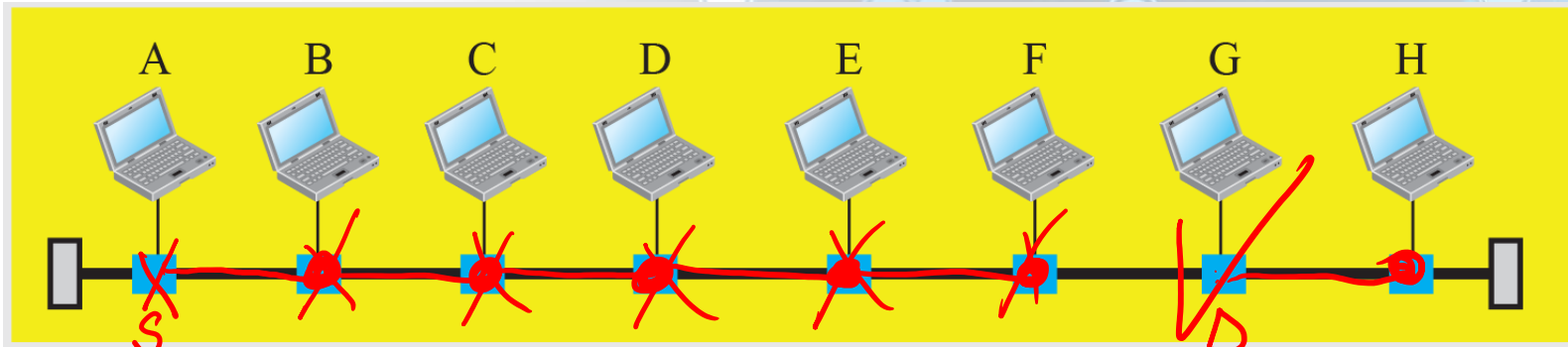
Define the type of the following destination addresses:

- a. 4A:30:10:21:10:1A ✓ 4A A → 1010 (0 → LS)
- b. 47:20:1B:2E:08:EE ✓ 47 7 → 0111 (1 → LS)
- c. FF:FF:FF:FF:FF:FF

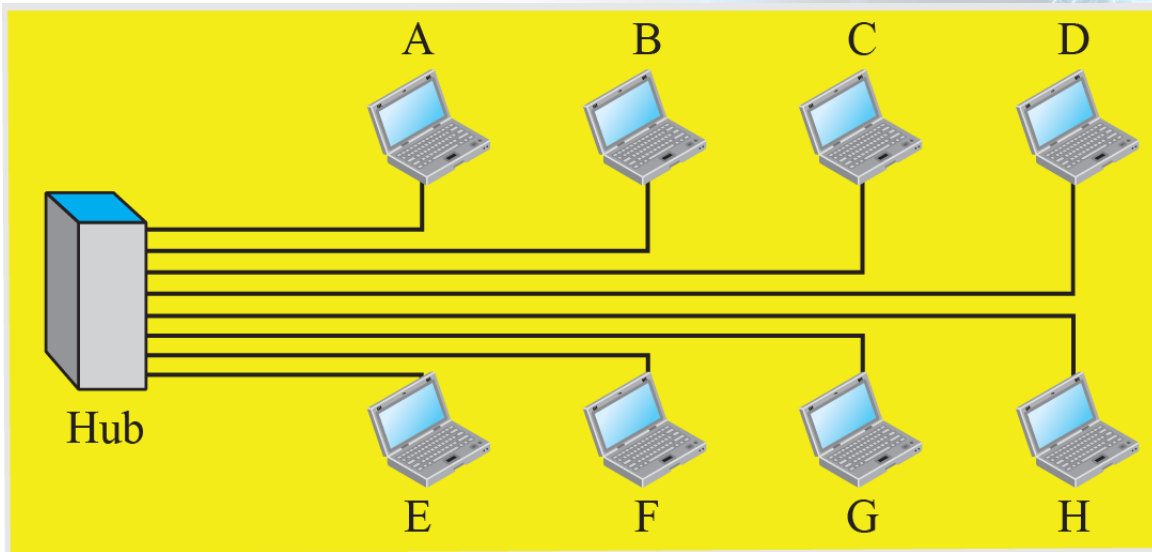
To find the type of the address, we need to look at the second hexadecimal digit from the left. If it is even, the address is unicast. If it is odd, the address is multicast. If all digits are Fs, the address is broadcast. Therefore, we have the following:

- a. This is a unicast address because A in binary is 1010 (even).
- b. This is a multicast address because 7 in binary is 0111 (odd).
- c. This is a broadcast address because all digits are Fs in hexadecimal.

Implementation of Standard Ethernet









a. A LAN with a bus topology using a coaxial cable



b. A LAN with a star topology using a hub

Legend

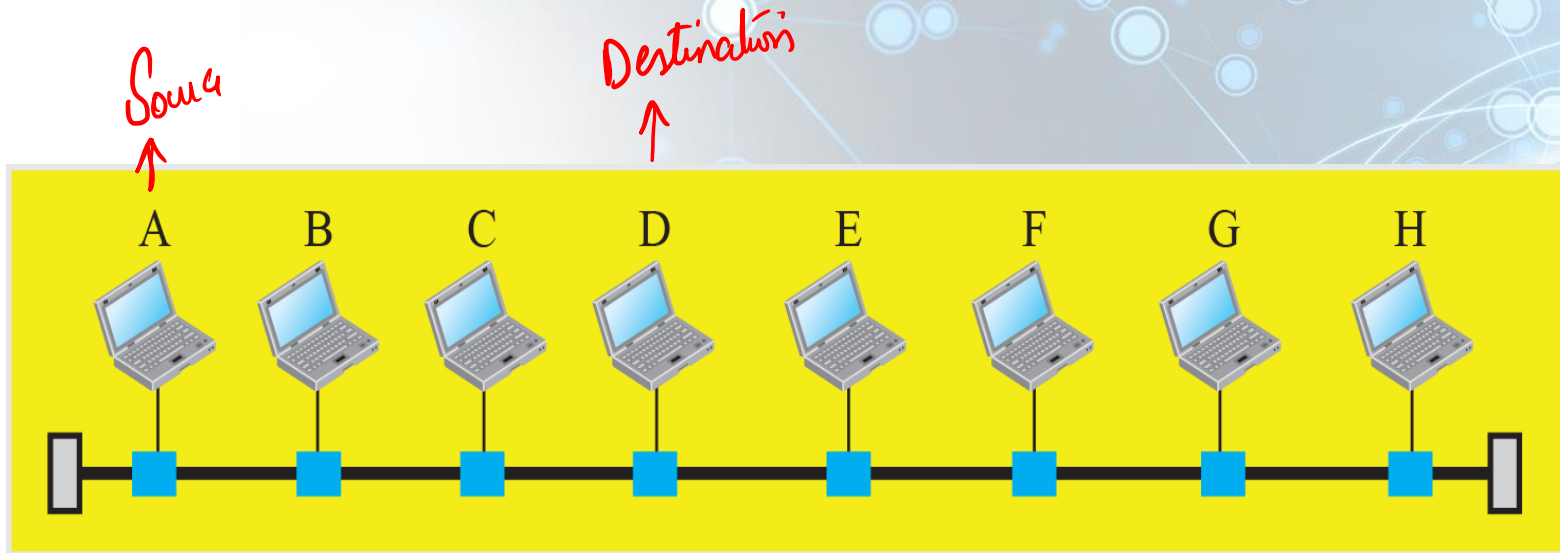
-  A host (of any type)
-  A hub
-  A cable tap
-  A cable end
-  Coaxial cable
-  Twisted pair cable

Broadcast

Access Method in Standard Ethernet

- **Since the network that uses the standard Ethernet protocol is a broadcast network, we need to use an access method to control access to the sharing medium**
- **The standard Ethernet chose CSMA/CD with 1-Persistent Method**

Access Method in Standard Ethernet



a. A LAN with a bus topology using a coaxial cable

- ① Station A → sensed medium for full duration of frame — no collision
- ② Station A → senses a collision
↳ Backoff (48-bit Jam signal)
- CSMA/CD
↓
measuring energy on medium (100µs)

Efficiency of Standard Ethernet

- The ratio of the time used by a station to send data to the time the medium is occupied by this station
- The practical efficiency of standard Ethernet has been measured to be:

$$\text{Efficiency} = 1/(1 + 6.4 \times a)$$

where a = number of frames that can fit on a medium

Example

In the Standard Ethernet with the transmission rate of 10 Mbps, we assume that the length of the medium is 2500 m and the size of the frame is 512 bits. The propagation speed of a signal in a cable is normally 2×10^8 m/s.

$$\text{Propagation Delay} = \frac{2500 \text{ m}}{2 \times 10^8 \text{ m/s}} = 12.5 \mu\text{sec}$$

$$\text{Transmission Delay} = \frac{512}{10^7} = 51.2 \mu\text{sec}$$

$$a = \frac{\text{Prop. Delay}}{\text{Trans Delay}} = \frac{12.5}{51.2} = 0.24 \rightarrow 0.24 \text{ of a frame occupies medium}$$

$$\underline{\underline{\epsilon}} = \frac{1}{(1 + 6.4 \times a)} = 39\% \rightarrow \text{moderate only } 61\% \text{ of time}$$

IDEAL

$a=0$

$\epsilon=1$

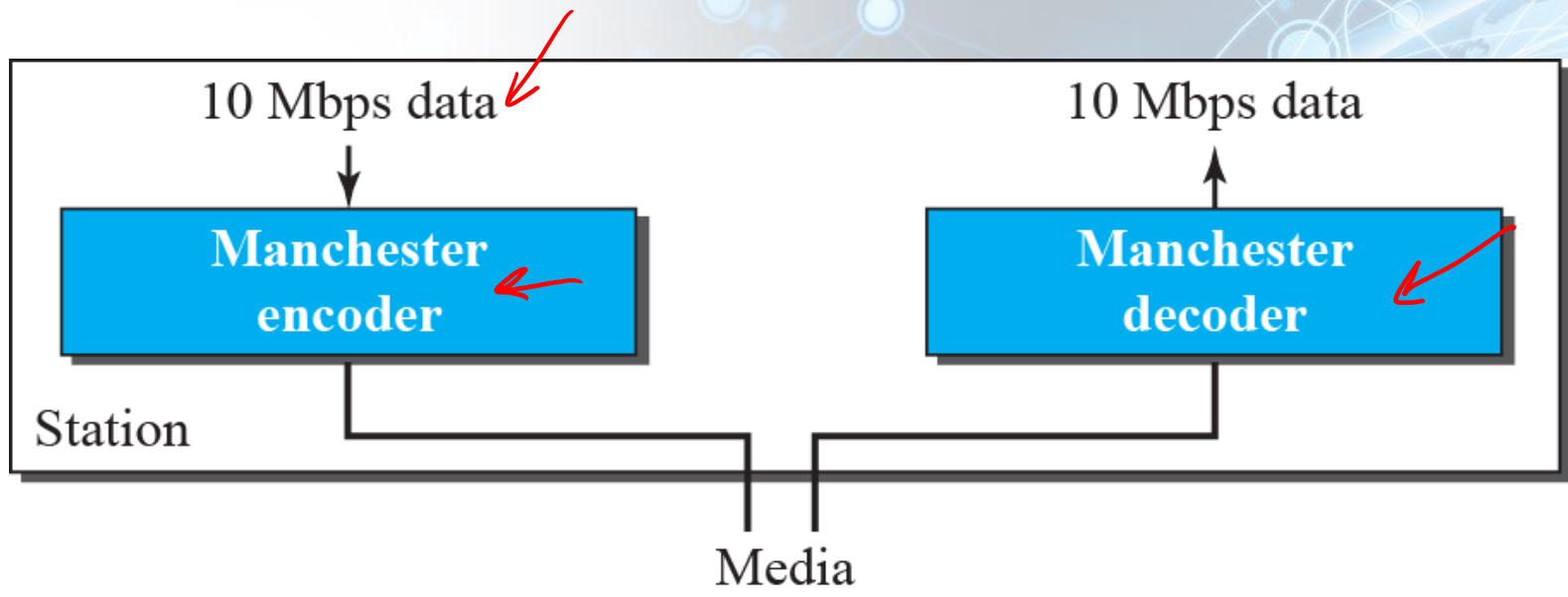
Implementation of Standard Ethernet

- **The Standard Ethernet defined several implementations, but only four of them became popular during the 1980s**

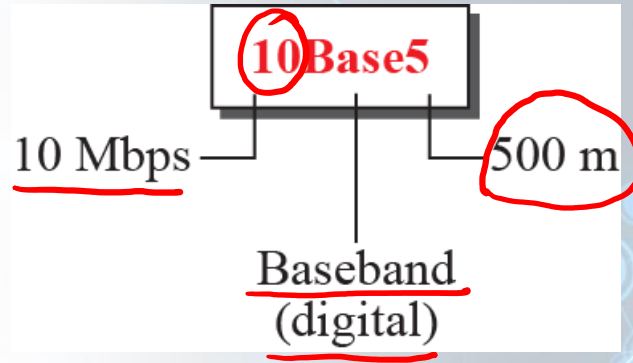
Summary of Standard Ethernet implementations

<i>Implementation</i>	<i>Medium</i>	<i>Medium Length</i>	<i>Encoding</i>
10Base5 ✓	Thick coax ✓	500 m ✓	Manchester ✓
10Base2 ✓	Thin coax ✓	185 m ✓	Manchester ✓
10Base-T ✓	2 UTP ✓	100 m ✓	Manchester ✓
10Base-F ✓	2 Fiber ✓	2000 ✓	Manchester ✓

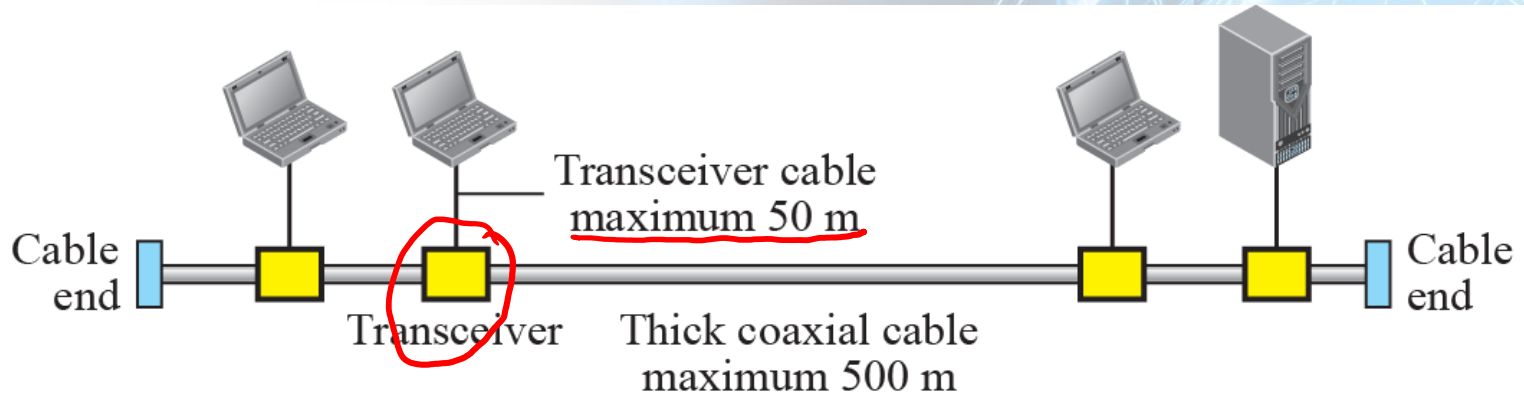
Encoding in Standard Ethernet



10Base5 implementation

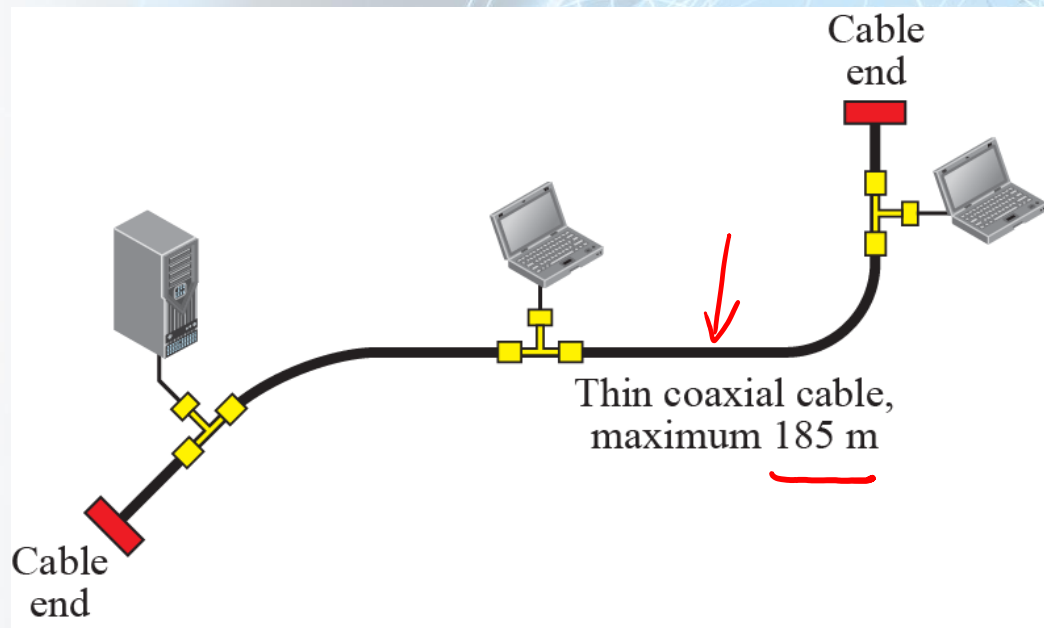
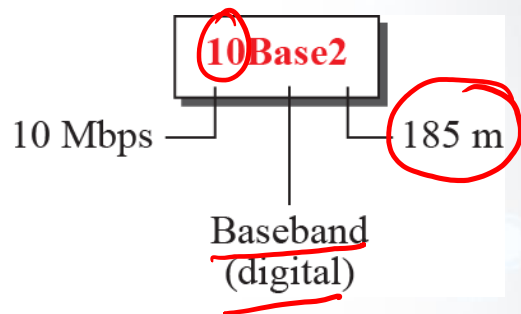


- Thick Ethernet
- Thickenet
- Repeaters

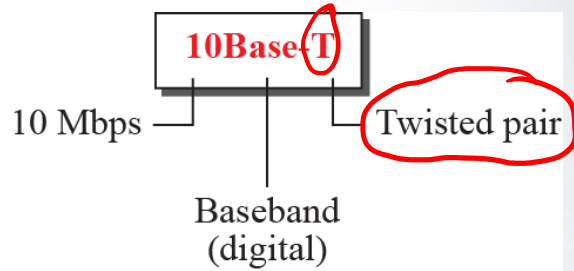


10Base2 implementation

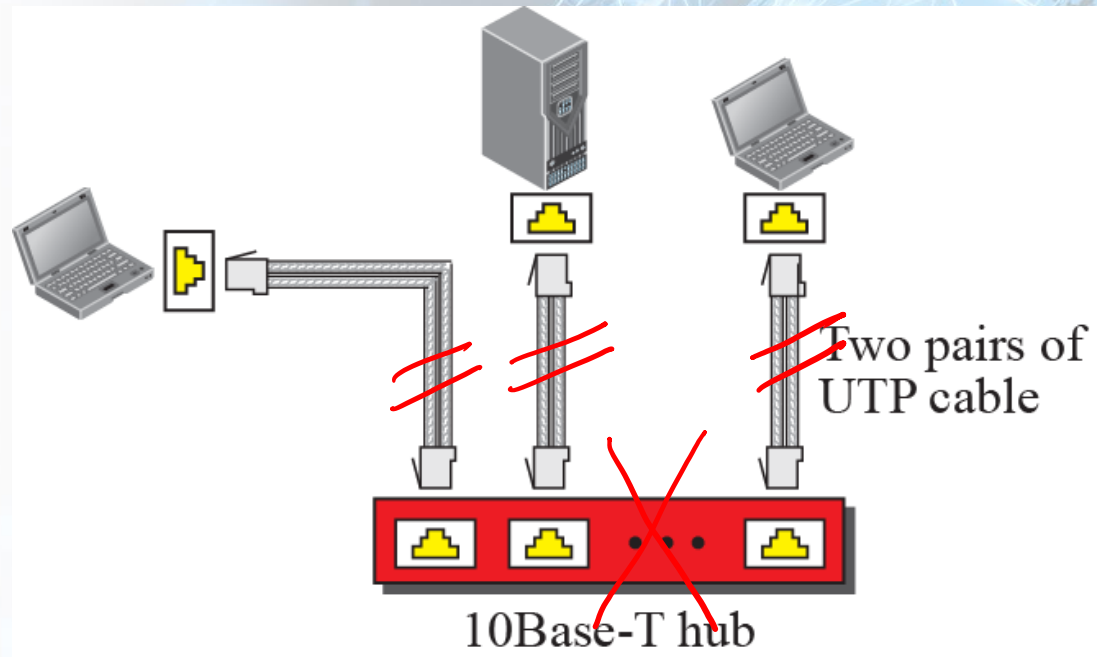
→ Thin Ethernet



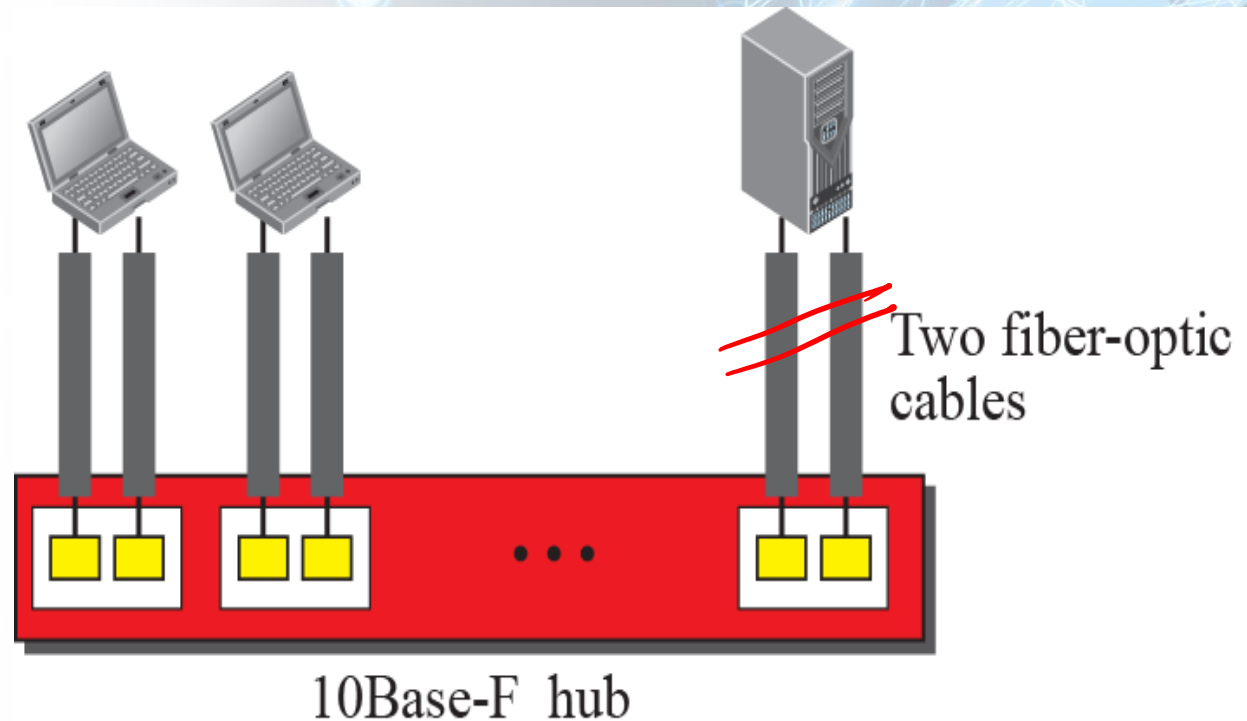
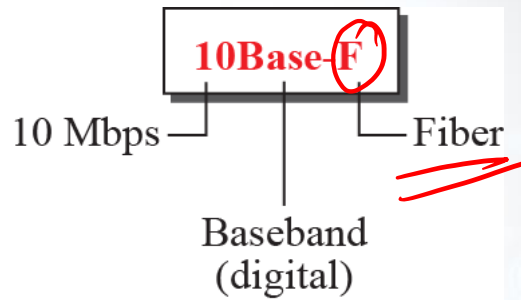
10Base-T implementation



*- Twisted Pair
Ethernet*



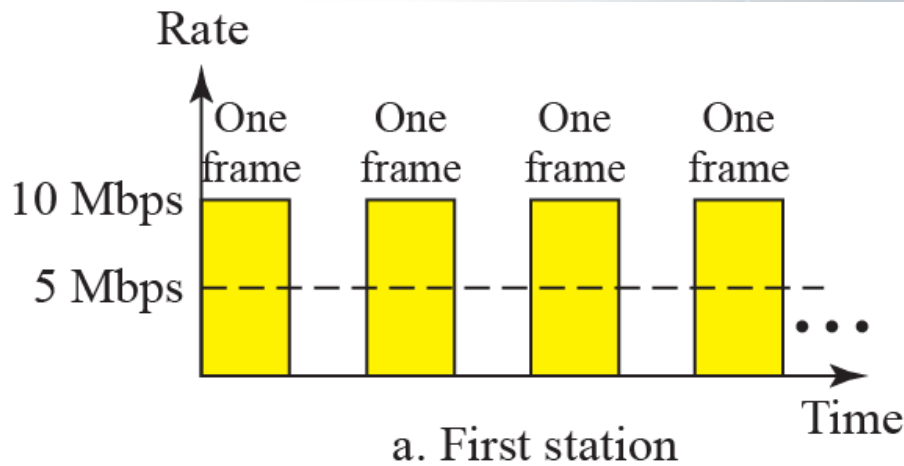
10Base-F implementation



Changes in the Standard

- The changes that occurred to the 10-Mbps Standard Ethernet opened the road to the evolution of the Ethernet to become compatible with other high-data-rate LANs
 - ✓ Bridged Ethernet
 - ✓ Switched Ethernet
 - ✓ Full-Duplex Ethernet

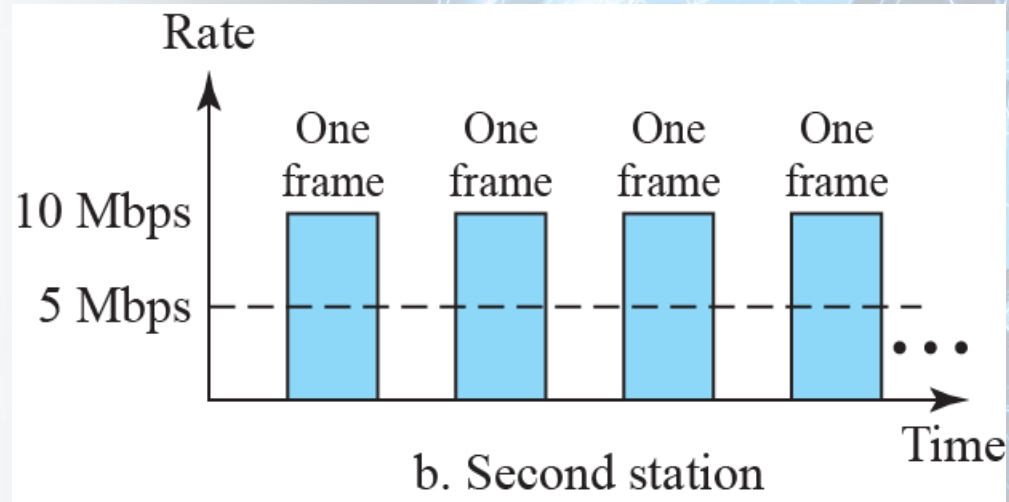
Bridged Ethernet- Sharing Bandwidth



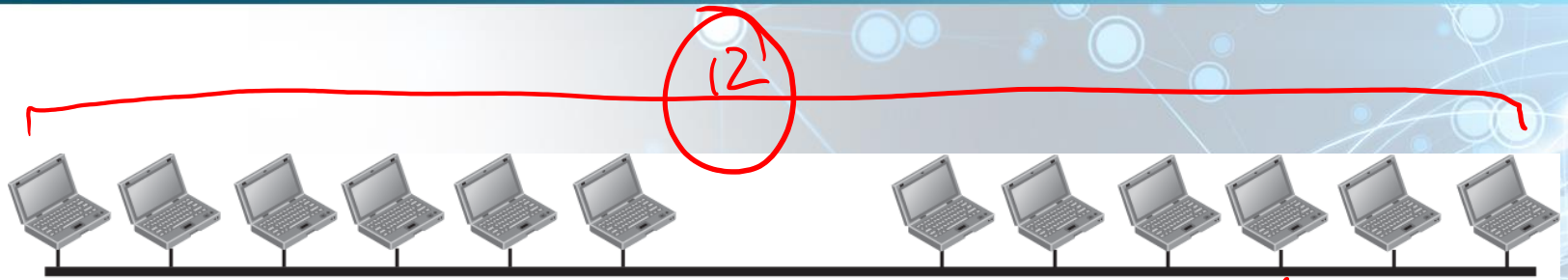
10 Mbps → One station

Two station ⇒ 5 Mbps

⋮

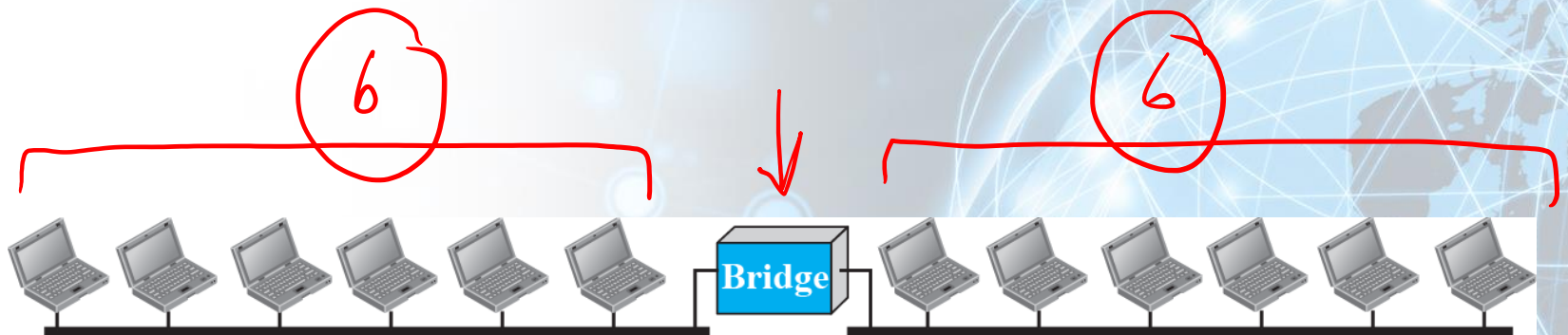


A Network with and without Bridging



a. Without bridging

10 Mbps / 12



b. With bridging

10 Mbps / 6

10 Mbps / 6

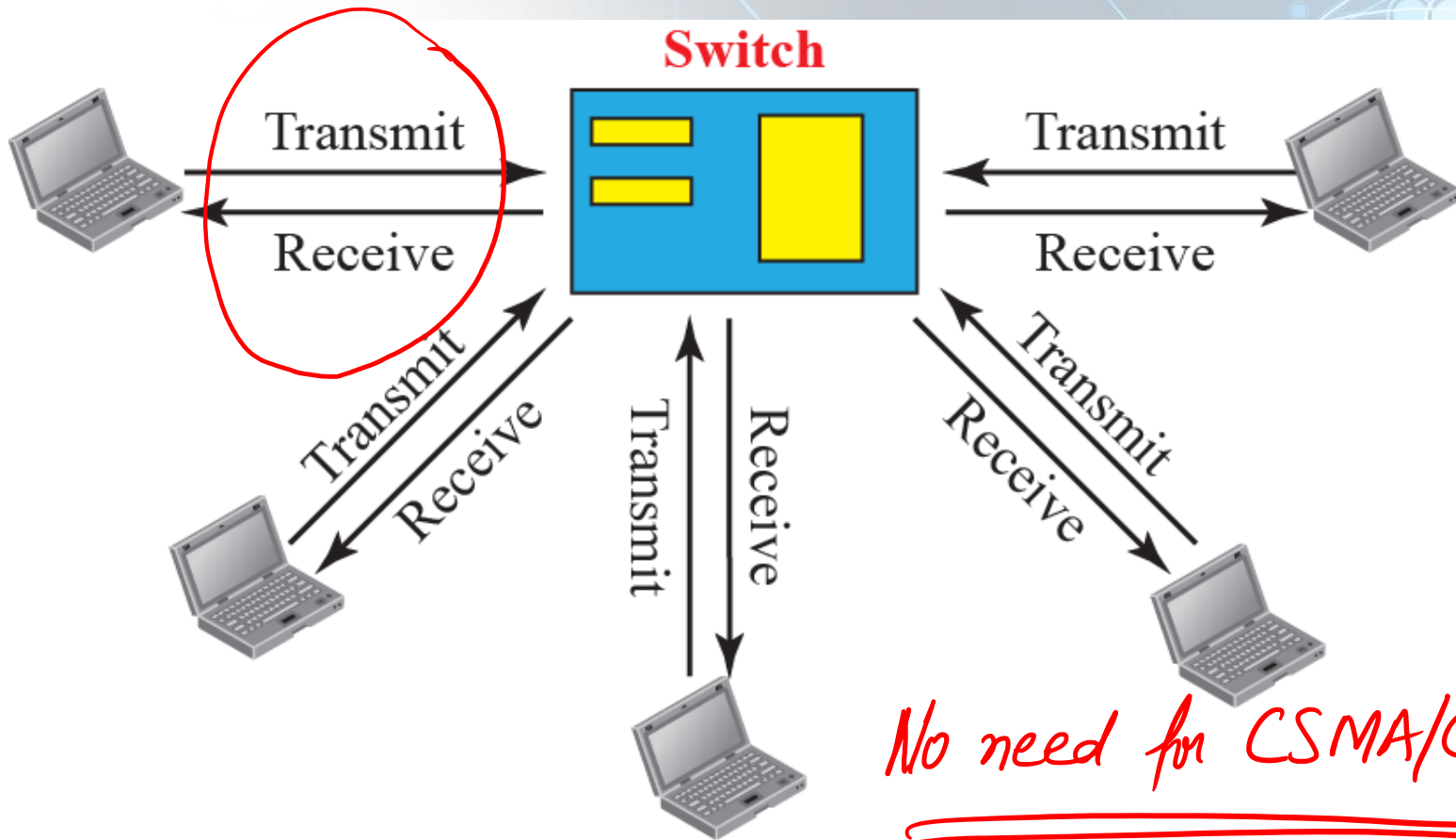
* Collision Domains

4 port bridge \rightarrow 10 / 4 Mbps \rightarrow 3 times more than unbridged

Changes in the Standard

- The changes that occurred to the 10-Mbps Standard Ethernet opened the road to the evolution of the Ethernet to become compatible with other high-data-rate LANs
 - ✓ Bridged Ethernet
 - ✓ Switched Ethernet
 - ✓ Full-Duplex Ethernet

Full – Duplex Switched Ethernet



Fast Ethernet

- In the 1990s, Ethernet made a big jump by increasing the transmission rate to 100 Mbps, and the new generation was called the Fast Ethernet
- To make it compatible with the Standard Ethernet, the MAC sublayer was left unchanged

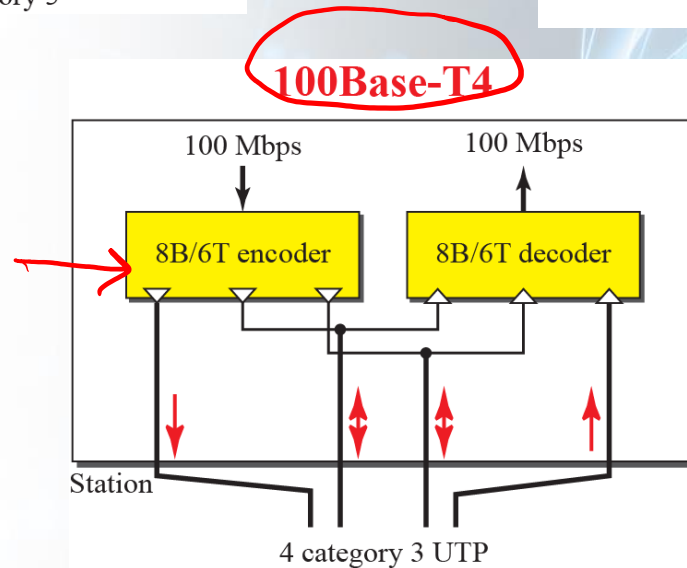
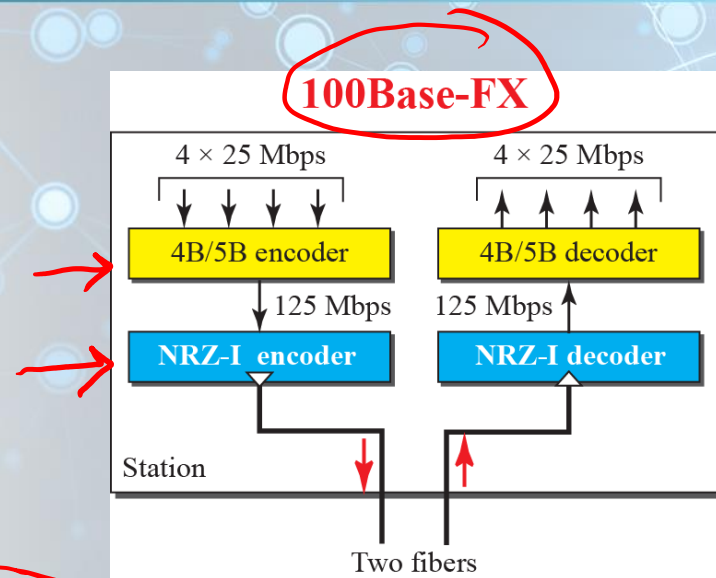
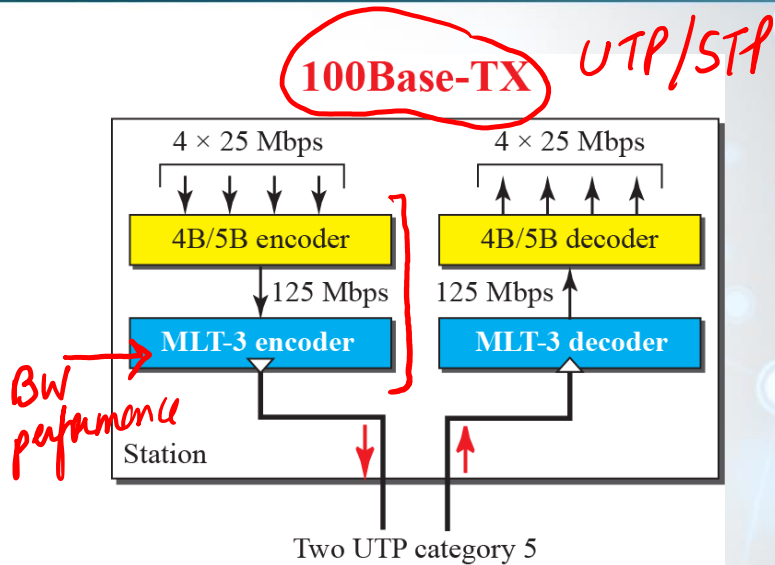
Fast Ethernet

- **But the features of the Standard Ethernet that depend on the transmission rate, had to be changed**
- **Goals of Fast Ethernet:**
 - ✓ **Upgrade data rate to 100Mbps**
 - ✓ **Make it compatible with Standard Ethernet**
 - ✓ **Keep same 48-bit address**
 - ✓ **Keep same frame format**

Physical Layer

- To be able to handle a 100 Mbps data rate, several changes need to be made at the physical layer

Encoding for Fast Ethernet



Implementation of Fast Ethernet implementations

<i>Implementation</i>	<i>Medium</i>	<i>Medium Length</i>	<i>Wires</i>	<i>Encoding</i>
100Base-TX ✓	STP ✓	100 m ✓	2 ✓	4B5B + MLT-3 ✓
100Base-FX ✓	Fiber ✓	185 m ✓	2 ✓	4B5B + NRZ-I ✓
100Base-T4 ✓	UTP ✓	100 m ✓	4 ✓	Two 8B/6T ✓

Gigabit Ethernet

- **Need for an even higher data rate resulted in the design of IEEE Standard 802.3z Gigabit Ethernet Protocol (1000 Mbps)**

Gigabit Ethernet

- The goals of the Gigabit Ethernet were:
 - ✓ Upgrade the data rate to 1 Gbps
 - ✓ Make it compatible with standard or Fast Ethernet
 - ✓ Use same 48 bit address
 - ✓ Use the same frame format
 - ✓ Keep same minimum and maximum frame lengths

MAC Sub-layer

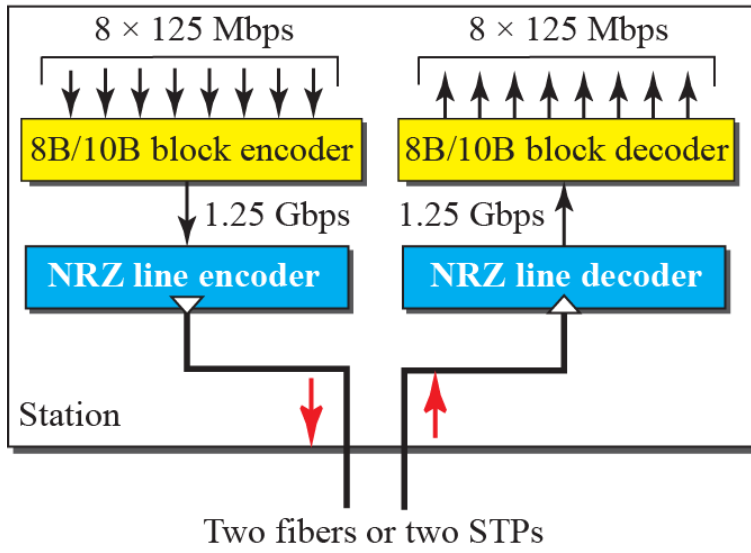
- A main consideration in the evolution of Ethernet was to keep the MAC sublayer untouched
- To achieve a data rate of 1 Gbps, this was no longer possible
- Gigabit Ethernet has two distinctive approaches for medium access:
 - ✓ Half-duplex
 - ✓ Full-duplex

Physical Layer

- **The physical layer in Gigabit Ethernet is more complicated than that in Standard or Fast Ethernet**
- **We briefly discuss some features of this layer:**

Encoding in Gigabit Ethernet

1000Base-SX, 1000Base-LX, and 1000Base-CX

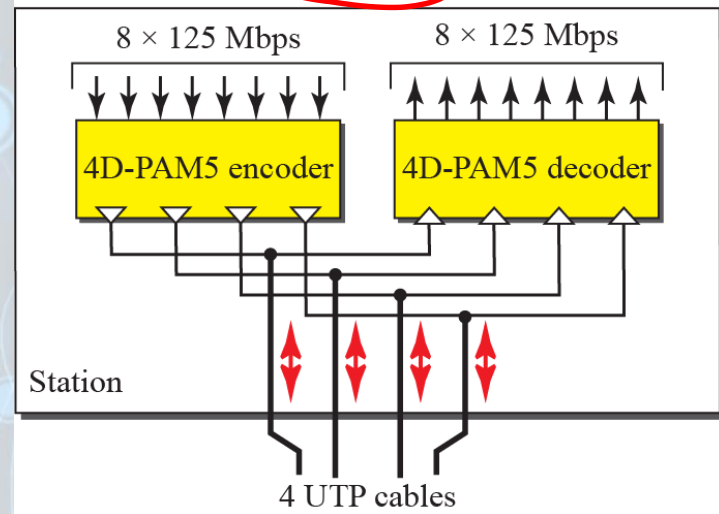


Fiber → 1000 Base SX
1000 Base LX

STP → 1000 Base CX

UTP → 1000 Base T

1000Base-T



Summary of Gigabit Ethernet Implementations

<i>Implementation</i>	<i>Medium</i>	<i>Medium Length</i>	<i>Wires</i>	<i>Encoding</i>
1000Base-SX ✓	Fiber S-W ✓	550 m ✓	2 ✓	8B/10B + NRZ ✓
1000Base-LX ✓	Fiber L-W ✓	5000 m	2	8B/10B + NRZ ✓
1000Base-CX	STP	25 m	2	8B/10B + NRZ
1000Base-T4	UTP	100 m	4	4D-PAM5

10-gigabit Ethernet

- The idea is to extend the technology, the data rate, and the coverage distance so that the Ethernet can be used in LANs and MANs (metropolitan area network)
- The IEEE committee created 10 Gigabit Ethernet and called it Standard 802.3ae

Implementation

- **10 Gigabit Ethernet operates only in full-duplex mode, which means there is no need for contention; CSMA/CD is not used in 10 Gigabit Ethernet**
- **Four implementations are most common:**

Implementation

<i>Implementation</i>	<i>Medium</i>	<i>Medium Length</i>	<i>Number of wires</i>	<i>Encoding</i>
10GBase-SR	Fiber 850 nm ✓	300 m ✓	2 ✓	64B66B ✓
10GBase-LR	Fiber 1310 nm ✓	10 Km ✓	2 ✓	64B66B ✓
10GBase-EW	Fiber 1350 nm ✓	40 Km ✓	2 ✓	SONET ✓
10GBase-X4	Fiber 1310 nm ✓	300 m to 10 Km ✓	2 ✓	8B10B ✓

Other Wired Networks

- **Access Networks**
 - ✓ **Networks that connect a small LAN to an ISP**
- **Wide Area Networks**
 - ✓ **Wired networks used to transfer data over long distances**

Telephone Network

- The telephone network had its beginnings in the late 1800s
- Plain Old Telephone System (POTS) was originally an analog system using analog signals to transmit voice
- With the advent of the computer era, the network, in the 1980s, began to carry data in addition to voice

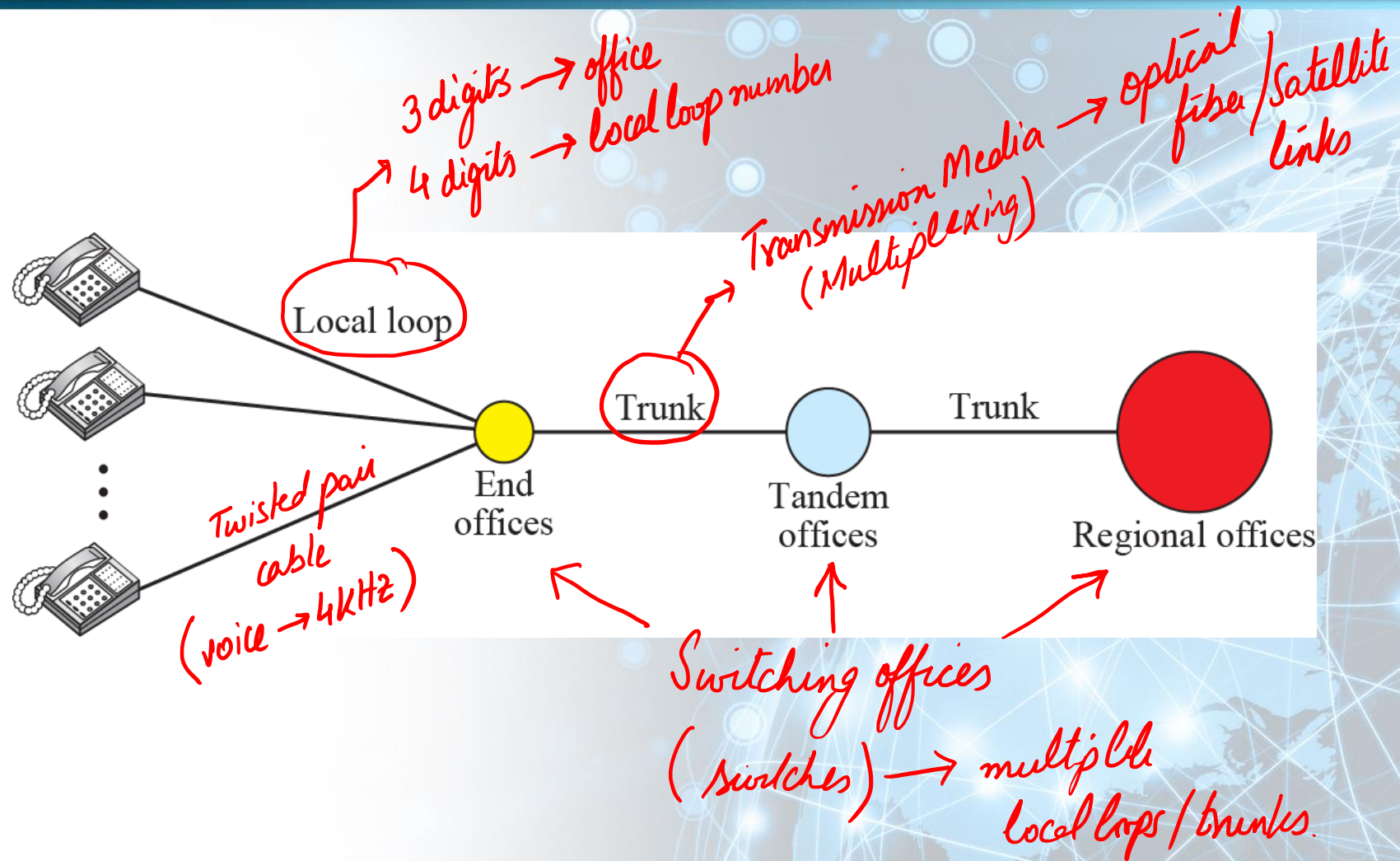
Telephone Network

- During the last decade, the telephone network has undergone many technical changes and the network is now Digital as well as Analog

Major Components

- The telephone network is made of three major components:
 - ✓ Local Loops
 - ✓ Trunks
 - ✓ Switching offices
- The telephone network has several levels of switching offices:
 - ✓ End offices
 - ✓ Tandem offices
 - ✓ Regional offices

A Telephone System



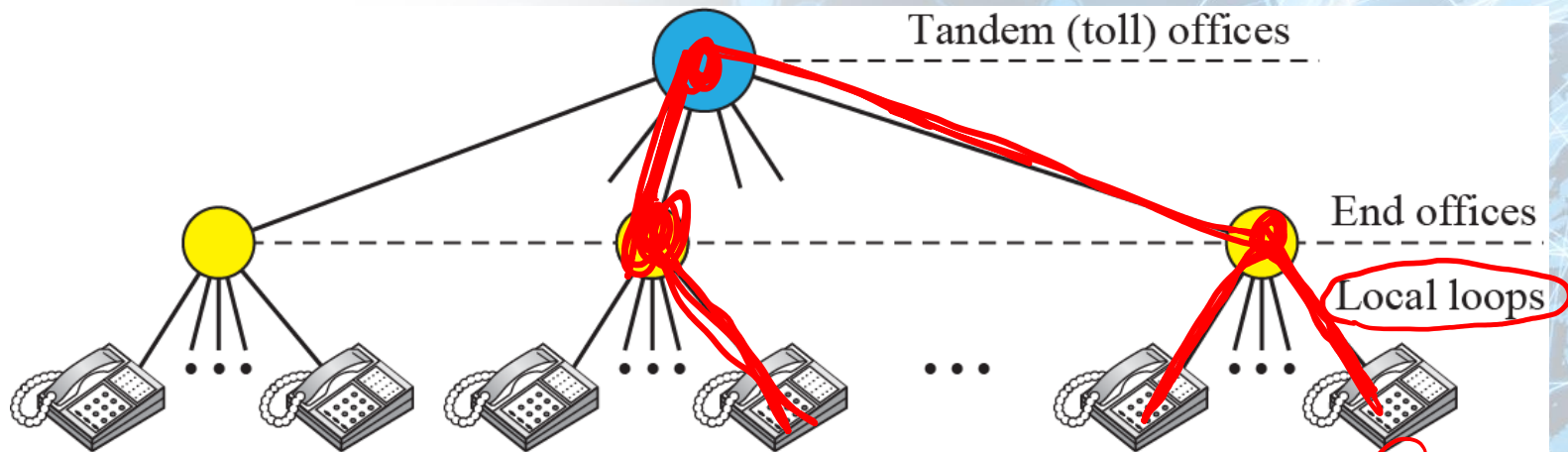
Local-Access Transport Areas (LATAs)

- A LATA can be a small or large metropolitan area
- A small state may have a single LATA; a large state may have several LATAs
- A LATA boundary may overlap with state boundary; part of a LATA can be in one state, part in another state

Intra-LATA and Inter-LATA Services

- **Services offered by Telephone companies inside a LATA are called Intra-LATA services and between LATAs are called Inter-LATA services**
- **Carrier that handles Intra-LATA are called a Local Exchange Carrier (LEC) and the ones that handle Inter-LATA are called Interexchange Carriers (IXCs)**

Switching Offices in a LATA



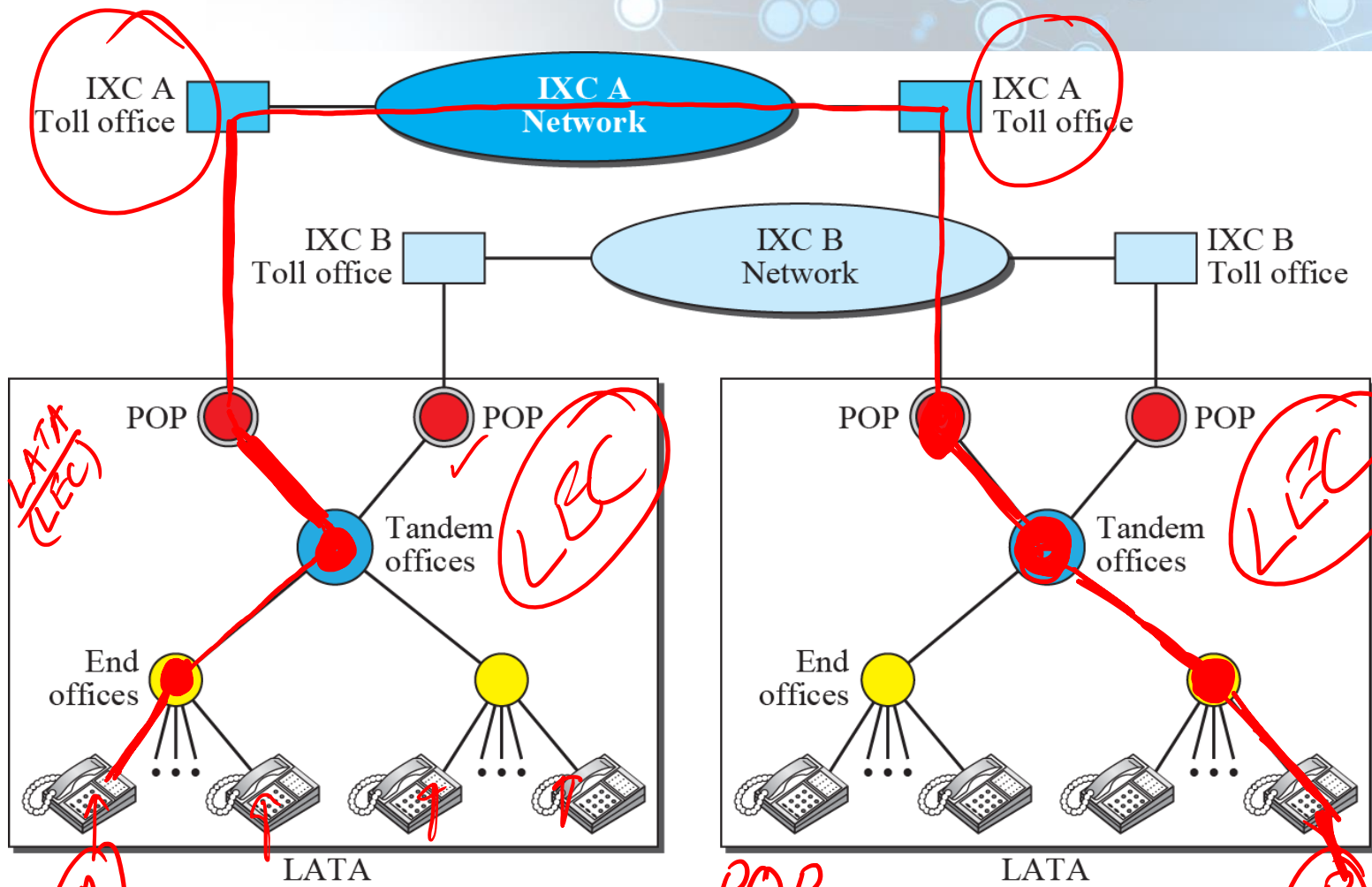
C
↓
Toll call

B

↓
Toll free

A

Points of Presence (POPs)



LEC
(intra LATA)

POP → IXC's
(inter-LATA)

Signaling

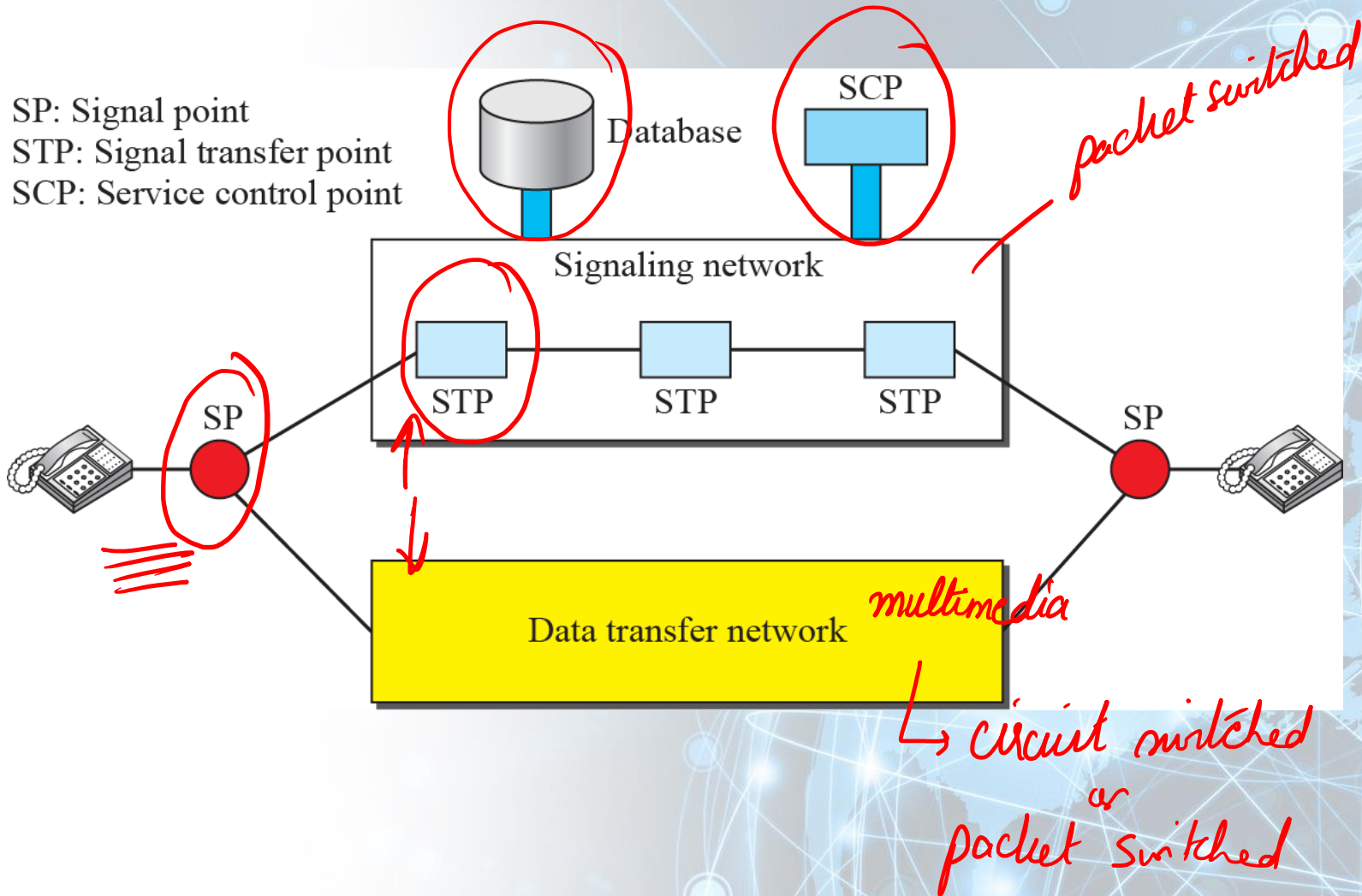
- The telephone network in the beginning, used a circuit-switched network with dedicated links to transfer voice communication
- The operator connected the two parties by using a wire with two plugs inserted into the corresponding two jacks
- Later, the signaling system became automatic

Signaling

- Rotary telephones were invented that sent a digital signal defining each digit in a multi-digit telephone number
- As telephone networks evolved into a complex network, the functionality of the signaling system increased

Data Transfer and Signaling Network

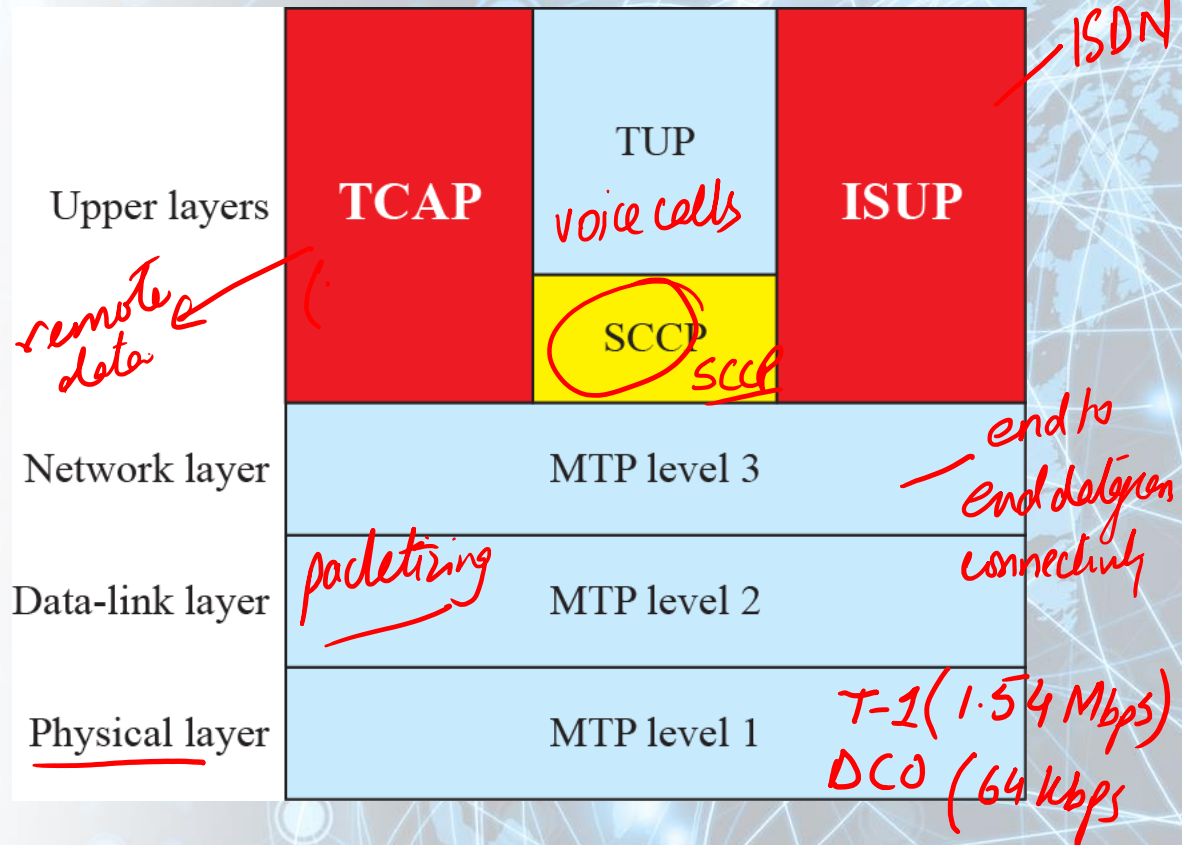
SP: Signal point
STP: Signal transfer point
SCP: Service control point



Layers in SS7

Signalling System 7

- MTP:** Message transfer part
- SCCP:** Signaling connection control point
- TCAP:** Transaction capabilities application port
- TUP:** Telephone user port
- ISUP:** ISDN user port



Services

- Telephone companies provide two types of services:
 - ✓ Analog Services
 - Analog Switched Services
 - Analog Leased Services
 - ✓ Digital Services
 - Switched /56 Service
 - Digital Data Service

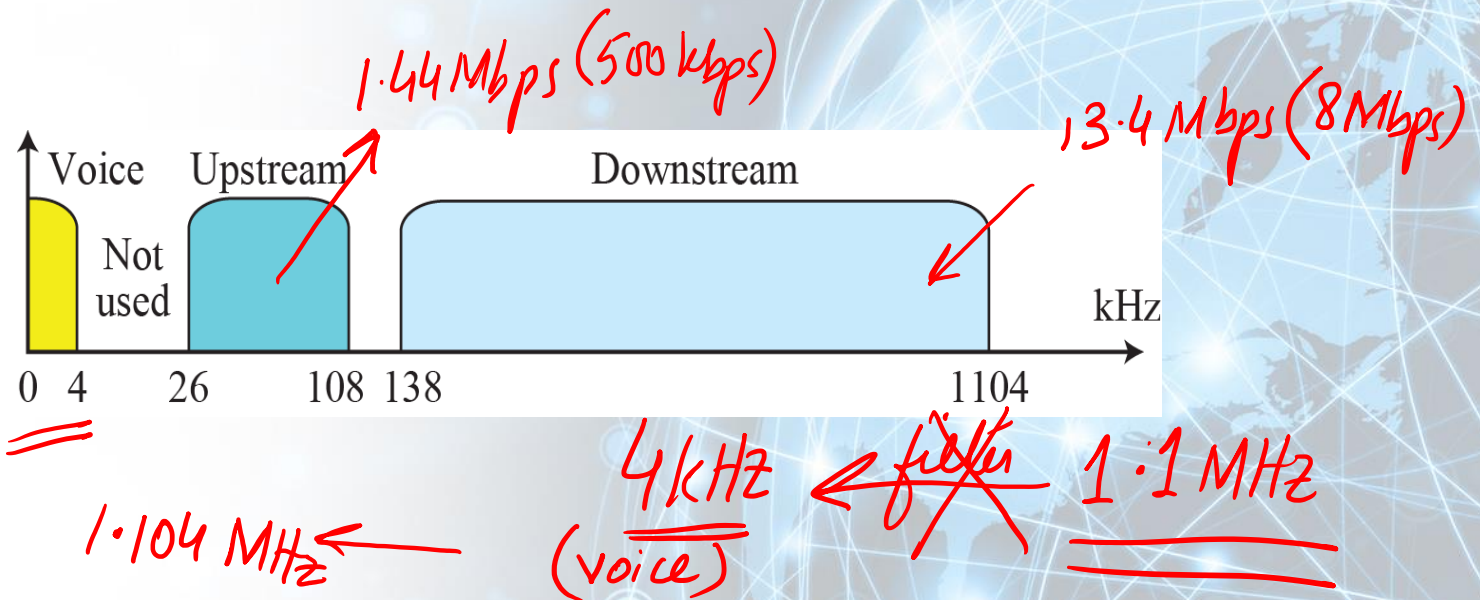
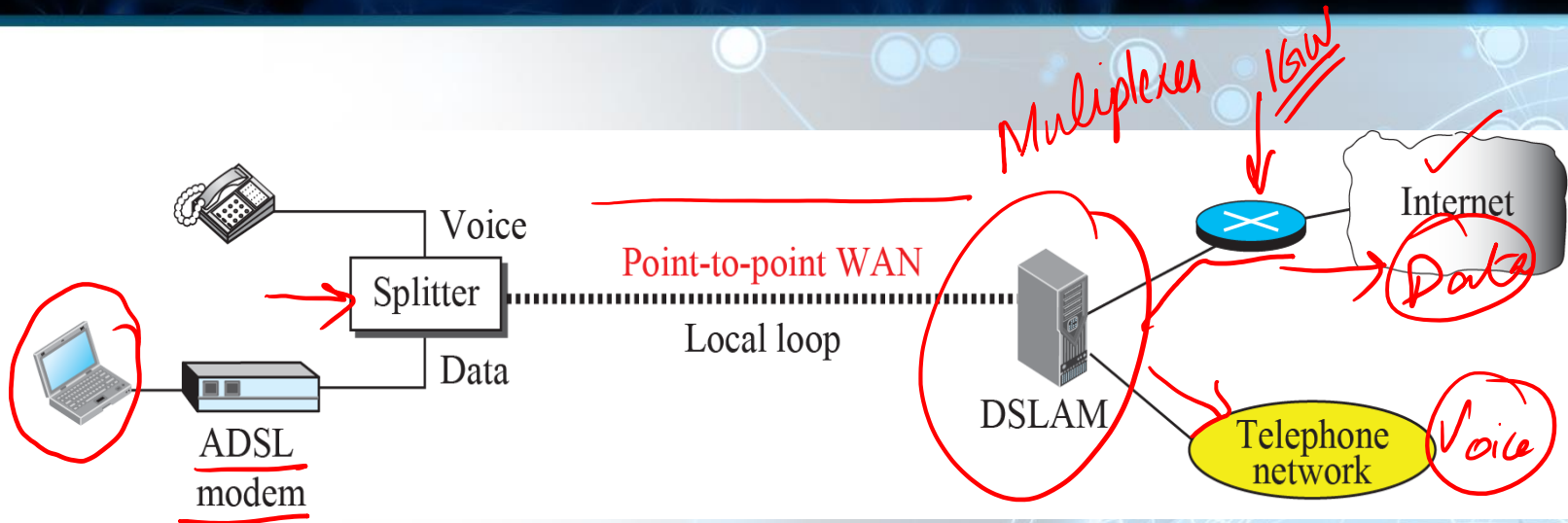
Digital Subscriber Line (DSL)

- After traditional dial-up modems reached their peak data rate, telephone companies developed another technology, DSL, to provide higher-speed access to the Internet
- DSL supports high-speed digital communication over the existing telephone

Digital Subscriber Line (DSL)

- DSL technology is a set of technologies, each differing in the first letter (ADSL, VDSL, HDSL, and SDSL)

ADSL Point-to-Point Network



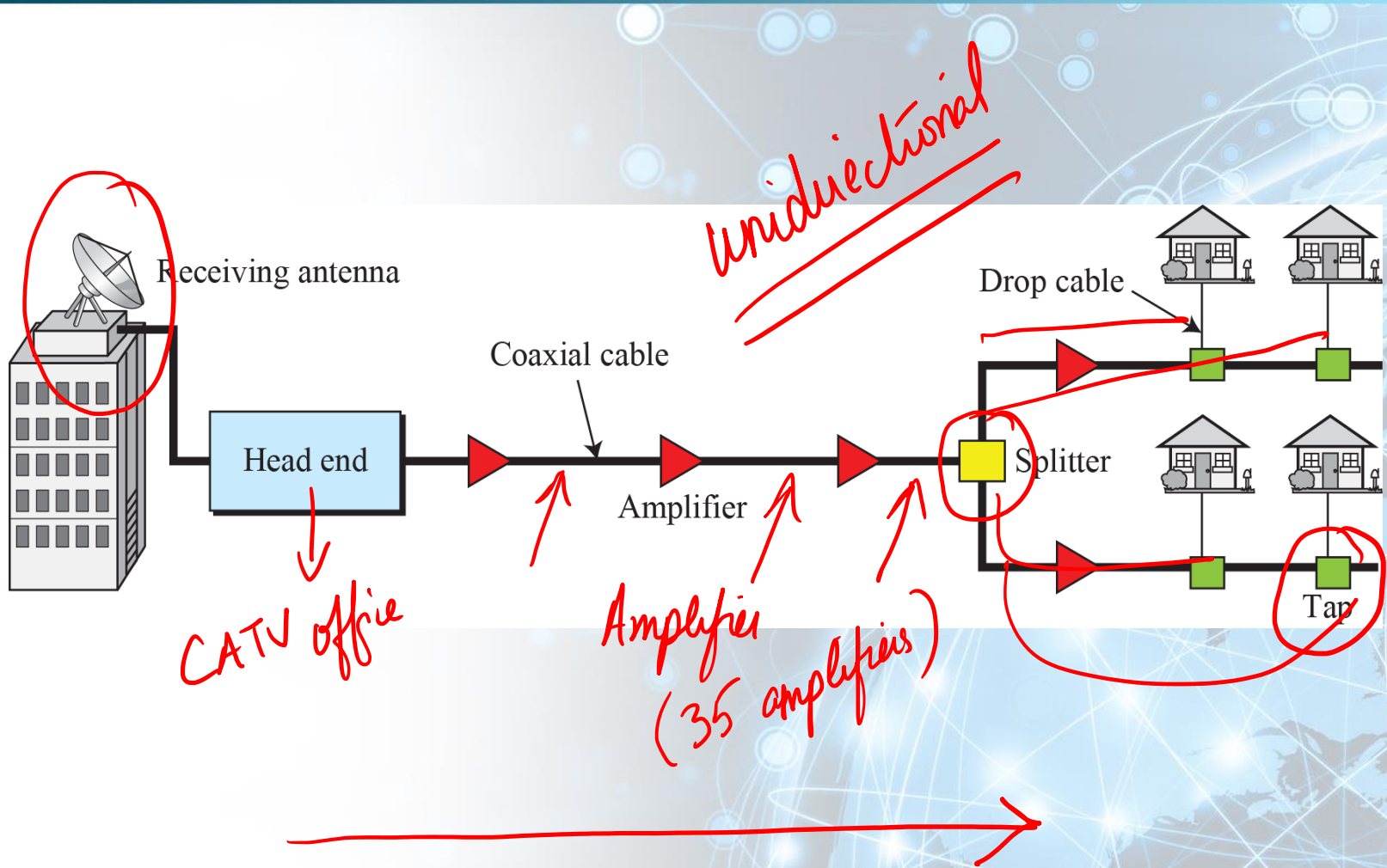
Cable Network

- The Cable TV networks were initially created to provide remote subscribers access to TV programs
- Cable networks enabled access to remote broadcasting stations via microwave connections
- Cable TV also found a good ISP market by using some of the channels originally designed for video

Traditional Cable Networks

- Cable TV started to distribute broadcast video signals to locations with poor or no reception in the late 1940s
- It was called community antenna television (CATV) because an antenna at the top of a tall hill or building received the signals from the TV stations

Traditional Cable TV Network

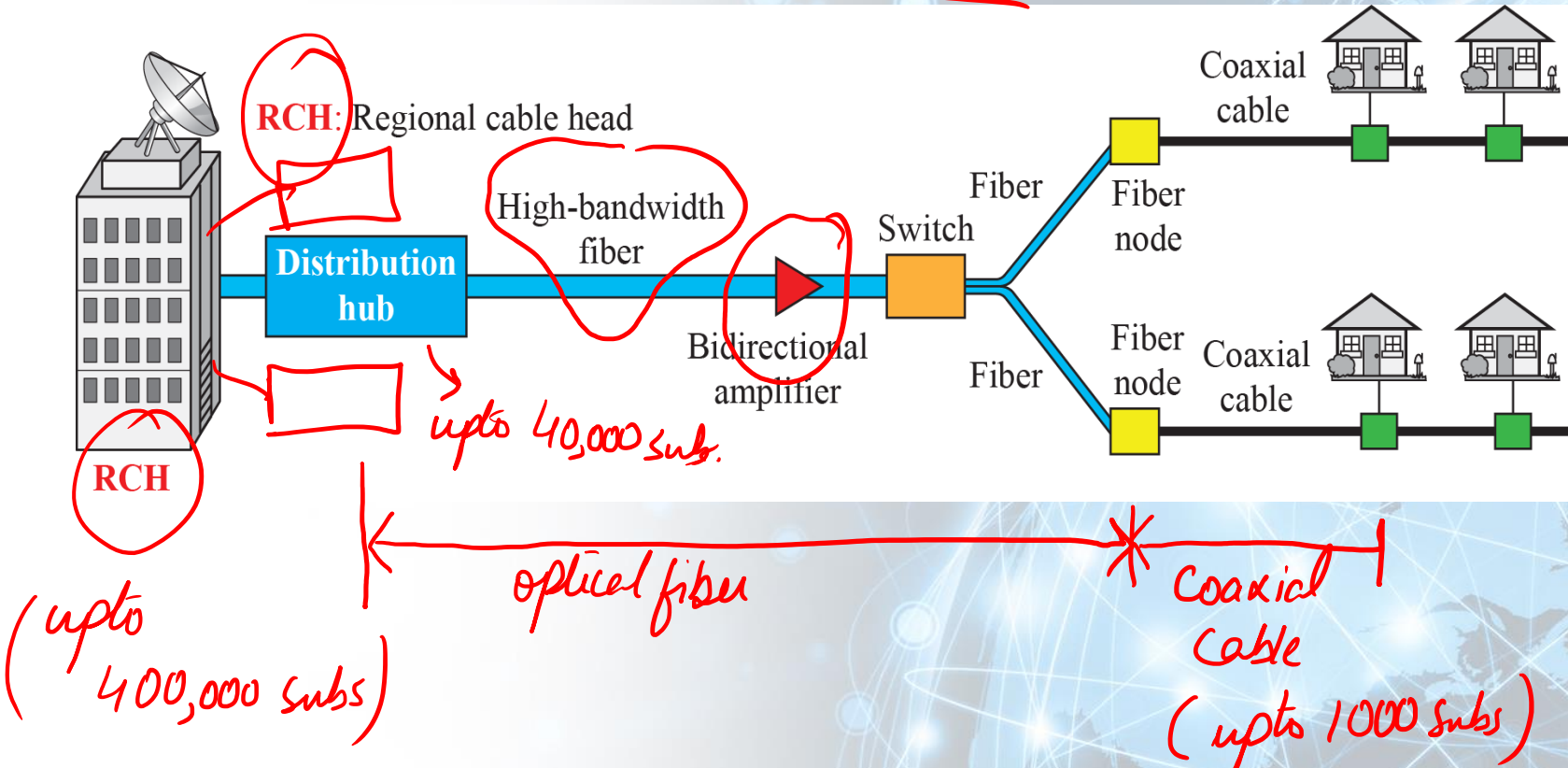


Hybrid Fiber Coaxial (HFC) Network

- **Second generation of cable network is called a Hybrid Fiber-Coaxial (HFC) network**
- **The network uses a combination of fiber-optic and coaxial cable**

Hybrid Fiber-Coaxial (HFC) Network

Bidirectional



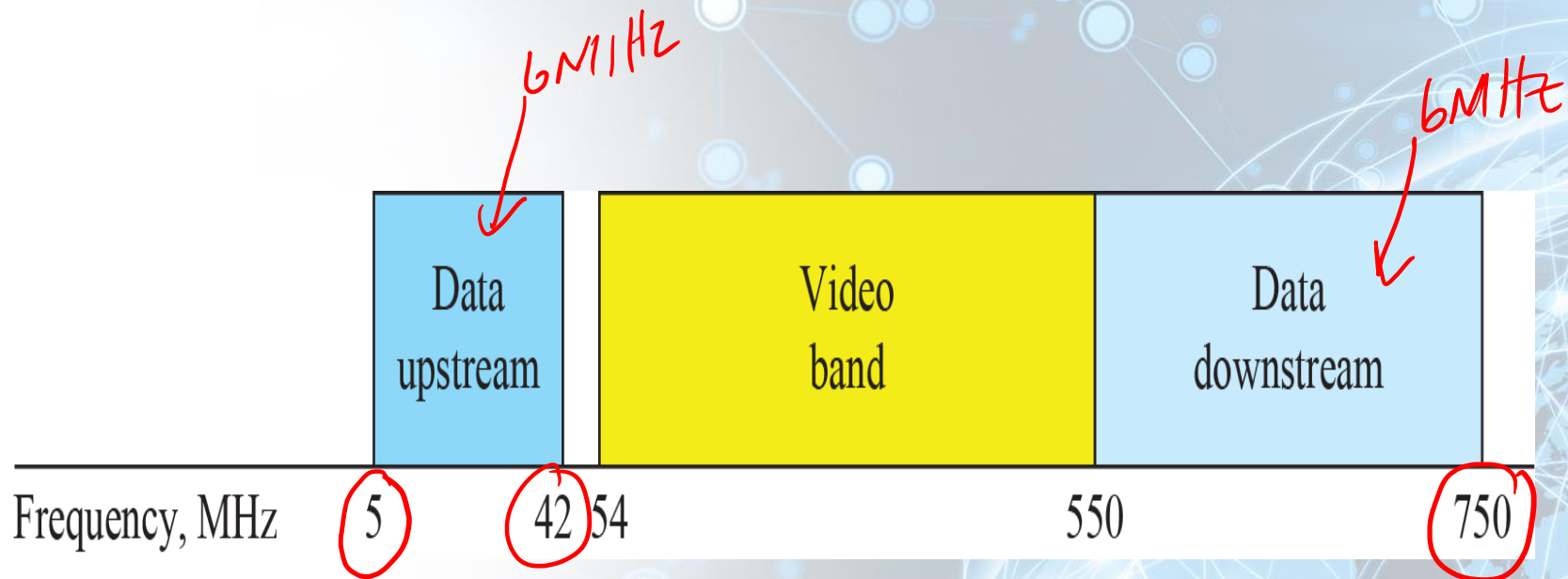
Cable TV for Data Transfer

- Cable companies are now competing with telephone companies for the residential customer who wants high-speed data transfer
- DSL technology provides high-data-rate connections for residential subscribers over the local loop BUT UTP is susceptible to Interference

Cable TV for Data Transfer

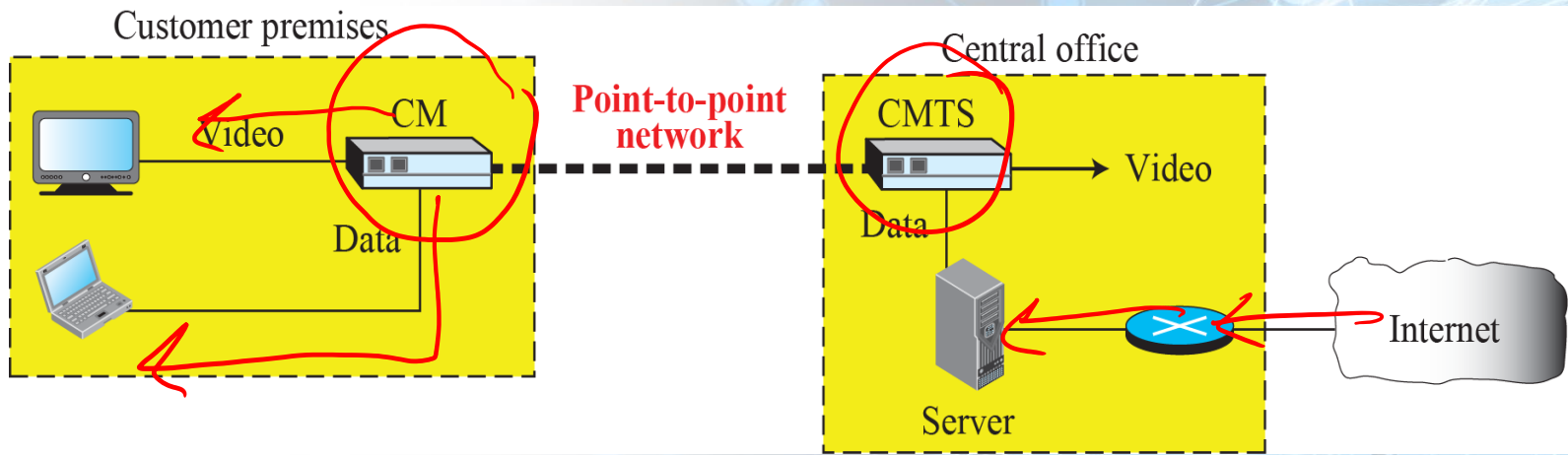
- This imposes an upper limit on the data rate. A solution is the use of the cable TV network

Division of Coaxial Cable Band by CATV



Video $\rightarrow 54 \text{ MHz} - 550 \text{ MHz} = 496 \text{ MHz}$
Each TV channel = 6 MHz
 $\rightarrow 80 \text{ TV channels } (80 \times 6 \text{ MHz} = \underline{480 \text{ MHz}})$

Cable Modem Transmission System (CMTS)



*CM → Cable Modem (Subscriber premise)
CMTS → cable company.*

Synchronous Optical Network (SONET)

- A wide area network (WAN) that is used as a transport network to carry loads from other WANs
- ITU–T standard called Synchronous Digital Hierarchy (SDH)
- Architecture of a SONET system consists of signals, devices, and connections

SONET Architecture

- **Signals**
 - ✓ Synchronous Transport Signals (STS)
 - ✓ Optical Carriers (OCs)
 - ✓ Synchronous Transport Module (STM)
- **SONET Devcies**
 - ✓ STS Mux/Demux
 - ✓ Regenerators
 - ✓ Add-Drop Multiplexer and Terminals
- **Connections**
 - ✓ Section
 - ✓ Line
 - ✓ Path

SONET Signals

	ANSI SONET	ANSI SONET	Rate (Mbps)	SDH	
	STS	OC		STM	DS3
3 STS	STS-1	OC-1	51.840		44.73
	STS-3	OC-3	155.520	STM-1	
	STS-9	OC-9	466.560	STM-3	
	STS-12	OC-12	622.080	STM-4	Europe
	STS-18	OC-18	933.120	STM-6	
	STS-24	OC-24	1244.160	STM-8	
	STS-36	OC-36	1866.230	STM-12	
	STS-48	OC-48	2488.320	STM-16	
	STS-96	OC-96	4976.640	STM-32	
	STS-192	OC-192	9953.280	STM-64	

Handwritten annotations: "3 STS" with arrows pointing to STS-1, STS-3, and STS-9; "USA" bracketed under STS-1 to STS-96; "Europe" bracketed under STM-4 to STM-64; "DS3" circled with an arrow pointing to 44.73; "STM-1" circled with an arrow pointing to 155.520; "51.840" circled; "Europe" written vertically on the right side.

SONET Architecture

- **Signals**
 - ✓ Synchronous Transport Signals (STS)
 - ✓ Optical Carriers (OCs)
 - ✓ Synchronous Transport Module (STM)
- **SONET Devcies**
 - ✓ STS Mux/Demux
 - ✓ Regenerators
 - ✓ Add-Drop Multiplexer and Terminals
- **Connections**
 - ✓ Section
 - ✓ Line
 - ✓ Path

SONET Devices

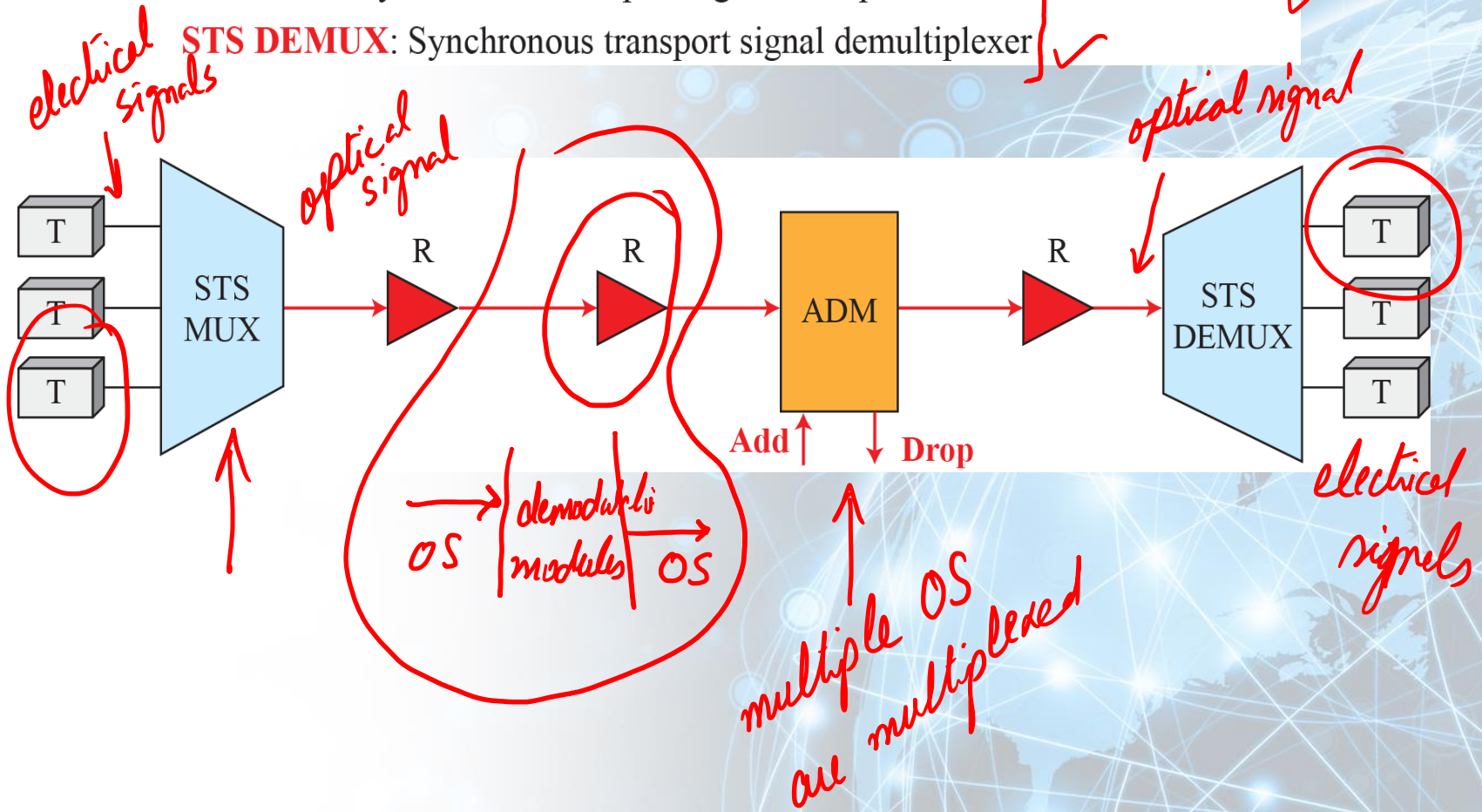
ADM: Add/drop multiplexer ✓

R: Regenerator ✓

STS MUX: Synchronous transport signal multiplexer

T: Terminal ✓

STS DEMUX: Synchronous transport signal demultiplexer ✓



SONET Connections

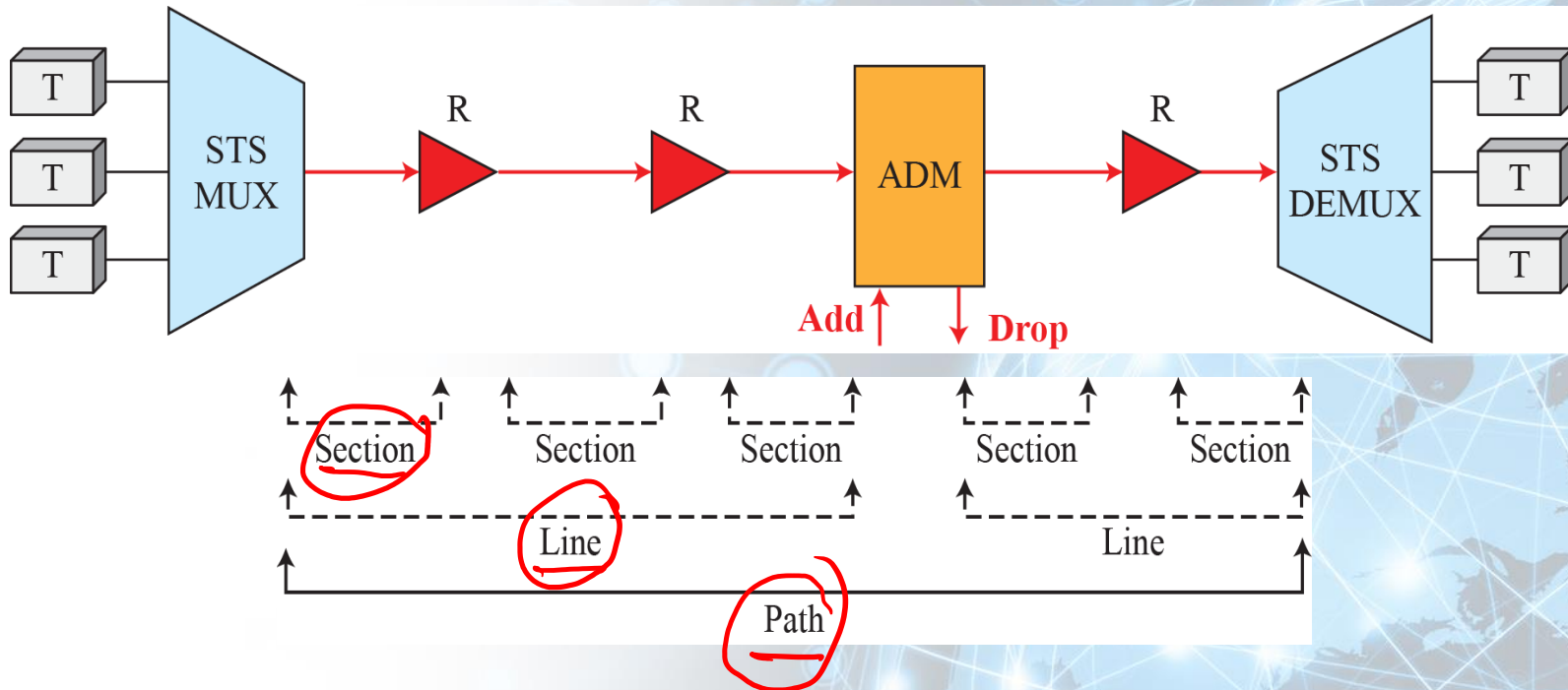
ADM: Add/drop multiplexer

R: Regenerator

STS MUX: Synchronous transport signal multiplexer

T: Terminal

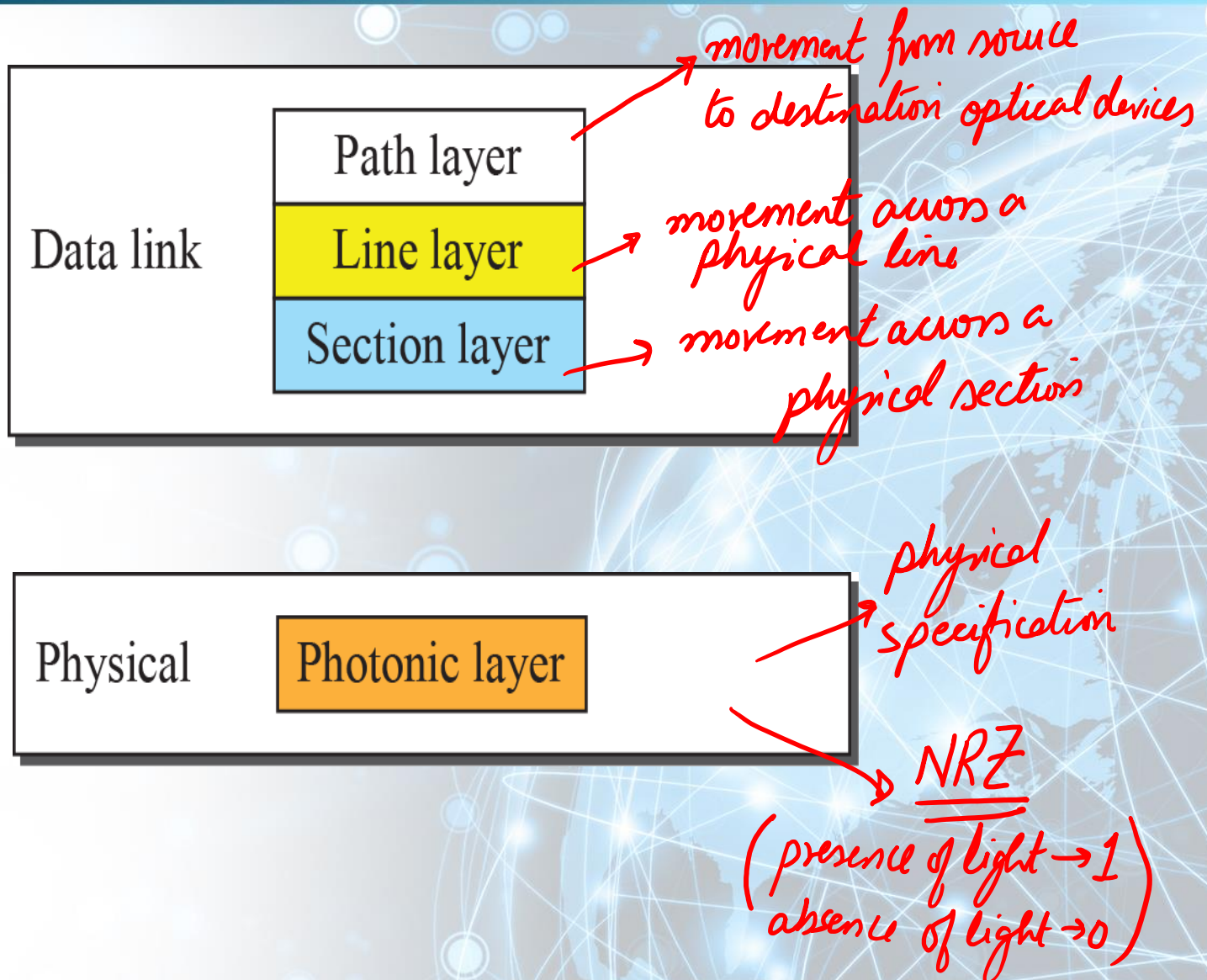
STS DEMUX: Synchronous transport signal demultiplexer



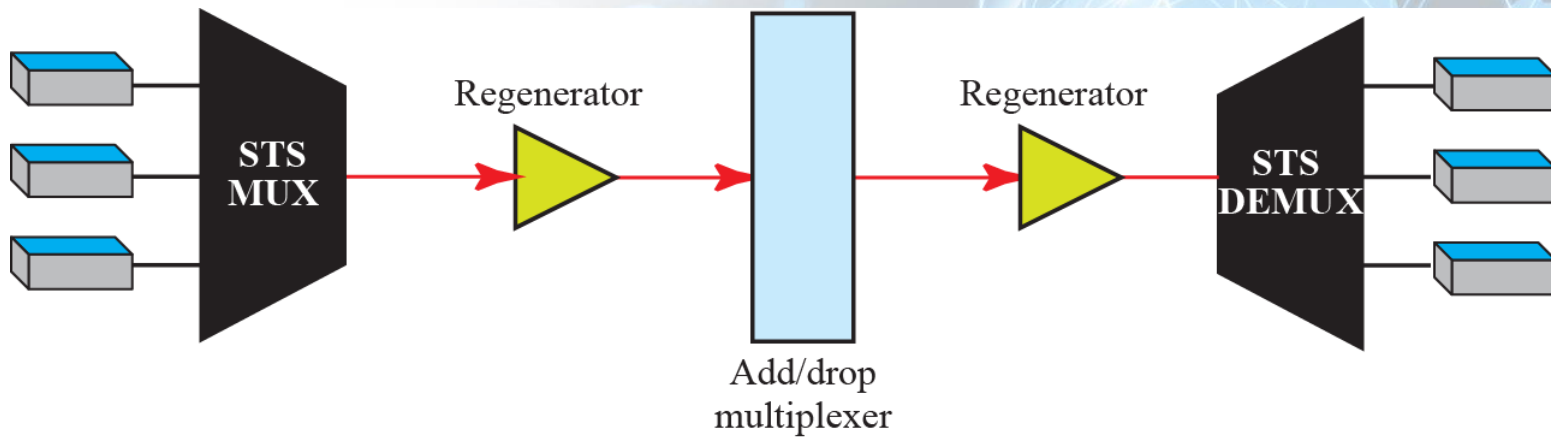
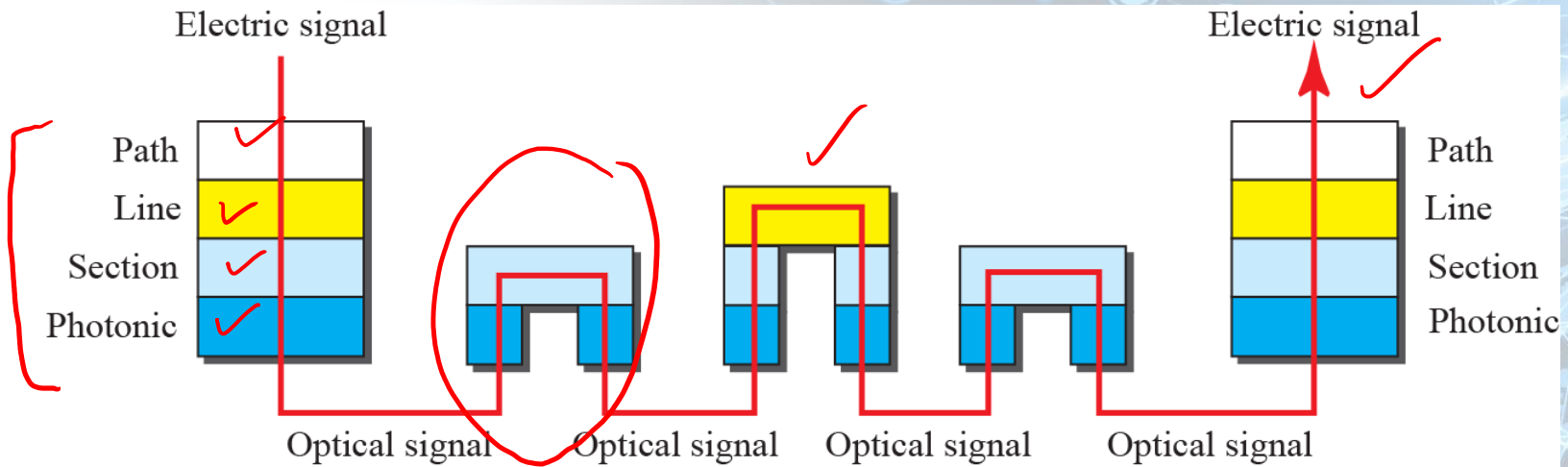
SONET Layers

- The SONET standard includes four functional layers:
 - ✓ The Path Layer
 - ✓ The Line Layer
 - ✓ The Section Layer
 - ✓ The Photonic Layer
- The layers correspond to both the physical and the data-link layers

SONET Layers



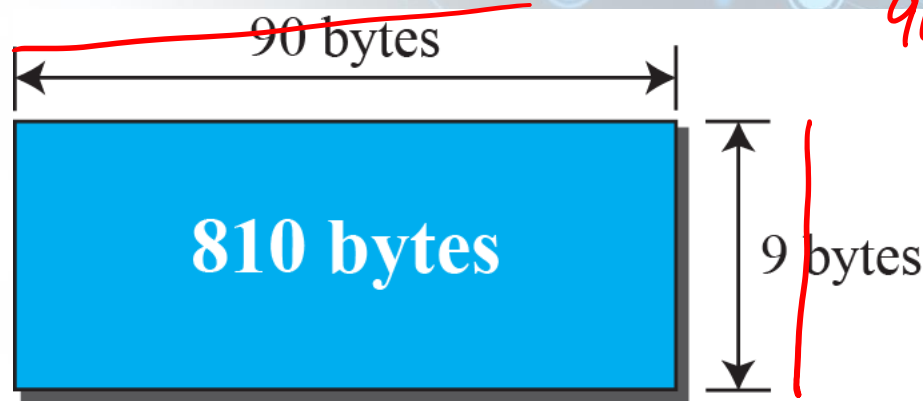
Device-Layer Relationship in SONET



SONET Frames

- Each synchronous transport signal STS-n is composed of 8000 frames
- Each frame is a two-dimensional matrix of bytes with 9 rows by $90 \times n$ columns
- STS-1 frame is 9 rows by 90 columns (810 bytes), and an STS-3 is 9 rows by 270 columns (2430 bytes)

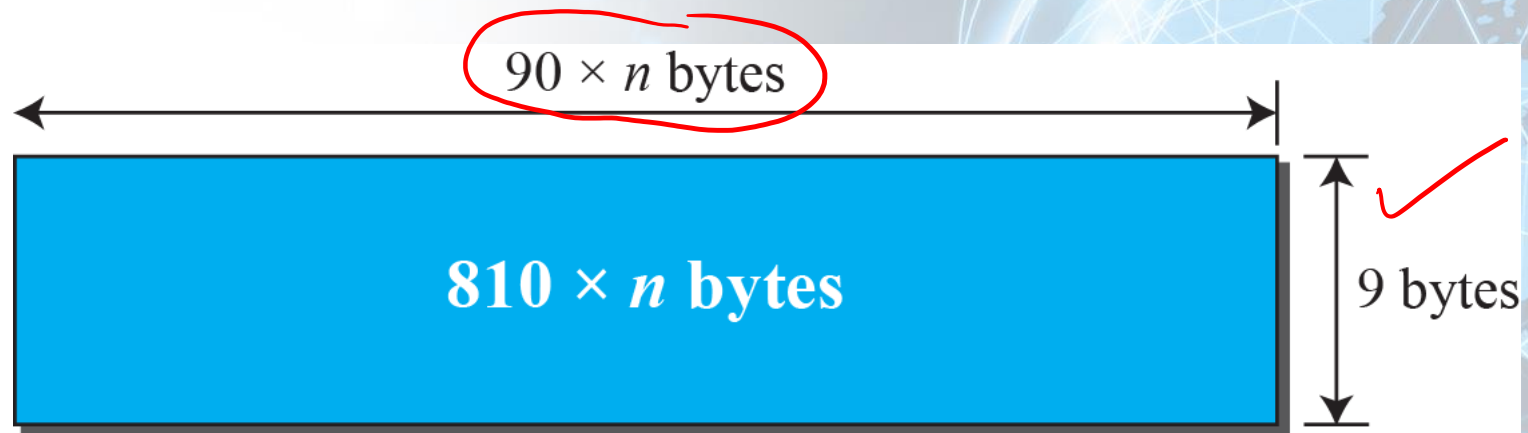
An STS-1 and an STS-n Frame



a. STS-1 frame

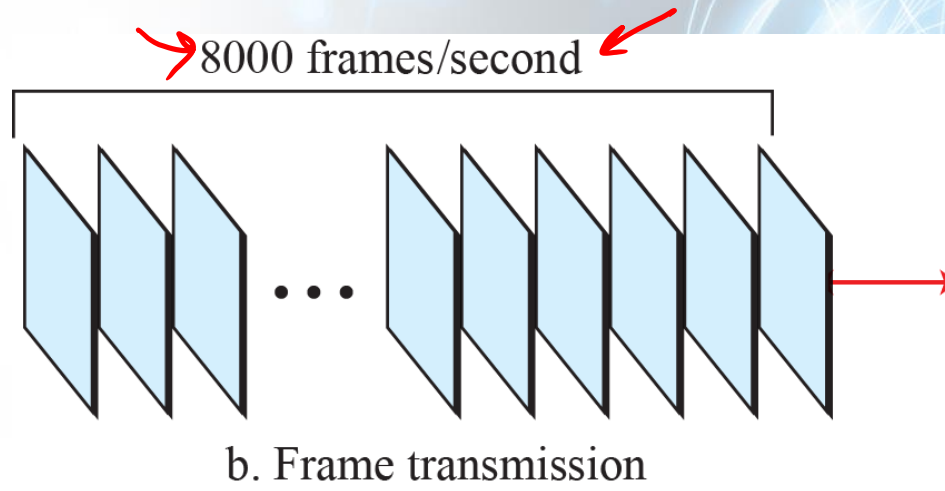
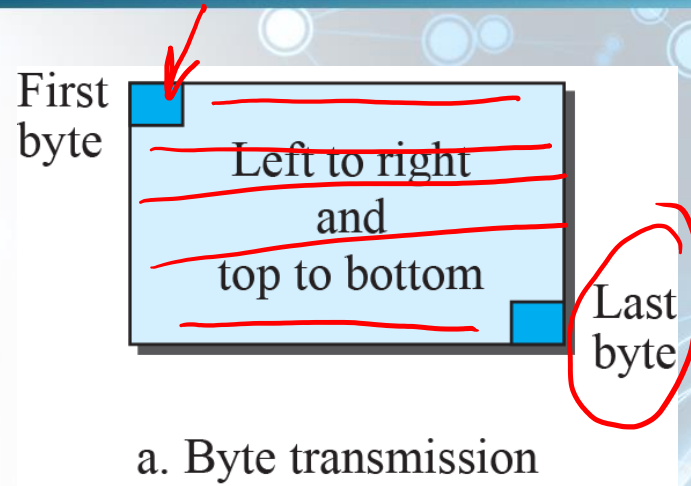
$$90 \times n = 90 \times 1$$
$$= 90 \text{ bytes}$$

810 bytes



b. STS- n frame

STS-1 Frames in Transition



Example

Find the data rate of an STS-1 signal

8000 frames per second

9 bytes \times (1 \times 90) bytes

$$\text{Data Rate} = 8000 \times 9(1 \times 90)$$

$$= \underline{\underline{51.84 \text{ Mbps}}}$$

Example

Find the data rate of an STS-3 signal

$$n=3$$

$$\text{Data Rate} = 8000 \times 9 (3 \times 90)$$

$$= 155.52 \text{ Mbps}$$

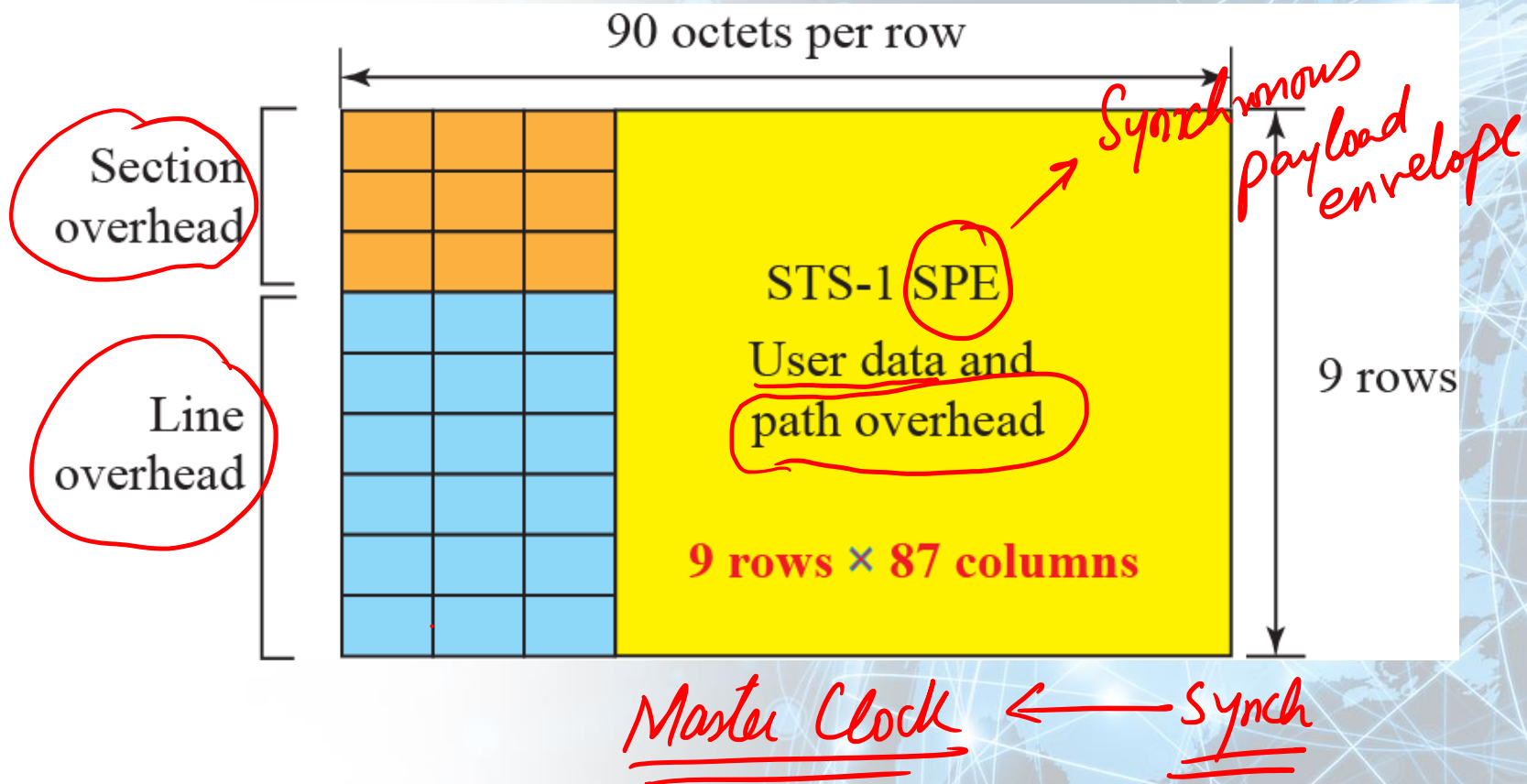


$$\text{STS-1 Data Rate} \times 3$$

$$= \text{STS-3 Data Rate.}$$

STS-1 Frame Format

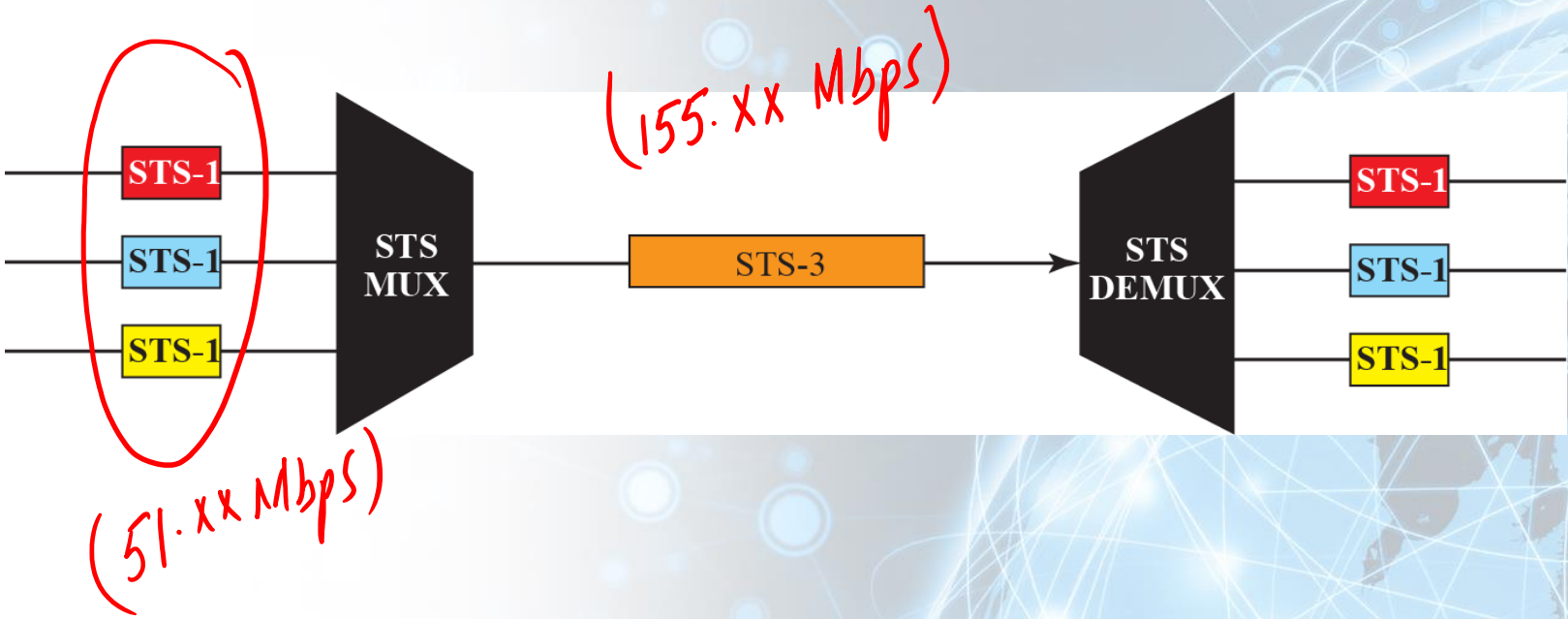
810 Bytes



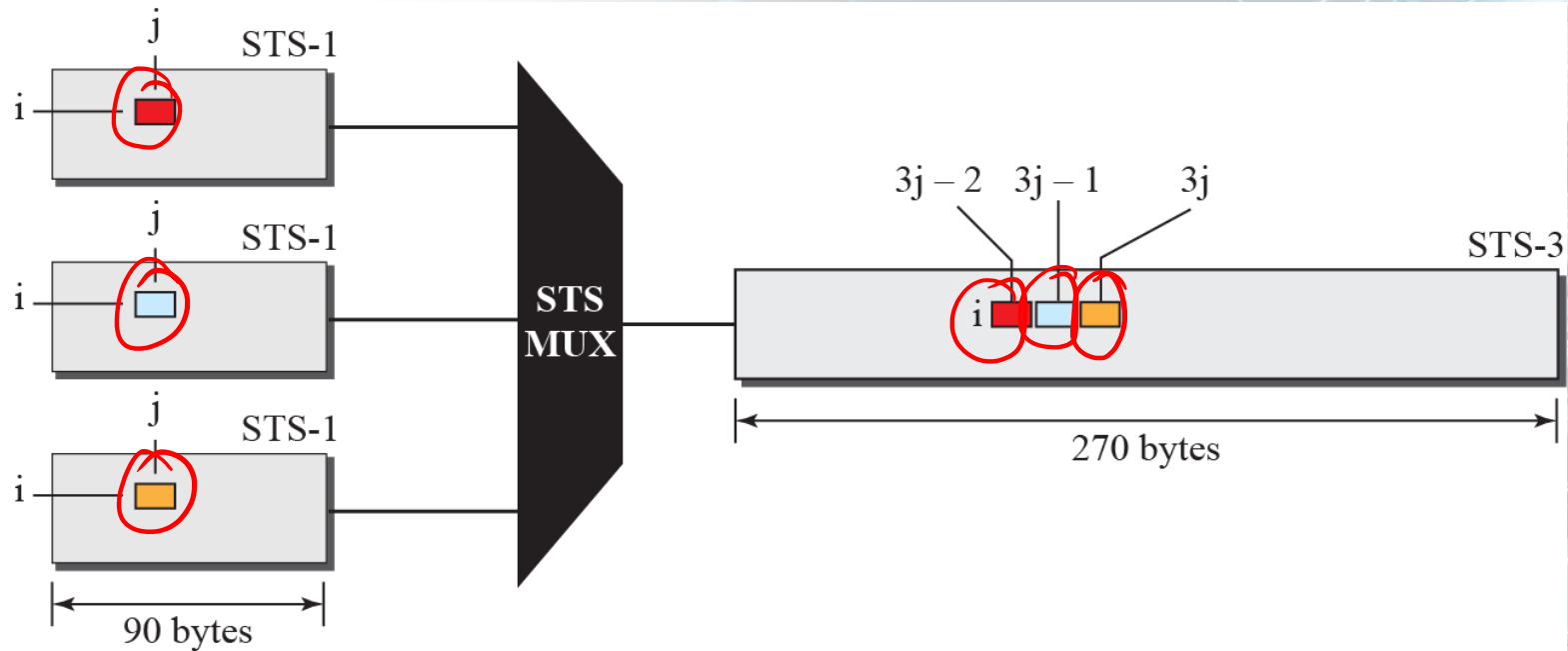
STS Multiplexing

- In SONET, frames of lower rate can be synchronously time-division multiplexed into a higher-rate frame
- For example, three STS-1 signals (channels) can be combined into one STS-3 signal (channel), four STS-3s can be multiplexed into one STS-12, and so on

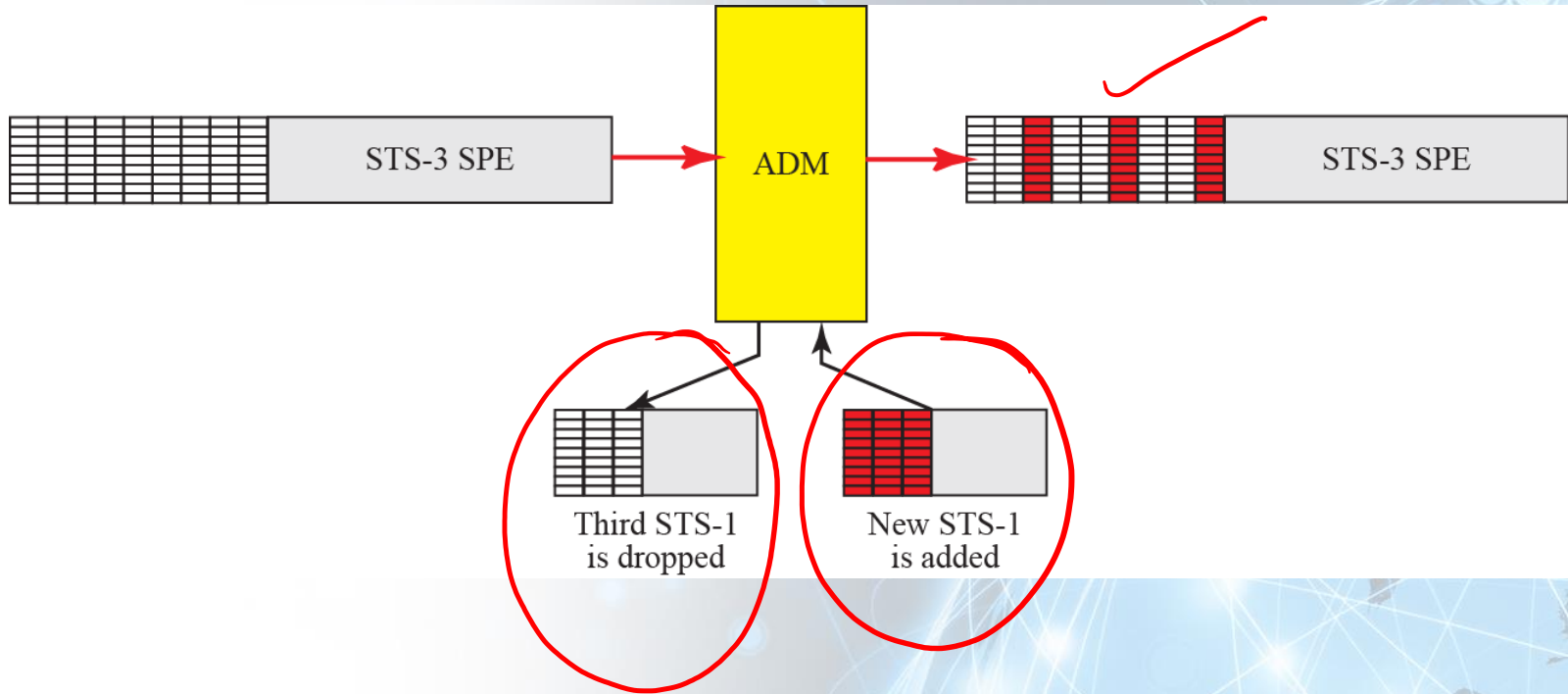
STS Multiplexing/Demultiplexing



Byte Interleaving



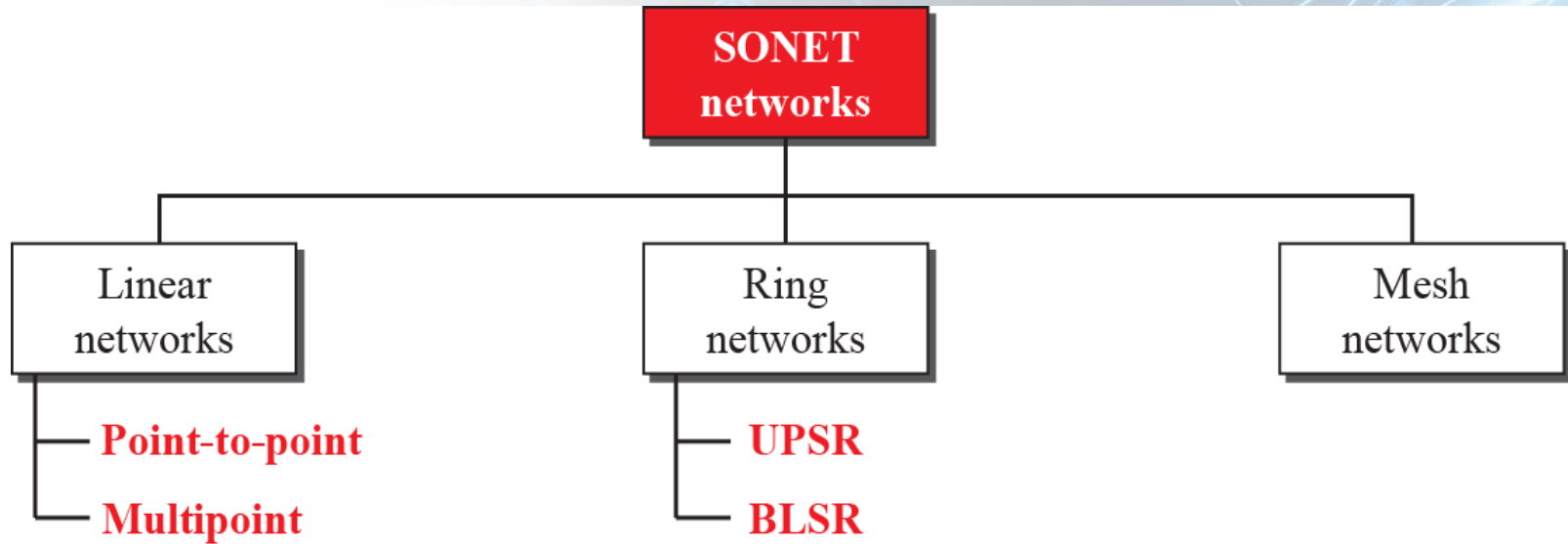
Add/Drop Multiplexer



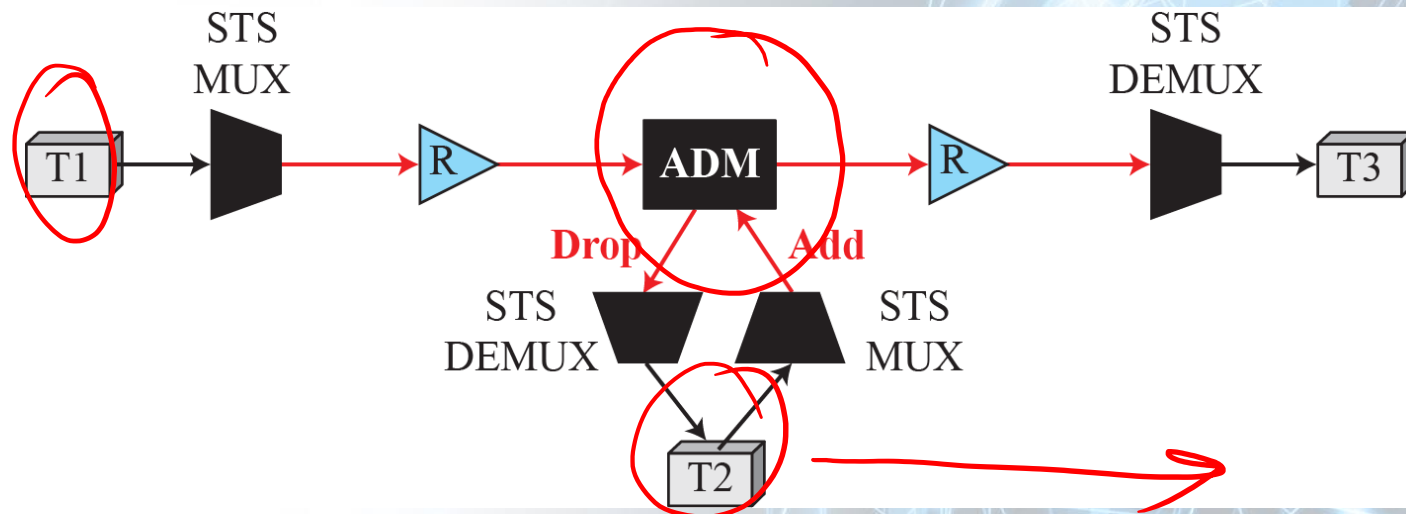
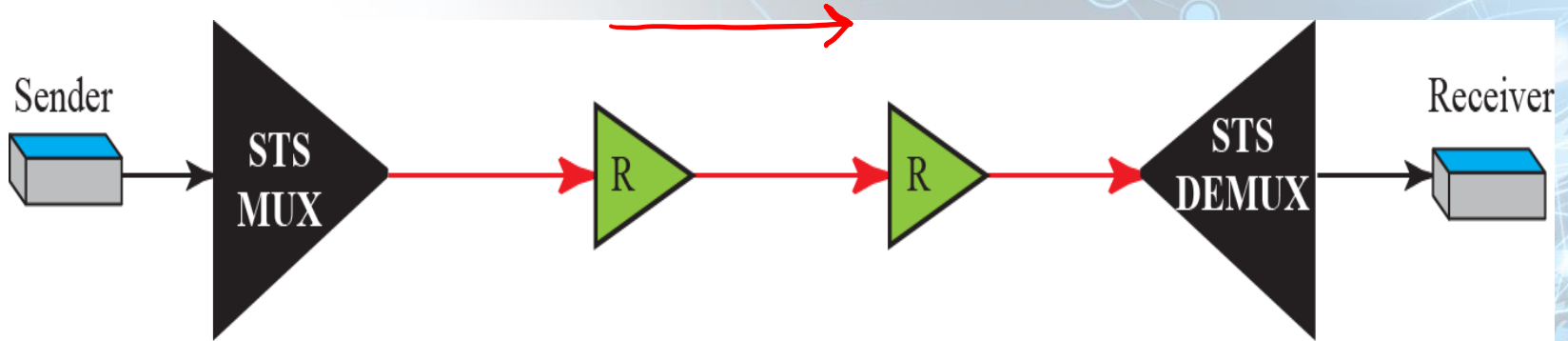
SONET Networks

- **SONET network can be used as a high-speed backbone carrying loads from other networks such as ATM or IP**
- **We can roughly divide SONET networks into three categories:**
 - ✓ **Linear Networks**
 - ✓ **Ring Networks**
 - ✓ **Mesh networks**

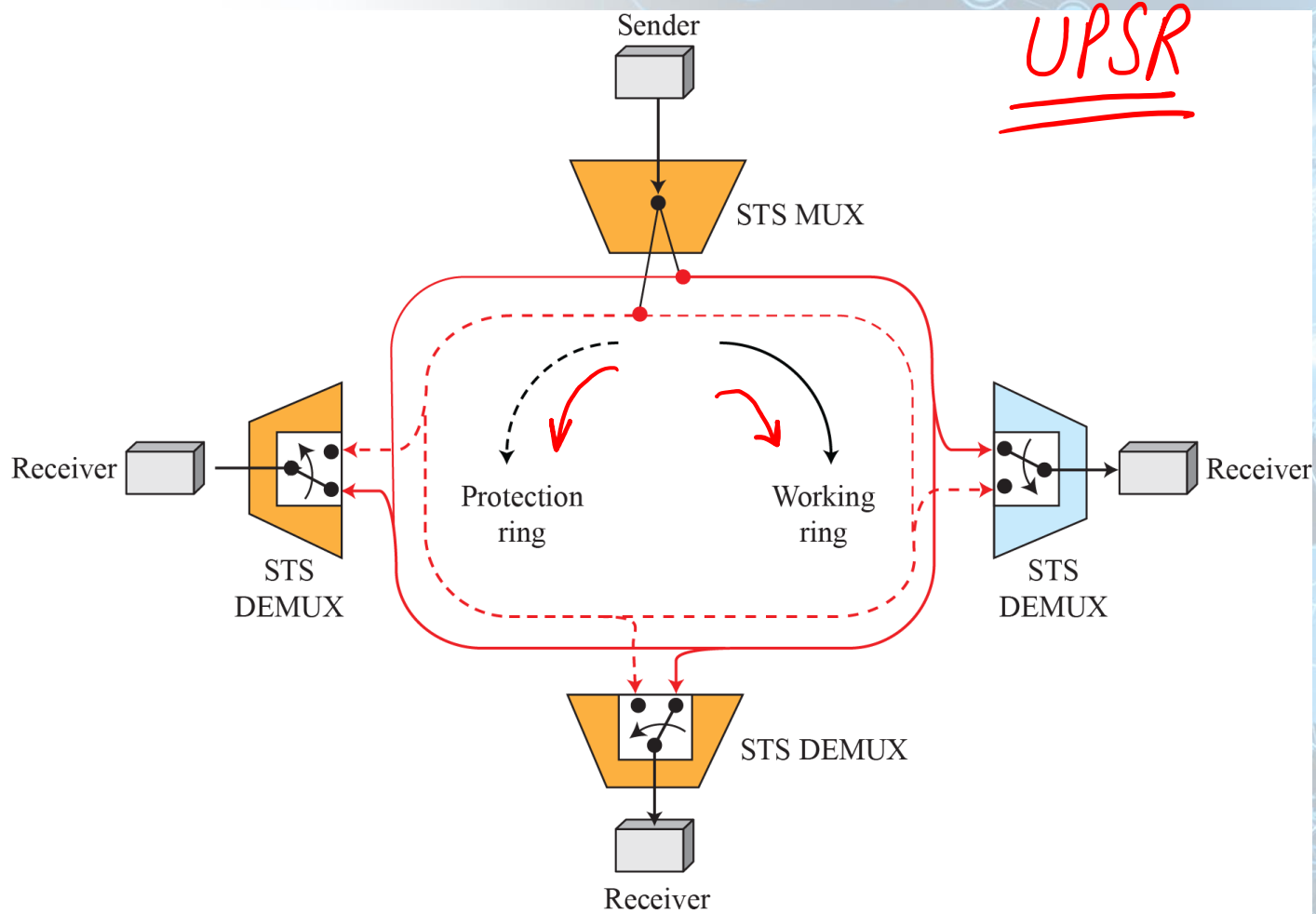
Taxonomy of SONET Networks



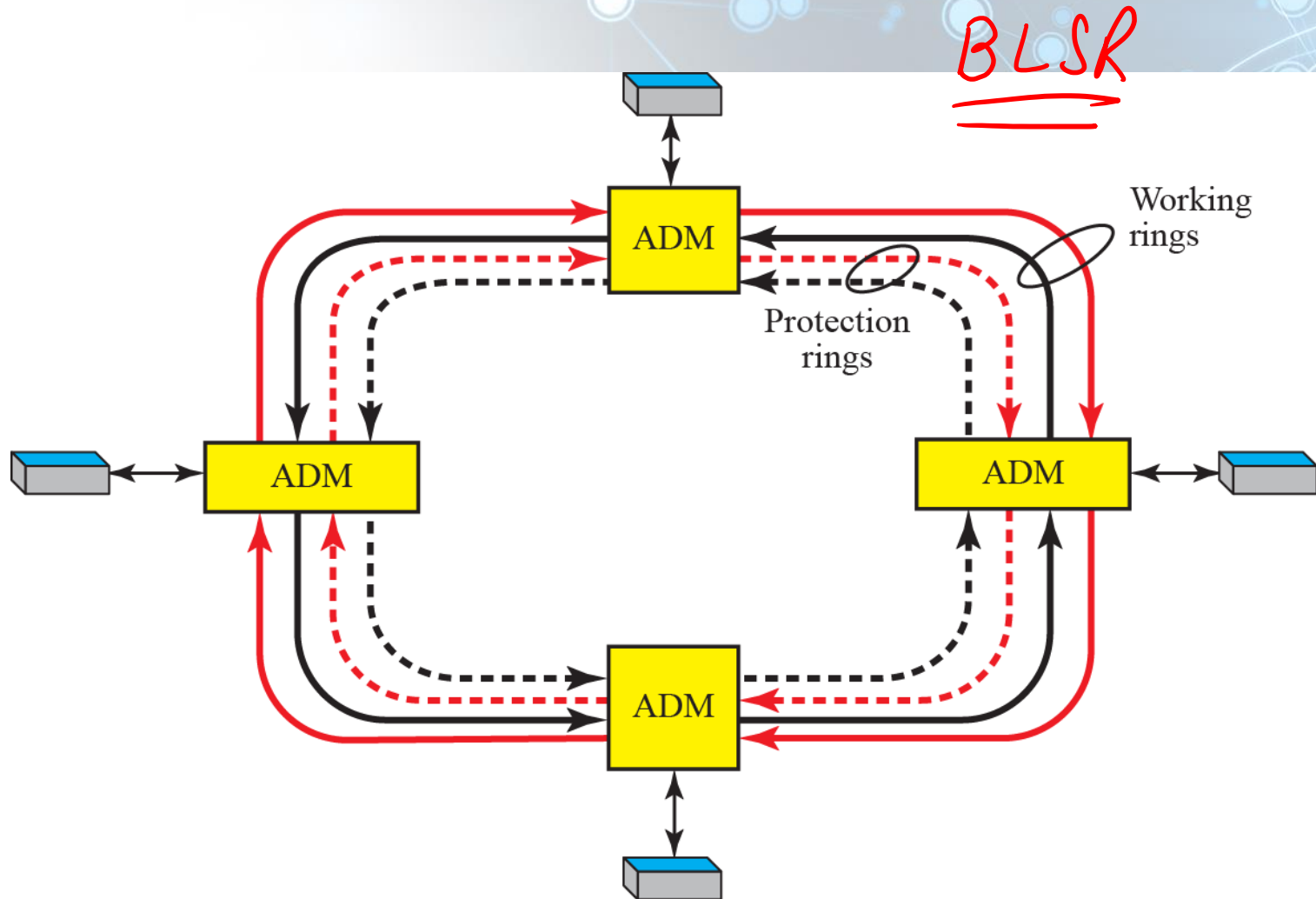
SONET Networks – Linear Networks



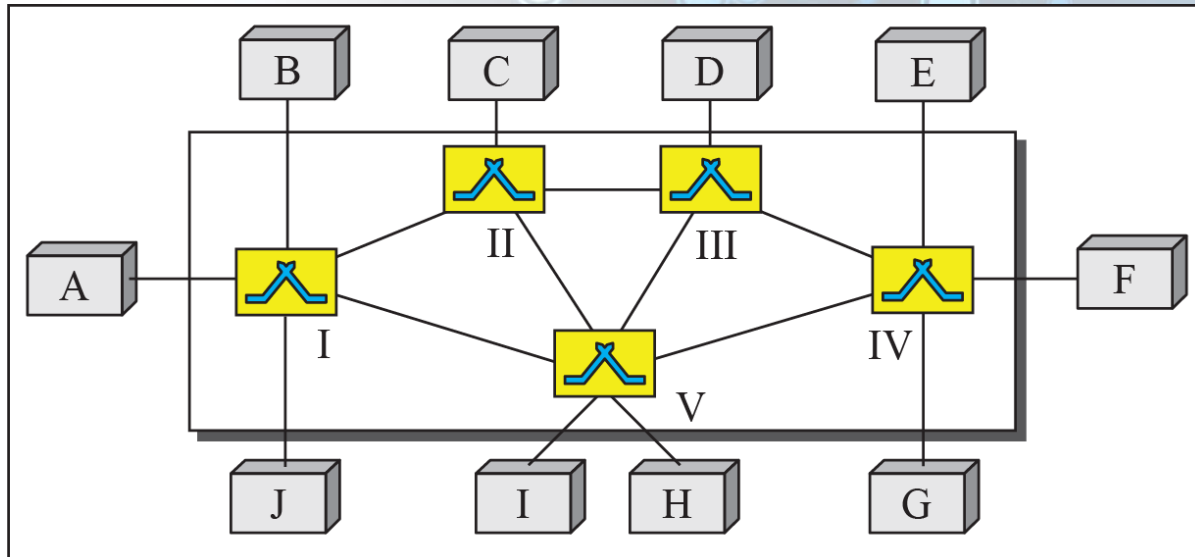
SONET Networks – Ring Networks



SONET Networks – Ring Networks

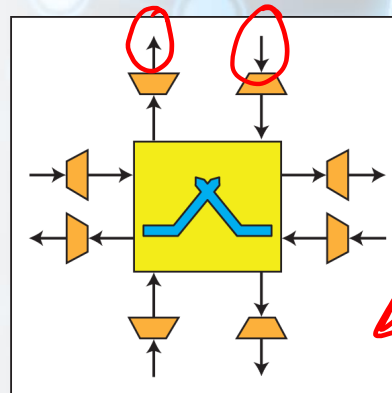


SONET Networks – Mesh Networks



Scalability
X

a. SONET mesh network



b. Cross-connect switch

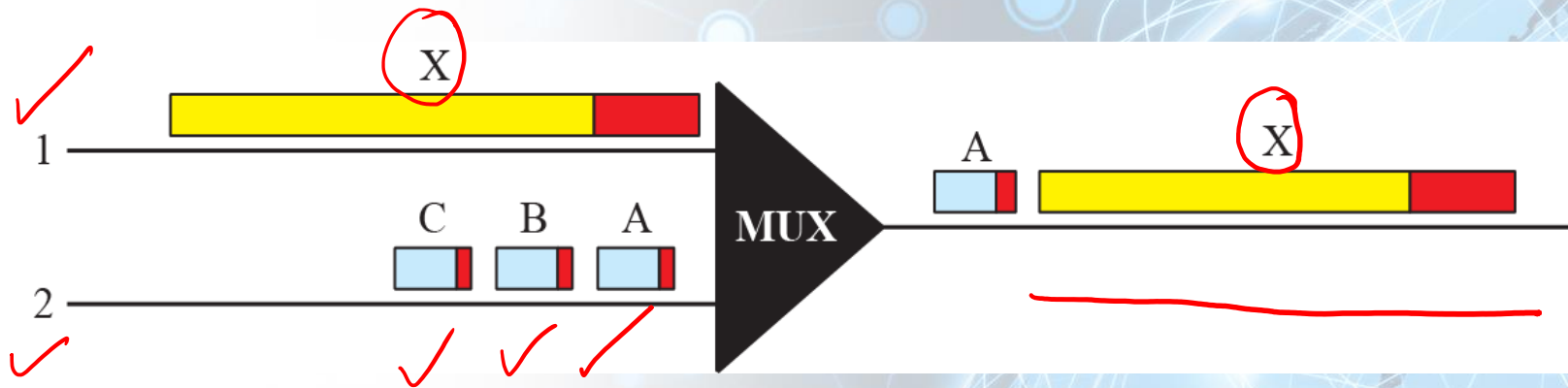
ATM

- **Asynchronous Transfer Mode (ATM) is a switched wide area network based on the cell relay protocol designed by the ATM forum**
- **The combination of ATM and SONET will allow high-speed interconnection of networks**

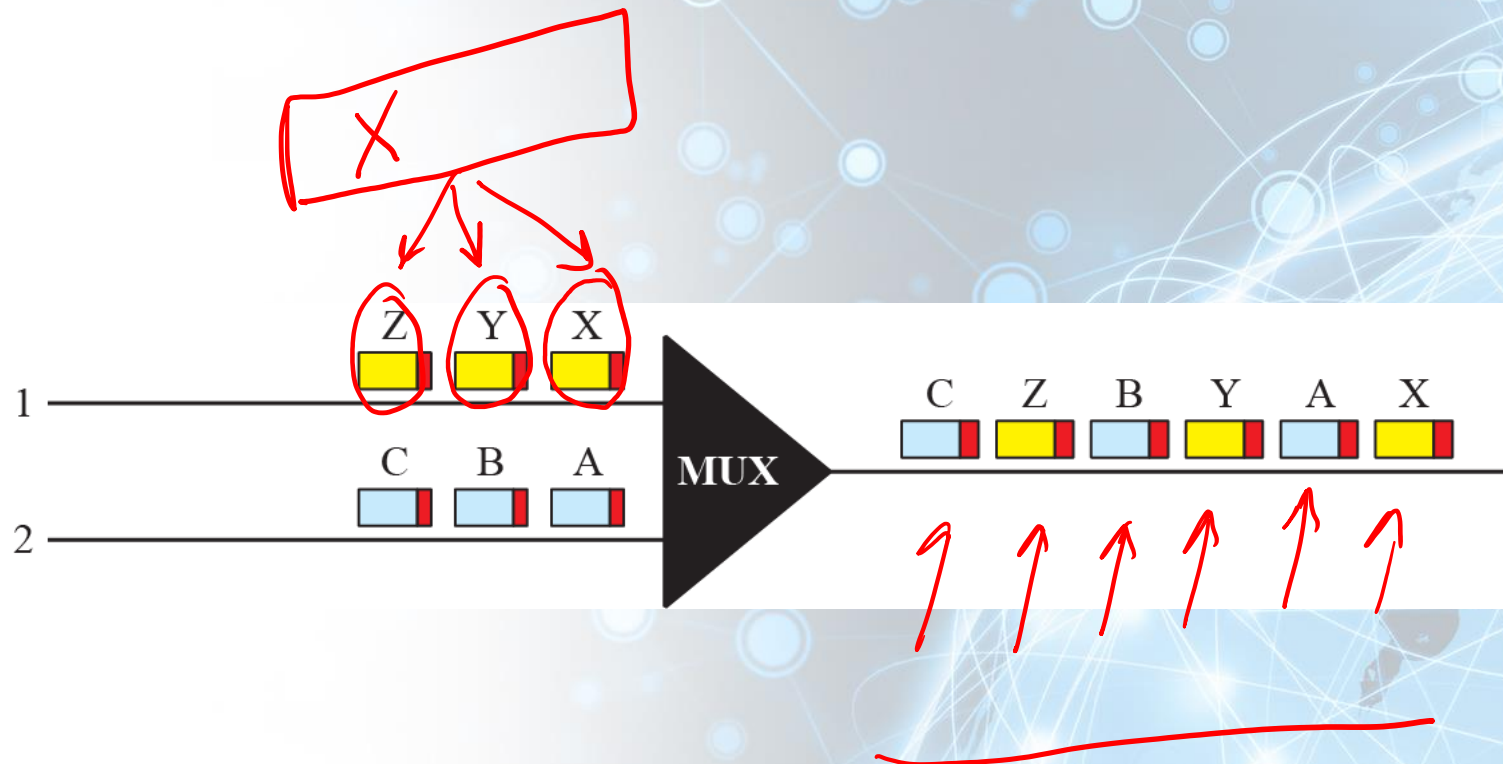
Problems

- Some of the problems associated with existing systems are:
 - ✓ Frame Networks
 - ✓ Mixed Network Traffic
- Solution
 - ✓ Cell Networks
 - ✓ Asynchronous TDM

Multiplexing using Different Frame Size

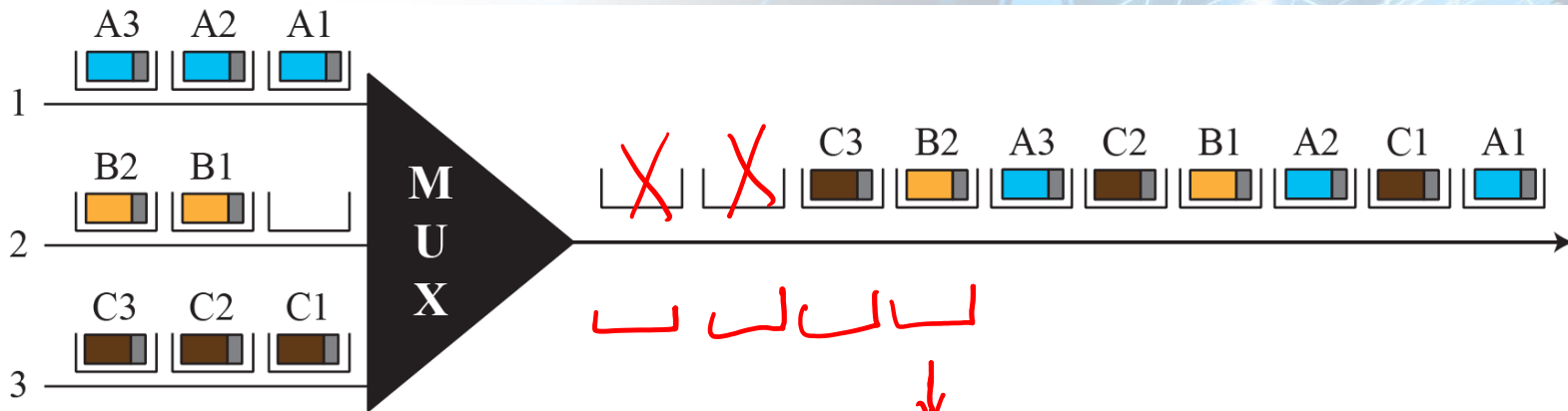


Multiplexing using Cells



ATM Multiplexing

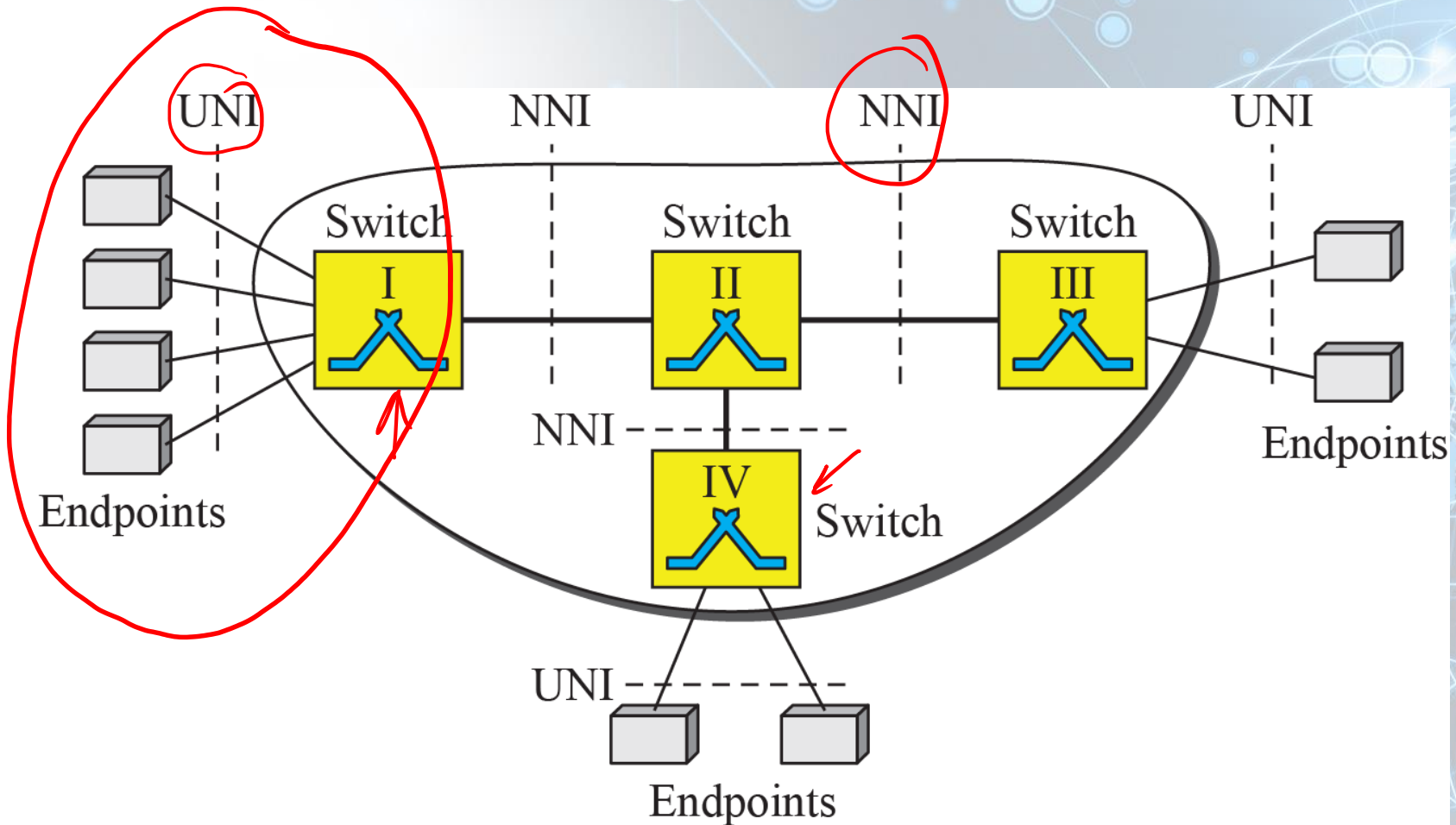
Asynchronous TDM



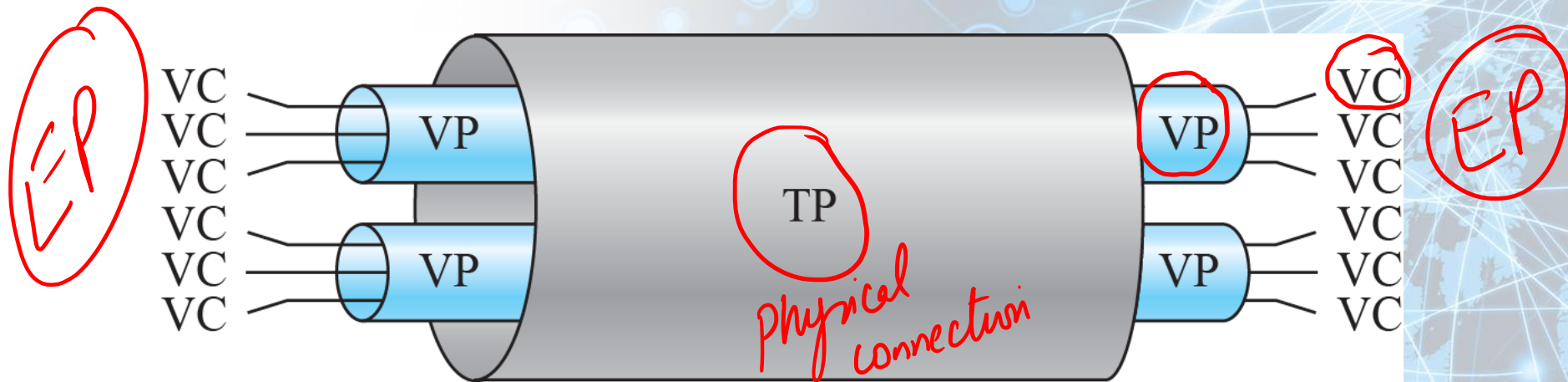
Architecture

- **ATM is a cell-switched network**
- **The user access devices, called the endpoints, are connected through a user-to-network interface (UNI) to the switches inside the network**
- **The switches are connected through network-to-network interfaces (NNIs)**

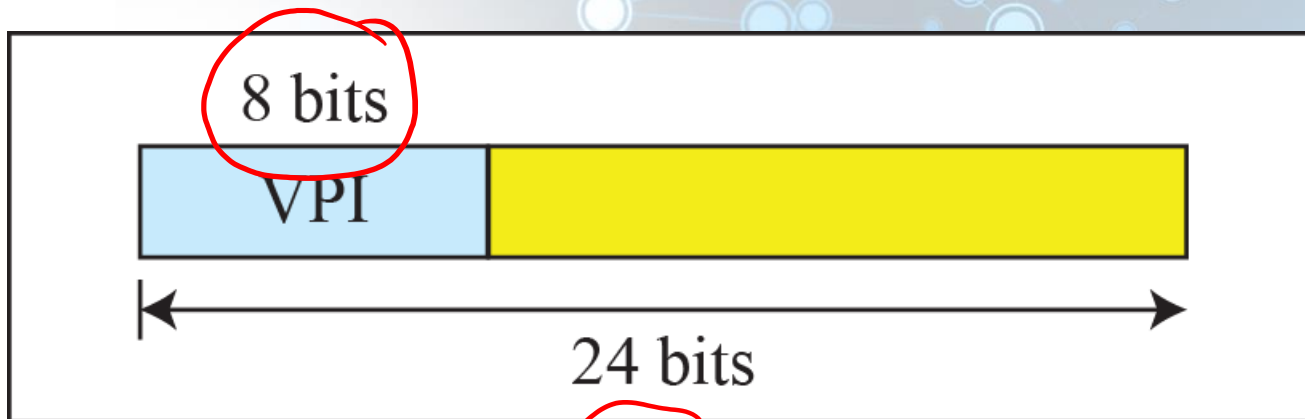
Architecture of an ATM Network



TP, VPs, and VCs

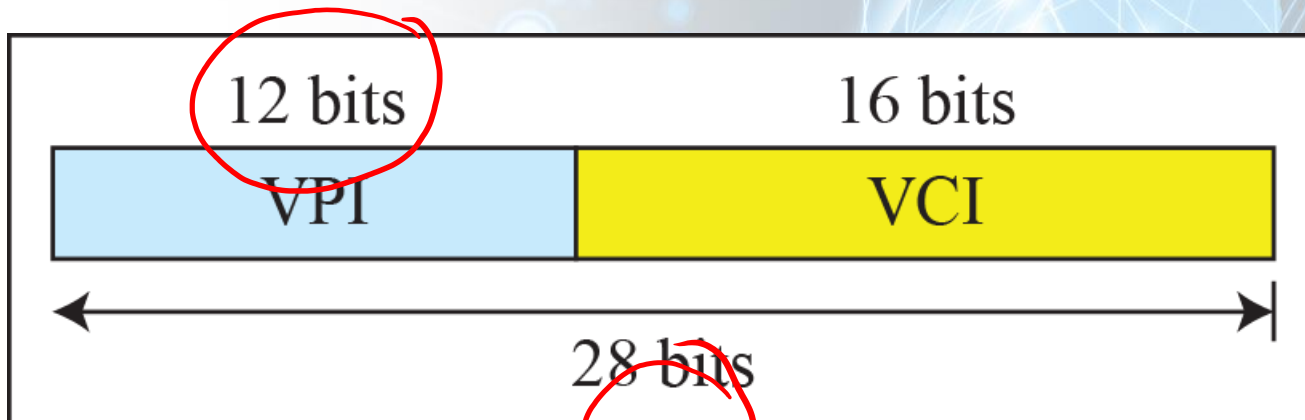


Virtual connection identifiers in UNIs & NNIs



24
bits

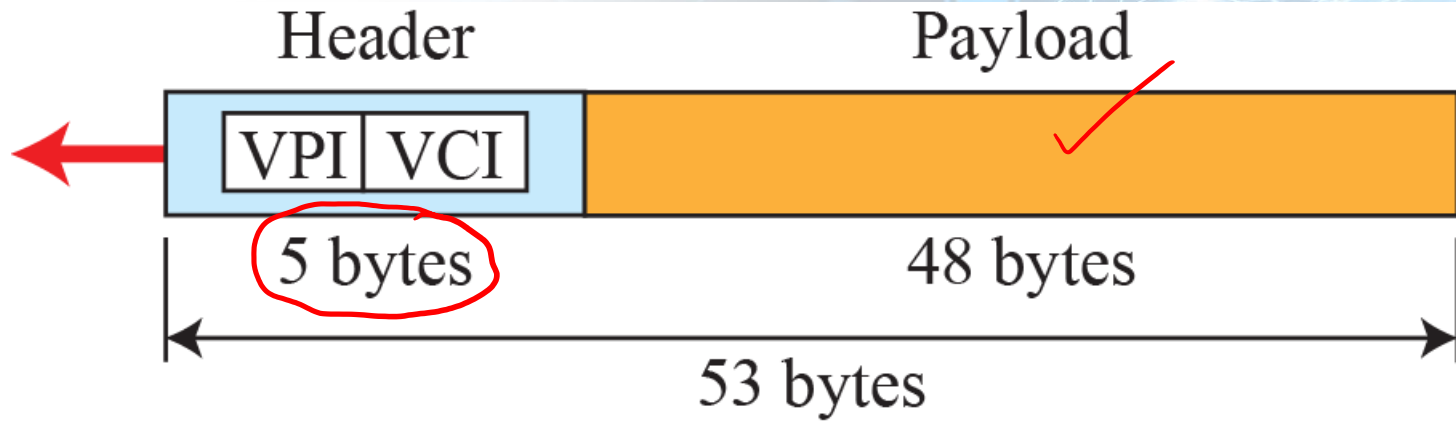
a. VPI and VCI in a UNI



28
bits

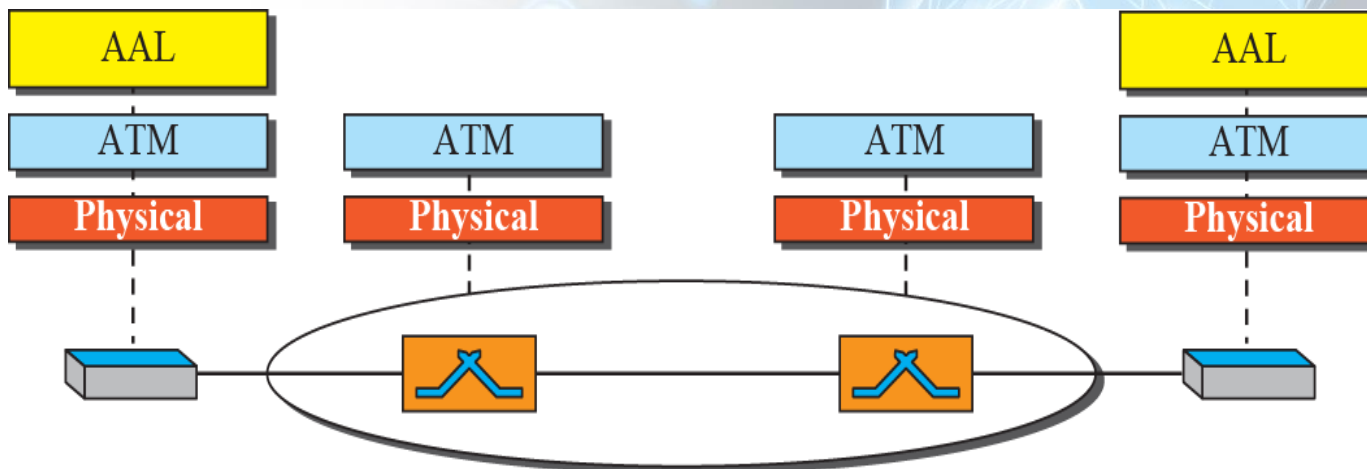
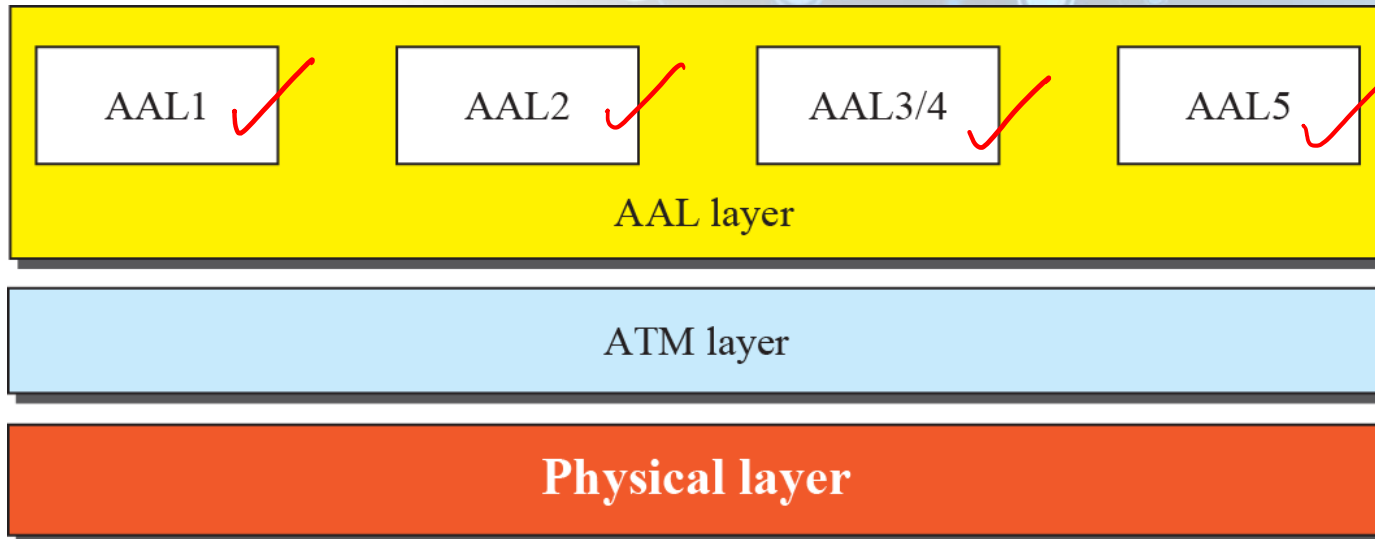
b. VPI and VCI in an NNI

An ATM Cell



ATM cell \Rightarrow 53 Bytes

ATM Layers



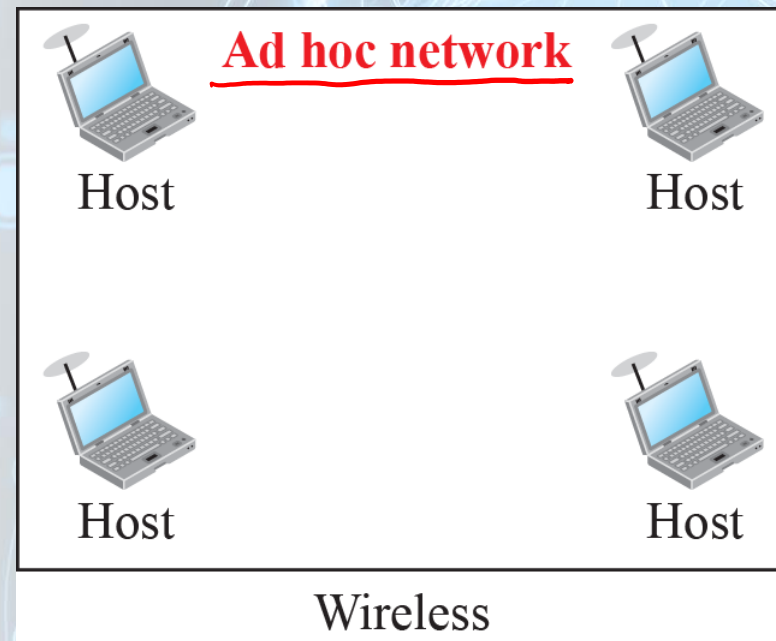
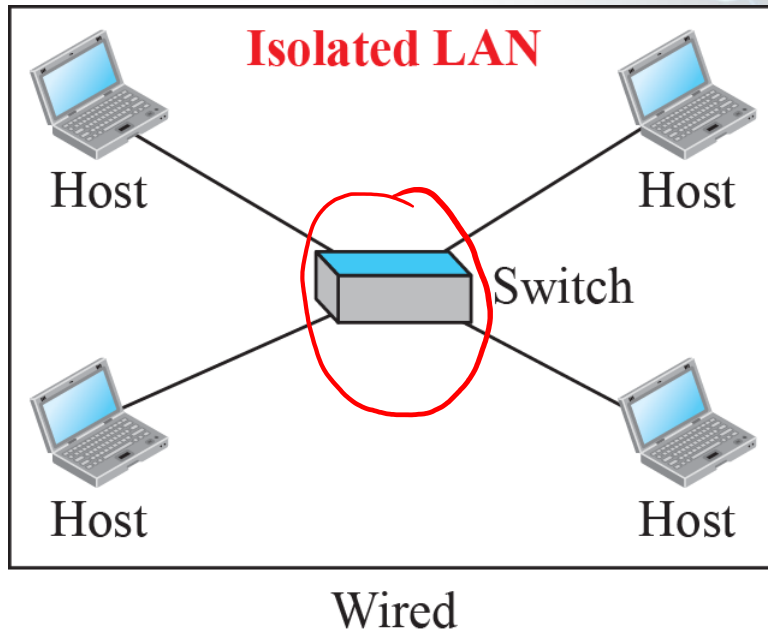
Introduction

- **Wireless communication is one of the fastest-growing technologies**
- **The demand for connecting devices without the use of cables is increasing everywhere**
- **Wireless LANs can be found on college campuses, in office buildings, and in many public areas**

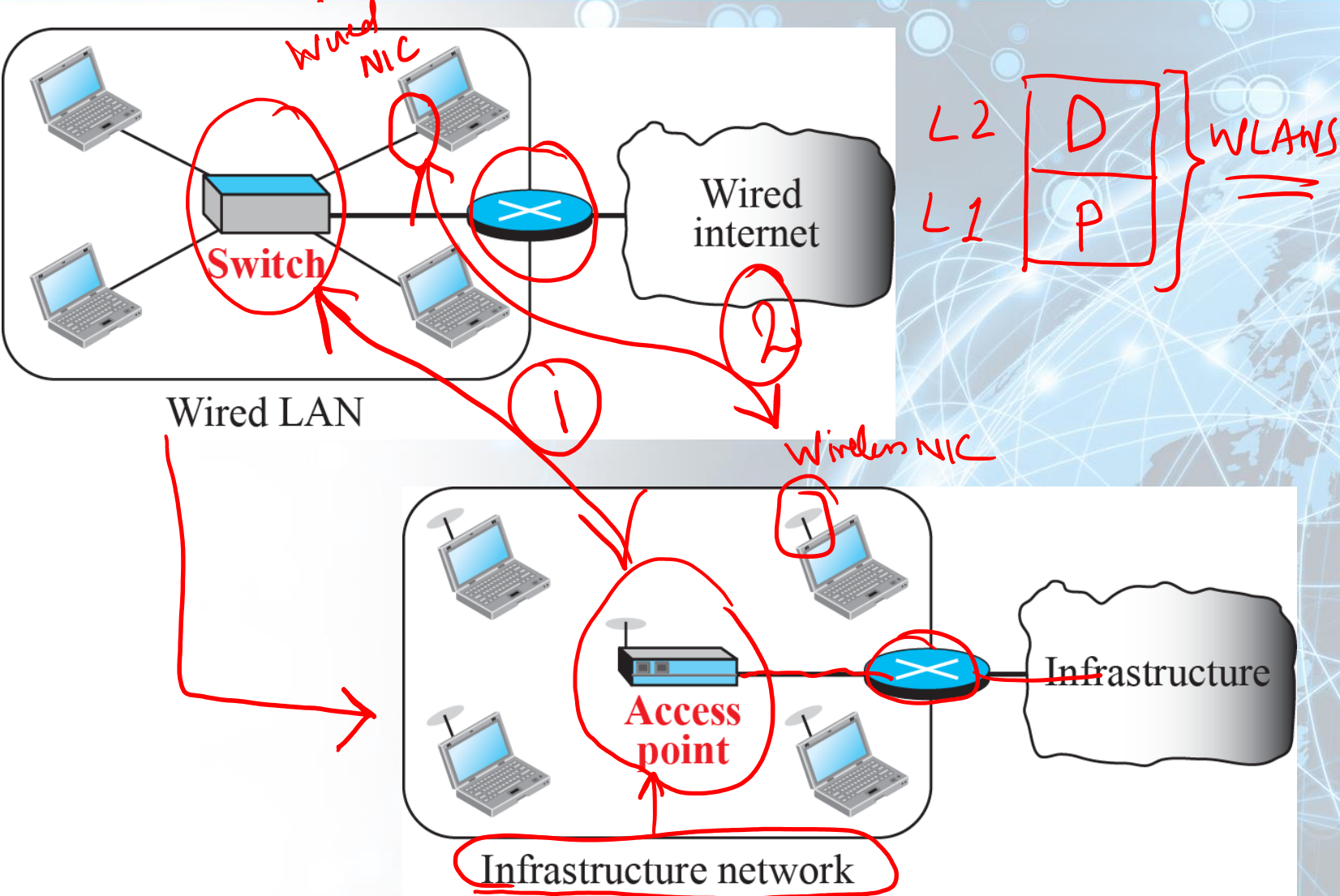
Architectural Comparison

- **Architecture comparison of wired and wireless LANs**
 - ✓ **Medium**
 - ✓ **Hosts**
 - ✓ **Isolated LANs**
 - ✓ **Connection to other Networks**
 - ✓ **Moving between Environments**

Isolated LANs: Wired versus Wireless



Connection of a Wired/Wireless LAN to other networks



Characteristics of a Wireless LAN

- **Several characteristics of wireless LANs either do not apply to wired LANs or the existence of these is negligible and can be ignored**
 - ✓ **Attenuation**
 - ✓ **Interference**
 - ✓ **Multipath Propagation**
 - ✓ **Error**

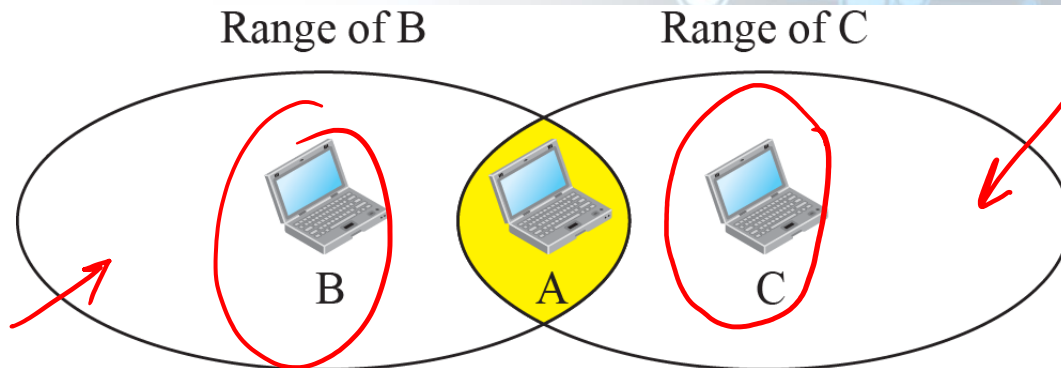
Access Control

- Most important issue in a wireless LAN is how a wireless host can get access to the shared medium (air)
- CSMA/CD does not work in wireless LANs for three reasons:
 1. Wireless hosts don't have power to send and receive at the same time

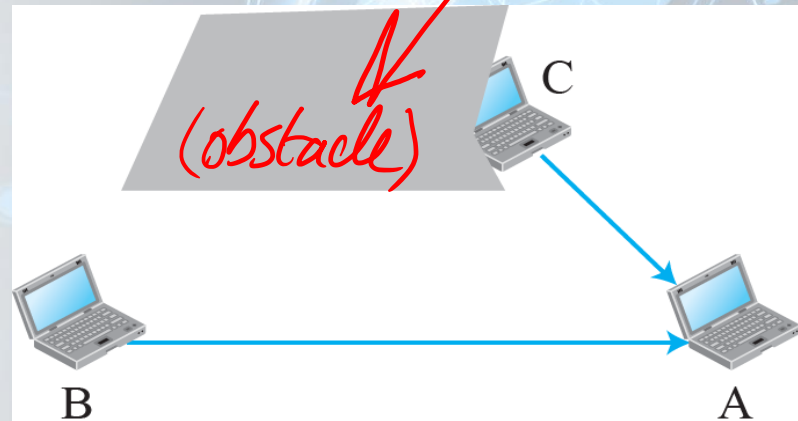
Access Control

- 2. The hidden station problem prevents collision detection**
- 3. The distance between stations can be large**

Hidden Station Problem



a. Stations B and C are not in each other's range.



b. Stations B and C are hidden from each other.

IEEE 802.11 PROJECT

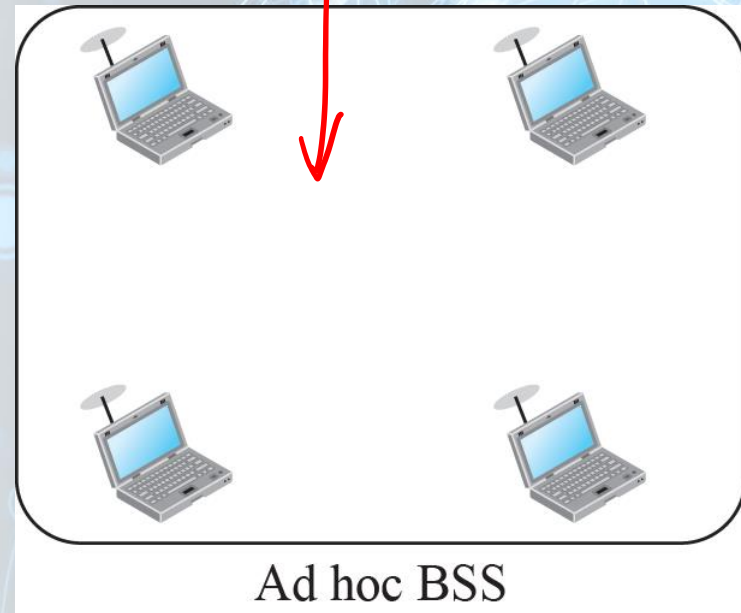
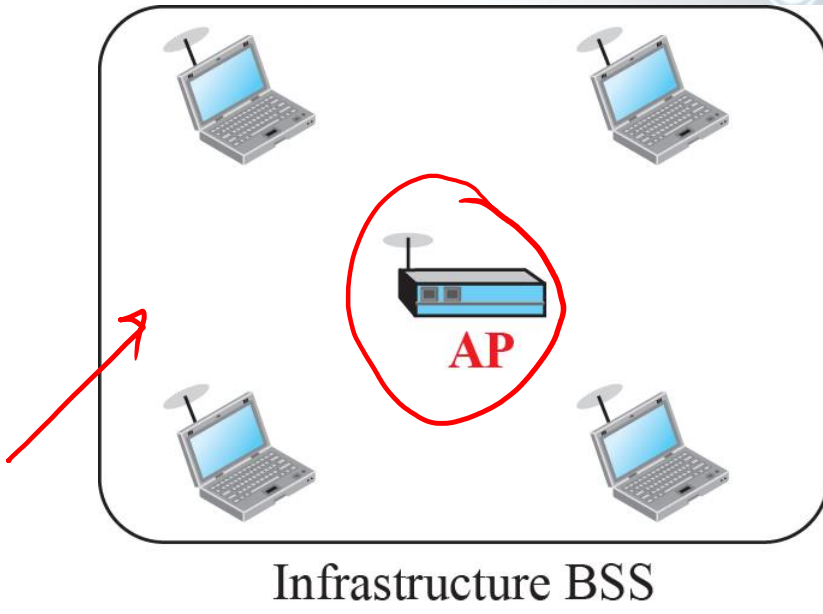
- IEEE has defined the specifications for a wireless LAN, called IEEE 802.11, which covers the physical and data-link layers
- It is sometimes called Wireless Ethernet
- The term WiFi (short for wireless fidelity) as a synonym for wireless LAN (certified by WiFi alliance)

Architecture

- The standard defines two kinds of services:
 - ✓ The basic service set (BSS); and
 - ✓ The Extended service set (ESS)

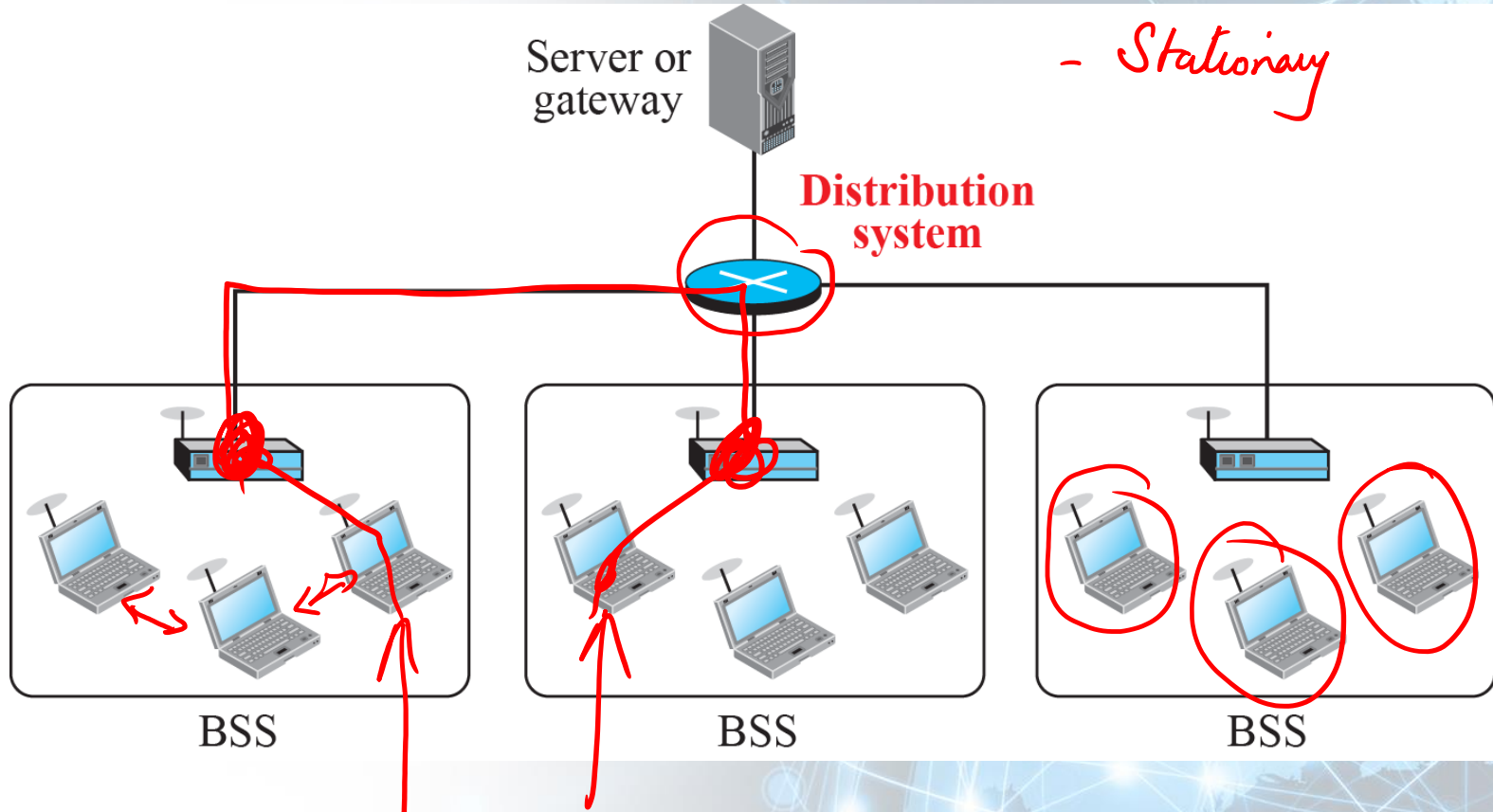
Basic Service Sets (BSSs)

Without AP → ad hoc network
With AP → Infrastructure BSS



Extended Service Set (ESS)

- Mobile
- Stationary



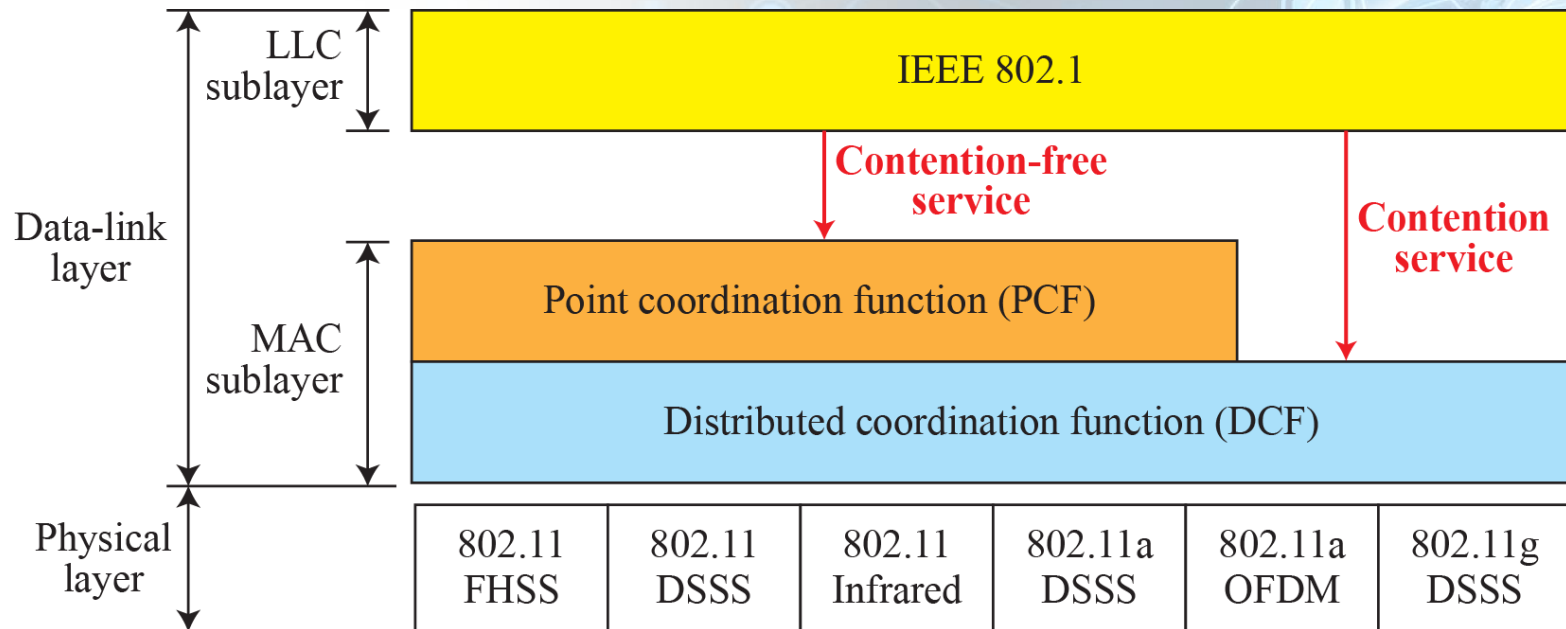
Types of Stations

- **No-Transition Mobility**
- **BSS-Transition Mobility**
- **ESS-Transition Mobility**

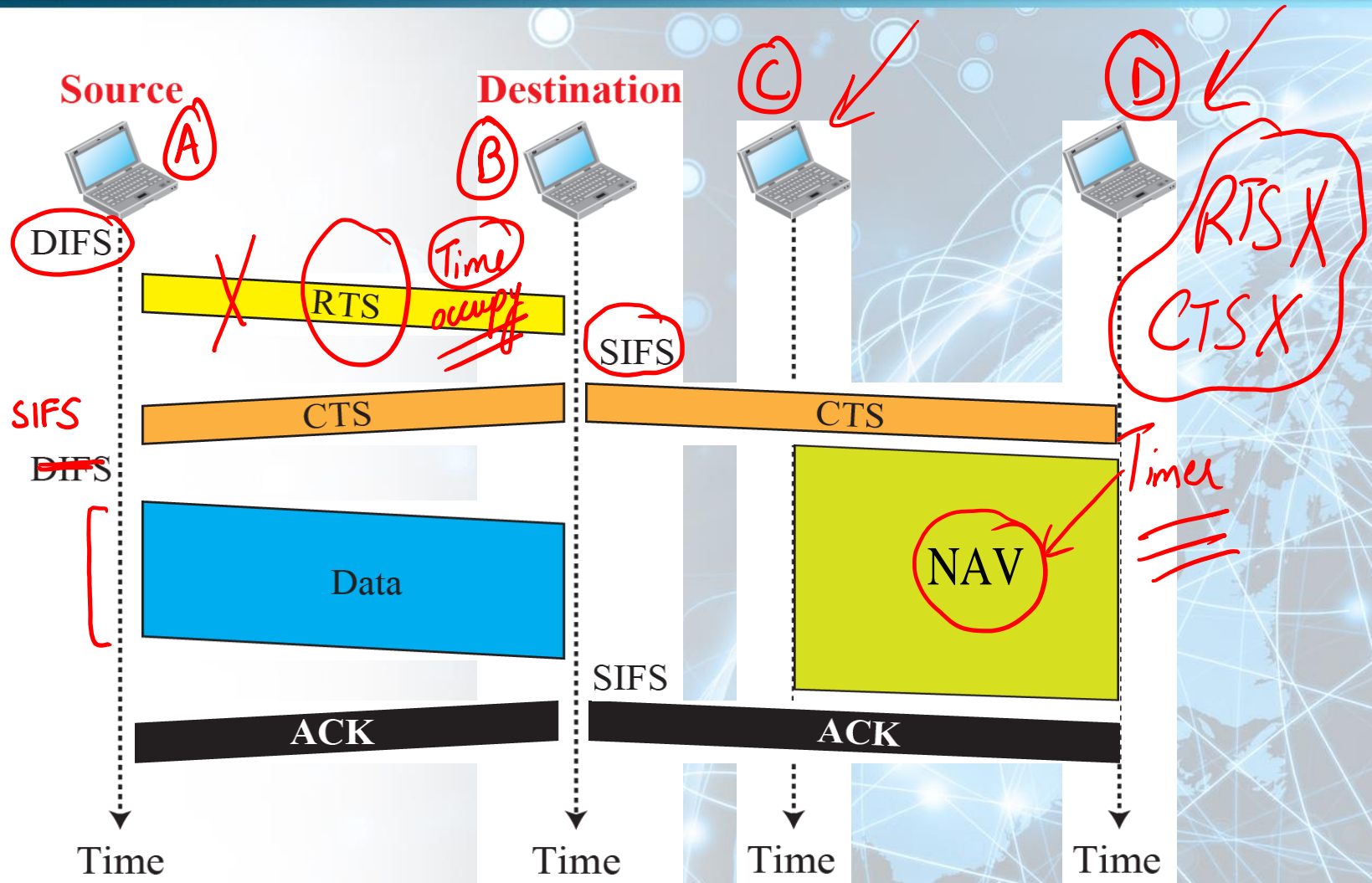
MAC Sub-layer

- **IEEE 802.11 defines two MAC sub-layers:**
 - ✓ **The Distributed Coordination Function (DCF) ; and**
 - ✓ **The Point Coordination Function (PCF)**

MAC Layers in IEEE 802.11 Standard



CSMA/CA and NAV



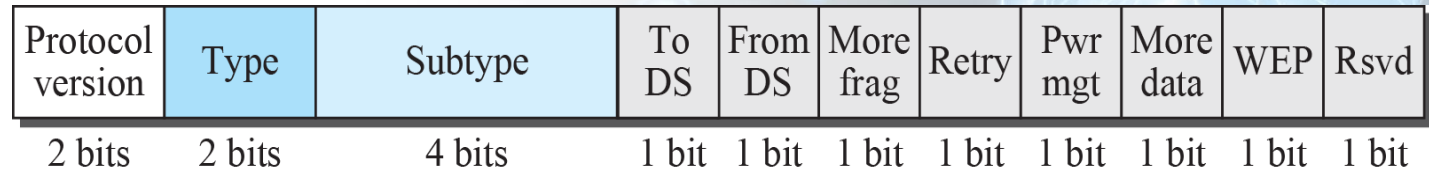
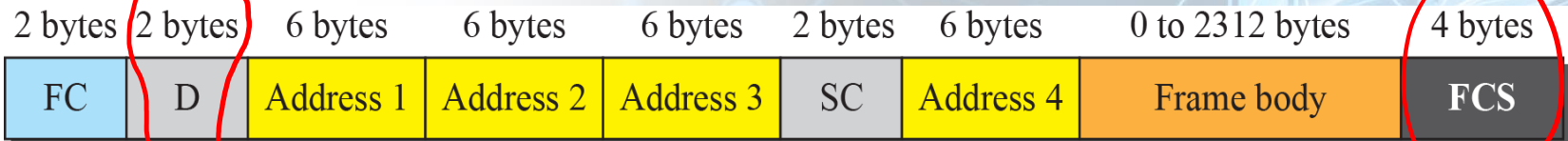
MAC Sub-layer

- **IEEE 802.11 defines two MAC sub-layers:**
 - ✓ **The Distributed Coordination Function (DCF) ; and**
 - ✓ **The Point Coordination Function (PCF)**

Frame Format

** Fragmentation*

NAV



CRC-32

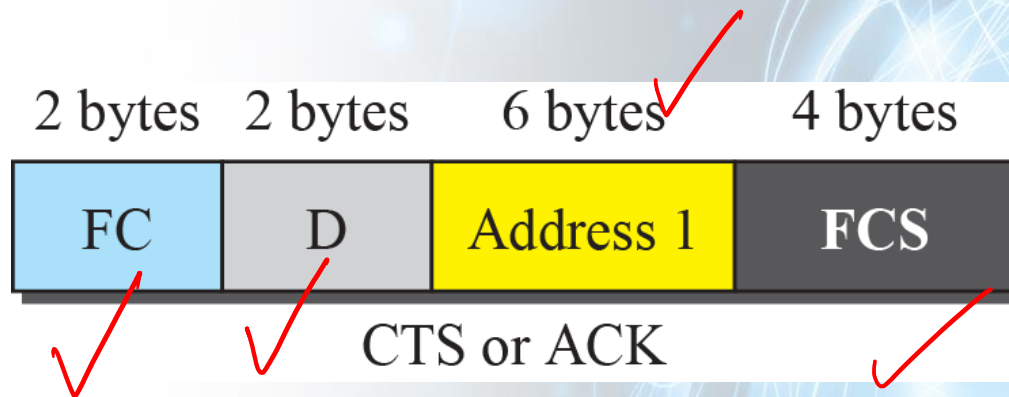
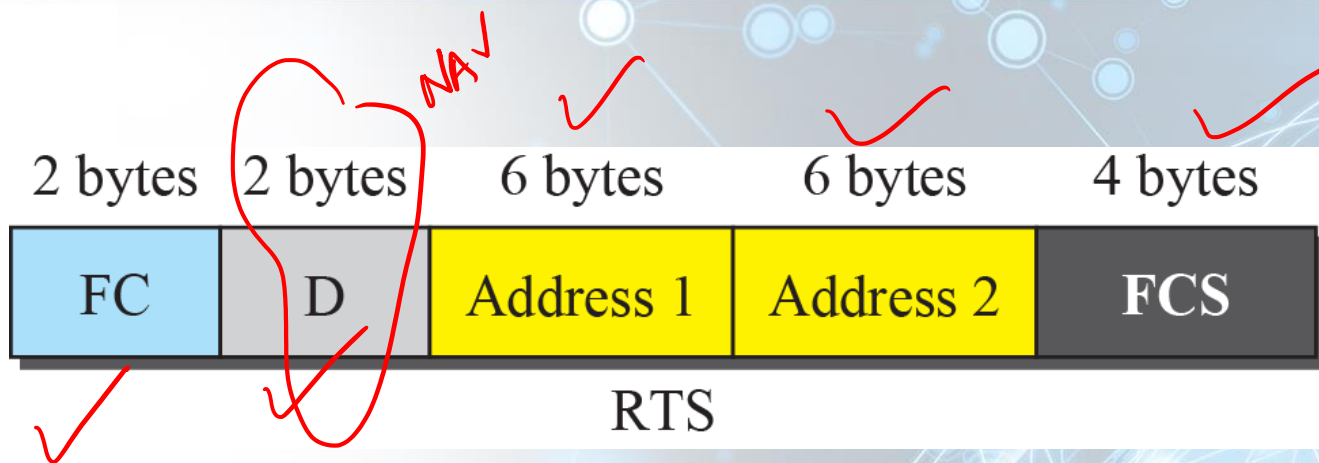
Subfields in FC field

<i>Field</i>	<i>Explanation</i>
Version	Current version is 0
Type	Type of information: management (00), control (01), or data (10)
Subtype	Subtype of each type (see Table 6.2)
To DS	Defined later
From DS	Defined later
More flag	When set to 1, means more fragments
Retry	When set to 1, means retransmitted frame
Pwr mgt	When set to 1, means station is in power management mode
More data	When set to 1, means station has more data to send
WEP	Wired equivalent privacy (encryption implemented)
Rsvd	Reserved

Frame Types

- **Management Frames**
- **Control Frames**
- **Data Frames**

Control Frames



Values of Subfields in Control Frames

<i>Subtype</i>	<i>Meaning</i>
1011	Request to send (RTS) ✓
1100	Clear to send (CTS) ✓
1101	Acknowledgment (ACK) ✓

Physical Layer

- All physical implementations, except the infrared, operate in the industrial, scientific, and medical (ISM) band, which defines 3 unlicensed bands in 3 ranges:
 - ✓ 902–928 MHz
 - ✓ 2.400–4.835 GHz
 - ✓ 5.725–5.850 GHz

Specifications

<i>IEEE</i>	<i>Technique</i>	<i>Band</i>	<i>Modulation</i>	<i>Rate (Mbps)</i>
802.11	FHSS ✓	2.400–4.835 GHz	FSK ✓	1 and 2 ✓
	DSSS ✓	2.400–4.835 GHz	PSK ✓	1 and 2 ✓
	None ✓	Infrared	PPM ✓	1 and 2 ✓
802.11a	OFDM	5.725–5.850 GHz	PSK or QAM	6 to 54
802.11b	DSSS	2.400–4.835 GHz	PSK	5.5 and 11
802.11g	OFDM	2.400–4.835 GHz	Different	22 and 54
802.11n	OFDM	5.725–5.850 GHz	Different	600

BLUETOOTH

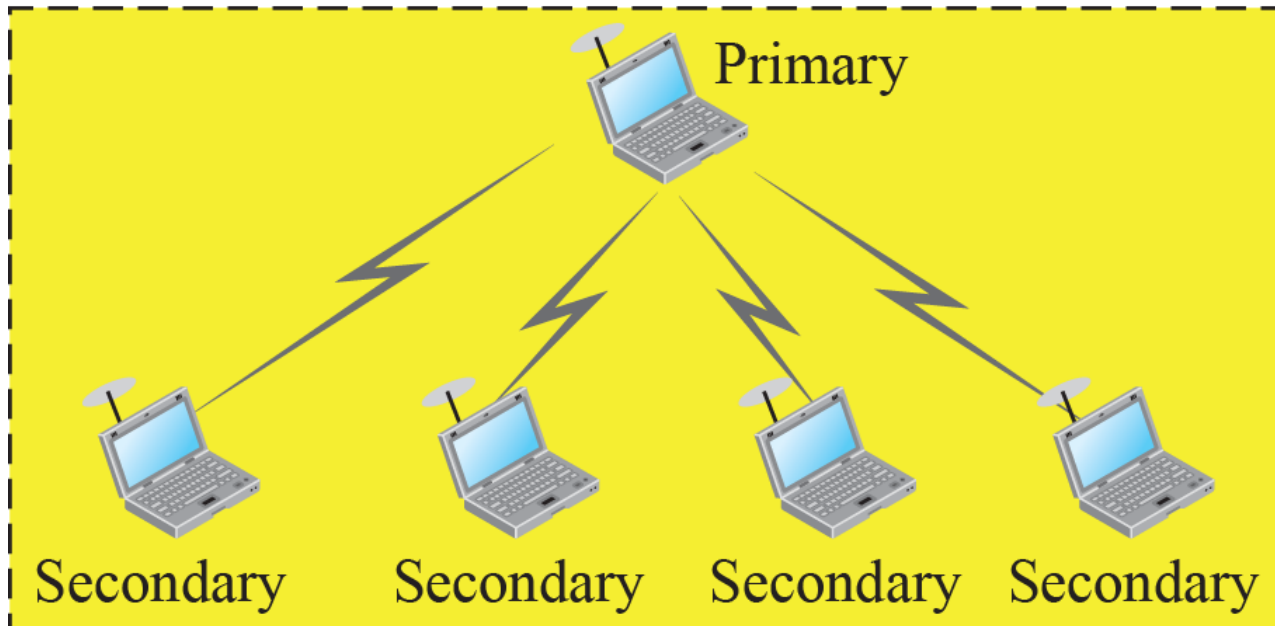
- **Bluetooth is a wireless LAN technology designed to connect devices of different functions when they are at a short distance from each other**
- **A Bluetooth LAN is an ad hoc network**
- **The devices, sometimes called gadgets, find each other and make a network called a Piconet**

Architecture

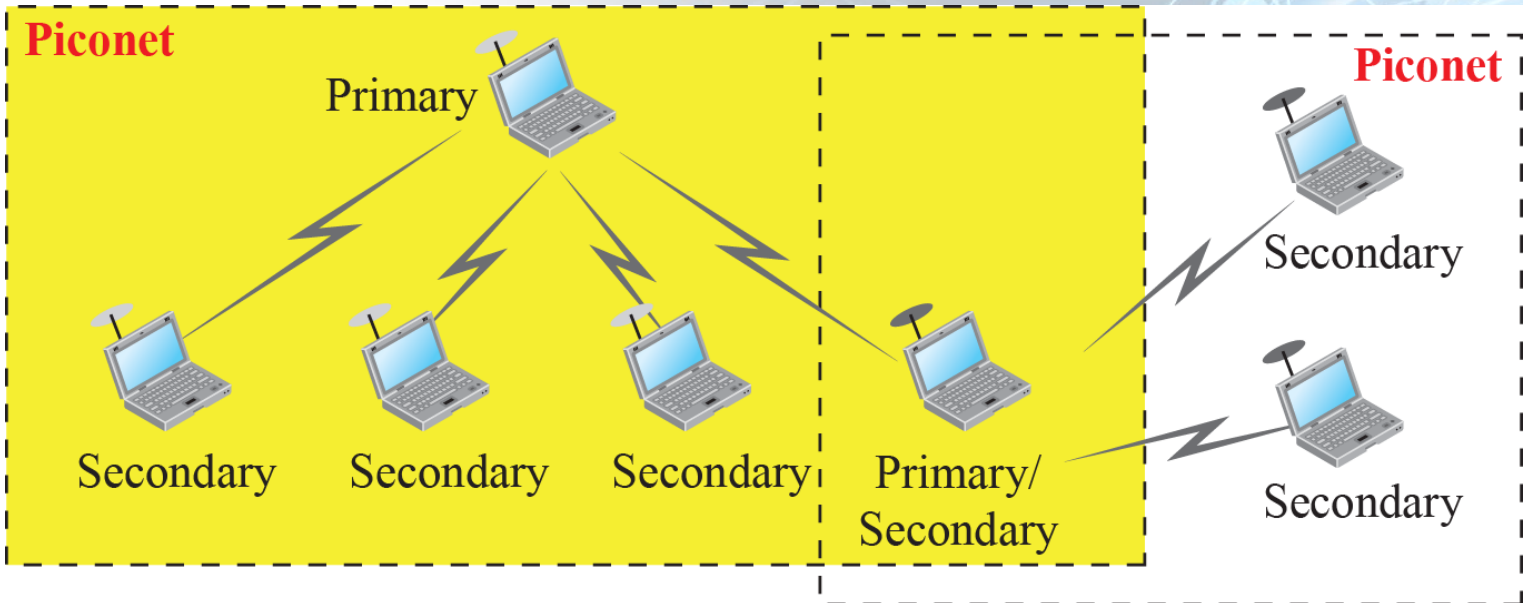
- **Bluetooth defines two types of networks:**
 - ✓ **Piconet**
 - ✓ **Scatternet**

Piconet

Piconet



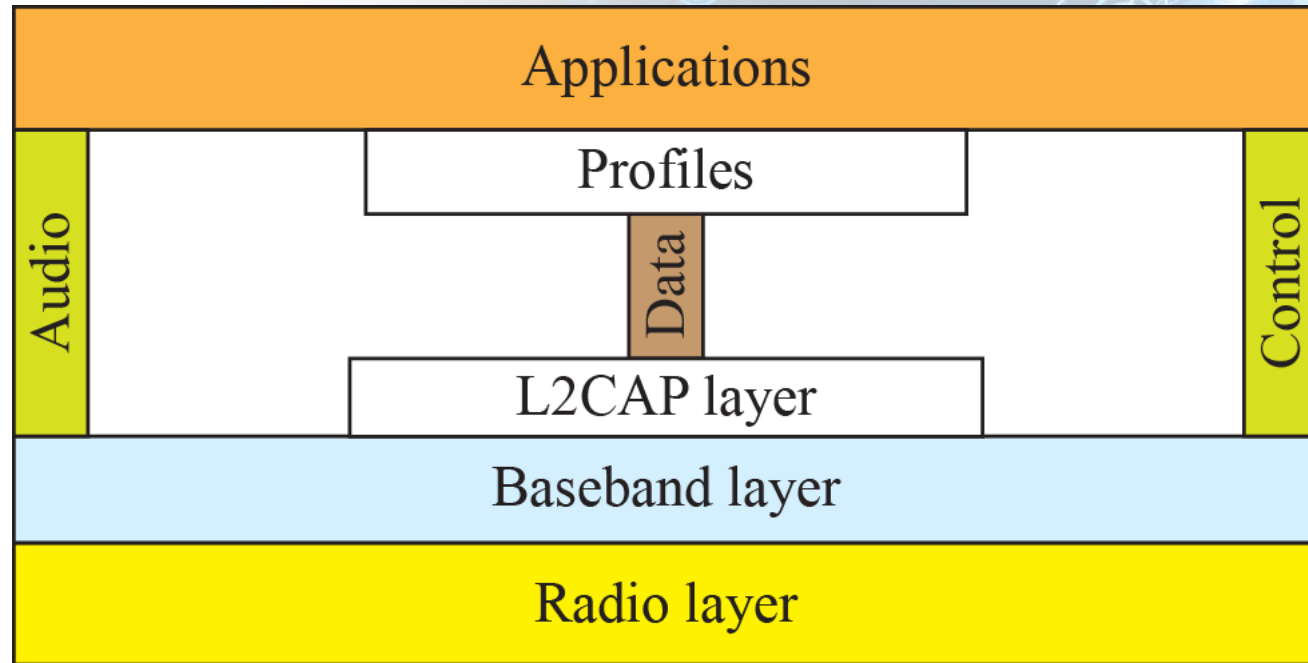
Scatternet



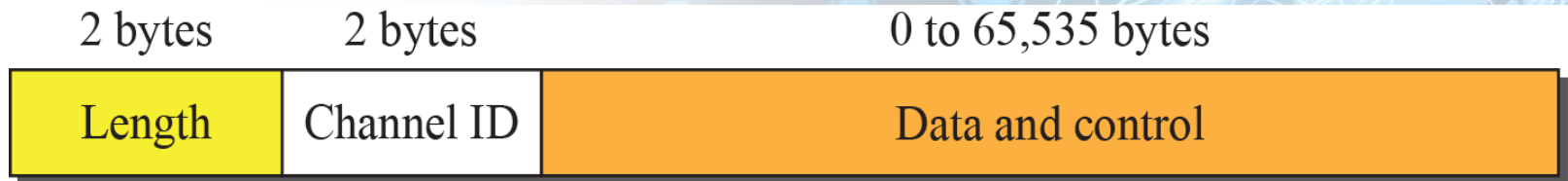
Bluetooth Layers

- **Bluetooth uses several layers that do not exactly match those of the Internet model we have defined in this book**

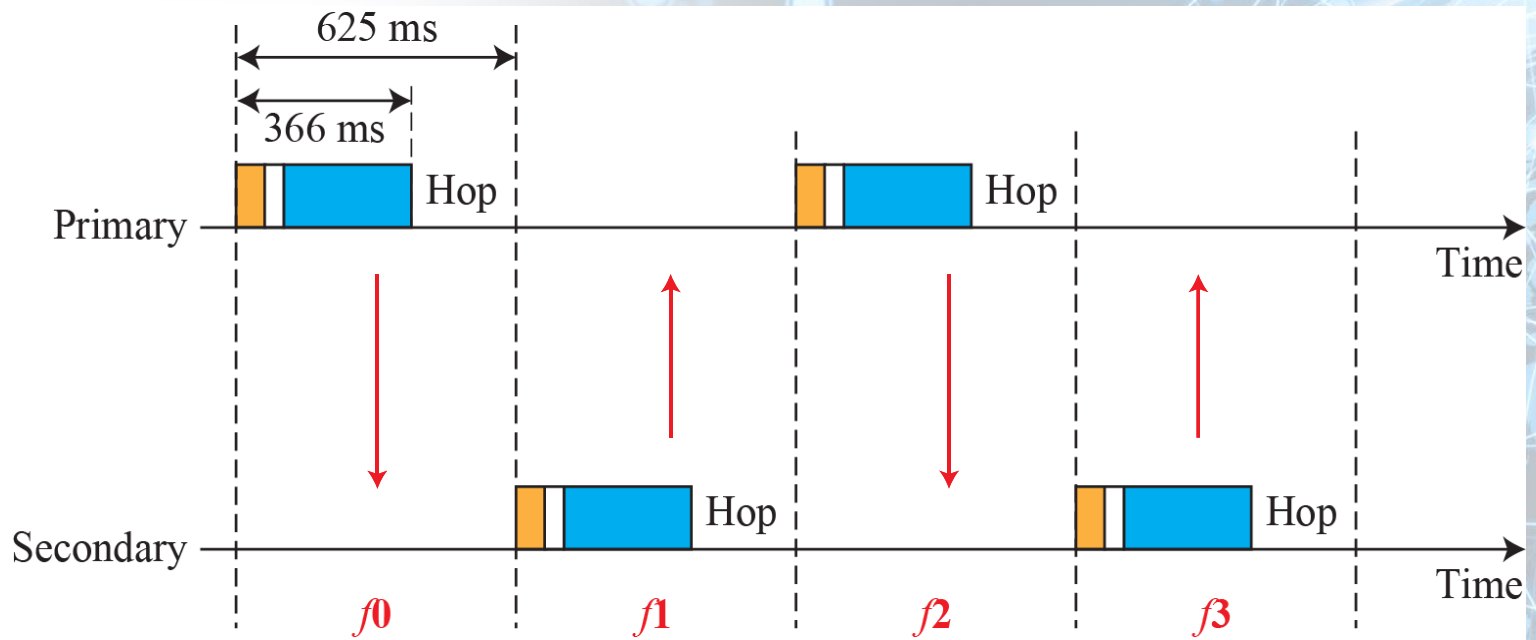
Bluetooth Layers



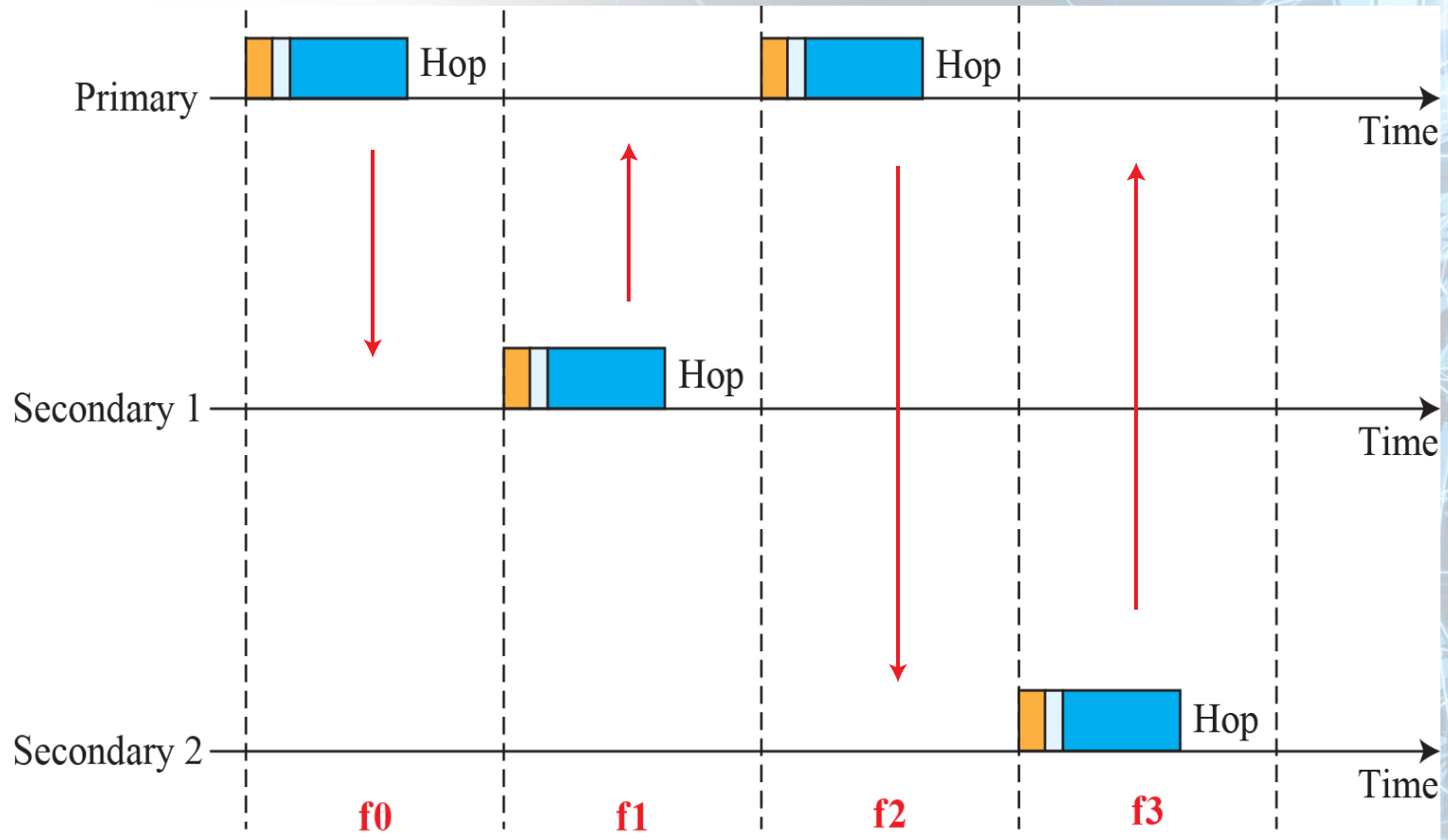
L2CAP Data Packet Format



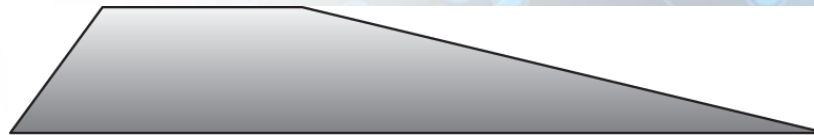
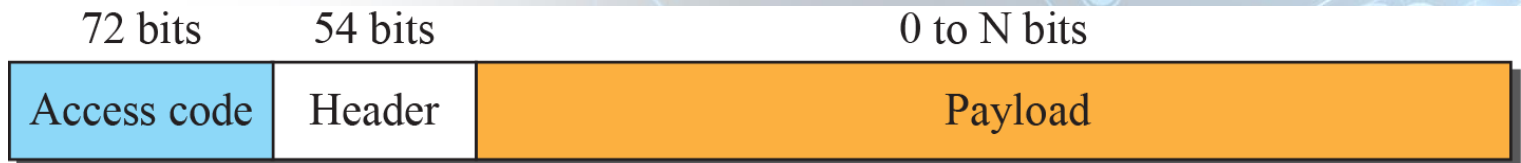
Single-Secondary Communication



Multiple-Secondary Communication



Frame Format Types



3 bits 4 bits 1 1 1 8 bits

This 18-bit part is repeated 3 times.

N = 240 for 1-slot frame

N = 1490 for 3-slot frame

N = 2740 for 5-slot frame

Bluetooth

- **Bluetooth is a wireless LAN technology designed to connect devices of different functions when they are at a short distance from each other**
- **A Bluetooth LAN is an ad hoc network**
- **The devices, sometimes called gadgets, find each other and make a network called a Piconet**

Bluetooth

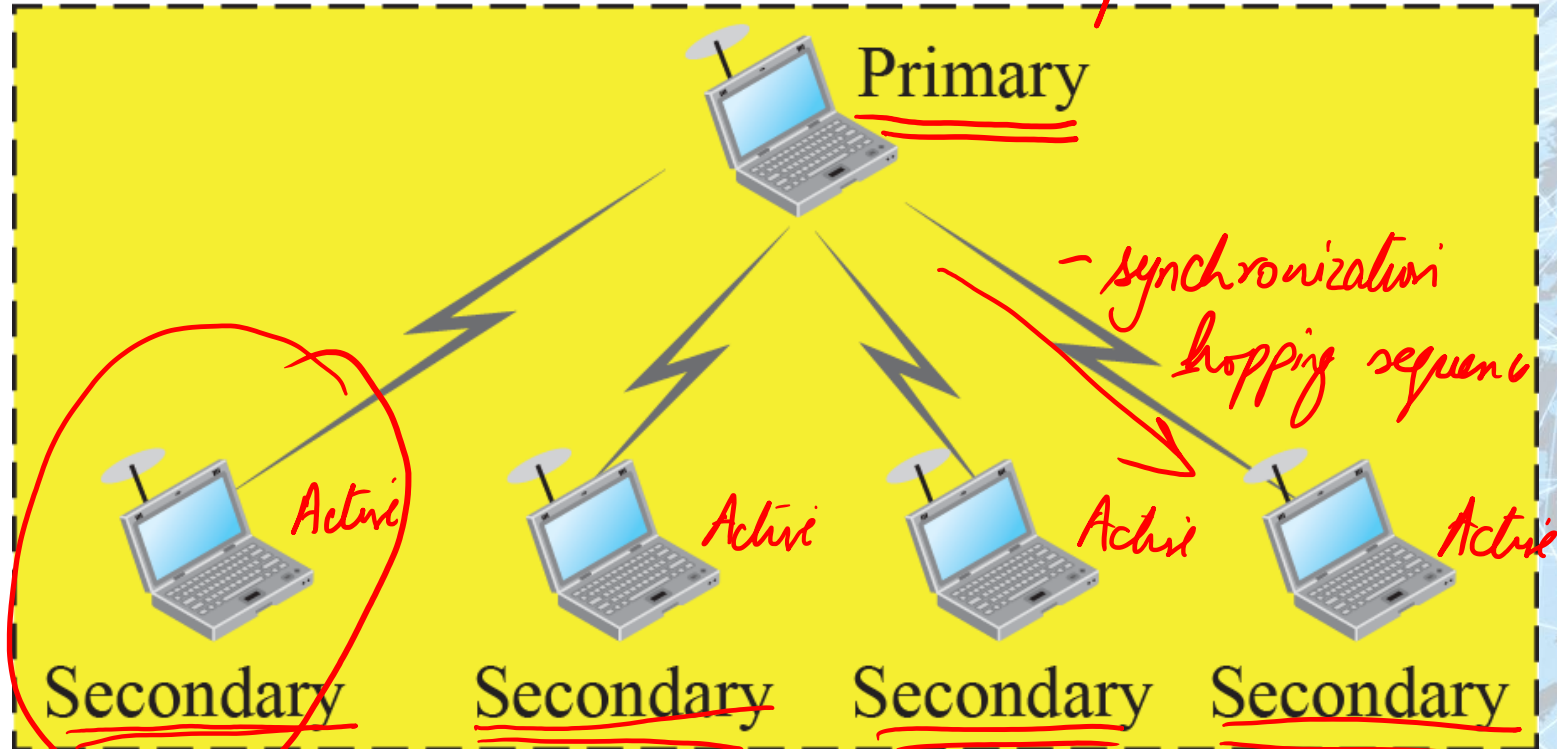
- **Bluetooth technology is the implementation of a protocol defined by the IEEE 802.15 standard**
- **The standard defines a wireless Personal-Area Network (PAN) operable in an area the size of a room or a hall**

Architecture

- **Bluetooth defines two types of networks:**
 - ✓ **Piconet**
 - ✓ **Scatternet**

Piconet

Piconet



upto 8 stations

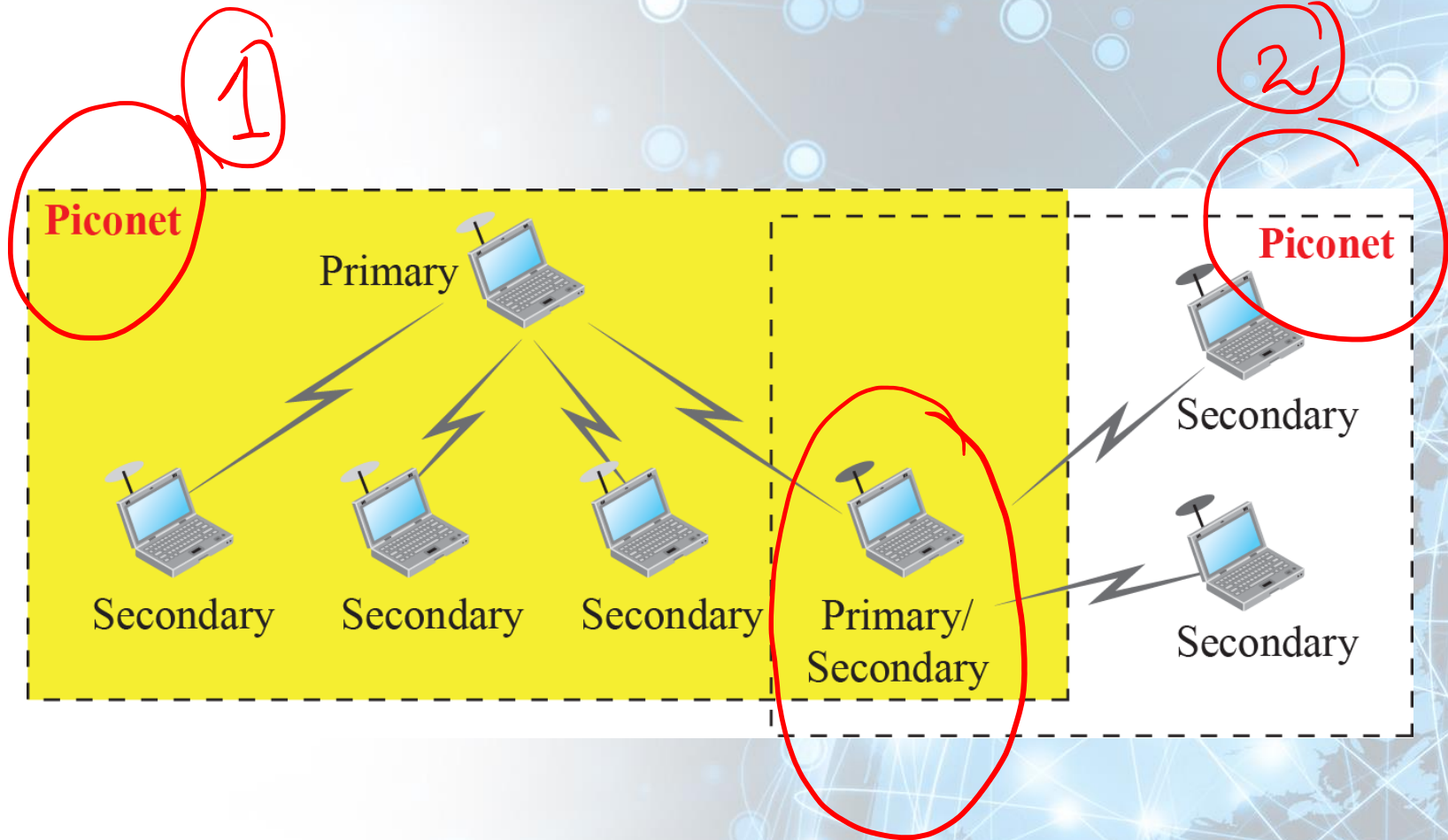
- synchronization hopping sequence

Parked state

Active State

Parked state

Scatternet



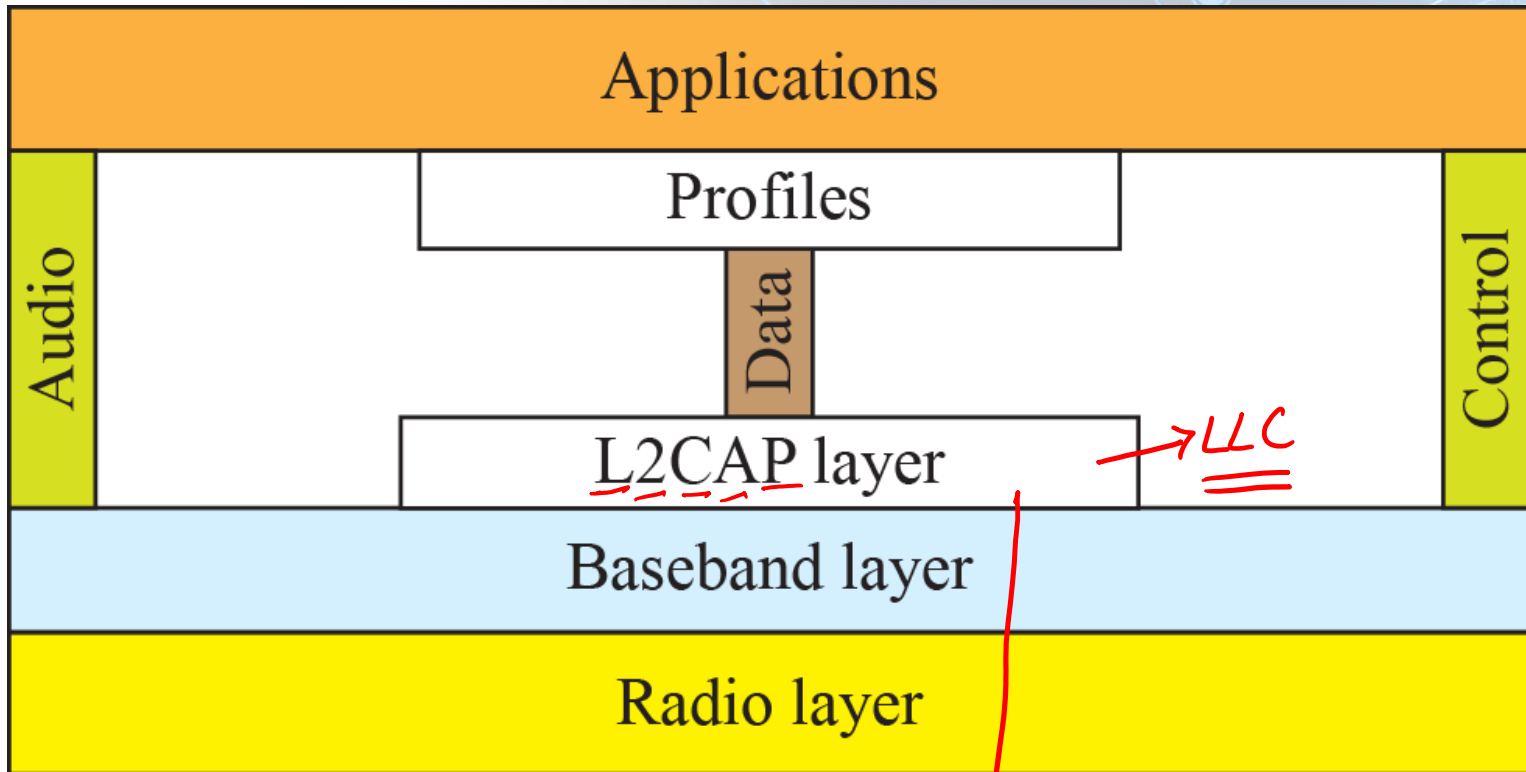
Bluetooth Devices

- A Bluetooth device has a built-in short-range radio transmitter
- The current data rate is 1 Mbps with a 2.4-GHz bandwidth
- This means that there is a possibility of interference between the IEEE 802.11b wireless LANs and Bluetooth LANs

Bluetooth Layers

- **Bluetooth uses several layers that do not exactly match those of the Internet model we have defined already**

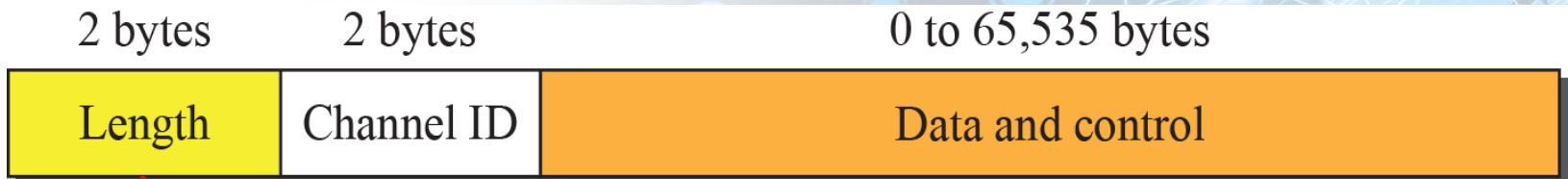
Bluetooth Layers



QoS

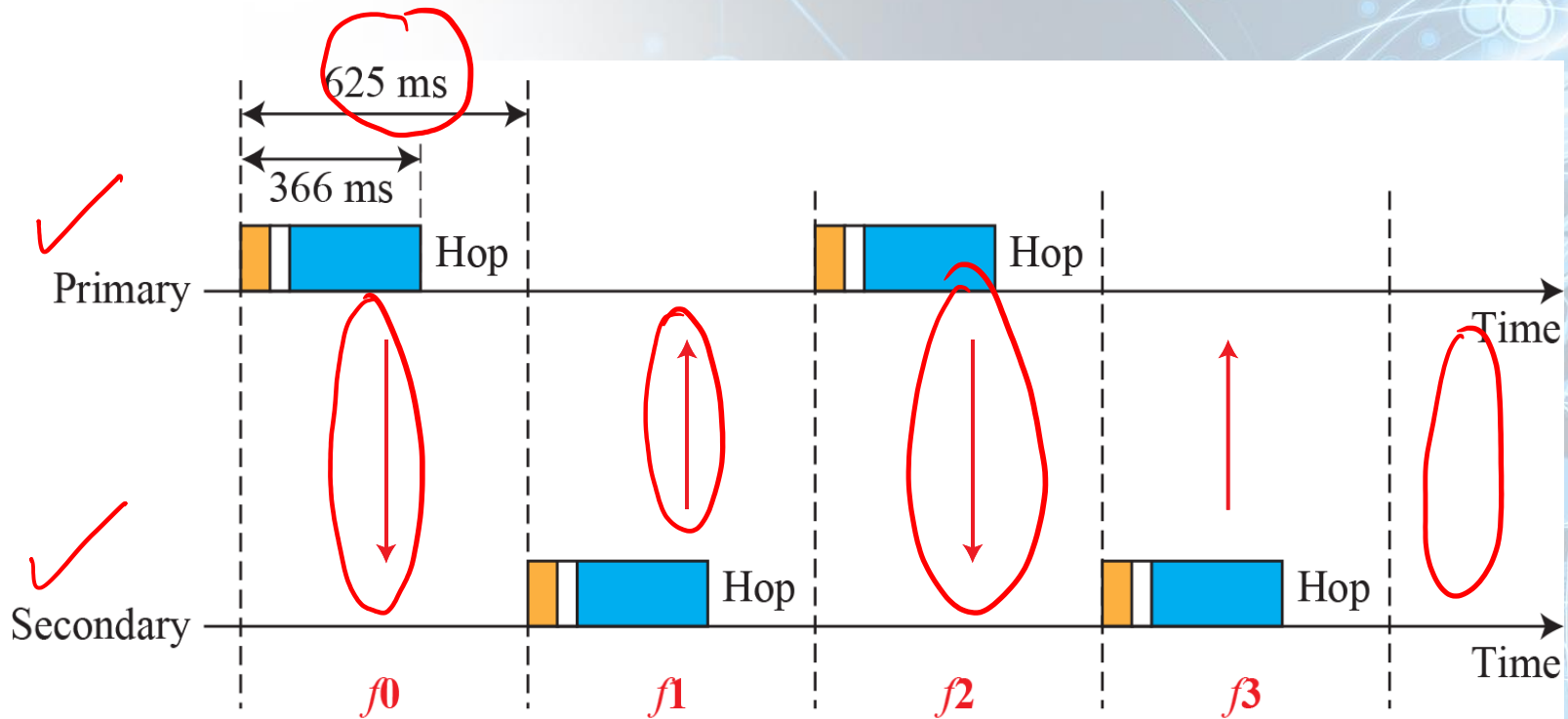
Multiplexing
Segmentation
Reassembly

L2CAP Data Packet Format

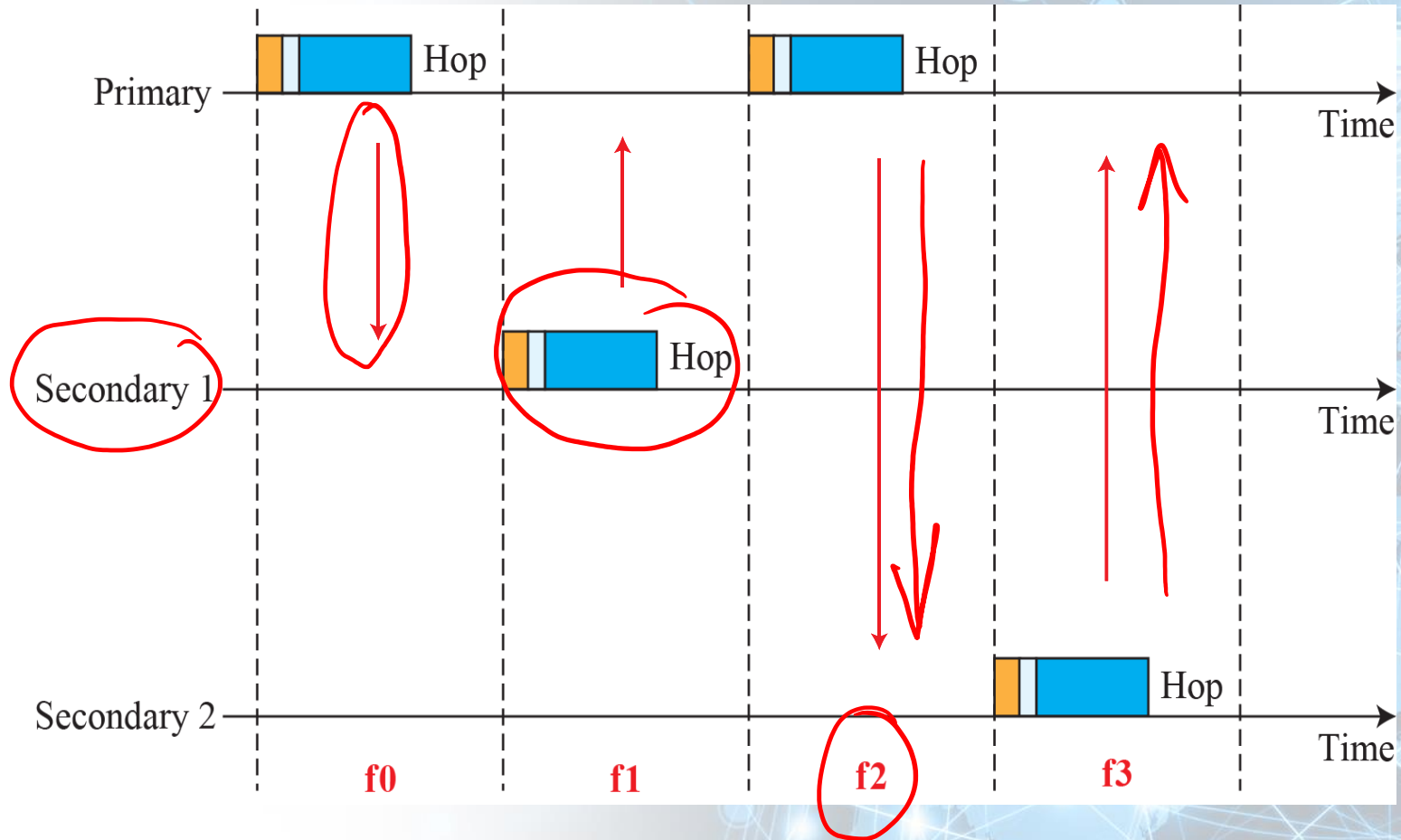


Single-Secondary Communication

TDD-TDMA



Multiple-Secondary Communication



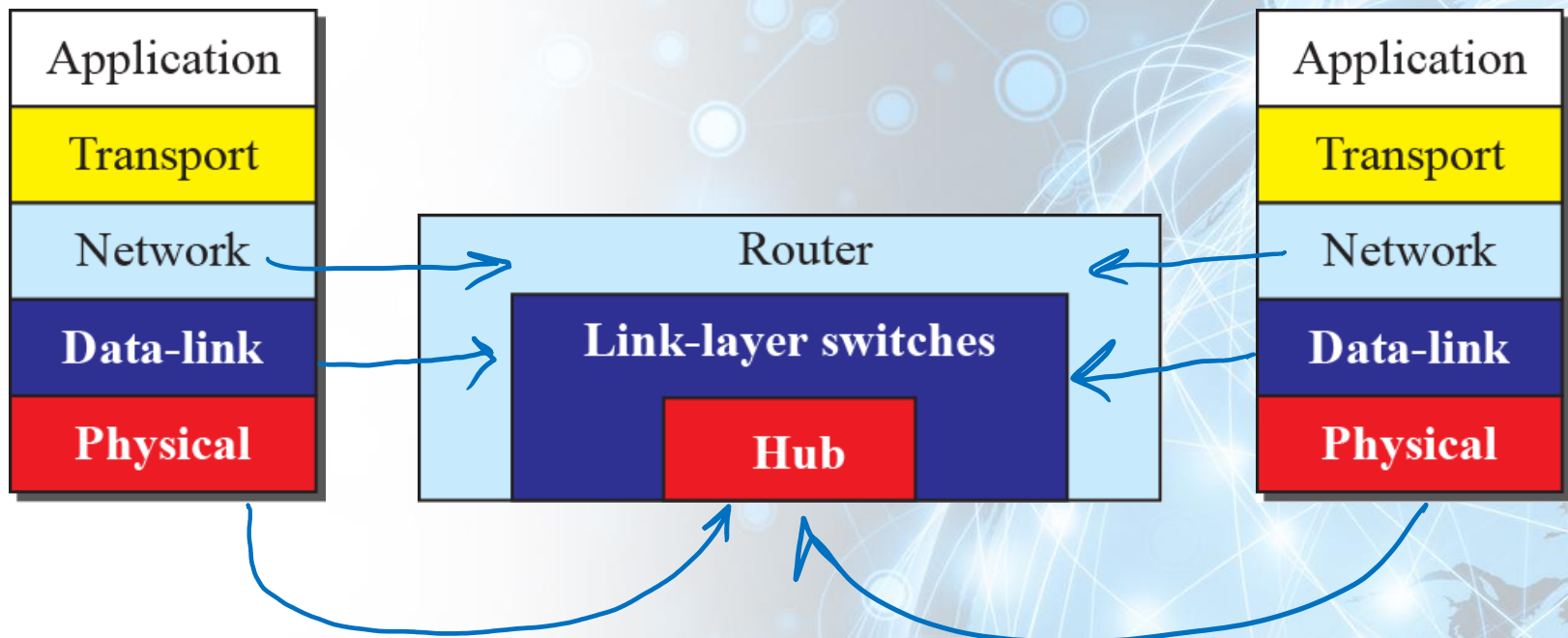
Connecting Devices

- **Hosts and networks do not normally operate in isolation**
- **Connecting devices connect hosts together to make a network or connect networks together to make an internet**
- **Connecting devices can operate in different layers of the Internet model**

Connecting Devices

- **Three kinds of connecting devices:**
 - ✓ **Hubs**
 - ✓ **Link-layer switches**
 - ✓ **Routers**

Three Categories of Connecting Devices



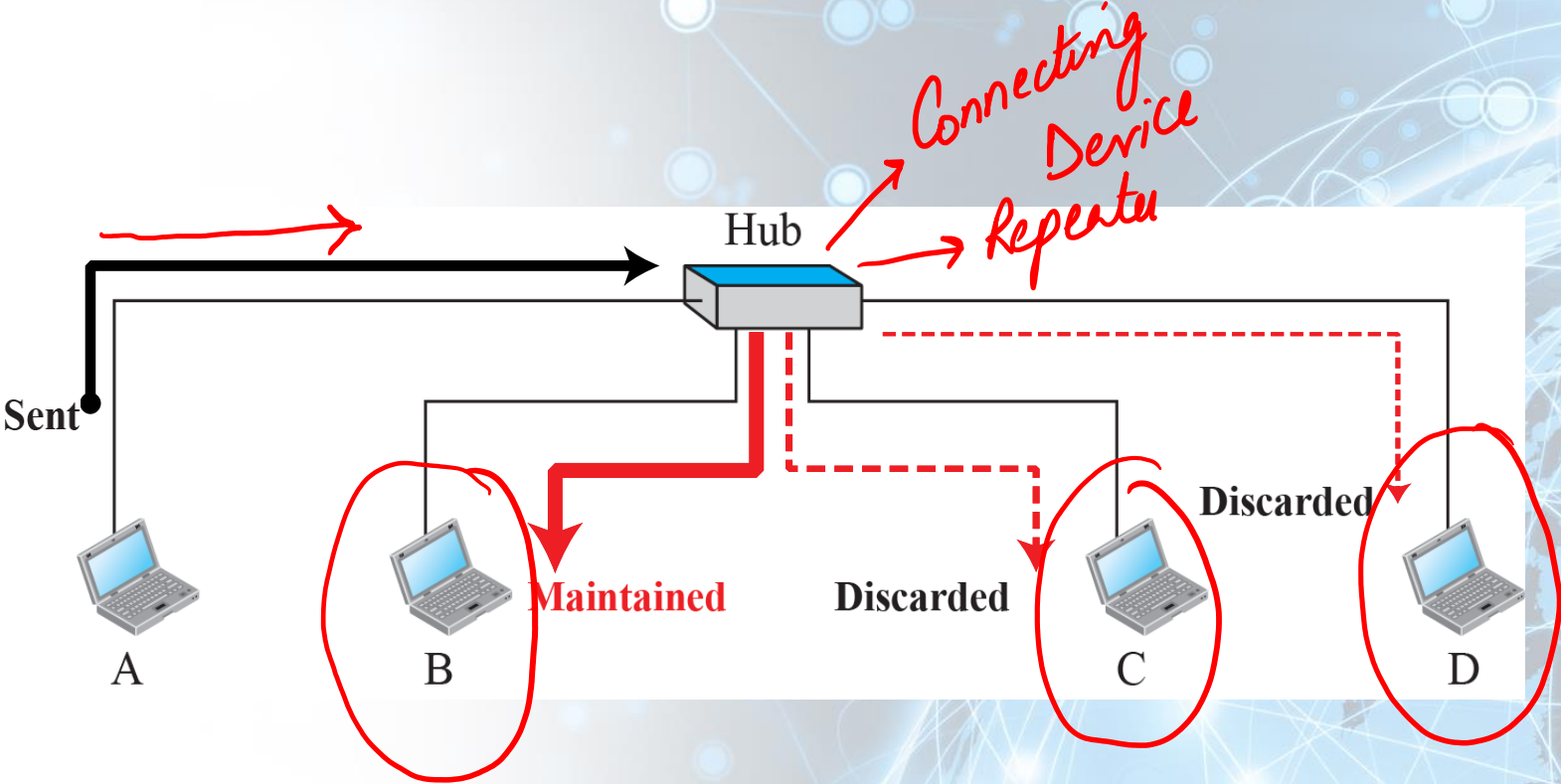
Hubs

- Hub is a device that operates only in the physical layer
- Signals that carry information within a network can travel a fixed distance before attenuation impacts the data
- A hub (repeater) receives a signal and, before it becomes too weak or corrupted, regenerates it

Hubs

- Hub is a device that operates only in the physical layer

Hub



Filtering

Link-Layer Switches

- A link-layer switch (or switch) operates in both the physical and the data-link layers
- As a physical-layer device, it regenerates the signal it receives
- As a link-layer device, the link-layer switch can check the MAC addresses (source and destination) contained in the frame

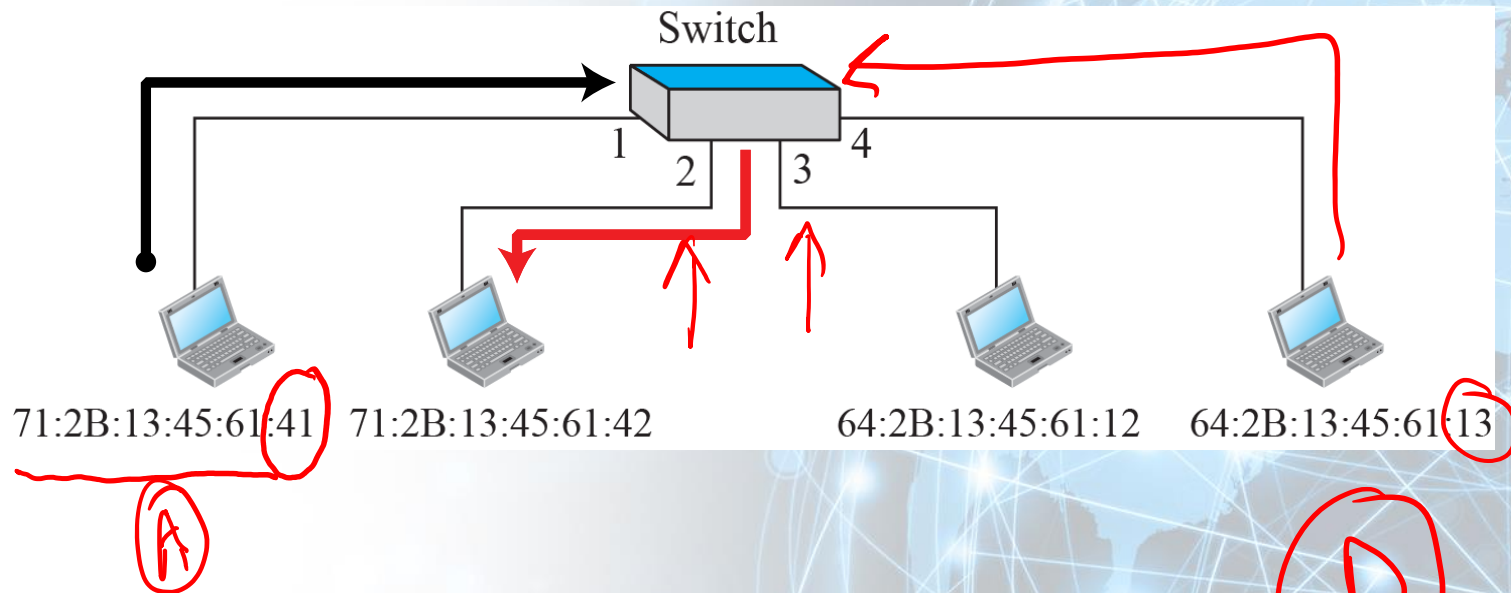
Switch versus Hub

- **Switch has the 'Filtering' capability**
- **Unlike hub, a switch can check the destination address of a frame and decide on outgoing port**
- **Switch eliminates collisions and does not require carrier sensing**
- **Switches connect heterogeneous devices**

Link-Layer Switch

Switching table

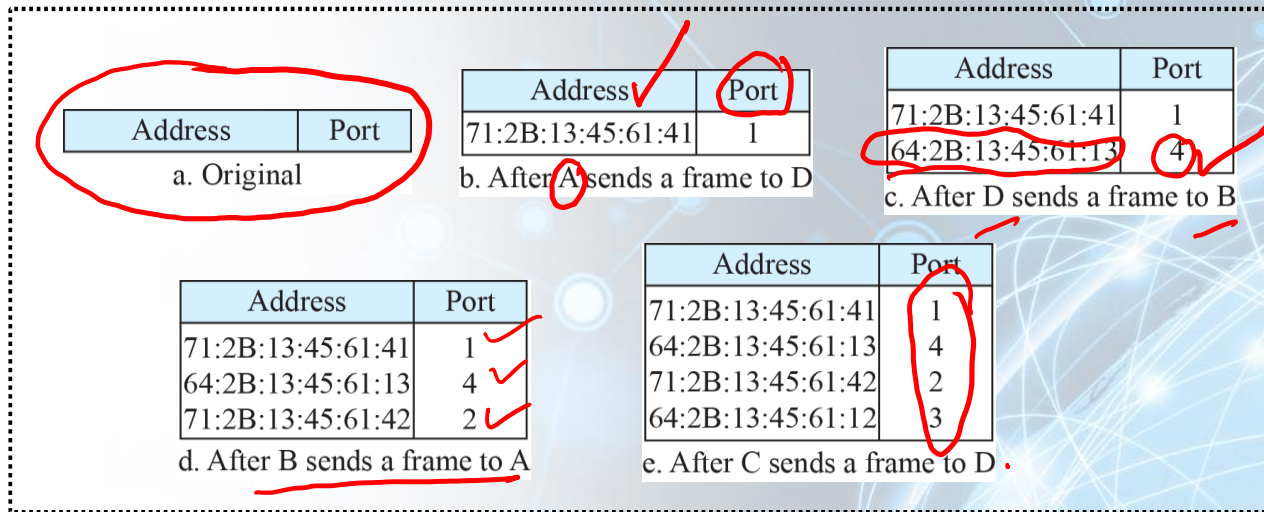
Address	Port
71:2B:13:45:61:41	1
71:2B:13:45:61:42	2
64:2B:13:45:61:12	3
64:2B:13:45:61:13	4



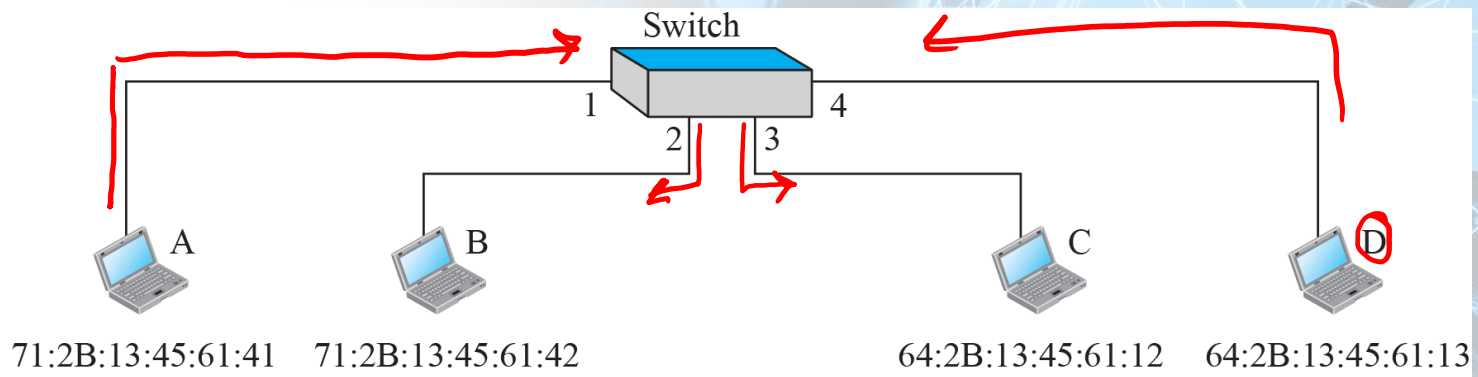
Link-Layer Switches

- A link-layer switch (or switch) operates in both the physical and the data-link layers

Learning Switch



Gradual building of Table

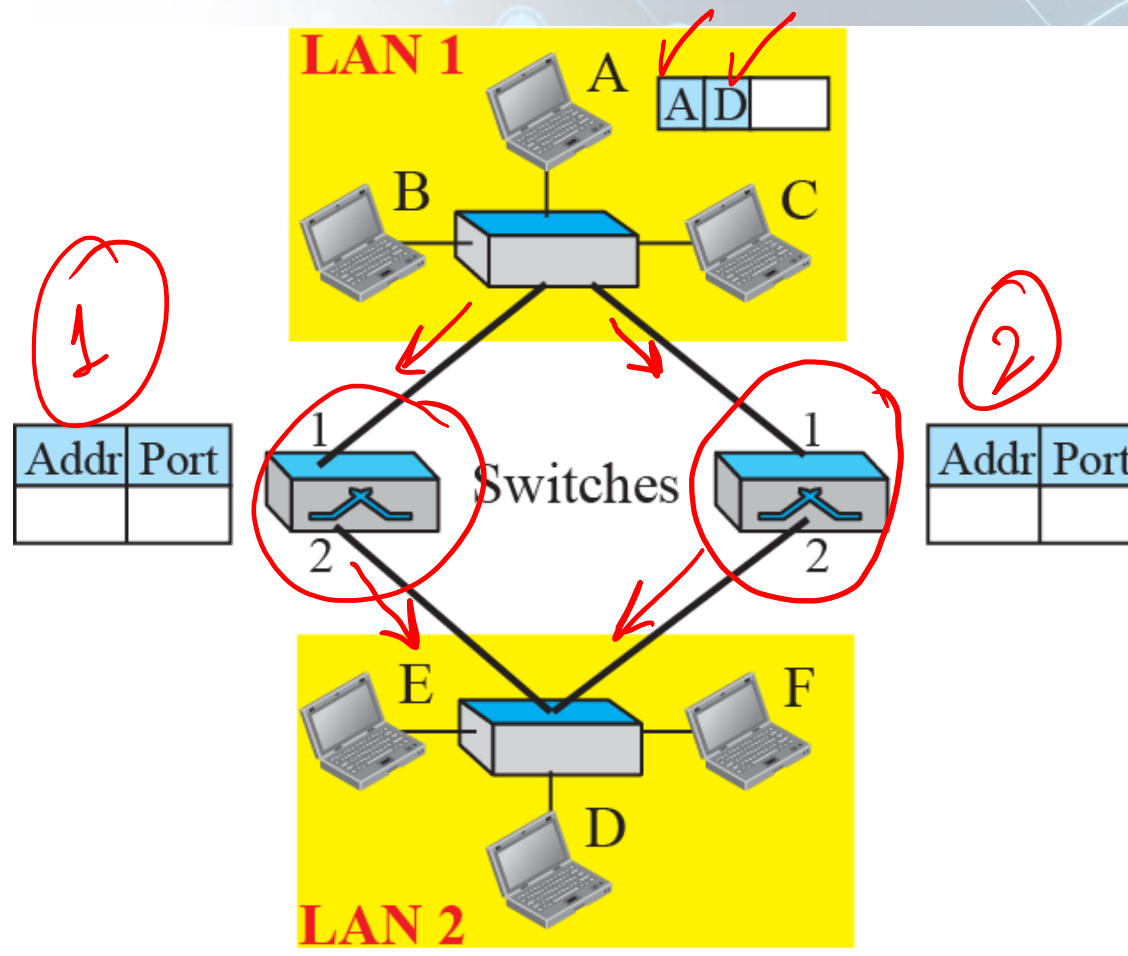


Loop Problem in a Switch

- **Redundant switches create Loops in the system**
- **Created when two or more broadcasting LANs are connected by more than one switch**

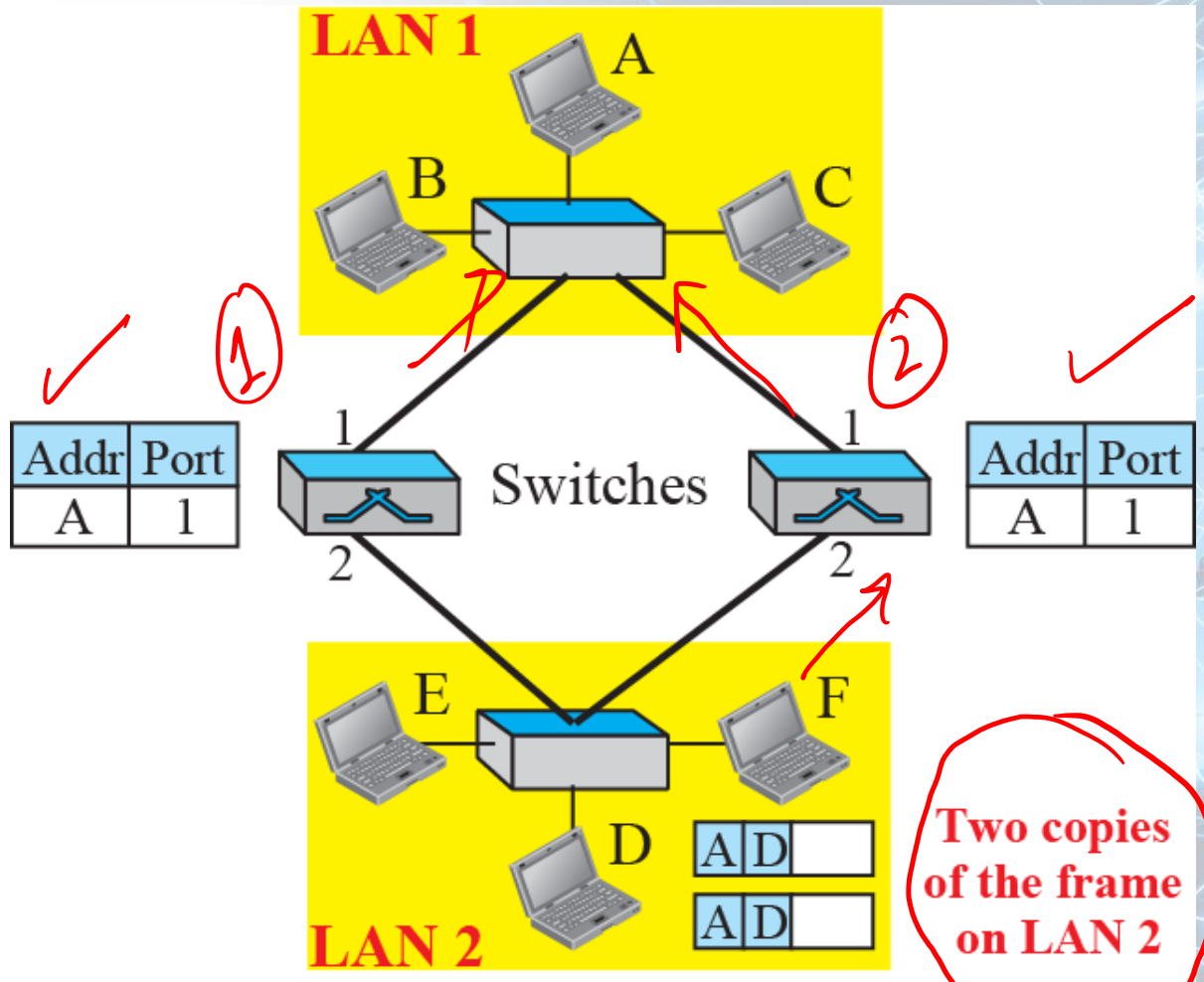
Loop Problem in a Learning Switch (Part a)

a. Station A sends a frame to station D



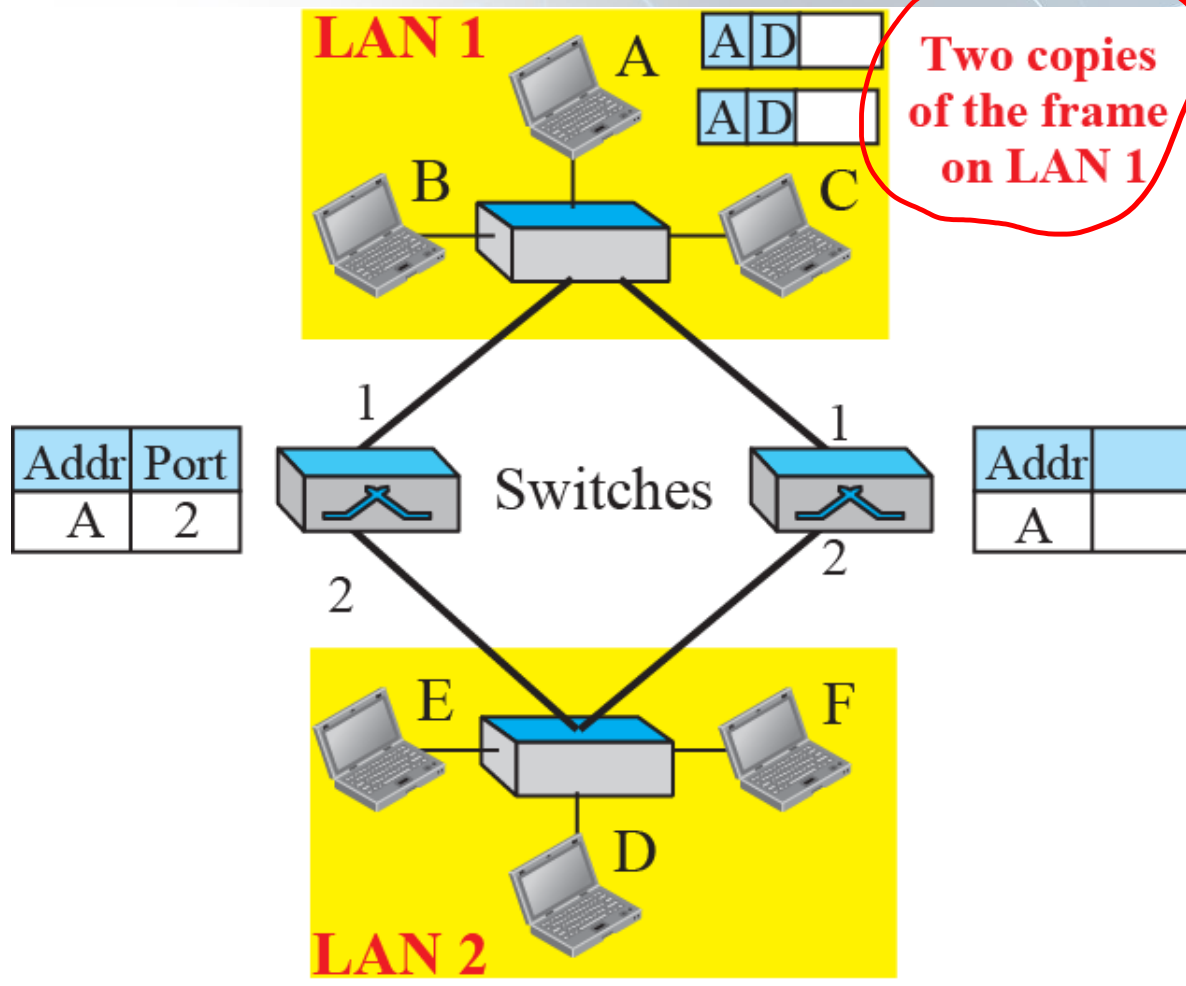
Loop Problem in a Learning Switch (Part b)

b. Both switches forward the frame



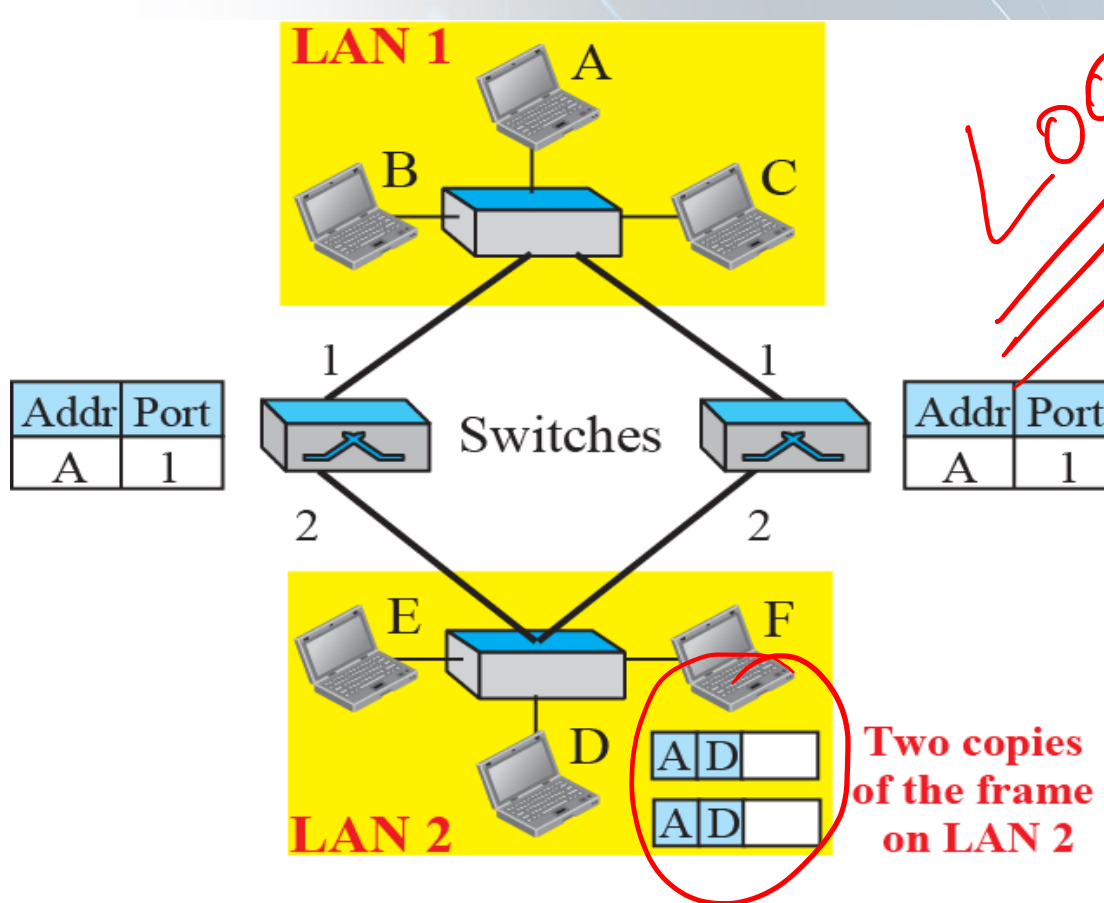
Loop Problem in a Learning Switch (Part c)

c. Both switches forward the frame



Loop Problem in a Learning Switch (part d)

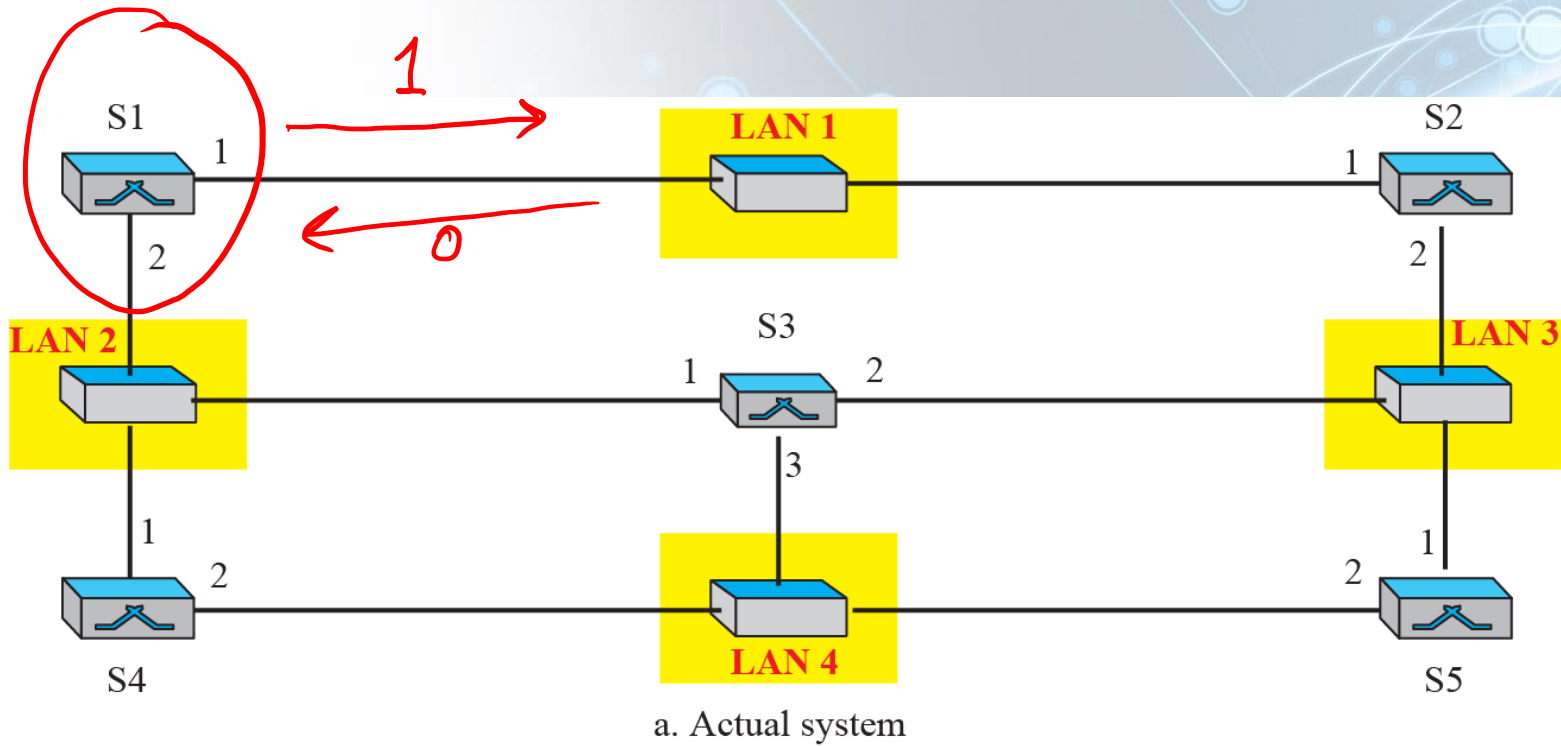
d. Both switches forward the frame



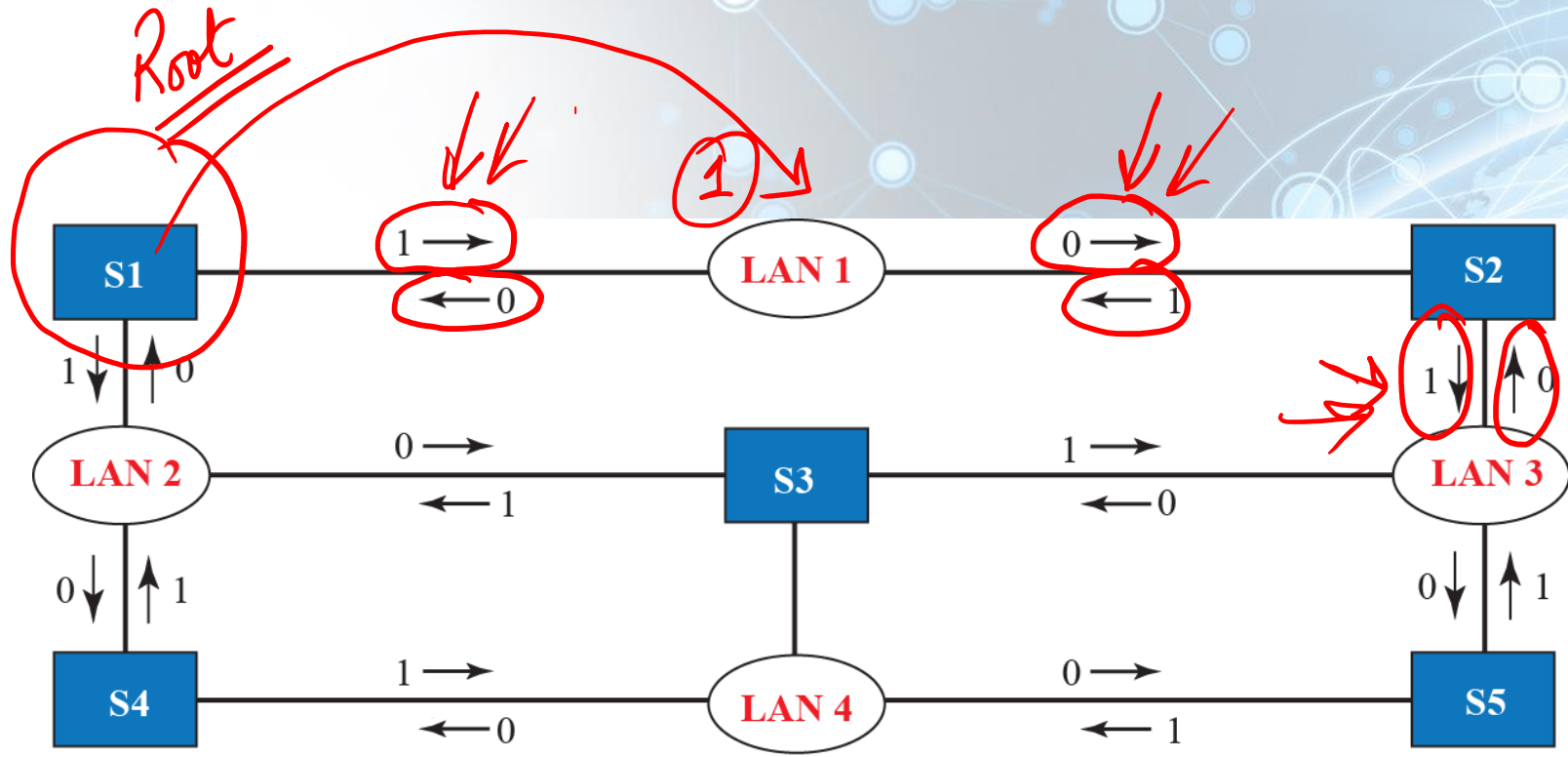
Spanning Tree Algorithm

- In graph theory, Spanning Tree is a graph in which there is no loop
- In a switched LAN, this means creating a topology in which each LAN can be reached from any other LAN through one path only (no loop)
- To find the spanning tree, we assign a cost (metric) to each LAN link

A system of Connected LANs and its Graph (Part a)

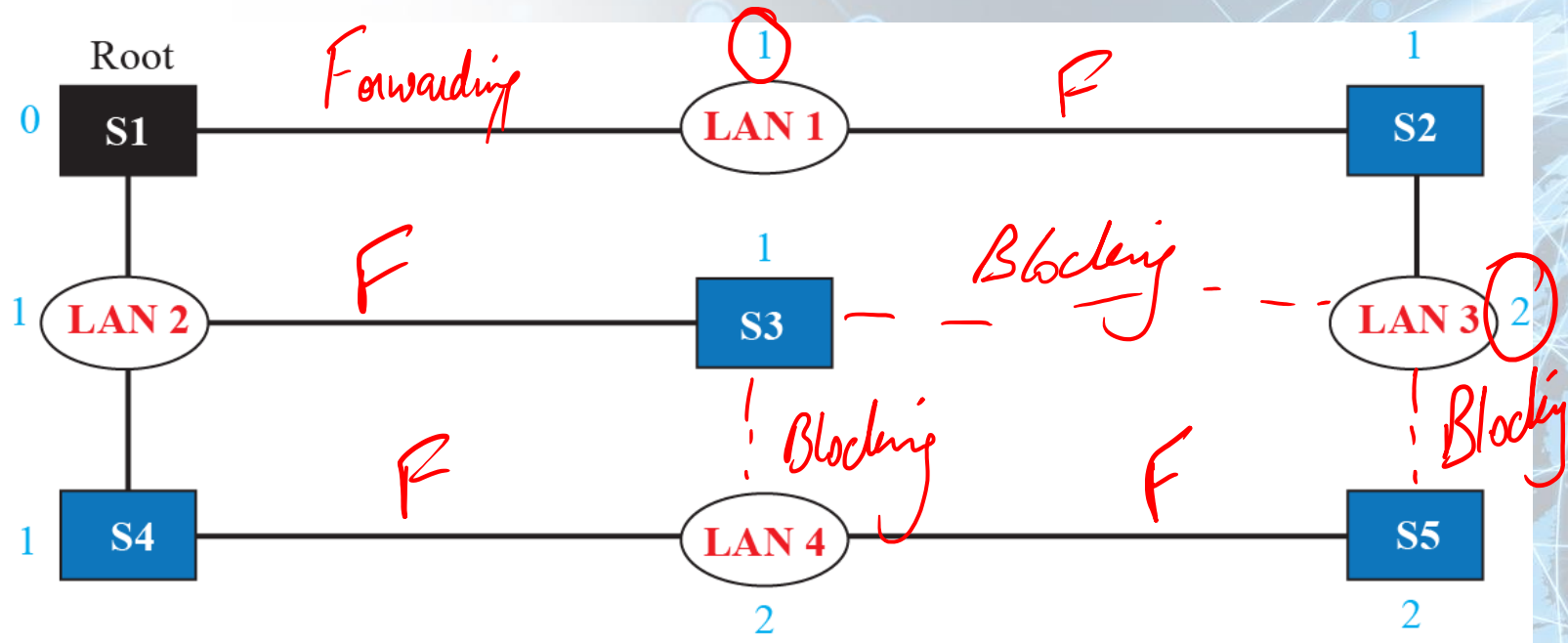


A System of Connected LANs and its Graph (Part b)



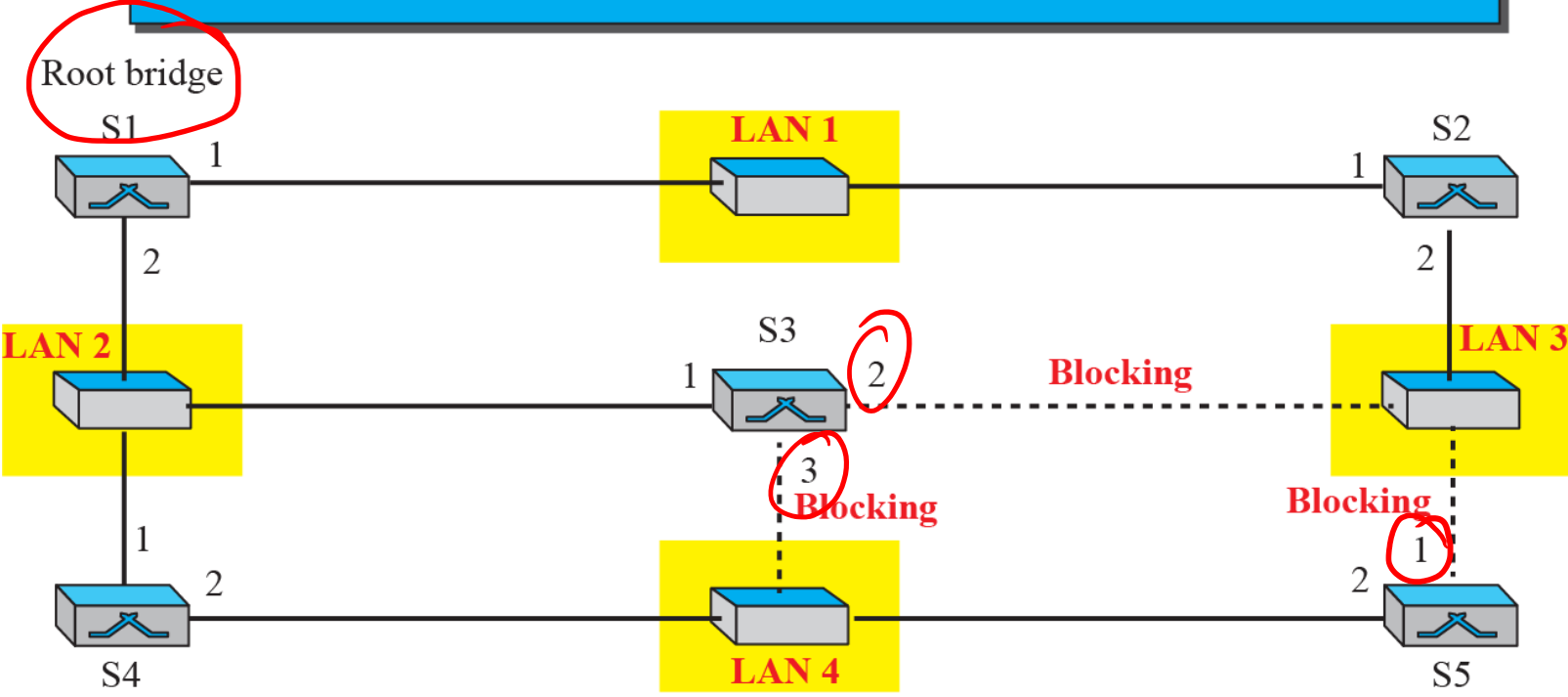
b. Graph representation with cost assigned to each arc

Finding Shortest Path/Spanning Tree for a Switch



Forwarding & Blocking Ports after using Spanning Tree

Ports 2 and 3 of bridge S3 are blocking ports (no frame is sent out of these ports).
Port 1 of bridge S5 is also a blocking port (no frame is sent out of this port).



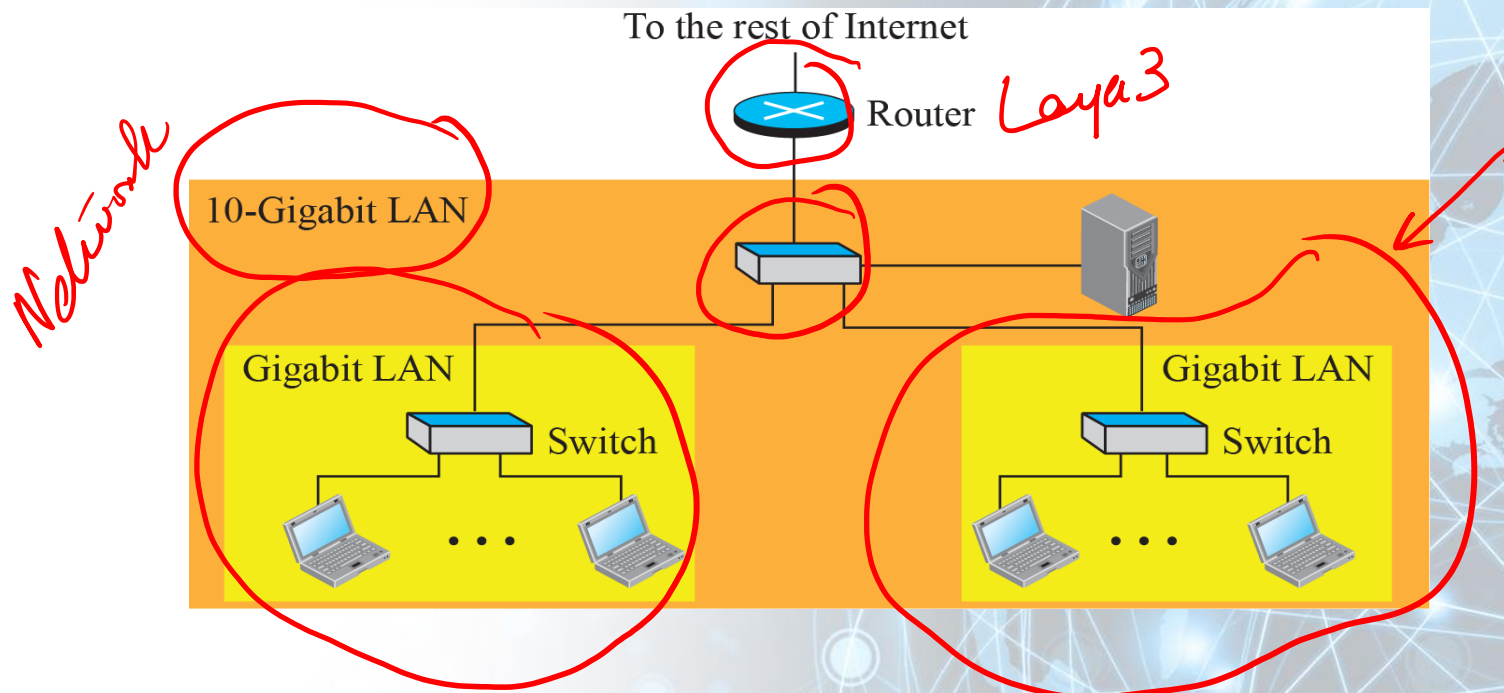
Routers

- We compare routers to two-layer switch and a hub
- A router is a three-layer device; it operates in the physical, data-link, and network layers

Router vs. Switch

Three differences between a router and a repeater or a switch:

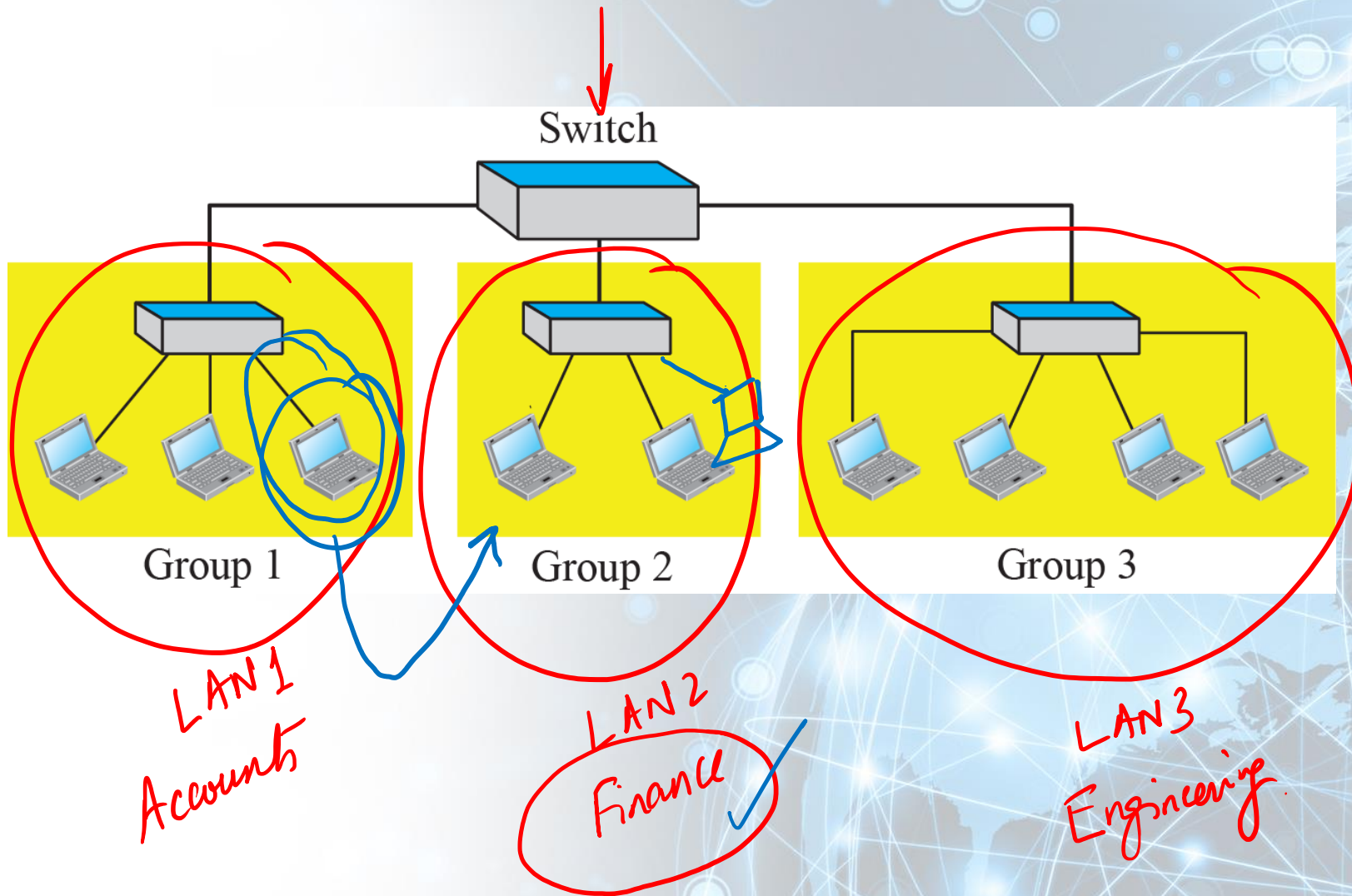
1. A router has a physical and logical (IP) address for each of its interfaces.
2. A router acts only on those packets in which the link-layer destination address matches the address of the interface at which the packet arrives.
3. A router changes the link-layer address of the packet (both source and destination) when it forwards the packet.



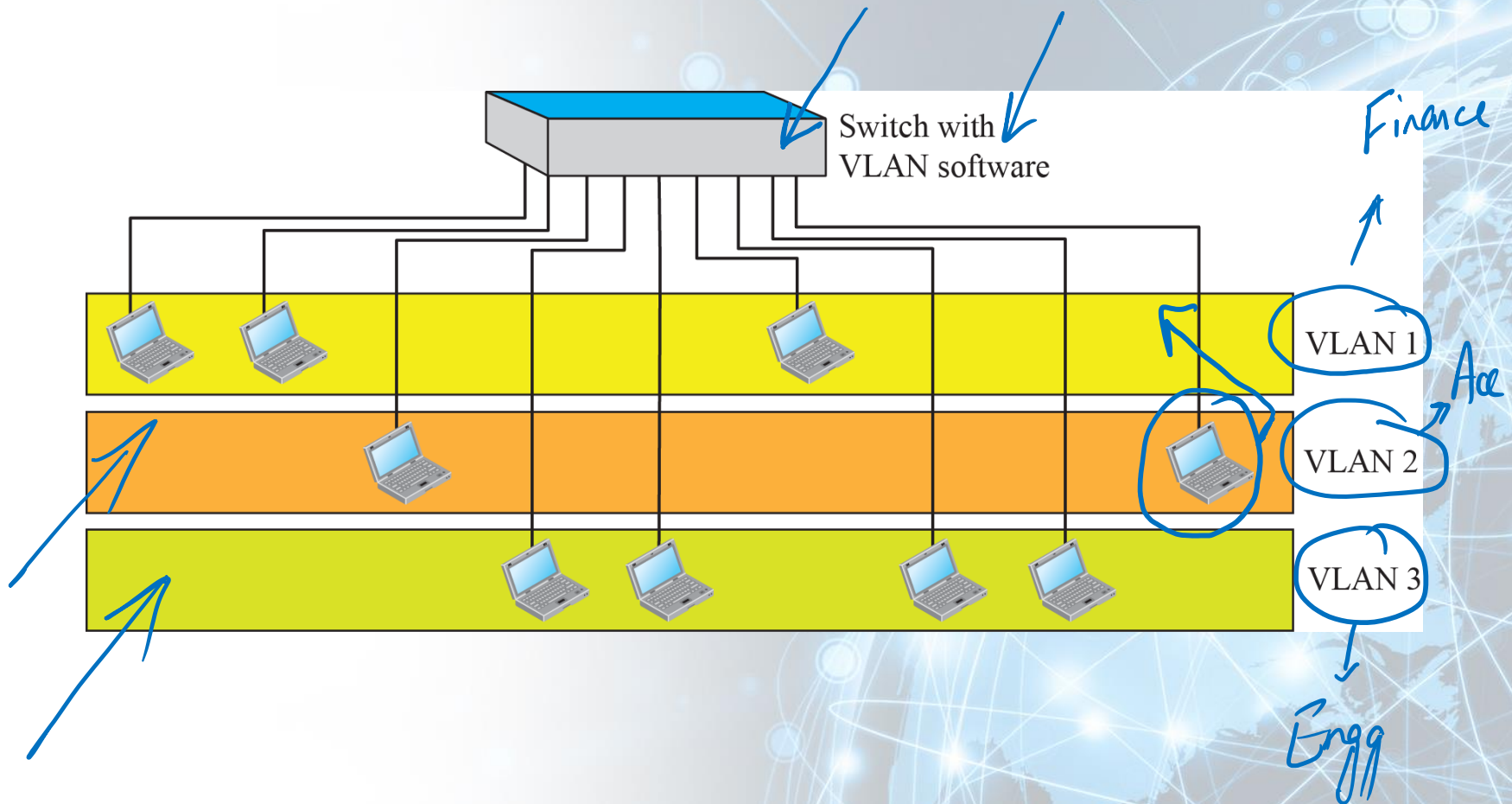
VIRTUAL LANS (VLAN)

- A VLAN is a LAN configured by software, not by physical wiring
- A station is considered part of a LAN if it physically belongs to that LAN i.e. The criterion of membership is geographic
- Provides a virtual connection between two stations belonging to two different physical LANs

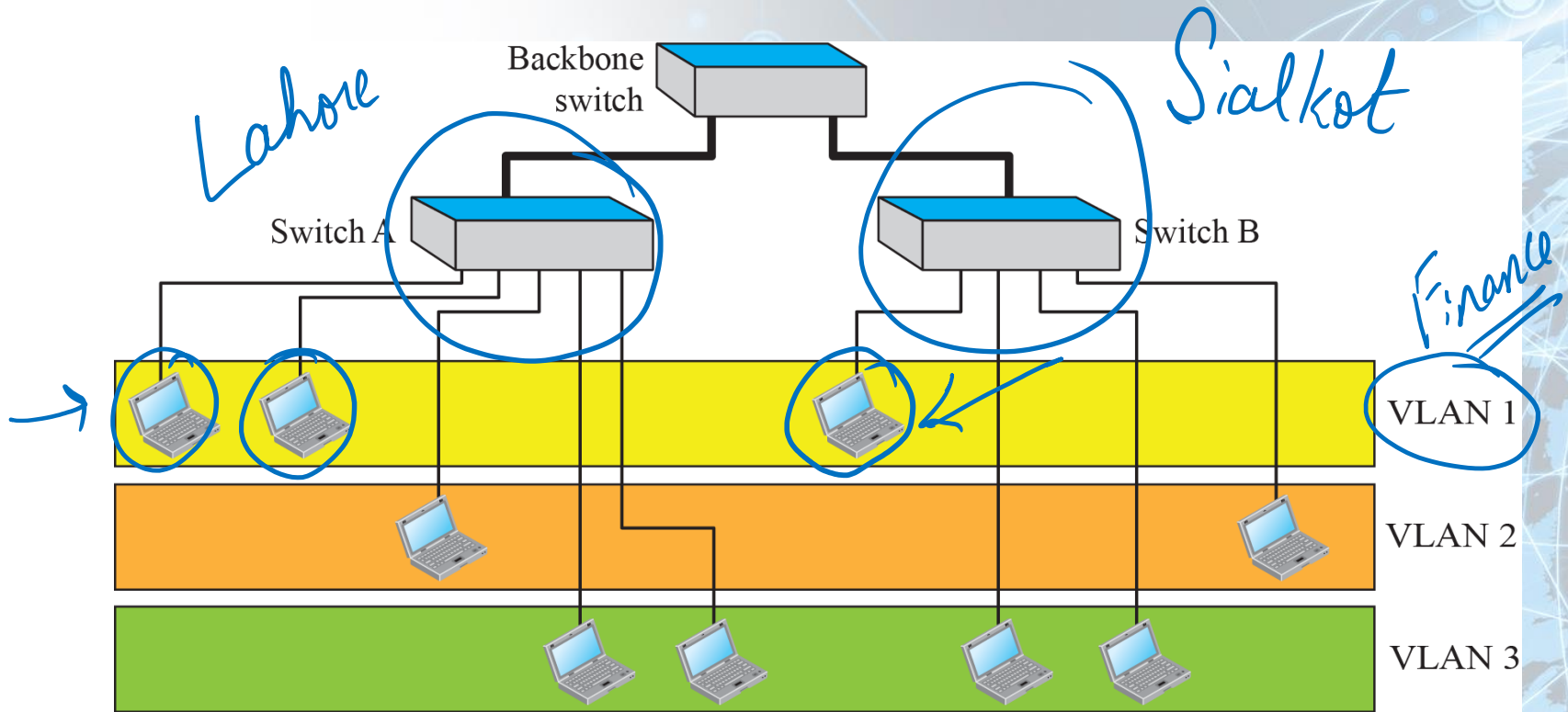
A Switch Connecting three LANs



A Switch using VLAN Software



Two Switches in a Backbone using VLAN Software



Membership of a VLAN

- **What characteristic can be used to group stations in a VLAN?**
- **Vendors use different characteristics such as interface numbers, port numbers, MAC addresses, IP addresses, IP multicast addresses, or a combination of two or more of these**

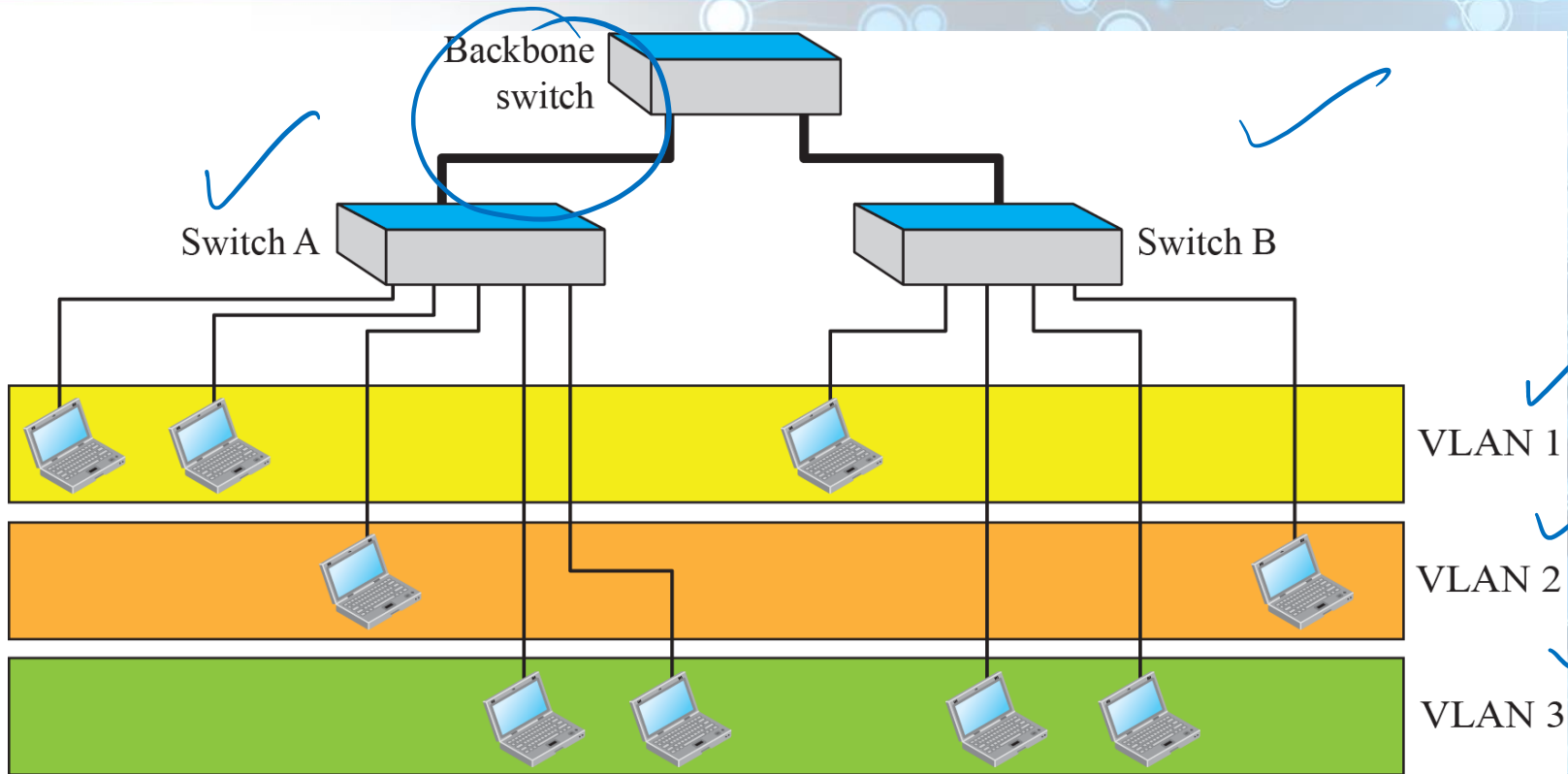
Configuration of a VLAN

- How are the stations grouped into different VLANs?
- Stations are configured in one of three ways:
 - ✓ Manually
 - ✓ Semi-Automatically
 - ✓ Automatically

Communication between Switches

- In a multi-switched backbone, each switch must know:
 - ✓ Which station belongs to which VLAN; and
 - ✓ The membership of stations connected to other switches

Communication between Switches



Switch A must know the membership status of stations connected to switch B, and switch B must know the same about switch A. Three methods have been devised for this purpose: table maintenance, frame tagging, and time-division multiplexing.

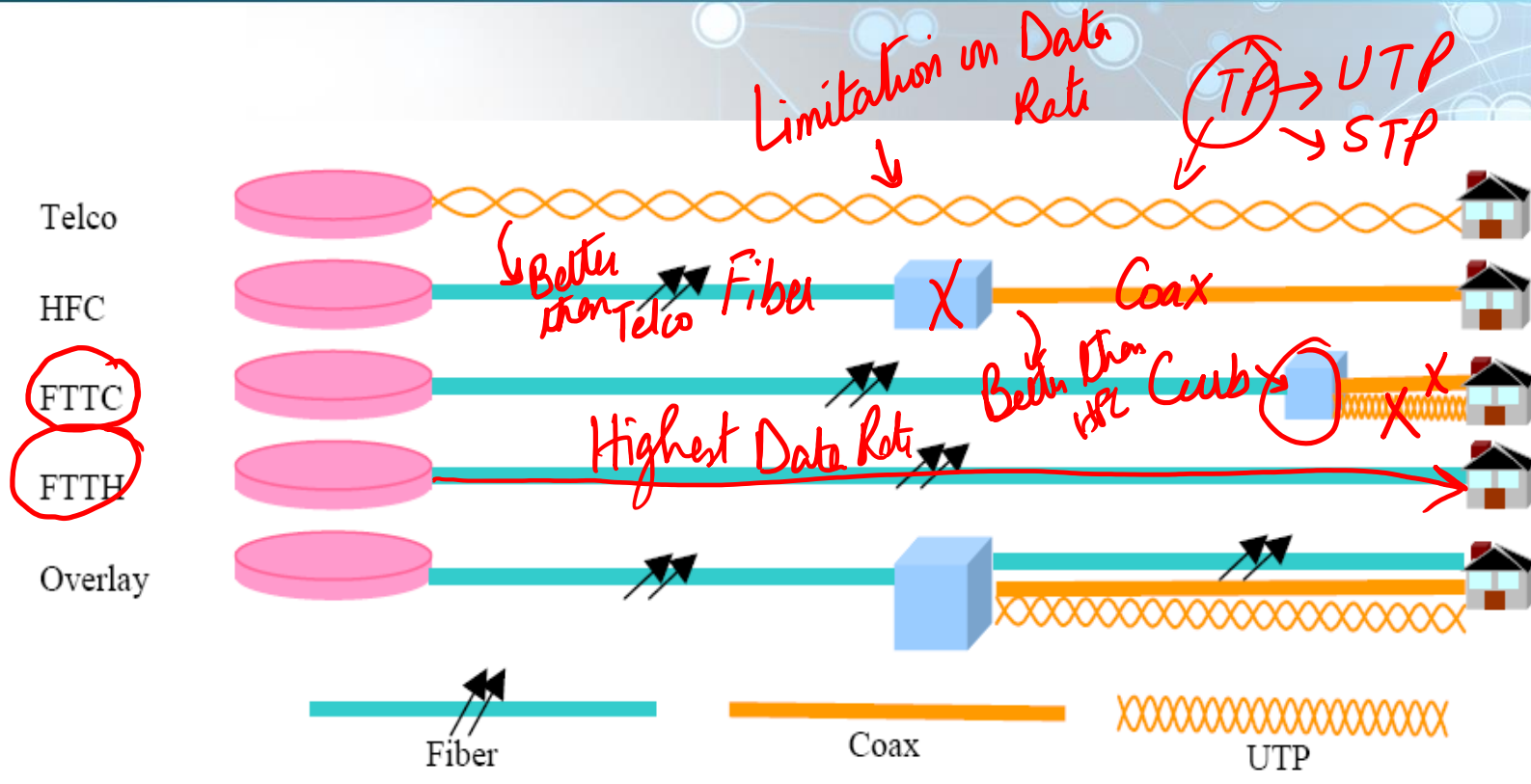
Advantages of using VLANs

- **Cost and Time Reduction**
- **Creating virtual Workgroups**
- **Security**

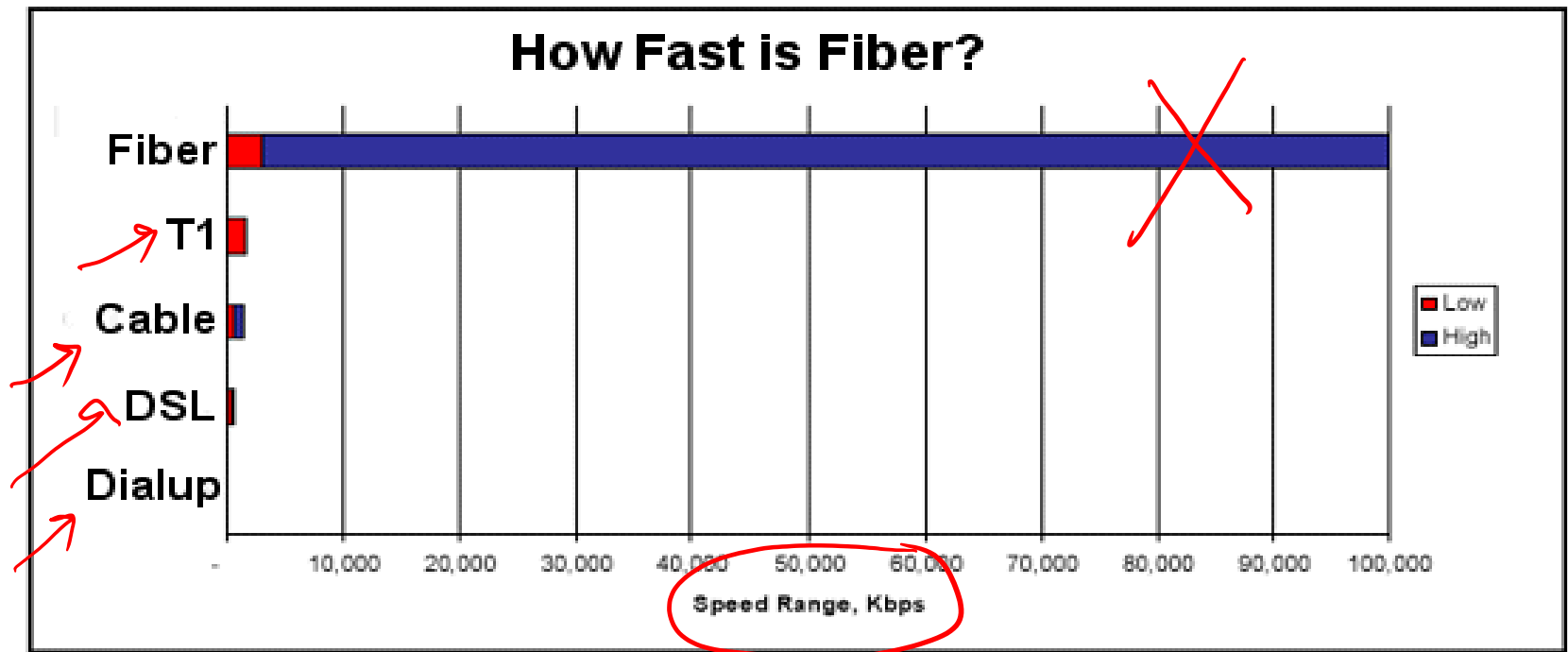
Comparison of Modern Access Technologies

- Telco
- HFC
- FTTx

Comparison of Modern Access Technologies



Fiber – The Medium of the Future!



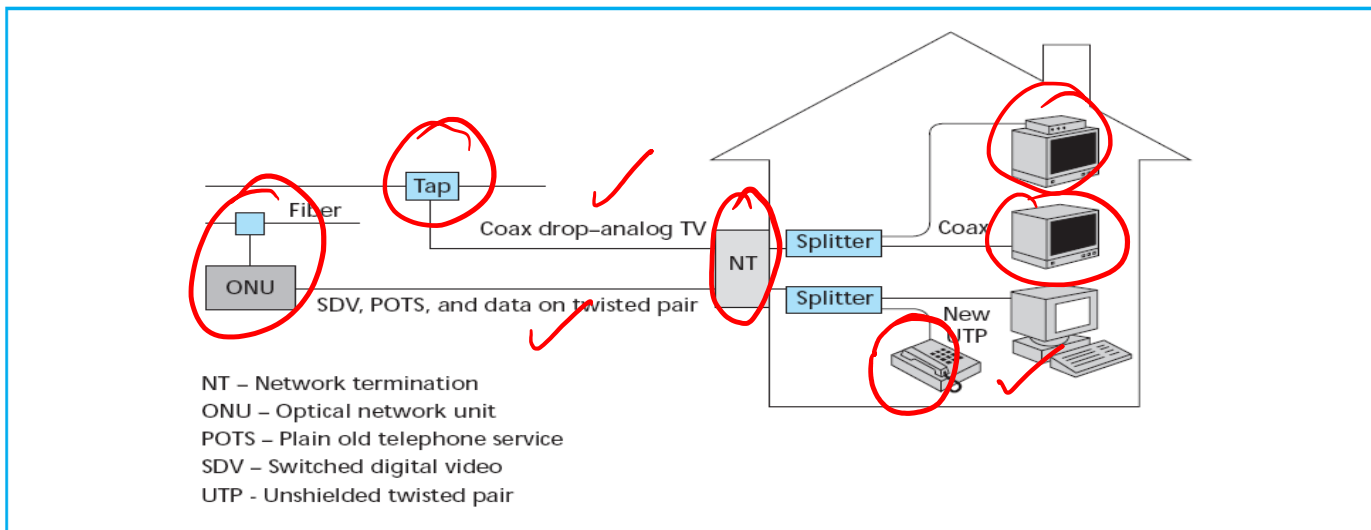
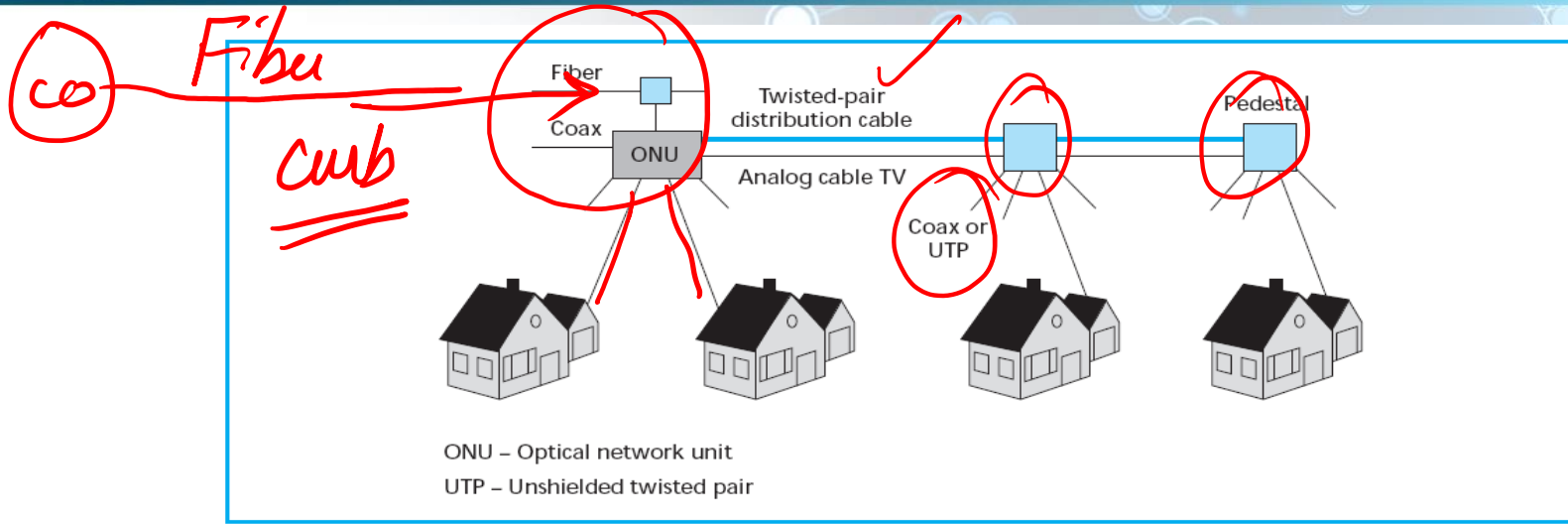
Fiber To The Curb (FTTC)

- An access network in which fiber is used for part, but not the entire link from the provider to the end-user
- An optical to electrical (O/E) conversion takes place somewhere near the end-user
- The terminal network segment of a FTTC network is usually twisted pair or coaxial cable

Fiber To The Curb (FTTC)

- **The final optical receiver in a FTTC network typically serves several customers**

Fiber To The Curb (FTTC)



Fiber To The Home (FTTH)

- **Need: High-speed data, reliable voice and high-quality video**
- **Problems:**
 - ✓ **How to get high speed lines out to each customer?**
 - ✓ **How to future-proof the architecture?**
- **Solution: FTTH**

Fiber To The Home (FTTH)

- **Fiber-to-the-home (FTTH) is the installation of optical fiber from a telephone switch directly into the subscriber's home**
- **It is one of the latest access technologies**
- **FTTH is also referred to as Fiber-to-the-Building (FTTB)**

Fiber To The Home (FTTH)

